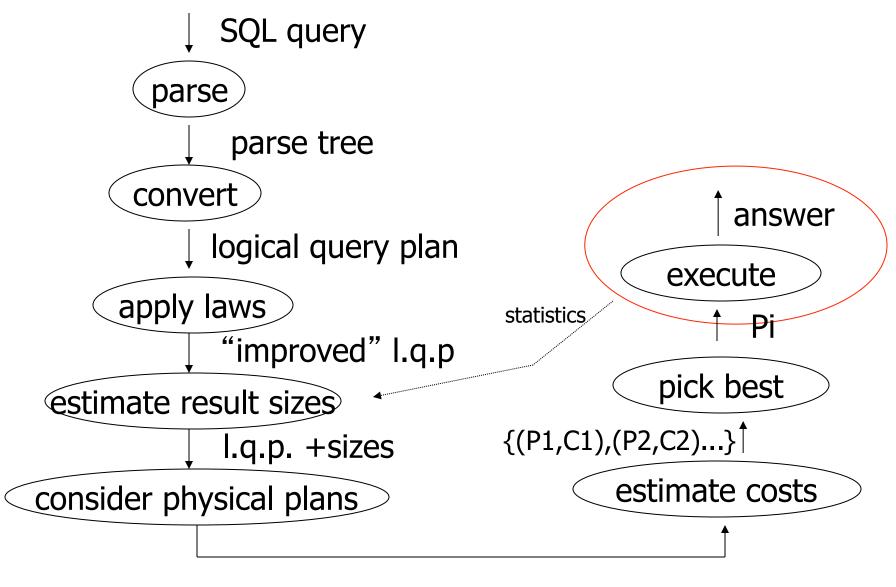
CS 525: Advanced Database Organization 10: Query Execution

Boris Glavic

Slides: adapted from a <u>course</u> taught by Hector Garcia-Molina, Stanford InfoLab









{P1,P2,....}

Notes 10 - Query Execution



Query Execution

- Here only:
 - how to implement operators
 - what are the costs of implementations
 - how to implement queries
 - Data flow between operators
- Next part:
 - How to choose good plan





Execution Plan

- A tree (DAG) of physical operators that implement a query
- May use indices
- May create temporary relations
- May create indices on the fly
- May use auxiliary operations such as sorting





How to estimate costs

- If everything fits into memory
 - Standard computational complexity
- If not
 - Assume fixed memory available for buffering pages
 - Count I/O operations
 - Real systems combine this with CPU estimations





Estimating IOs:

 Count # of disk blocks that must be read (or written) to execute query plan



To estimate costs, we may have additional parameters:

B(R) = # of blocks containing R tuples f(R) = max # of tuples of R per block M = # memory blocks available





To estimate costs, we may have additional parameters:

B(R) = # of blocks containing R tuples $f(R) = \max \#$ of tuples of R per block M = # memory blocks available

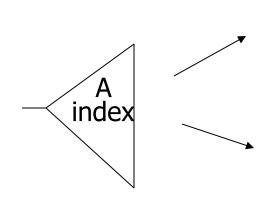
HT(i) = # levels in index i
LB(i) = # of leaf blocks in index i





Clustered index

Index that allows tuples to be read in an order that corresponds to physical order



A

10	
15	
17	

19	
35	
37	



Operators Overview

- (External) Sorting
- Joins (Nested Loop, Merge, Hash, ...)
- Aggregation (Sorting, Hash)
- Selection, Projection (Index, Scan)
- Union, Set Difference
- Intersection
- Duplicate Elimination



Operator Profiles

- Algorithm
- In-memory complexity: e.g., O(n²)
- Memory requirements
 - Runtime based on available memory
- #I/O if operation needs to go to disk
- Disk space needed
- Prerequisites
 - Conditions under which the operator can be applied





Execution Strategies

- Compiled
 - Translate into C/C++/Assembler code
 - Compile, link, and execute code
- Interpreted
 - Generic operator implementations
 - Generic executor
 - Interprets query plan





