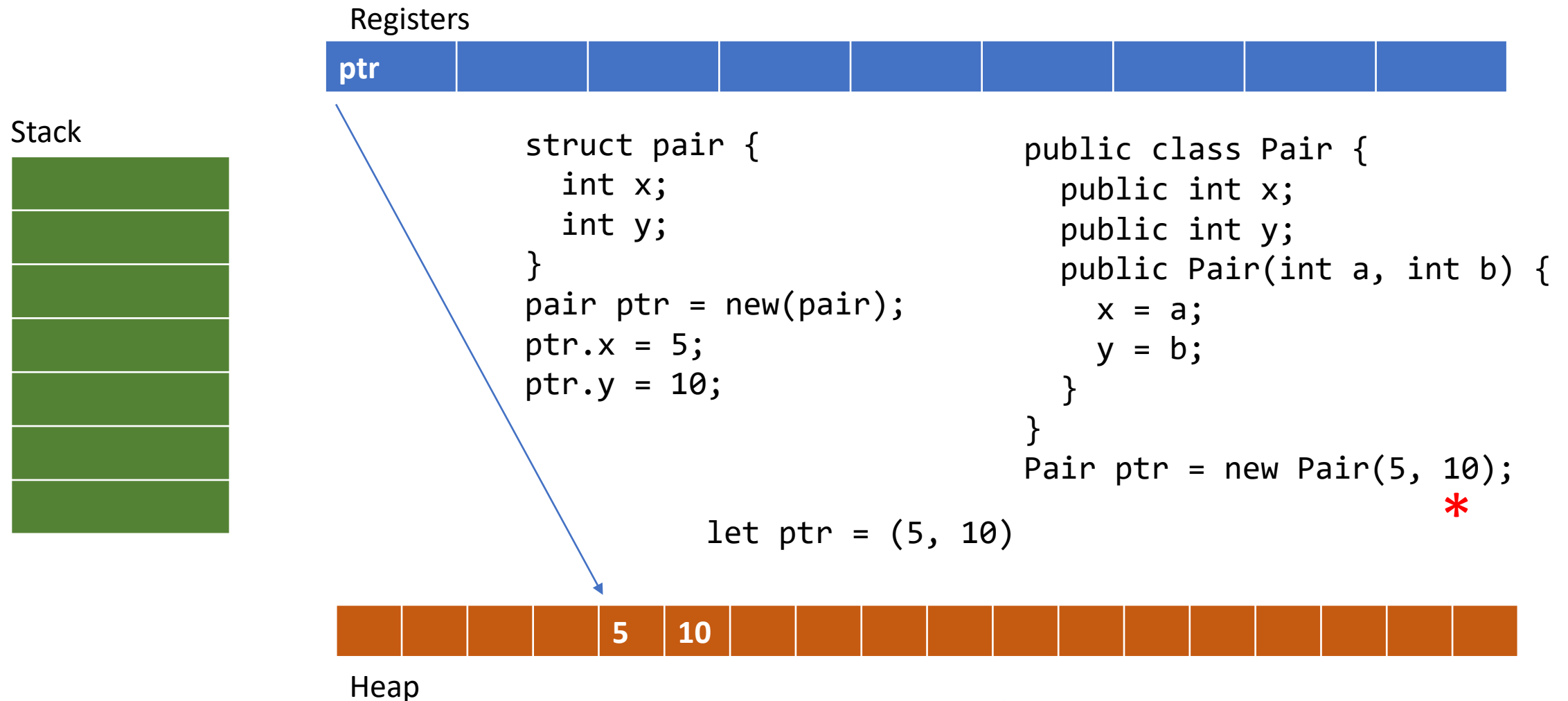


CS443: Compiler Construction

Lecture 24: Memory Management & Garbage Collection

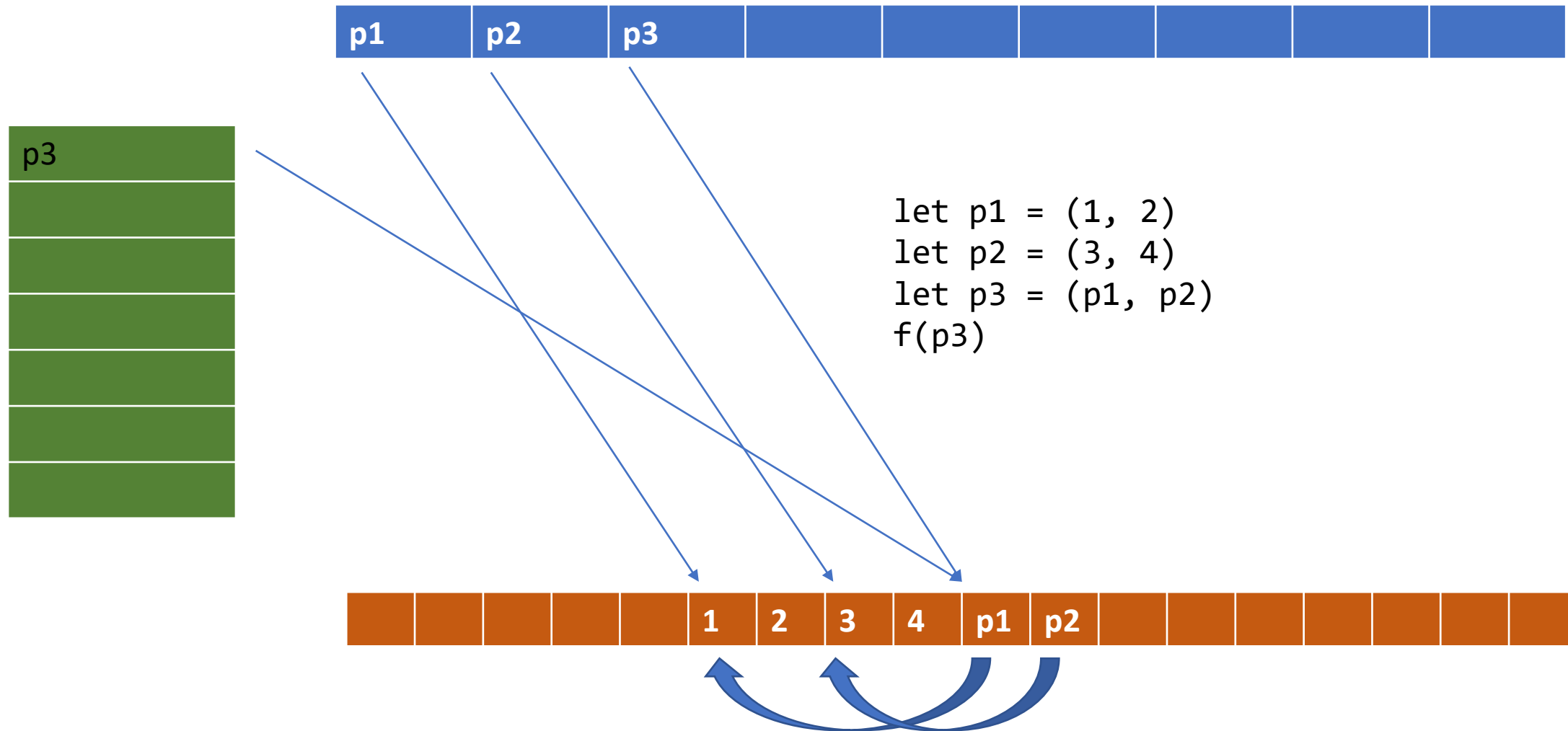
Stefan Muller

Memory layout



*In Java, there would also be a tag

Objects can be nested



Memory management answers two questions

- How do we allocate memory?
- What do we do with it when we're done?

MM breaks down into two basic strategies

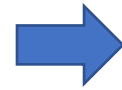
- Manual – programmer says when to allocate (`malloc/new`) and free (`free/drop`)
 - Good control
 - Might forget to free/free twice/use after free
- Automatic – free memory automatically when no longer needed
 - (“Garbage collection”)
 - Some runtime overhead

What about Rust?

- Still manual, the compiler just inserts calls to `drop` when variables go out of scope (definitely can't be used any more)
- Overly conservative, but prevents errors with `free`.
- Manual doesn't have to mean awful!

Manual Memory Management

```
Let  
pair a = pair(x, y);  
mean  
pair a =  
malloc(sizeof(pair));  
a.fst = x;  
a.snd = y;
```

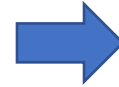


```
pair a = pair(1, 2);  
pair b = pair(3, 4);  
pair c = pair(5, 6);  
pair d = pair(a, b);  
d.snd = c;  
free(b);  
pair e = pair(7, 8);
```



Manual Memory Management

```
Let  
pair a = pair(x, y);  
mean  
pair a =  
malloc(sizeof(pair));  
a.fst = x;  
a.snd = y;
```



```
pair a = pair(1, 2);  
pair b = pair(3, 4);  
pair c = pair(5, 6);  
pair d = pair(a, b);  
d.snd = c;  
free(b);  
pair e = pair(7, 8);
```

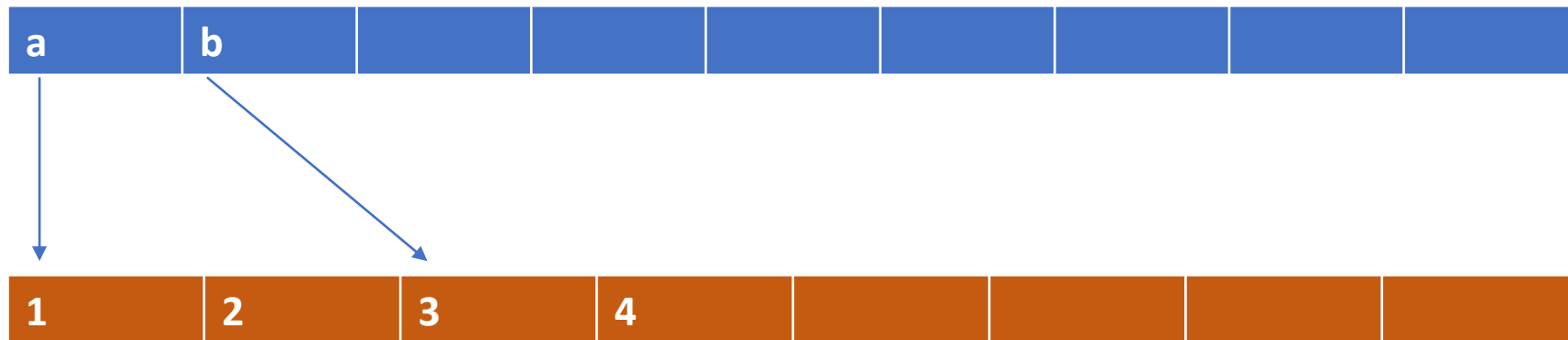


Manual Memory Management

```
Let  
pair a = pair(x, y);  
mean  
pair a =  
malloc(sizeof(pair));  
a.fst = x;  
a.snd = y;
```



```
pair a = pair(1, 2);  
pair b = pair(3, 4);  
pair c = pair(5, 6);  
pair d = pair(a, b);  
d.snd = c;  
free(b);  
pair e = pair(7, 8);
```

