\S Locks and locking strategies



Thread A

count = count + 1a1



Thread B

.

b1 count = count + 1





Thread A

count = count + 1a1



Thread B

b1 count = count + 1



count



Thread A

count = count + 1a1



Thread B

b1count = count + 1



Thread A

count = count + 1a1



Thread B

b1 count = count + 1



count



Thread A

count = count + 1a1



Thread B

b1 count = count + 1



Locking strategies

- We may use a single lock to guard access to all shared resources
 - We call this a global or **coarse-grained** locking strategy
- Or we may assign locks to individual resources (or subsets of resources)
- We call this a **fine-grained** locking strategy



E.g., coarse-grained locking







E.g., coarse-grained locking







E.g., coarse-grained locking





Coarse-grained locking ...

- ... is (typically) easier to reason about
- ... but results in a lot of lock contention
- ... may result in poor resource utilization





E.g., fine-grained locking





Fine-grained locking ...

- ... may reduce (individual) lock contention
- ... may improve resource utilization
- ... can result in a lot of locking overhead
- ... but can be much harder to verify correctness!





E.g., fine-grained locking problem



deadlocked!





E.g., lock API: pthreads "mutex"

// initialize mutex (can also use PTHREAD_MUTEX_INITIALIZER for defaults) int pthread_mutex_init(pthread_mutex_t *mtx, pthread_mutexattr_t *attr);

int pthread_mutex_lock(pthread_mutex_t *mtx);

// release lock on mutex (a blocked thread may acquire it) int pthread_mutex_unlock(pthread_mutex_t *mtx);

// destroy mutex (only safe on an unlocked mutex) int pthread_mutex_destroy(pthread_mutex_t *mtx);

- // acquire lock on mutex (if mutex is already locked, block the calling thread)



E.g., protecting counter increment

```
int counter = 0;
pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;
void *inc(void *num) {
    for (int i=0; i<1000000; i++) {</pre>
        pthread_mutex_lock(&lock);
        counter += 1;
        pthread_mutex_unlock(&lock);
    }
    printf("Thread %ld counter = %d\n", pthread_self(), counter);
    pthread_exit(NULL);
}
int main() {
    pthread_t tid[5];
    for (int i=0; i<5; i++){</pre>
        pthread_create(&tid[i], NULL, inc, NULL);
        printf("Created thread %ld\n", tid[i]);
    for (int i=0; i<5; i++) {</pre>
        pthread_join(tid[i], NULL); // wait for other threads
    pthread_mutex_destroy(&lock);
    return 0;
}
```

Created	l thread	13988274	+6513152		
Created	l thread	13988273	38120448		
Created	l thread	13988272	29727744		
Created	l thread	13988272	21335040		
Created	l thread	13988271	12942336		
Thread	13988272	21335040	counter	=	4782346
Thread	13988272	29727744	counter	=	4904819
Thread	13988273	38120448	counter	=	4976793
Thread	13988274	+6513152	counter	=	4986816
Thread	13988271	L2942336	counter	=	5000000

- Lots of lock contention!
- Note that counter values are still unpredictable until the end
 - Can we fix this?

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E.g., protecting counter increment

```
int counter = 0;
pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;
void *inc(void *num) {
    pthread_mutex_lock(&lock);
    for (int i=0; i<1000000; i++) {</pre>
       counter += 1;
    printf("Thread %ld counter = %d\n", pthread_self(), counter);
    pthread_mutex_unlock(&lock);
    pthread_exit(NULL);
}
int main() {
    pthread_t tid[5];
    for (int i=0; i<5; i++){</pre>
        pthread_create(&tid[i], NULL, inc, NULL);
        printf("Created thread %ld\n", tid[i]);
    for (int i=0; i<5; i++) {</pre>
        pthread_join(tid[i], NULL); // wait for other threads
    pthread_mutex_destroy(&lock);
    return 0;
```

Created	l thread	14007713	30561280		
Created	l thread	14007712	22168576		
Created	l thread	14007711	L3775872		
Created	l thread	14007710	95383168		
Created	l thread	14007709	96990464		
Thread	14007712	22168576	counter	=	1000000
Thread	14007711	3775872	counter	=	2000000
Thread	14007716	95383168	counter	=	3000000
Thread	14007713	80561280	counter	=	4000000
Thread	14007709	6990464	counter	=	5000000

- Less locking overhead
- Predictable counter outputs
- But virtually no concurrency



E.g., protecting counter increment

```
int counter = 0;
pthread_mutex_t lock = PTHREAD_MUTEX_INITIALIZER;
void *inc(void *num) {
    pthread_mutex_lock(&lock);
    for (int i=0; i<1000000; i++) {</pre>
       counter += 1;
    printf("Thread %ld counter = %d\n", pthread_self(), counter);
    pthread_exit(NULL);
    pthread_mutex_unlock(&lock);
}
int main() {
    pthread_t tid[5];
    for (int i=0; i<5; i++){</pre>
        pthread_create(&tid[i], NULL, inc, NULL);
        printf("Created thread %ld\n", tid[i]);
    for (int i=0; i<5; i++) {</pre>
        pthread_join(tid[i], NULL); // wait for other threads
    pthread_mutex_destroy(&lock);
    return 0;
}
```



- Mutex isn't released before thread termination — remaining threads are blocked forever
- Must pay careful attention to lock usage!