Virtual Machine Approach

- Implement virtual machine of low-level DBMS operations
- Compile query into machine-code for that machine





Iterator Model

- Need to be able to combine operators in different ways
 - E.g., join inputs may be scans, or outputs of other joins, ...
 - --> define generic interface for operators
 - be able to arbitrarily compose complex plans from a small set of operators



Iterator Model - Interface

Open

Prepare operator to read inputs

Close

Close operator and clean up

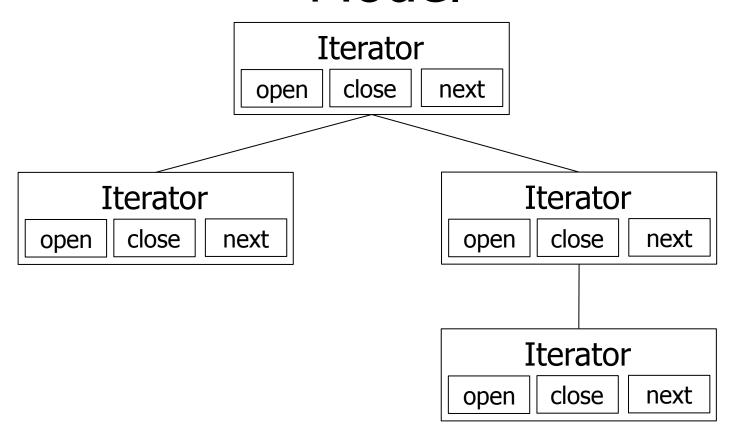
Next

Return next result tuple



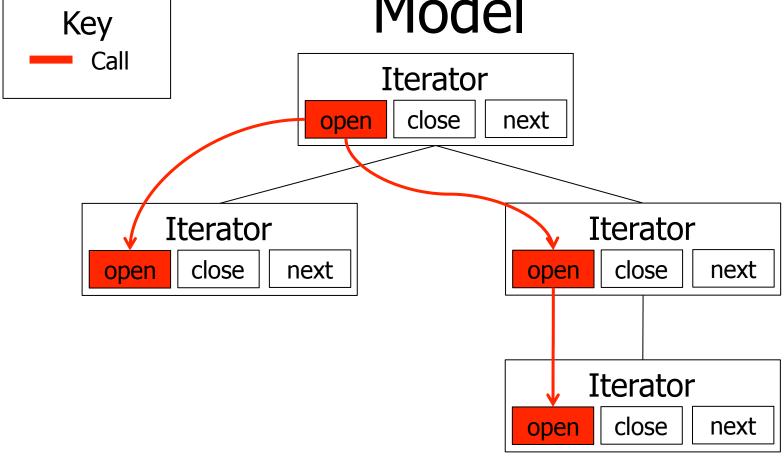


Query Execution – Iterator Model





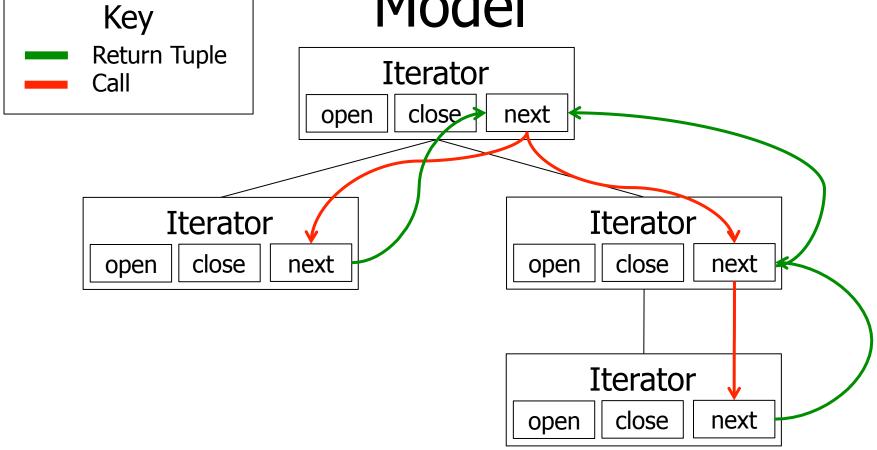
Query Execution – Iterator Model





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Query Execution – Iterator Model