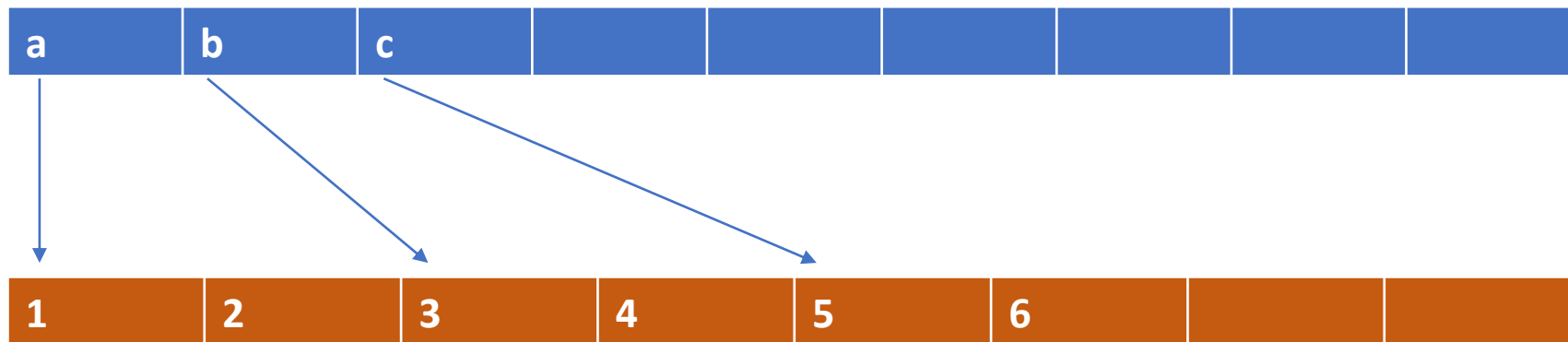


Manual Memory Management

```
Let  
pair a = pair(x, y);  
mean  
pair a =  
malloc(sizeof(pair));  
a.fst = x;  
a.snd = y;
```



```
pair a = pair(1, 2);  
pair b = pair(3, 4);  
pair c = pair(5, 6);  
pair d = pair(a, b);  
d.snd = c;  
free(b);  
pair e = pair(7, 8);
```

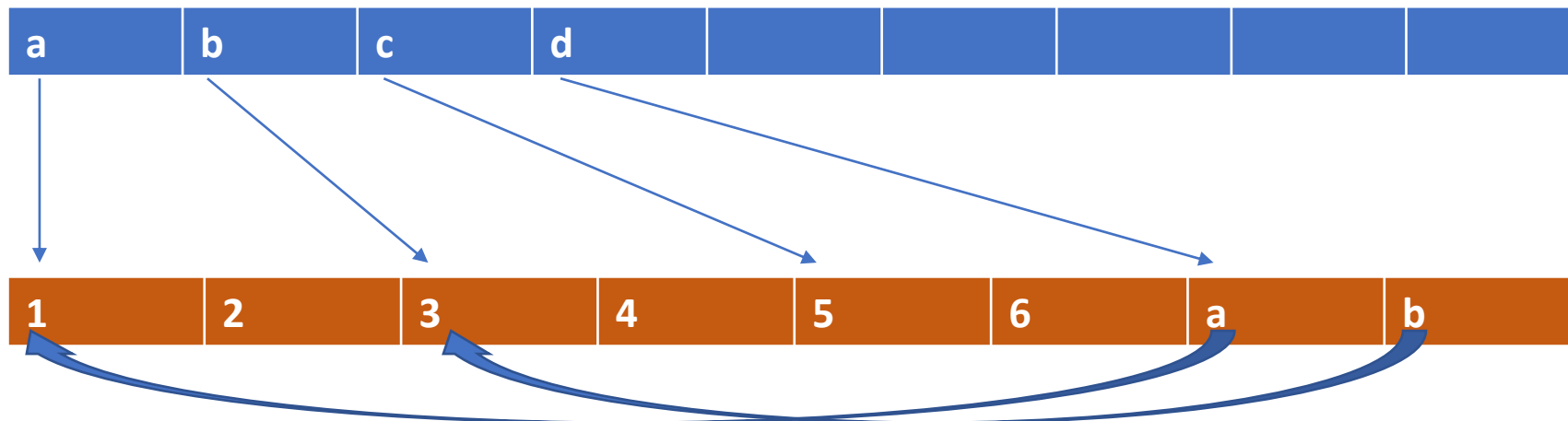


Manual Memory Management

```
Let  
pair a = pair(x, y);  
mean  
pair a =  
malloc(sizeof(pair));  
a.fst = x;  
a.snd = y;
```



```
pair a = pair(1, 2);  
pair b = pair(3, 4);  
pair c = pair(5, 6);  
pair d = pair(a, b);  
d.snd = c;  
free(b);  
pair e = pair(7, 8);
```

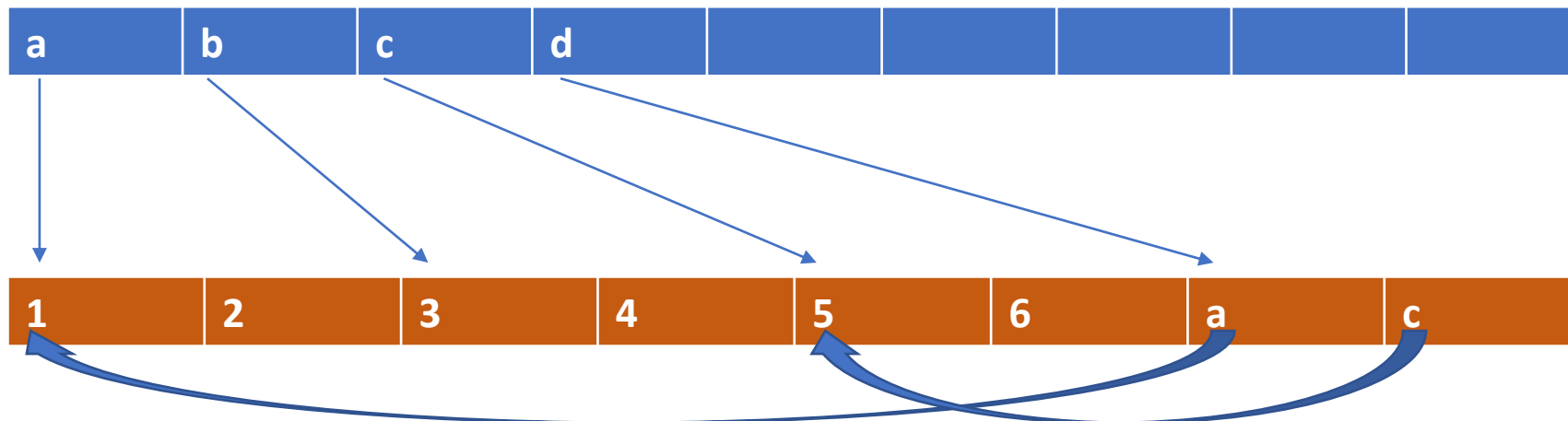


Manual Memory Management

```
Let  
pair a = pair(x, y);  
mean  
pair a =  
malloc(sizeof(pair));  
a.fst = x;  
a.snd = y;
```



```
pair a = pair(1, 2);  
pair b = pair(3, 4);  
pair c = pair(5, 6);  
pair d = pair(a, b);  
d.snd = c;  
free(b);  
pair e = pair(7, 8);
```



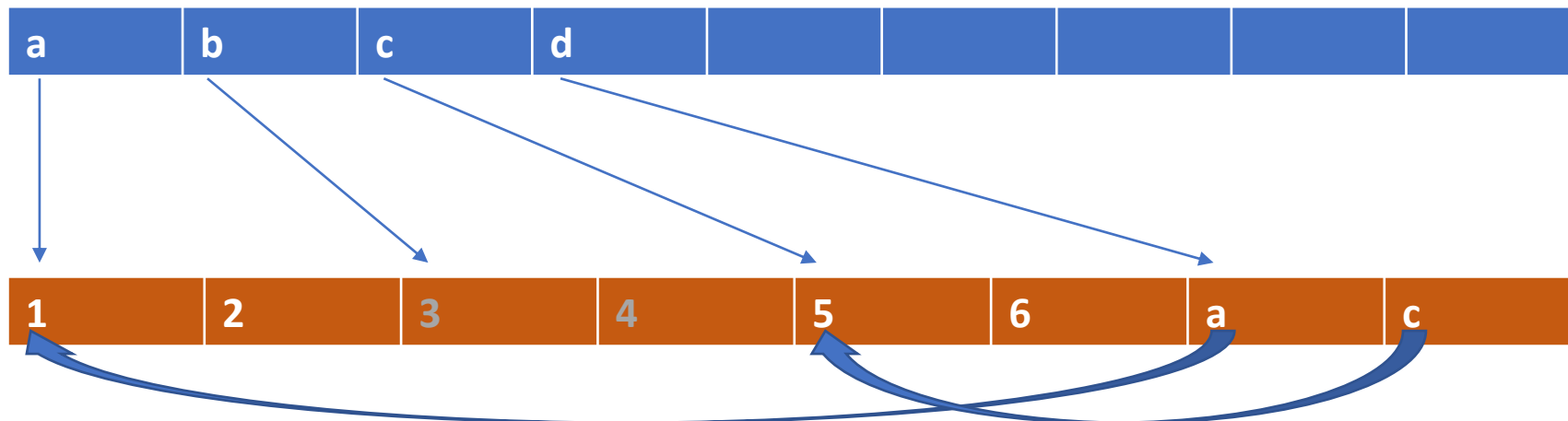
Manual Memory Management

```
Let  
pair a = pair(x, y);  
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pair a =  
malloc(sizeof(pair));  
a.fst = x;  
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```