Lock implementation

while others block

```
typedef struct { int locked; } lock_t;
```

```
void acquire(lock_t *1) {
    while (1) {
        if (!1->locked) {
             1 \rightarrow 1 = 1;
             break;
        }
```

- Basic idea: need an "acquire" function that lets only one caller through

void release(lock_t *1) { 3



Lock implementation

```
void acquire(lock_t *1) {
    while (1) {
        1 \rightarrow 1 = 1; \leftarrow
            break;
        }
}
```

- Race condition may allow multiple threads to acquire the lock!

problem: calling thread may be preempted between testing the value of the thread and setting its value

- Cannot easily fix this problem in software — rely on hardware support



"Test-and-Set" operation

- Many architectures support an atomic test-and-set operation - E.g., on x86 we have the "atomic exchange" instruction: xchg - Can use it to implement acquire:

note: pseudo-assembly! acquire: movl \$1, %eax # set up "new" value in reg xchgl l->locked, %eax # swap values in reg & lock testl %eax, %eax acquire # spin if old value ≠ 0 jne



Spin lock

- This implementation ensures mut is very expensive
 - Blocked threads are burning Cl to repeatedly check the lock state
- "Starvation" issue: no guarantee acquire the lock!

itex. but	acquire:		
	movl	\$1, %eax	
	xchgl	l->locked,	%eax
PI I time	testl	%eax, %eax	
ratus	jne	acquire	

- "Starvation" issue: no guarantee if/when a thread stuck looping will



Ticket lock

- Clever starvation-free alternative to test-and-set based spinlock

```
void acquire(lock *lock) {
typedef struct {
                                    int tkt = lock->ticket++; // need atomic ++
    int ticket;
                                    while (tkt != lock->turn)
    int turn;
                                         ; // spin
} lock_t;
                                }
lock_t lock = \{ 0, 0 \};
                                void release(lock *lock) {
```

}

- Once a thread gets a "ticket", it will eventually acquire the lock
- Requires an atomic increment instruction; e.g., xadd on x86

```
lock - turn = lock - turn + 1;
```



Eliminating "spin"

- Would like to minimize CPU usage of tasks blocking on a lock
 - Ideally: try to check/acquire lock again only when there's good reason (e.g., it's been released by another thread)
- Typically rely on OS support for distinct scheduler state and explicit unblocking mechanism
 - e.g., in xv6, processes may be "SLEEPING", and sleep/wakeup functions allow processes to block on and wait for notifications on specific "channels"



```
E.g., xv6 sleep/wakeup
  // Put calling process to sleep on chan
  void sleep(void *chan)
```

```
proc->chan = chan;
proc->state = SLEEPING;
sched(); // context switch away from proc
proc->chan = 0;
```

- What happens if sleep and wakeup are called concurrently?
 - be put to sleep latter scenario is termed a "lost wakeup"
 - Fix this with mutex around critical sections

```
// Wake up all processes sleeping on chan
void wakeup1(void *chan)
  struct proc *p;
  for(p=ptable.proc; p<&ptable.proc[NPROC]; p++)</pre>
   if(p->state == SLEEPING && p->chan == chan)
      p->state = RUNNABLE;
3
```

- Race condition! Process calling sleep may either be continue to run or



```
E.g., xv6 sleep/wakeup
```

```
void sleep(void *chan, struct spinlock *lk)
٤
 if(lk != &ptable.lock){
    acquire(&ptable.lock);
    release(lk);
  proc->chan = chan;
  proc->state = SLEEPING;
  sched(); // note: scheduler releases lock
  proc->chan = 0;
 if(lk != &ptable.lock){
    release(&ptable.lock);
    acquire(lk);
  }
3
```

- Note that acquire/release still make use of spinlocks -
 - But they are held only for a fairly short period of time

```
void wakeup(void *chan)
Ę
  acquire(&ptable.lock);
  wakeup1(chan);
  release(&ptable.lock);
}
void wakeup1(void *chan)
  struct proc *p;
  for(p=ptable.proc; p<&ptable.proc[NPROC]; p++)</pre>
    if(p->state == SLEEPING && p->chan == chan)
      p->state = RUNNABLE;
}
```