Parallelism

- Iterator Model
 - Pull-based query execution
- Potential types of parallelism
 - Inter-query (every multiuser system)
 - Intra-operator
 - Inter-operator





Intra-Operator Parallelism

- Execute portions of an operator in parallel
 - Merge-Sort
 - Assign a processor to each merge phase
 - Scan
 - Partition tables
 - Each process scans one partition





Inter-Operator Parallelism

 Each process executes one or more operators

Pipelining

- Push-based query execution
- Chain operators to directly produce results
- Pipeline-breakers
 - Operators that need to consume the whole input (or large parts) before producing outputs



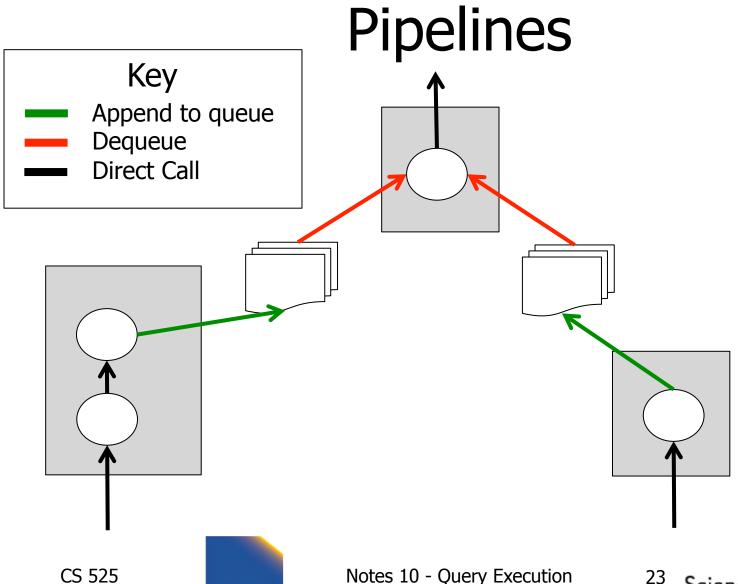
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Pipelining Communication

Queues

- Operators push their results to queues
- Operators read their inputs from queues
- Direct call
 - Operator calls its parent in the tree with results
 - Within one process





Pipeline-breakers

- Sorting
 - All operators that apply sorting
- Aggregation
- Set Difference
- Some implementations of
 - Join
 - Union



Operators Overview

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Sorting

- Why do we want/need to sort
 - Query requires sorting (ORDER BY)
 - Operators require sorted input
 - Merge-join
 - Aggregation by sorting
 - Duplicate removal using sorting



In-memory sorting

- Algorithms from data structures 101
 - Quick sort
 - Merge sort
 - Heap sort
 - Intro sort

— ...



External sorting

- Problem:
 - Sort N pages of data with M pages of memory

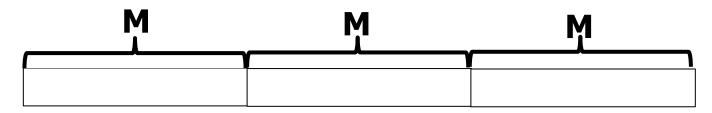
Solutions?





First Idea

- Split data into runs of size M
- Sort each run in memory and write back to disk
 - [N/M] sorted runs of size M
- Now what?



Merging Runs

- Need to create bigger sorted runs out of sorted smaller runs
 - Divide and Conquer
 - Merge Sort?
- How to merge two runs that are bigger than M?