```
pair a = pair(1, 2);  
pair b = pair(3, 4);  
pair c = pair(5, 6);  
pair d = pair(a, b);  
d.snd = c;  
free(b);  
pair e = pair(7, 8);
```



b still valid,
still points
to same loc,
but can
reuse
memory

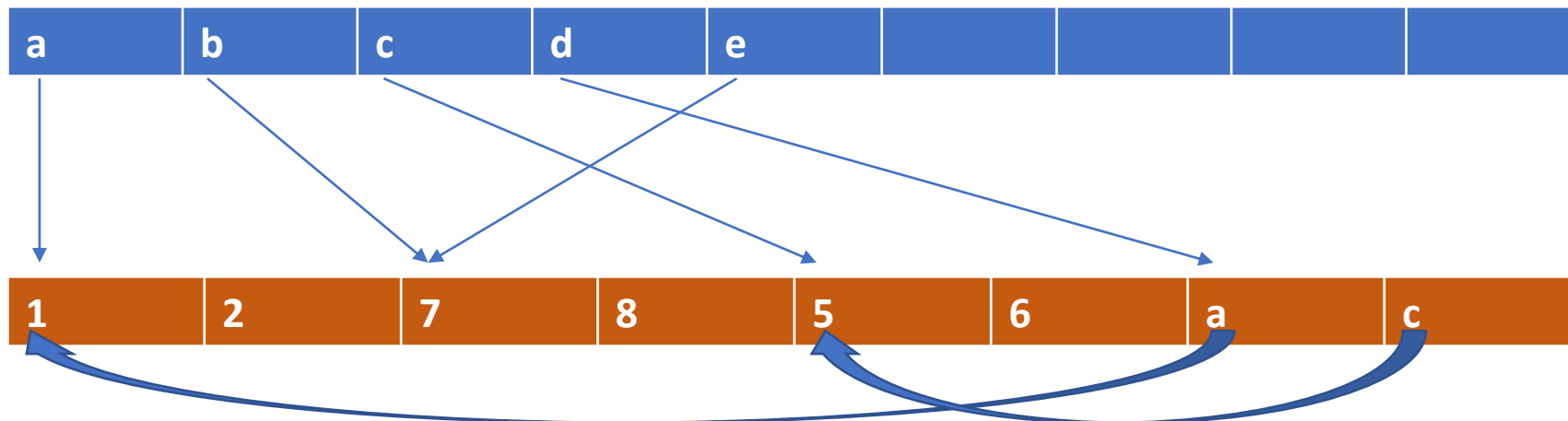


Manual Memory Management

```
Let  
pair a = pair(x, y);  
mean  
pair a =  
malloc(sizeof(pair));  
a.fst = x;  
a.snd = y;
```

Need to reuse
that space—
fragmentation

```
pair a = pair(1, 2);  
pair b = pair(3, 4);  
pair c = pair(5, 6);  
pair d = pair(a, b);  
d.snd = c;  
free(b);  
pair e = pair(7, 8);
```



Manual pros and cons

- Pros

- Space-efficient
- free is cheap
- Lots of control

- Cons

- malloc is expensive (and hard to implement)!
- Lots of control

Functional languages allocate *a lot*

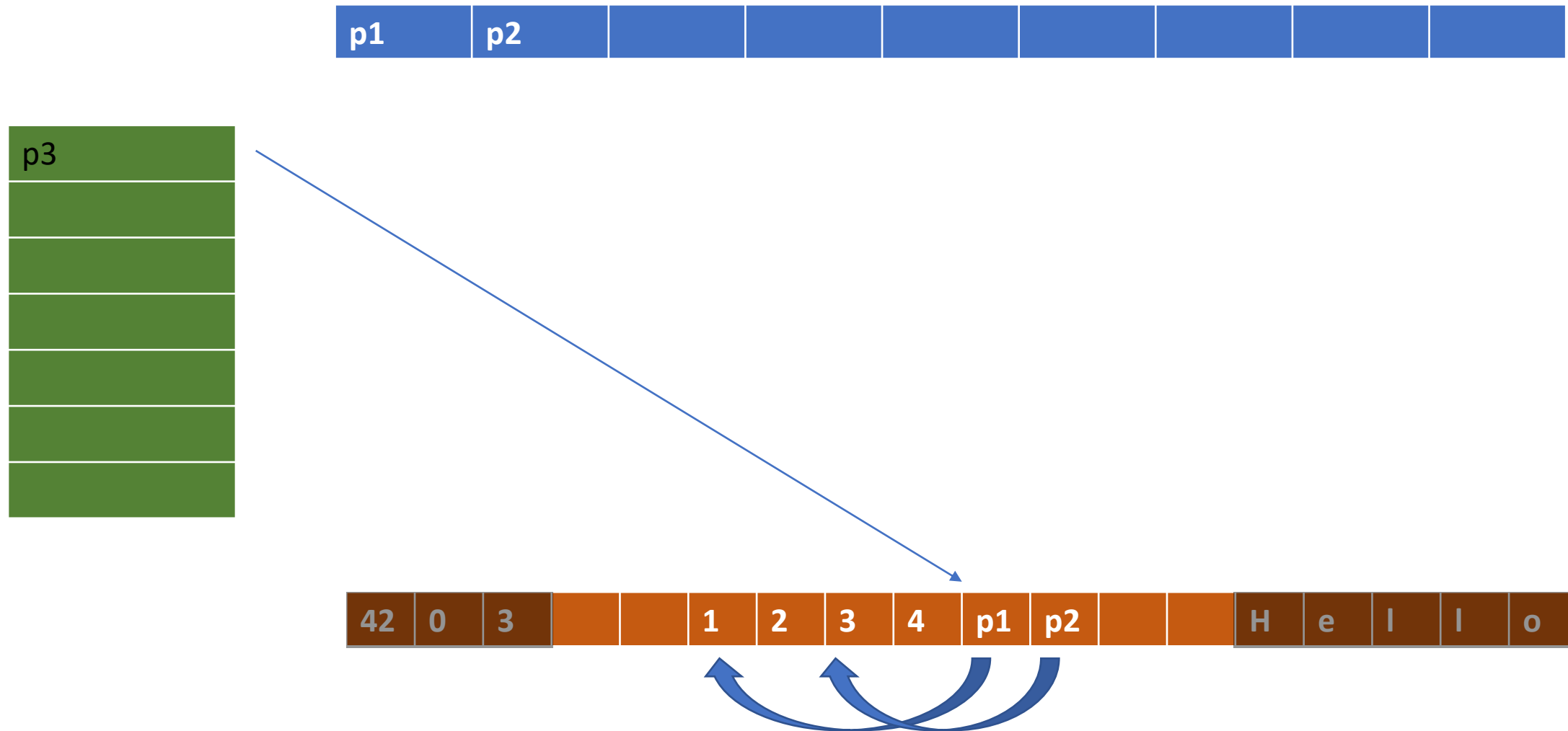
```
__list __ctemp52 = new(__list);
__ctemp52.list_tl = __env;
__ctemp52.list_hd = ((int)(__list)__ctemp51.list_hd);
__env = __ctemp52;
__list __ctemp53 = new(__list);
__ctemp53.list_tl = __env;
__ctemp53.list_hd = ((int)__ctemp51.list_tl);
__env = __ctemp53;
__clos __ctemp54 = ((__clos)__lookup(4, __env));
__clos __ctemp55 =
  ((__clos*)(int, __list))__ctemp54.clos_fun(((int)__lookup(1, __env)),
  __ctemp54.clos_env);
__clos __ctemp56 = __ctemp55;
__pair __ctemp57 =
  ((__pair*)(__list, __list))__ctemp56.clos_fun(((__list)__lookup(0,
  __env)), __ctemp56.clos_env);
__pair __ctemp58 = __ctemp57;
__list __ctemp59 = new(__list);
__ctemp59.list_tl = __env;
__ctemp59.list_hd = ((int)__ctemp58.pair_fst);
__env = __ctemp59;
__list __ctemp60 = new(__list);
__ctemp60.list_tl = __env;
__ctemp60.list_hd = ((int)__ctemp58.pair_snd);
```

And also can you imagine having to free everything manually?

Reachability and garbage

- Root set: Anything immediately reachable (registers, stack)
 - e.g., local variables, arguments
- Reachable (“live”): any objects (transitively) pointed to by root set
- Garbage (“dead”): any allocated objects not reachable


Objects not reachable from roots are dead/garbage



Knowing what points to what isn't as easy as it sounds

- In C:

```
int *p = (int *)0xdeadbeef;  
*p = 5;
```



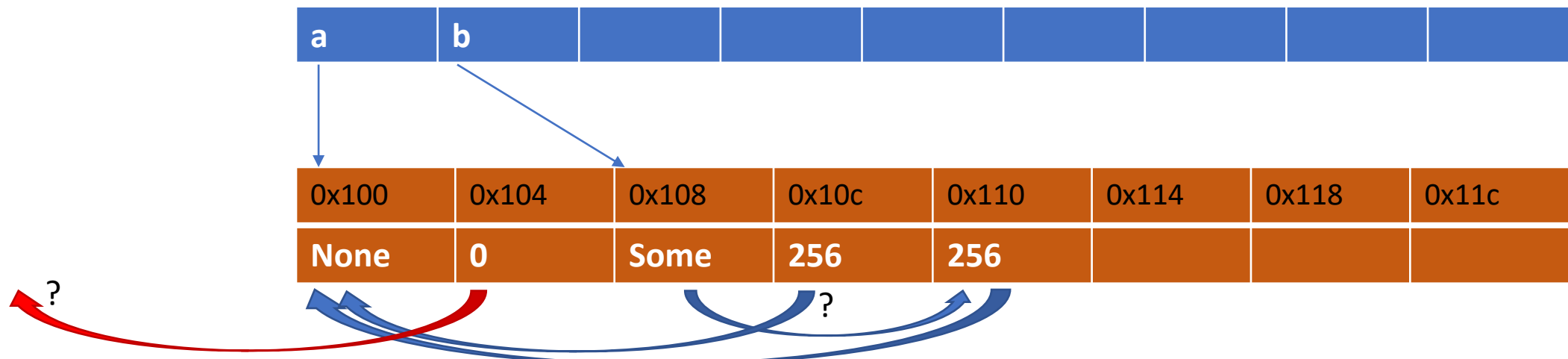
Garbage collection won't work well in C

Knowing what points to what isn't as easy as it sounds

In ML

```
let a = (None, 0)
```

```
let b = (Some a, 256)
```



OCaml's clever hack: use the LSB to indicate integer or pointer



LSB of a ptr is 0 anyway

$(1, 2, x + 1)$

OCaml's clever hack: use the LSB to indicate integer or pointer



LSB of a ptr is 0 anyway

(1, 2, x + 1)

```
12d43: 48 c7 00 03 00 00 00    movq    $0x3, (%rax)
12d4a: 48 c7 40 08 05 00 00    movq    $0x5, 0x8(%rax)
12d51: 00
12d52: 48 83 c3 02            add     $0x2, %rbx
12d56: 48 89 58 10            mov     %rbx, 0x10(%rax)
12d5a: 48 83 c4 08            add     $0x8, %rsp
12d5e: c3                    retq
```

OCaml's clever hack: use the LSB to indicate integer or pointer



LSB of a ptr is 0 anyway

$$3 = 1 \ll 1 + 1$$

(1, 2, x + 1)

```
12d43: 48 c7 00 03 00 00 00    movq   $0x3, (%rax)
12d4a: 48 c7 40 08 05 00 00    movq   $0x5, 0x8(%rax)
12d51: 00
12d52: 48 83 c3 02            add    $0x2, %rbx
12d56: 48 89 58 10            mov    %rbx, 0x10(%rax)
12d5a: 48 83 c4 08            add    $0x8, %rsp
12d5e: c3                    retq
```

OCaml's clever hack: use the LSB to indicate integer or pointer



LSB of a ptr is 0 anyway

$$5 = 2 \ll 1 + 1$$

(1, 2, x + 1)