E.g., sleep/wakeup in wait/exit

```
// Wait for a child process to exit
int wait(void)
٤
  struct proc *p;
 int havekids, pid;
 // this lock ensures we will not miss the wakeup
  acquire(&ptable.lock);
  for(;;){
    for(p=ptable.proc; p<&ptable.proc[NPROC]; p++){</pre>
      if(p->parent != proc)
        continue;
     if(p->state == ZOMBIE){
        pid = p->pid;
        release(&ptable.lock);
        return pid;
      }
    }
    // sleep on channel identified by parent proc
    sleep(proc, &ptable.lock);
3
```

```
// Exit the current process.
void exit(void)
  struct proc *p;
  acquire(&ptable.lock);
```

```
// wake up parent process to reap this one
wakeup1(proc->parent);
```

```
// init adopts & reaps orphaned children
for(p=ptable.proc; p<&ptable.proc[NPROC]; p++){</pre>
  if(p->parent == proc){
    p->parent = initproc;
    if(p->state == ZOMBIE)
      wakeup1(initproc);
  }
}
proc->state = ZOMBIE;
sched();
panic("zombie exit");
```





- One of many classical — i.e., paradigmatic — concurrent problems - Setup: concurrent producer & consumer threads sharing a finite buffer

```
// Producer (may be more than 1)
while (1) {
   buf->queue[buf->tail] = produce();
    buf->tail = (buf->tail + 1) % BSIZE;
    buf->n_items++;
}
// Consumer (may be more than 1)
while (1) {
   _consume(buf->queue[buf->head]);
    buf->head = (buf->head + 1) % BSIZE;
    buf->n_items--;
```

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```
// Producer
while (1) {
    buf->queue[buf->tail] = produce();
    buf->tail = (buf->tail + 1) % BSIZE;
    buf->n_items++;
3
```

- Must guard access to all shared data with a mutex
- But access to shared buffer must also be carefully synchronized
 - I.e., consumer may only consume from non-empty buffer, and producer may only produce into buffer with open slots

```
// Consumer
while (1) {
    consume(buf->queue[buf->head]);
    buf->head = (buf->head + 1) % BSIZE;
    buf->n_items--;
}
```



```
// Producer
while (1) {
   while (buf->n_items == BSIZE)
        ; // spin barrier
```

3

```
item = produce();
pthread_mutex_lock(&lock);
buf->queue[buf->tail] = item;
buf->tail = (buf->tail + 1) % BSIZE;
buf->n_items++;
pthread_mutex_unlock(&lock);
```

- producers may fall through spin barrier (and vice versa)

```
// Consumer
while (1) {
    while (buf->n_items == 0)
        ; // spin barrier
    pthread_mutex_lock(&lock);
    item = buf->queue[buf->head];
    buf->head = (buf->head + 1) % BSIZE;
    buf->n_items--;
    pthread_mutex_unlock(&lock);
    consume(item);
}
```

- More subtle race condition: when consumer updates n items, multiple

- Must check condition in mutex, but unlock to allow other thread to run



```
// Producer
while (1) {
    pthread_mutex_lock(&lock);
    while (buf->n_items == BSIZE) {
        pthread_mutex_unlock(&lock);
        // hope consumer decrements n_items
        pthread_mutex_lock(&lock);
    3
    pthread_mutex_unlock(&lock);
    item = produce();
    pthread_mutex_lock(&lock);
    buf->queue[buf->tail] = item;
    buf->tail = (buf->tail + 1) % BSIZE;
    buf->n_items++;
    pthread_mutex_unlock(&lock);
```

- Ridiculous!
- Prefer a way to block producer until consumer makes space available
 - Similar to sleep/wakeup mechanism in kernel



Condition variable

- Gives us mechanism for:
 - Representing a condition used for thread synchronization
 - Where a thread might wait (block) until the condition changes
 - Where a thread might signal other blocked threads to wake up and re-check the condition



E.g., pthreads "cond"

// initialize condition variable (or use PTHREAD_COND_INITIALIZER for defaults) int pthread_cond_init(pthread_cond_t *cv, pthread_condattr_t *attr);

// block on cv and release mtx (which must be held by calling thread) // mtx is automatically re-acquired before returning int pthread_cond_wait(pthread_cond_t *cv, pthread_mutex_t *mtx); // unblock one thread that is blocked on cv

int pthread_cond_signal(pthread_cond_t *cv);

// unblock all threads that are blocked on cv int pthread_cond_broadcast(pthread_cond_t *cv);



```
// Producer
while (1) {
    pthread_mutex_lock(&lock);
    while (buf->n_items == BSIZE)
        pthread_cond_wait(&has_space, &lock);
    pthread_mutex_unlock(&lock);
    item = produce();
    pthread_mutex_lock(&lock);
    buf->queue[buf->tail] = item;
    buf->tail = (buf->tail + 1) % BSIZE;
    buf->n_items++;
    rtheread_mutex_unlock(flock);
```

```
pthread_mutex_unlock(&lock);
```

```
pthread_cond_signal(&has_items);
```

}