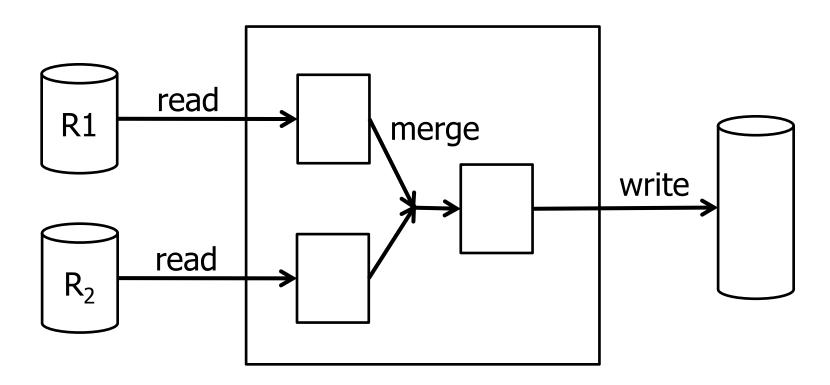


Merging Runs using 3 pages

- Merging sorted runs R₁ and R₂
- Need 3 pages
 - One page to buffer pages from R₁
 - One page to buffer pages from R₂
 - One page to buffer the result
 - Whenever this buffer is full, write it to disk



Merging Runs

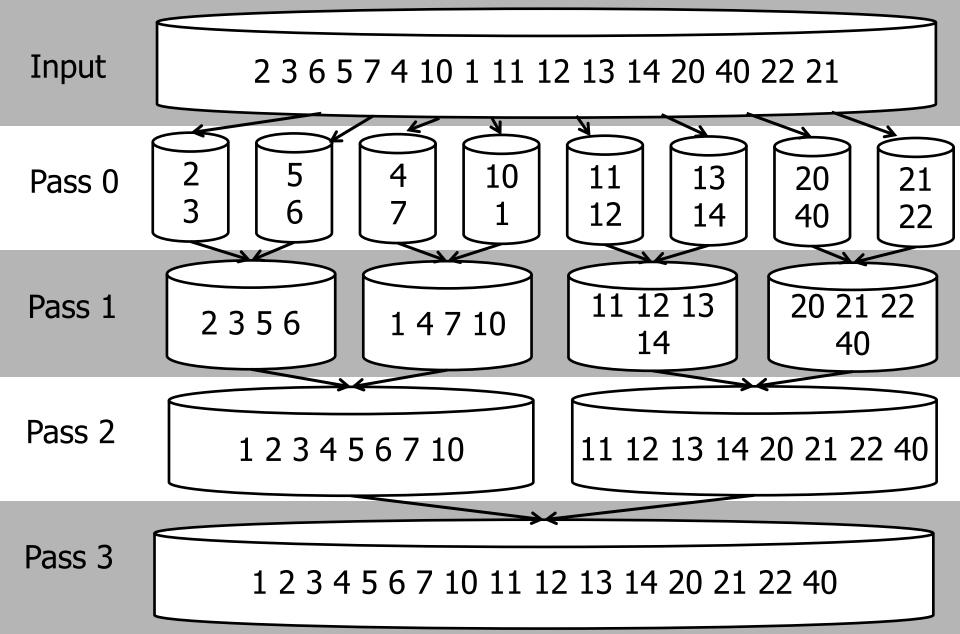




2-Way External Mergesort

- Repeat process until we have one sorted run
- Each iteration (pass) reads and writes the whole table once: 2 B(R) I/Os
- Each pass doubles the run size
 - $-1 + [\log_2 (B(R) / M)] runs$
 - $-2B(R)*(1 + [log_2(B(R)/M)]) I/Os$