```
12d43: 48 c7 00 03 00 00 00    movq    $0x3, (%rax)
12d4a: 48 c7 40 08 05 00 00    movq    $0x5, 0x8(%rax)
12d51: 00
12d52: 48 83 c3 02            add     $0x2, %rbx
12d56: 48 89 58 10            mov     %rbx, 0x10(%rax)
12d5a: 48 83 c4 08            add     $0x8, %rsp
12d5e: c3                    retq
```


OCaml's clever hack: use the LSB to indicate integer or pointer



LSB of a ptr is 0 anyway

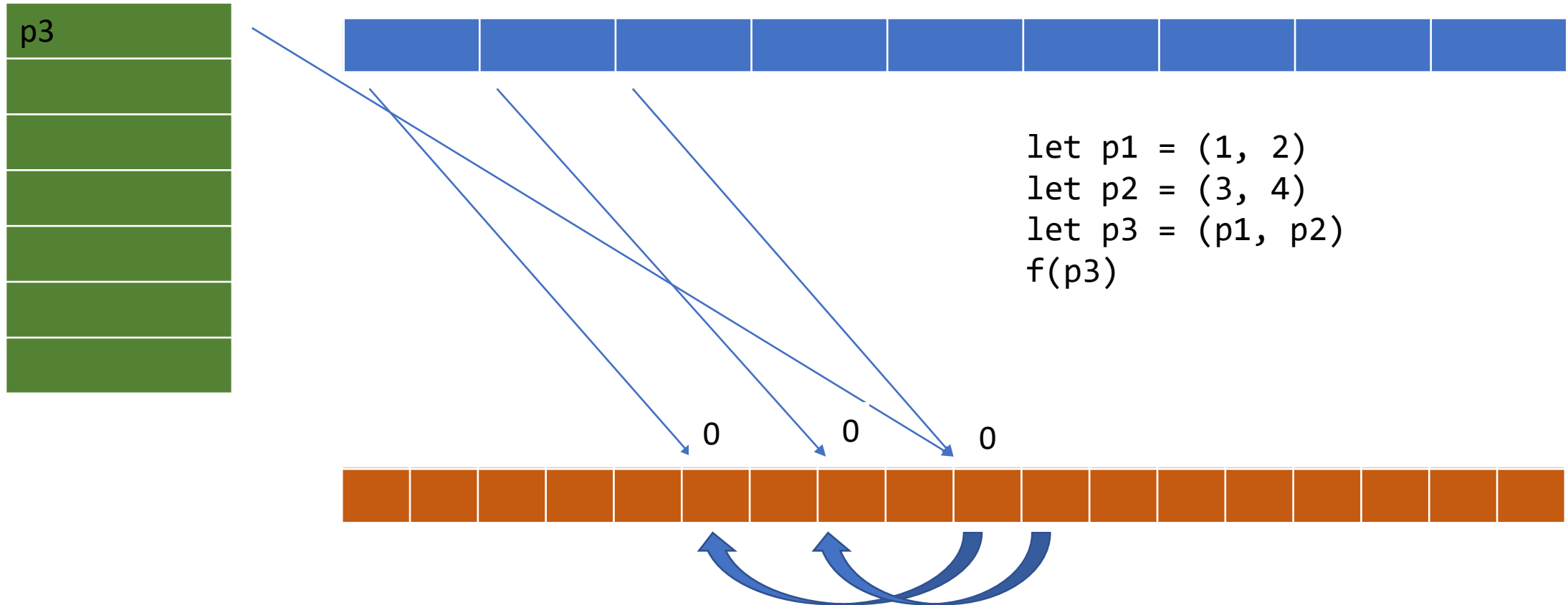
$$(x \ll 1 + 1) + (1 \ll 1) = (x + 1) \ll 1 + 1$$

(1, 2, x + 1)

```
12d43: 48 c7 00 03 00 00 00    movq    $0x3, (%rax)
12d4a: 48 c7 40 08 05 00 00    movq    $0x5, 0x8(%rax)
12d51: 00
12d52: 48 83 c3 02            add     $0x2, %rbx
12d56: 48 89 58 10            mov     %rbx, 0x10(%rax)
12d5a: 48 83 c4 08            add     $0x8, %rsp
12d5e: c3                    retq
```

GC Strategy #1: Reference counting

- Idea: keep track of how many references every object has



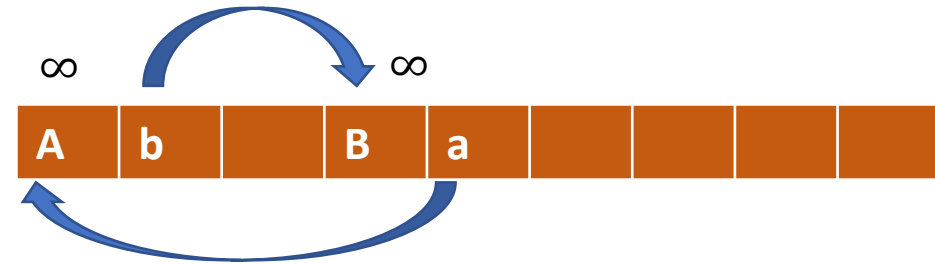
Reference counting pros

- Simple, intuitive
- Garbage collected immediately

Reference counting cons

- Cyclic data structures