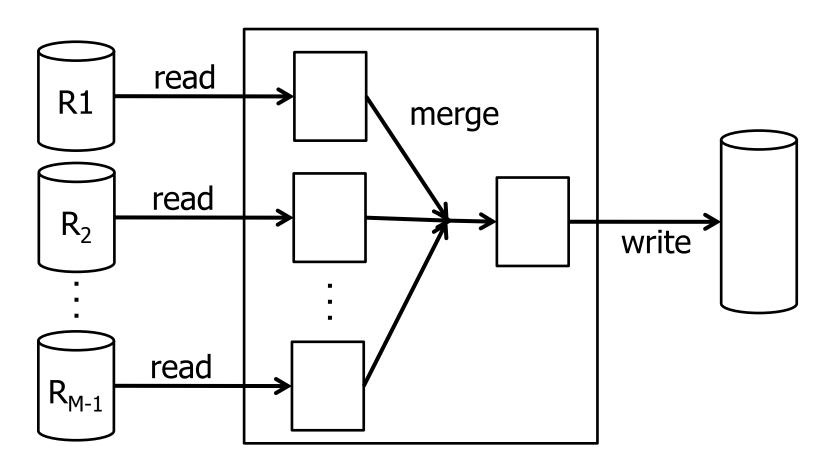
N-Way External Mergesort

- How to utilize M buffer during merging?
- Each pass merges M-1 runs at once
 - One memory page as buffer for each run
- #I/Os

```
1 + \lceil \log_{M-1} (B(R) / M) \rceil runs
2 B(R) *(1 + \lceil \log_{M-1} (B(R) / M) \rceil) I/Os
```



Merging Runs





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How many passes do we need?

N	M=17	M=129	M=257	M=513	M=1025
100	2	1	1	1	1
1,000	3	2	2	2	1
10,000	4	2	2	2	2
100,000	5	3	3	2	2
1,000,000	5	3	3	3	2
10,000,000	6	4	3	3	3
100,000,000	7	4	4	3	3
1,000,000,000	8	5	4	4	3



To put into perspective

- Scenario
 - Page size 4KB
 - 1TB of data (250,000,000)
 - 10MB of buffer for sorting (250)
- Passes
 - 4 passes



Merge

- In practice would want larger I/O buffer for each run
- Trade-off between number of runs and efficiency of I/O





Improving in-memory merging

- Merging M runs
 - To choose next element to output
 - Have to compare M elements
 - --> complexity linear in M: O(M)
- How to improve that?
 - Use priority queue to store current element from each run
 - $\rightarrow O(\log_2(M))$





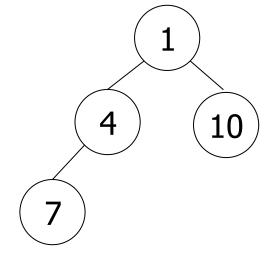
Priority Queue

- Queue for accessing elements in some given order
 - pop-smallest = return and remove smallest element in set
 - -Insert(e) = insert element into queue



Min-Heap

- Implementation of priority queue
 - Store elements in a binary tree
 - All levels are full (except leaf level)
 - Heap property
 - Parent is smaller than child
- Example: { 1, 4, 7, 10 }





Min-Heap Insertion

insert(e)

- 1. Add element at next free leaf node
 - This may invalidate heap property
- 2. If node smaller than parent then
 - Switch node with parent
- 3. Repeat until 2) cannot be applied anymore



Min-Heap Dequeue

pop-smallest

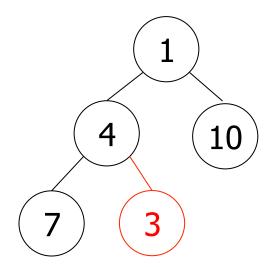
- 1. Return Root and use right-most leaf as new root
 - This may invalidate heap property
- 2. If node smaller than child then
 - Switch node with smaller child
- 3. Repeat until 2) cannot be applied anymore