```
a = new A();  
b = new B();  
A.b = b;  
B.a = a;
```



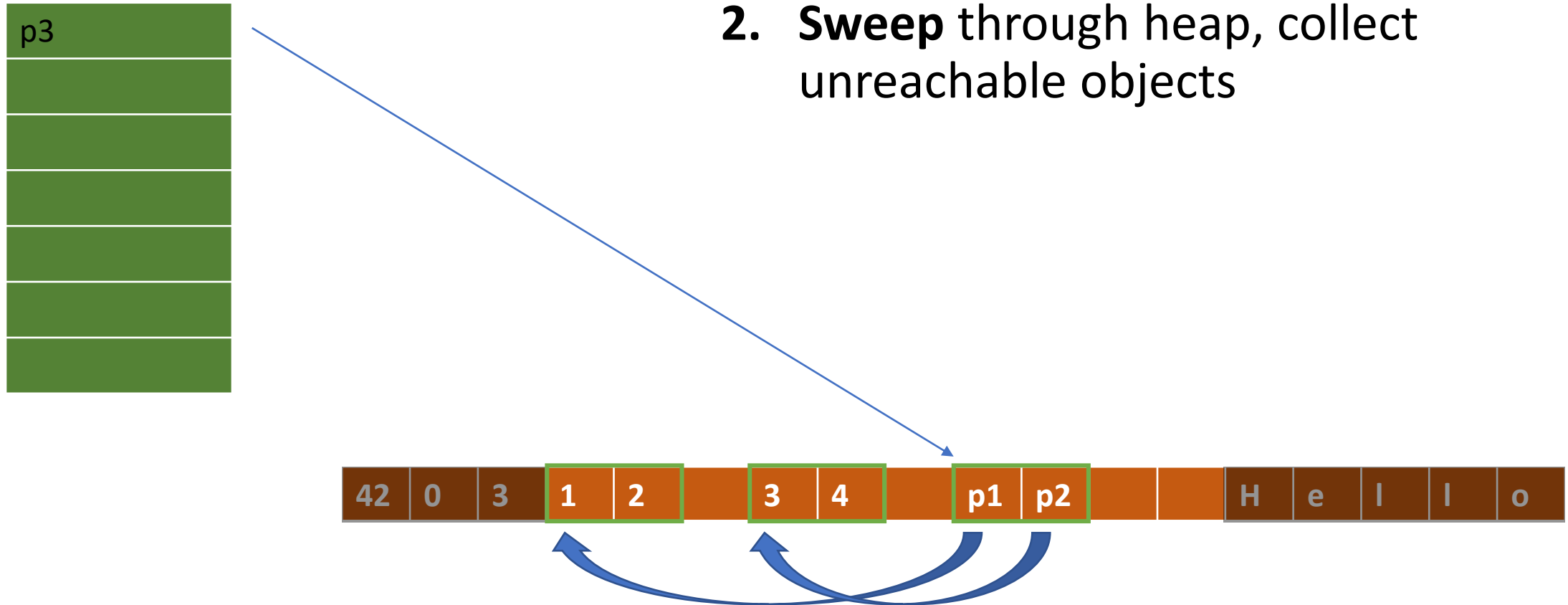
- Updating counts can be expensive

Announcements

- Start Project 6 ASAP
- Project 5 Graded

GC Strategy #2: Mark and sweep

1. **Mark** reachable objects
2. **Sweep** through heap, collect unreachable objects



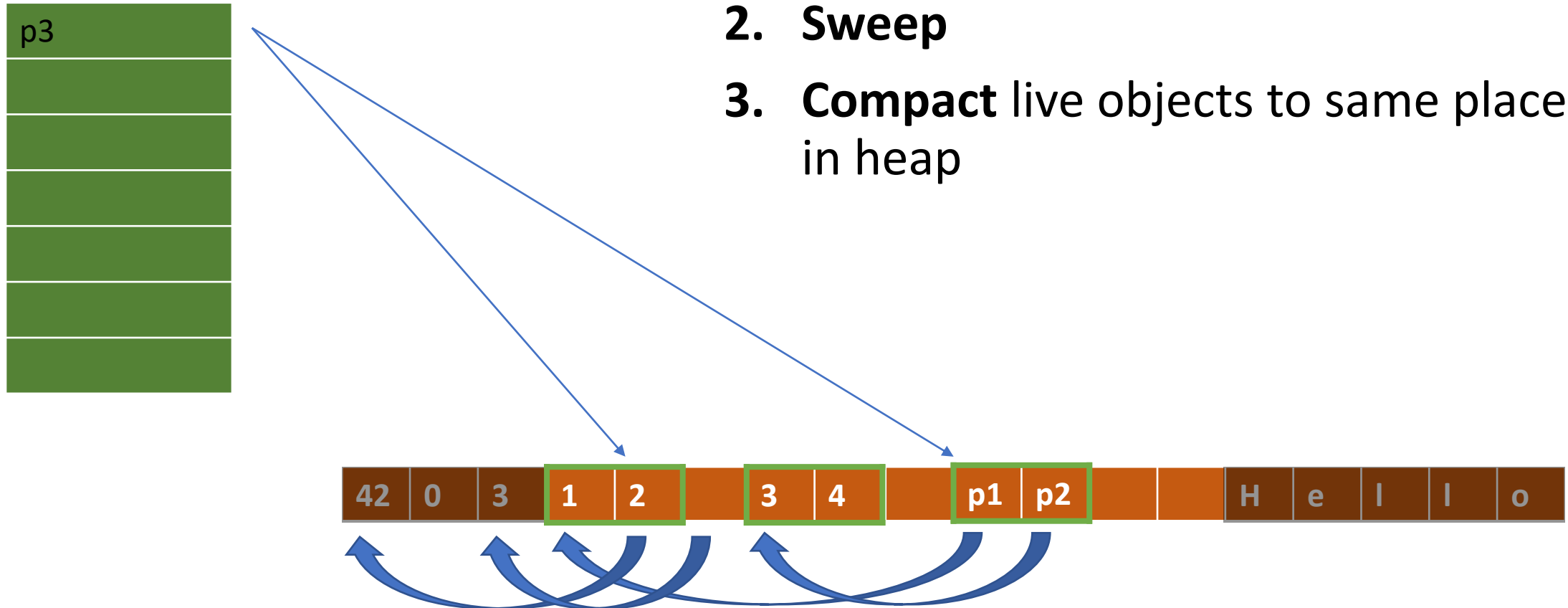
Mark and Sweep pros and cons

- Pros:
 - Works on cyclic references
 - Just traverse references once
- Cons:
 - Have to sweep through whole heap (can optimize)
 - Fragmentation



GC Strategy #2½: Mark and compact

1. **Mark**
2. **Sweep**
3. **Compact** live objects to same place in heap

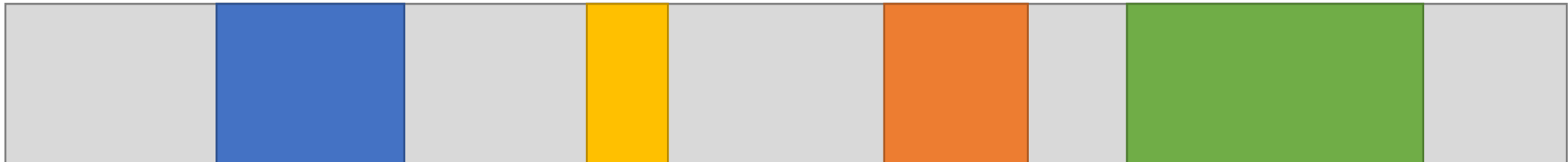


Mark and compact pros and cons

- Pros:
 - Fragmentation solved
- Cons:
 - Have to update pointers

Implementing Compaction (#1): Keep a “forwarding pointer” in each object

1. Compute new locations of objects
2. Update all pointers
3. Move



Implementing Compaction (#1): Keep a “forwarding pointer” in each object

1. Compute new locations of objects
2. Update all pointers
3. Move



Implementing Compaction (#1): Keep a “forwarding pointer” in each object

1. Compute new locations of objects
2. Update all pointers
3. Move



Implementing Compaction (#1): Keep a “forwarding pointer” in each object

1. Compute new locations of objects
2. Update all pointers
3. Move



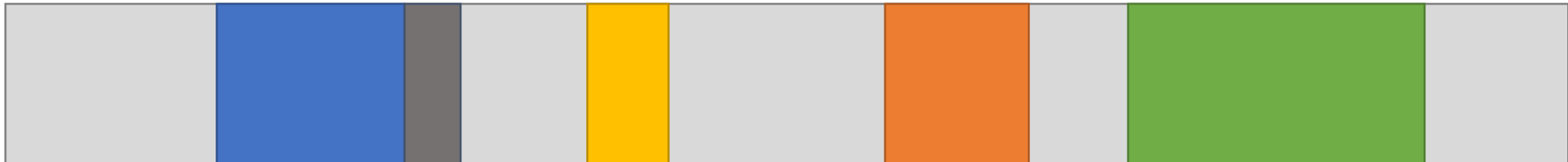
Implementing Compaction (#1): Keep a “forwarding pointer” in each object

1. Compute new locations of objects
2. Update all pointers
3. Move



Implementing Compaction (#2): Keep a table in free space

- Table maps **groups of consecutive objects** to new offsets



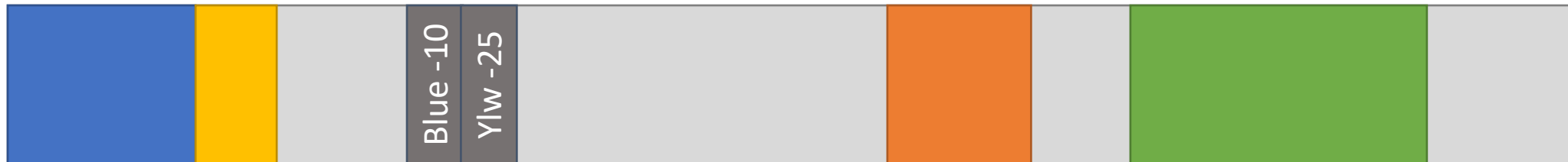
Implementing Compaction (#2): Keep a table in free space

- Table maps **groups of consecutive objects** to new offsets



Implementing Compaction (#2): Keep a table in free space

- Table maps **groups of consecutive objects** to new offsets



Implementing Compaction (#2): Keep a table in free space

- Table maps **groups of consecutive objects** to new offsets
- “Roll” the table into free space if needed



Implementing Compaction (#2): Keep a table in free space

- Table maps **groups of consecutive objects** to new offsets
- “Roll” the table into free space if needed



Implementing Compaction (#2): Keep a table in free space

- Table maps **groups of consecutive objects** to new offsets
- “Roll” the table into free space if needed
- Need to sort the table at the end



Compacting allows for **really** fast allocation

- “Bump allocation”
 - Heap pointer points to end of heap
 - To allocate N bytes:
 - Increment (“bump”) heap pointer by N
 - If we pass the end of the heap, trigger a GC
 - Return old value of heap pointer

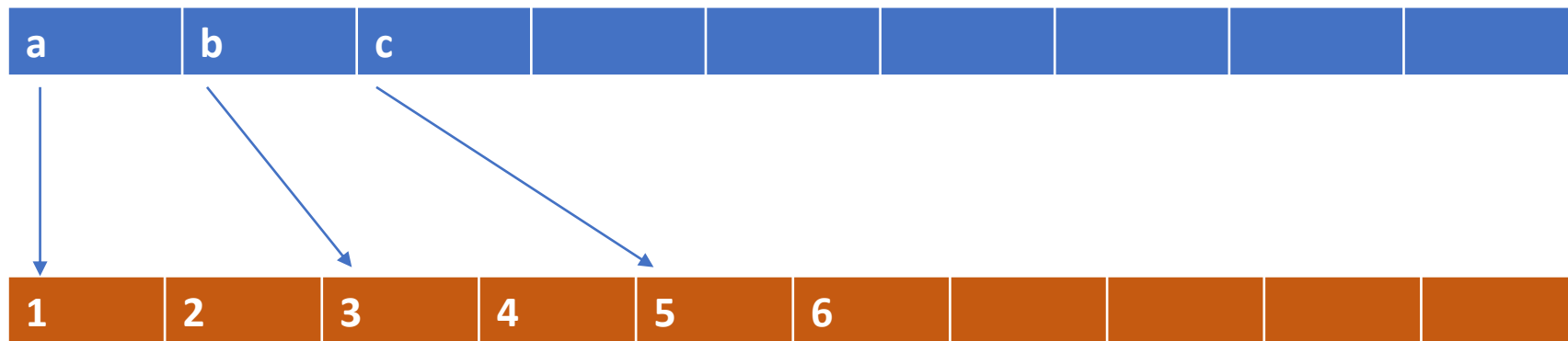
... yes. That's it. That's how we implement `malloc`

```
__malloc:
    lw t0,heapptr          # t0 = heap ptr
    lw t2,heapend         # t2 = end of heap
    add t1,t0,a0          # t1 = heap ptr + Nbytes
    blt t2,t1,__eom       # check if t1 > heap limit
    sw t1,heapptr         # heap ptr += Nbytes
    addi a0,t0,0          # a0 = old heap ptr
    jalr zero,ra,0        # return
__eom:                   # trigger GC
...

```

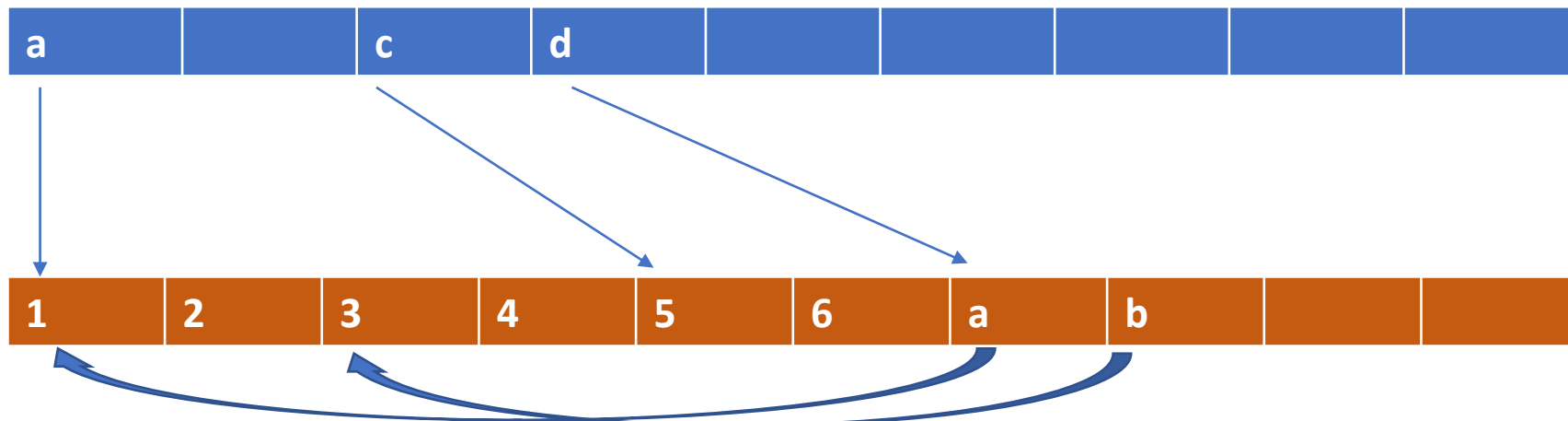
Bump allocation

```
let a = (1, 2)
let b = (3, 4)
let c = (5, 6)
let d = (a, b)
let d = (a, c)
let e = (7, 8)
```



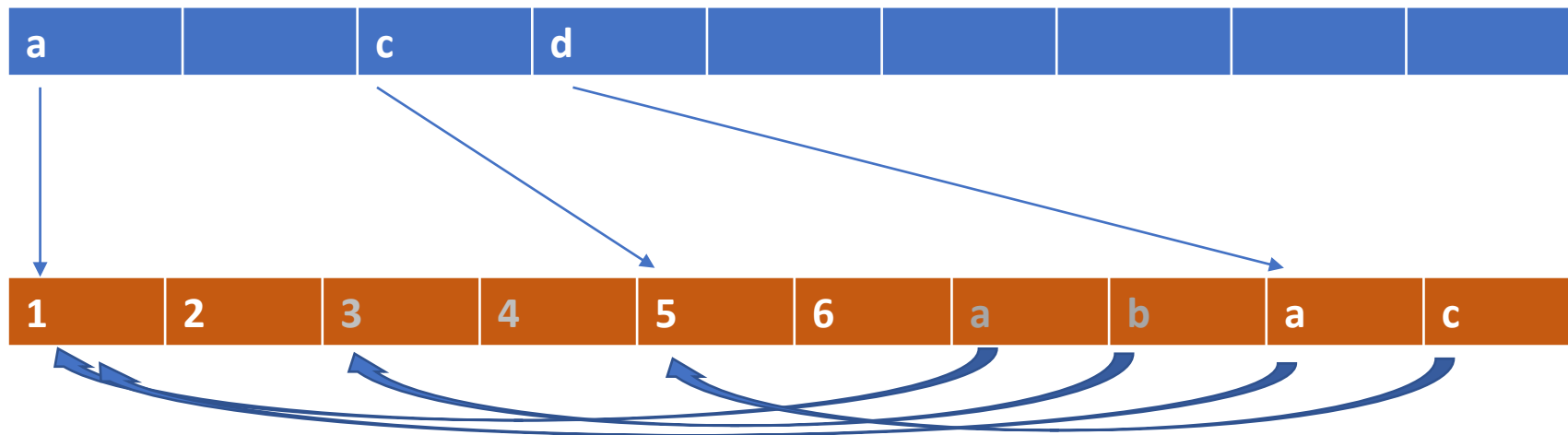
Bump allocation

```
let a = (1, 2)
let b = (3, 4)
let c = (5, 6)
let d = (a, b)
let d = (a, c)
let e = (7, 8)
```



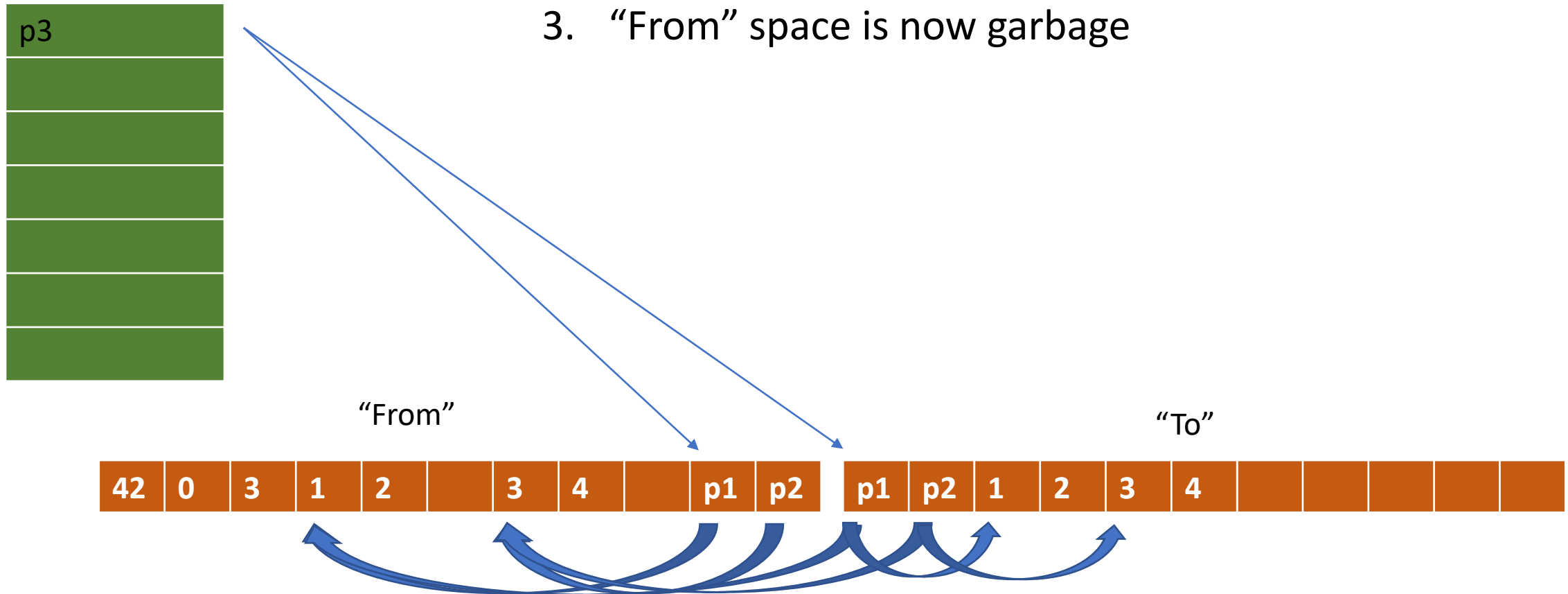
Bump allocation

```
let a = (1, 2)
let b = (3, 4)
let c = (5, 6)
let d = (a, b)
let d = (a, c)
let e = (7, 8)
```



GC Strategy #3: Copying

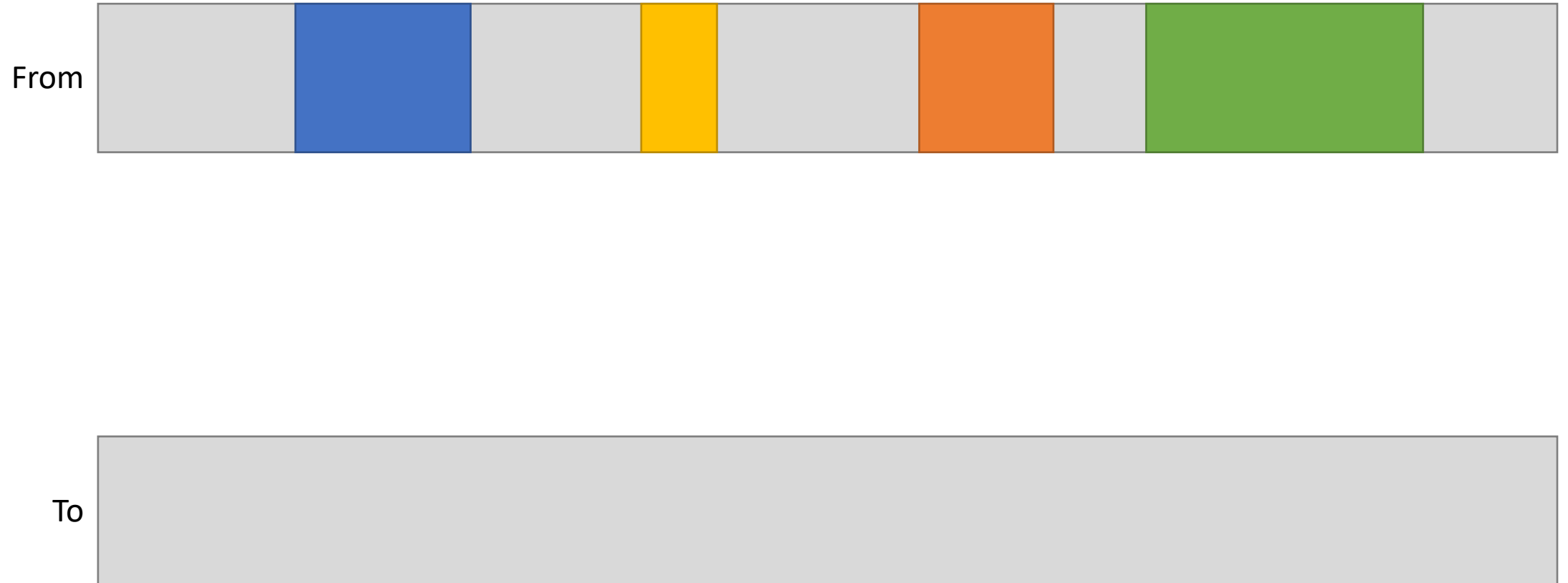
1. Divide heap into “from” space and “to” space
2. **Copy** live objects into “to” space
3. “From” space is now garbage



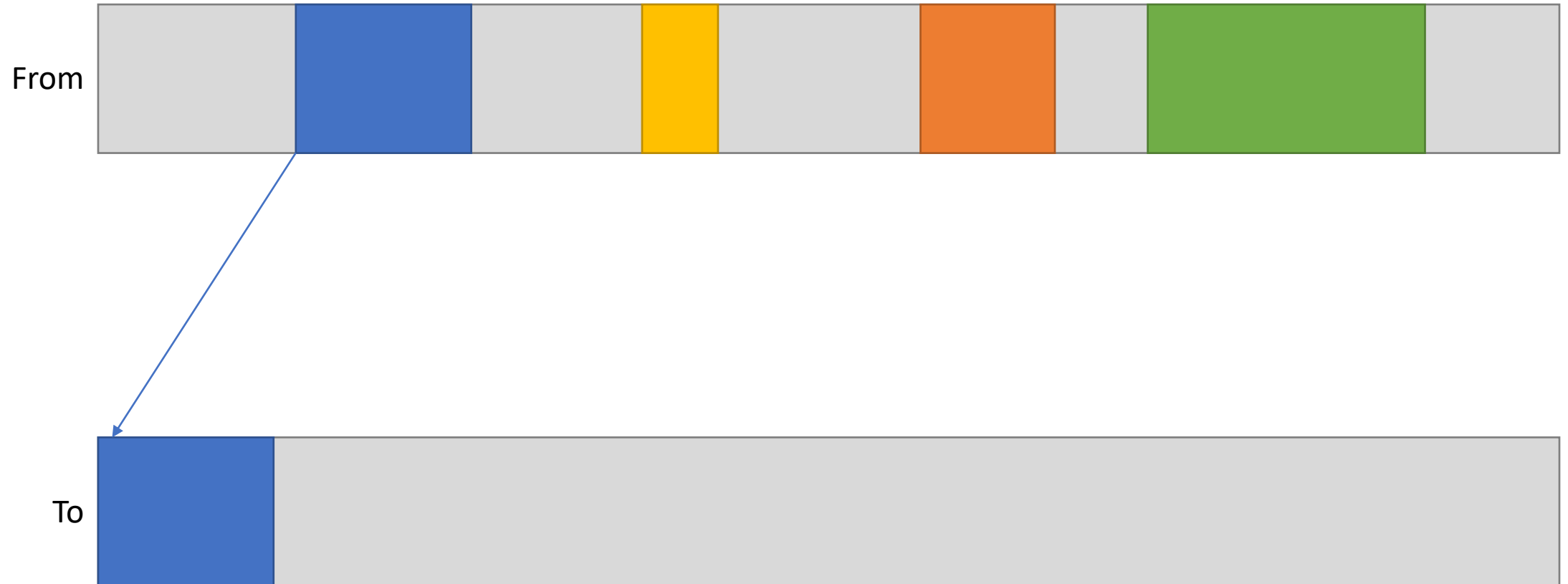
Copying pros and cons

- Pros
 - No traversing of whole heap
 - No fragmentation
- Cons
 - Heap size basically cut in half
 - Have to move pointers

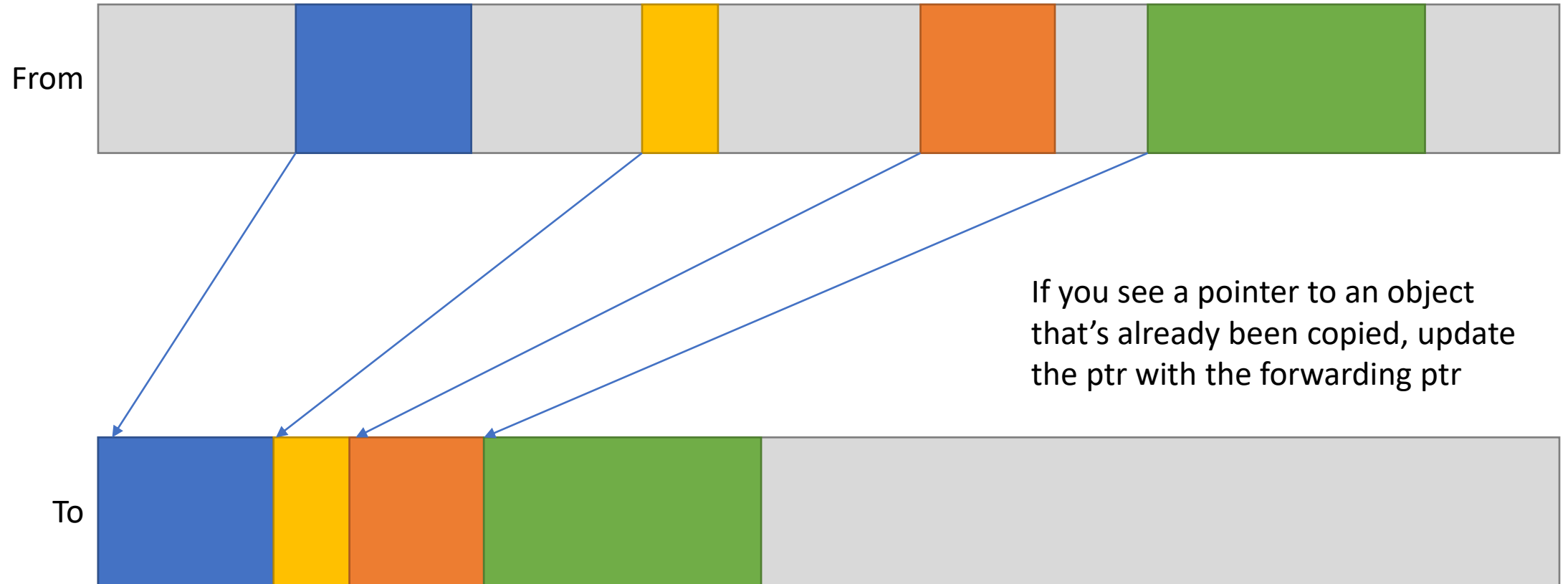
Copying Implementation: Just turn the from space into forwarding pointers



Copying Implementation: Just turn the from space into forwarding pointers



Copying Implementation: Just turn the from space into forwarding pointers



Another side benefit of copying

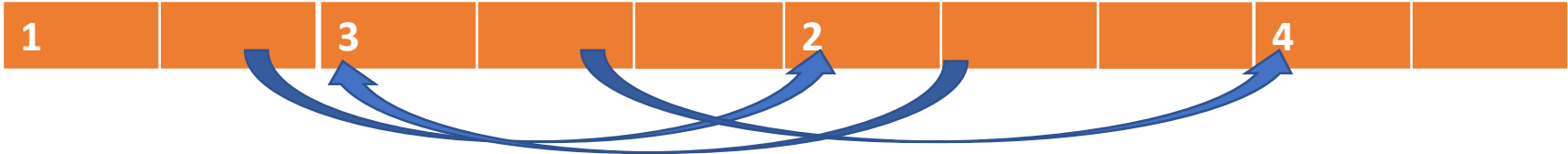
```
let rec list l n =  
  if n <= 0 then l  
  else  
    list ((List.length  
          (List.init (n mod 5) id))::l)  
        (n - 1)
```