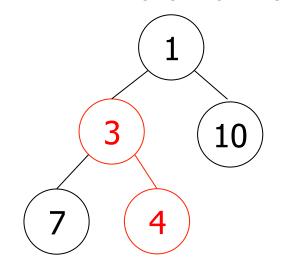
Insertion

Insert 3

Insert at first free position

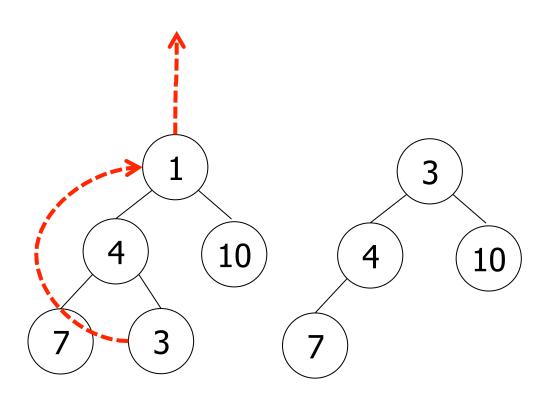


Restore heap property



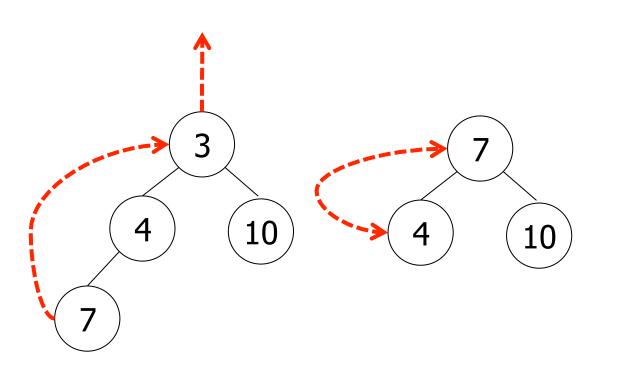


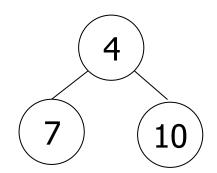
Dequeue





Dequeue







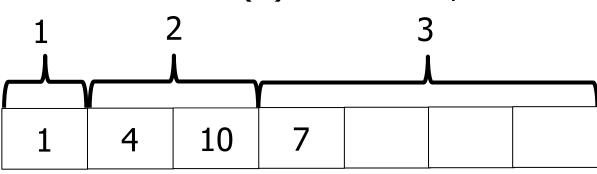
Min/Max-Heap Complexity

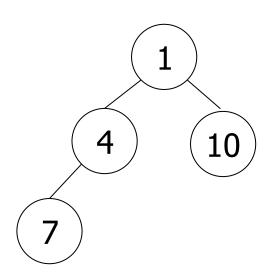
- Heap is a complete tree
 - Height is $O(log_2(n))$
- Insertion
 - Maximal height of the tree switches
 - $\rightarrow O(\log_2(n))$
- Dequeue
 - Maximal height of the tree switches
 - $\rightarrow O(\log_2(n))$



Min-Heap Implementation

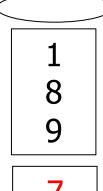
- Full tree
 - Use array to implement tree
- Compute positions
 - $-\operatorname{Parent}(n) = \lfloor (n-1) / 2 \rfloor$
 - Children(n) = 2n + 1, 2n + 2