```
let l = list [] 10000  
do_n_times 3 (fun _ -> traverse l)  
(* Do other stuff *)  
do_n_times 3 (fun _ -> traverse l)
```

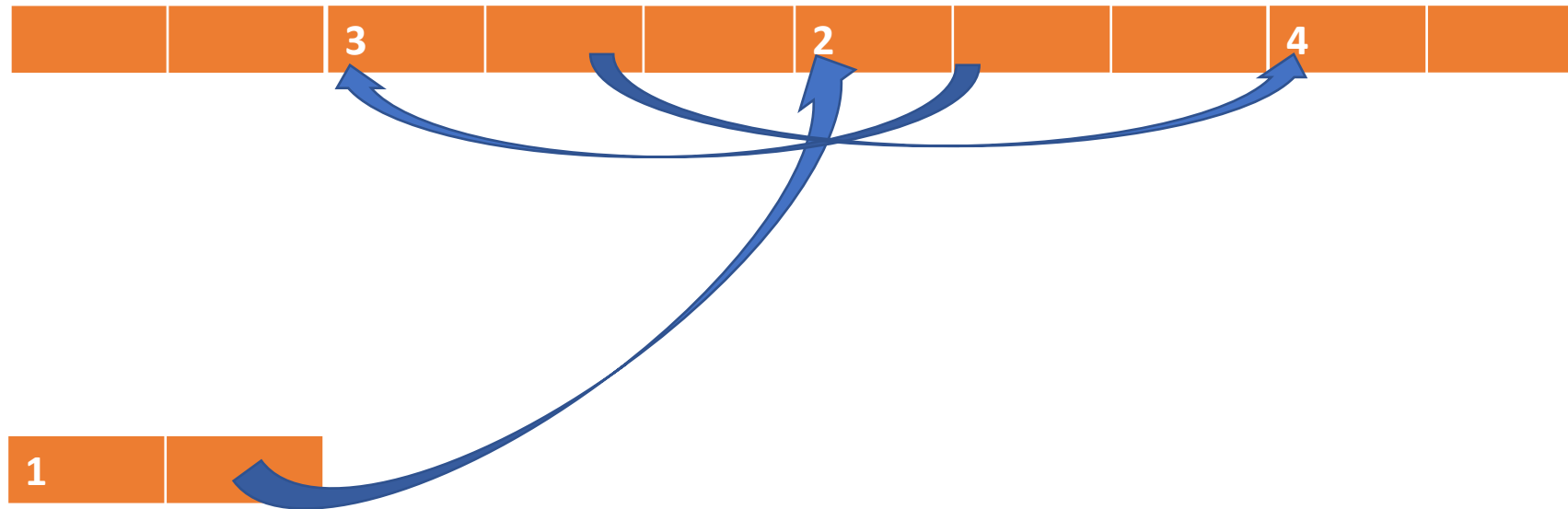
What happened here?

```
Traversed list in 0.00016s  
Traversed list in 0.00016s  
Traversed list in 0.00016s  
Starting new major GC cycle  
Traversed list in 0.00007s  
Traversed list in 0.00006s  
Traversed list in 0.00006s
```

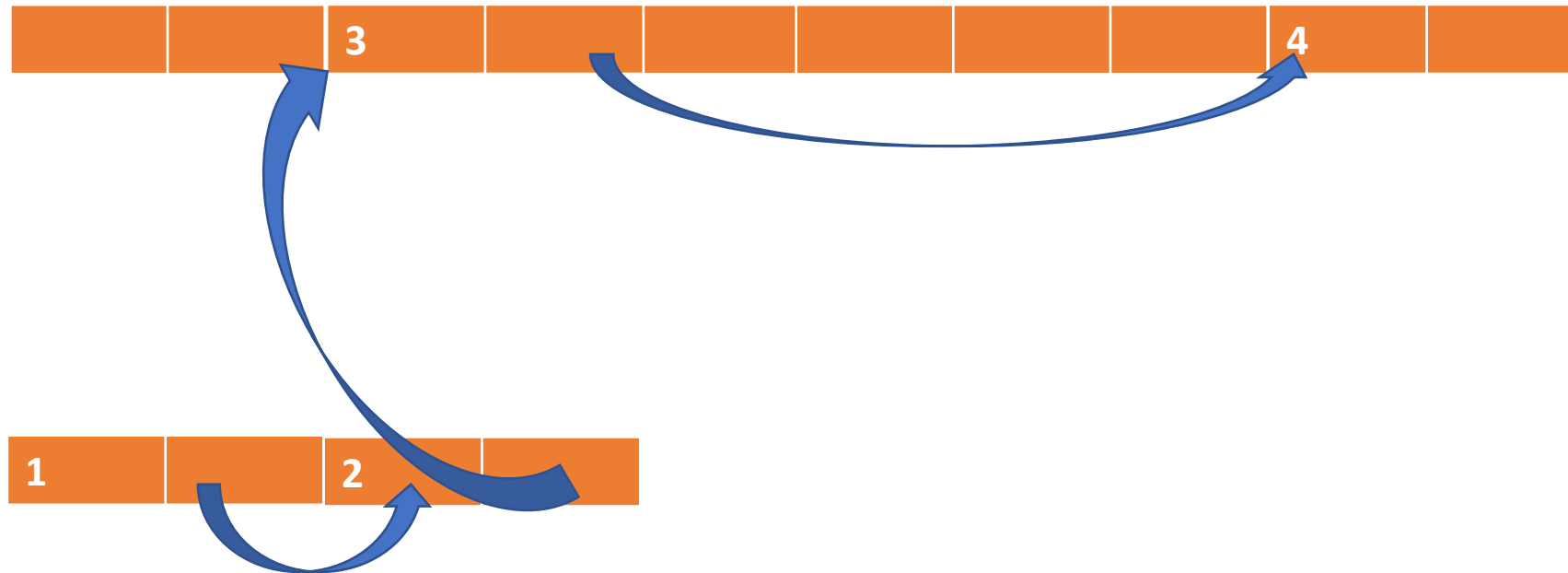
Another side benefit of copying



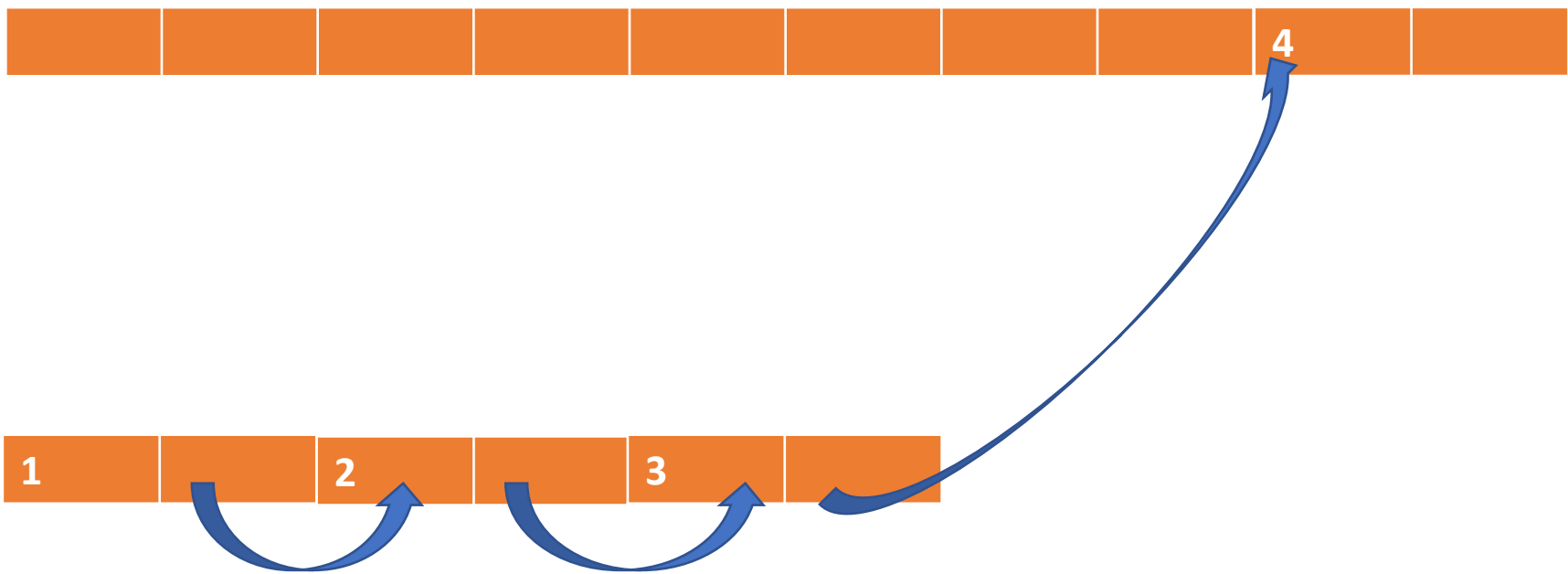
Another side benefit of copying



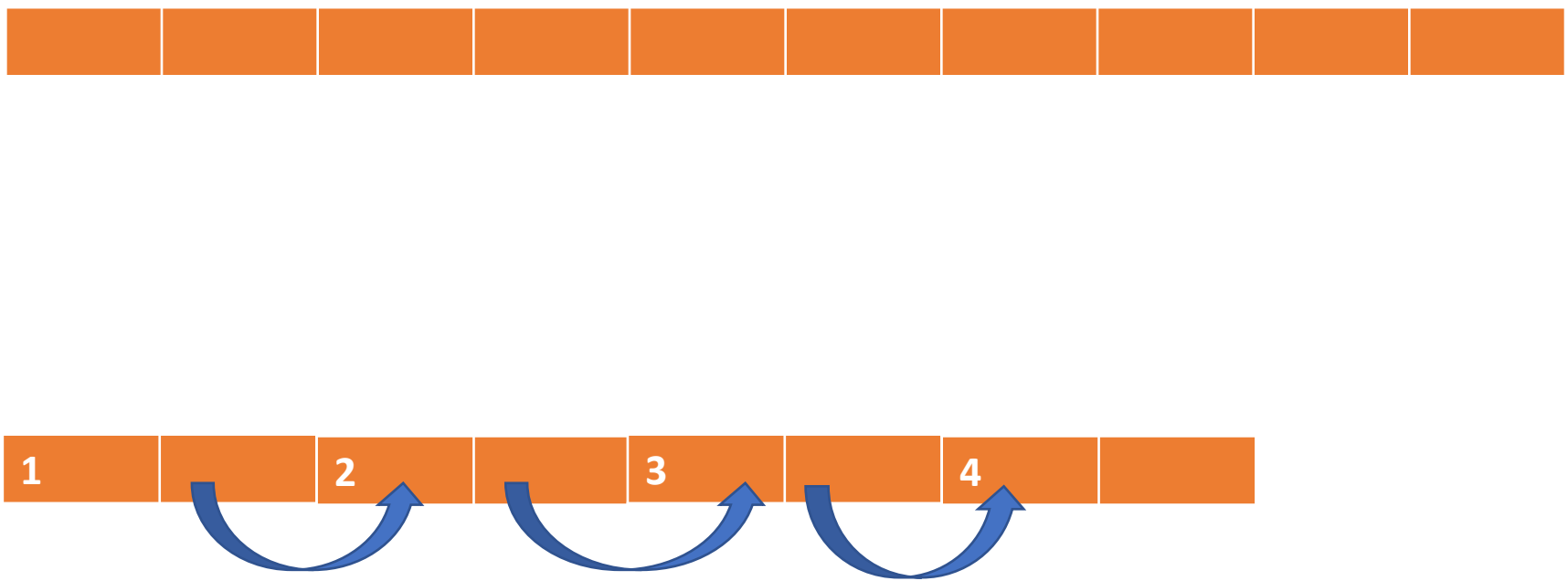
Another side benefit of copying



Another side benefit of copying

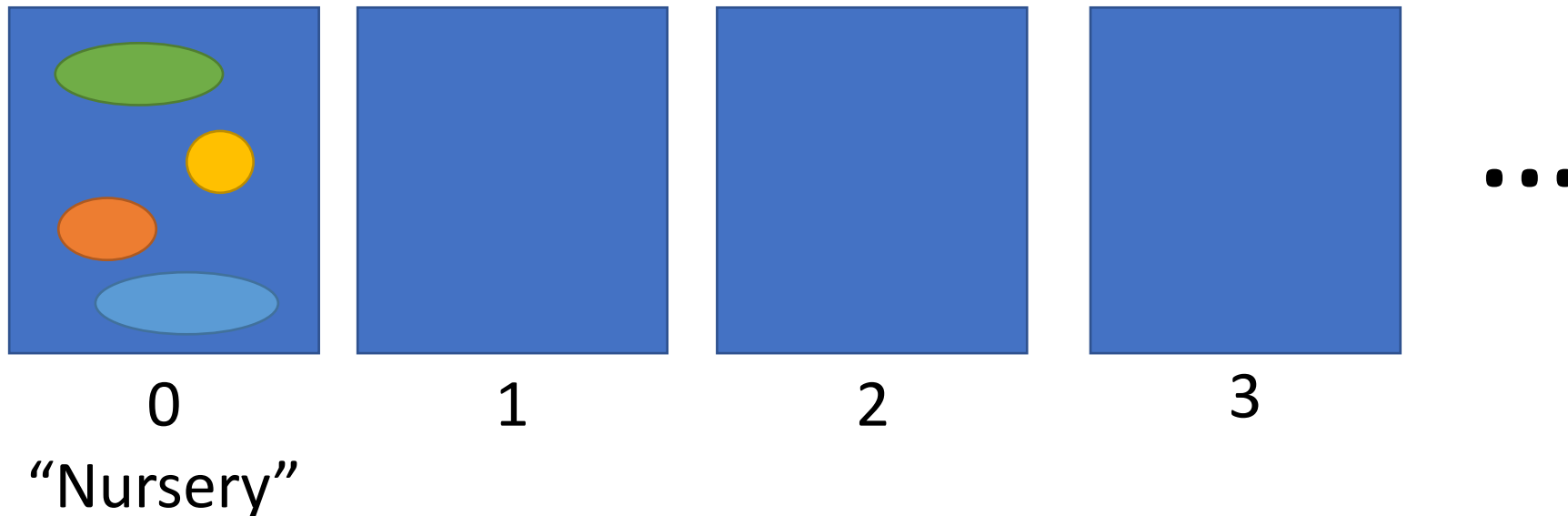


Another side benefit of copying



Generational garbage collection

- Idea: “most objects ‘die young’”
- Separate heap into areas called *generations*
- Collect younger generations more aggressively/frequently



Efficiency

- Most GCs we have discussed are “stop the world”
 - Stop program, do a collection
 - *Pause time*: amount of time a program must wait for the collector
- To reduce pause time, many real-world GCs are *concurrent* or *incremental* (do small amounts of work as the program runs)

In practice, pause times are pretty short

- Don't let people tell you GC makes it totally impractical to use functional languages for real code

GC type	time ms	number	bytes	bytes/sec
-----	-----	-----	-----	-----
copying	3,063	37	2,111,703,368	689,423,253
mark-compact	0	0	0	-
minor	0	11	4,520	-

total time: 19,902 ms

total GC time: 3,472 ms (17.4%)

max pause time: 433 ms

$3472 \text{ ms} / 37 = 93 \text{ms avg.}$

total bytes allocated: 15,794,832,336 bytes

max bytes live: 140,663,592 bytes

max heap size: 1,125,367,808 bytes

OCaml

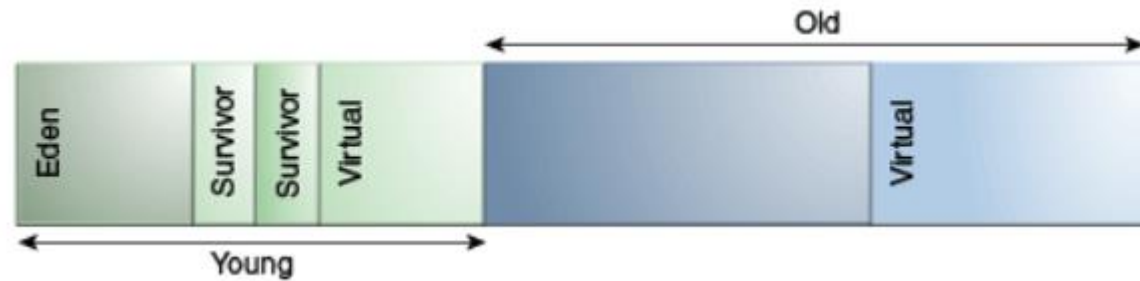
- Two generations: *minor heap* and *major heap*
 - Allocate large objects directly into major heap
 - “Minor collections” frequent
 - “Major collections” when necessary
- Major collections are (concurrent) mark-compact
 - Not to be confused with *parallel* GC (GC runs on multiple threads to reduce pause time)

Java (HotSpot JVM)

- Generational

- Eden (nursery)
- Live objects copied from Eden to one of two “survivor” spaces
- Copying collection used to copy between survivor spaces
- After a certain number of copies, moved to “old” generation

- Several different collection strategies available for different applications



Python

- Reference Counting
 - Periodically checks for cycles

Tail Call Optimization

- Recognize tail calls, implement properly
- *Continuation passing style*: automatically turn *every* call into a tail call!

Parallelism and Concurrency

- Language mechanisms for parallelism/concurrency
- Concerns for language runtimes (especially GC!)

Concurrent GC

- Collect small bits of the heap at more allocations to avoid long pauses

Compiling OO languages

- Representing Objects
- Dynamic Dispatch
 - With inheritance, a method can be defined in many places. Which one to call?