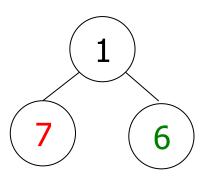


Merging with Priority Queue



10

13

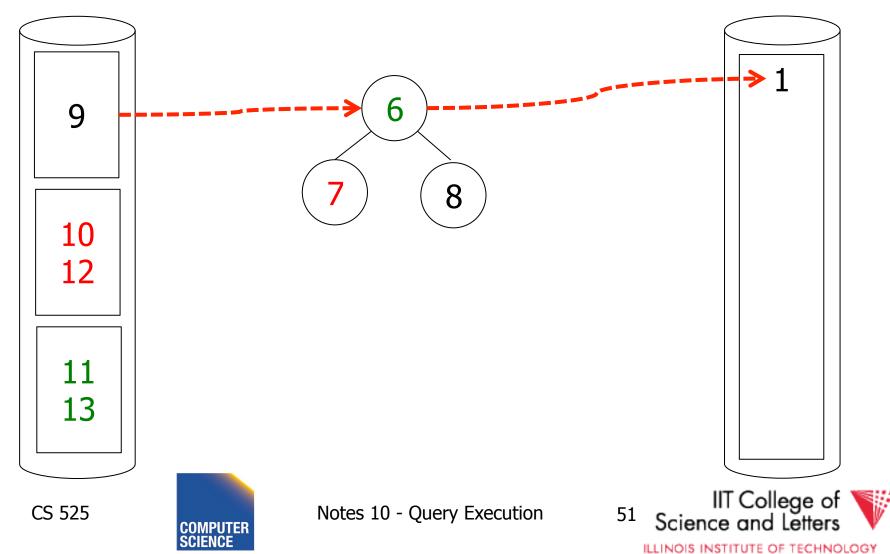




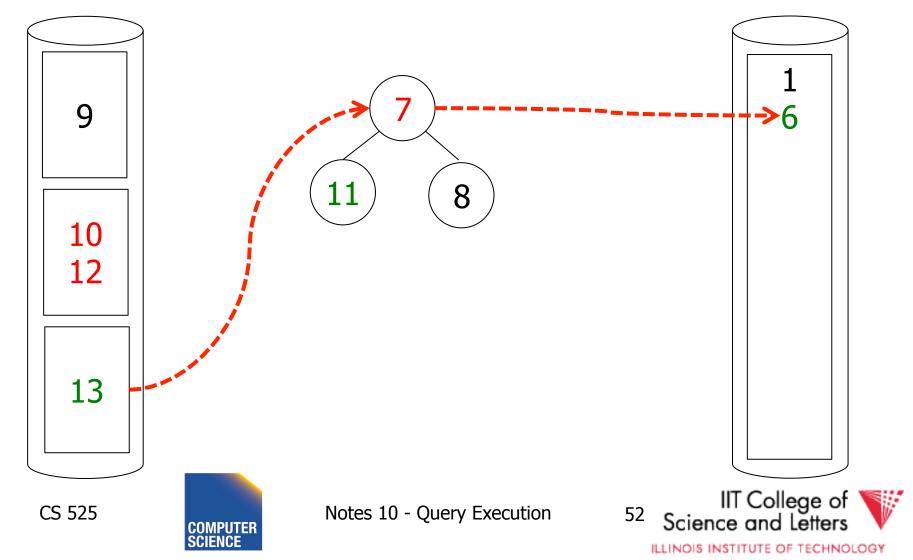




Merging with Priority Queue

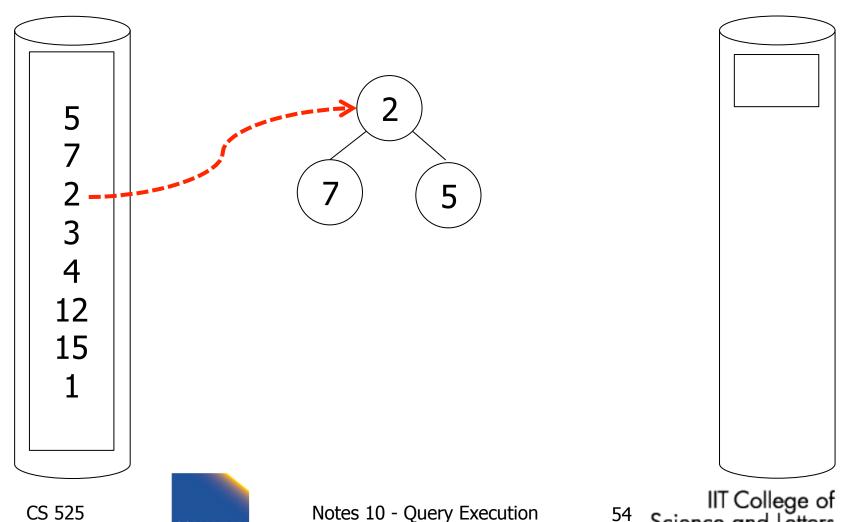


Merging with Priority Queue

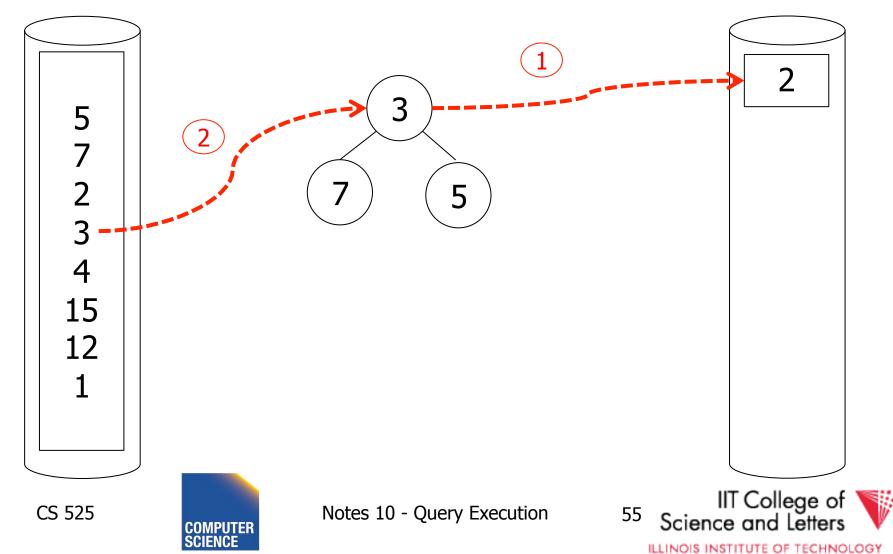


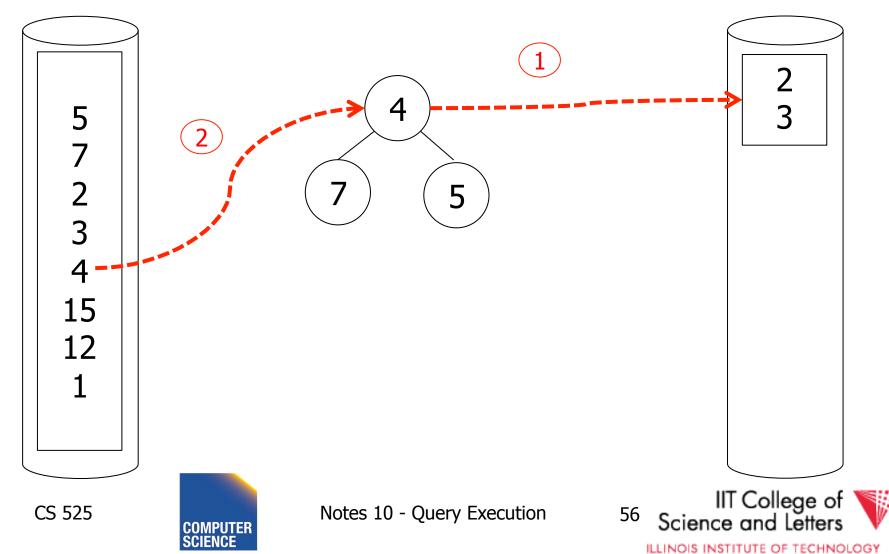
- Read inputs into heap
 - Until available memory is full
- Replace elements
 - Remove smallest element from heap
 - If larger then last element written of current run then write to current run
 - Else create a new run
 - Add new element from input to heap

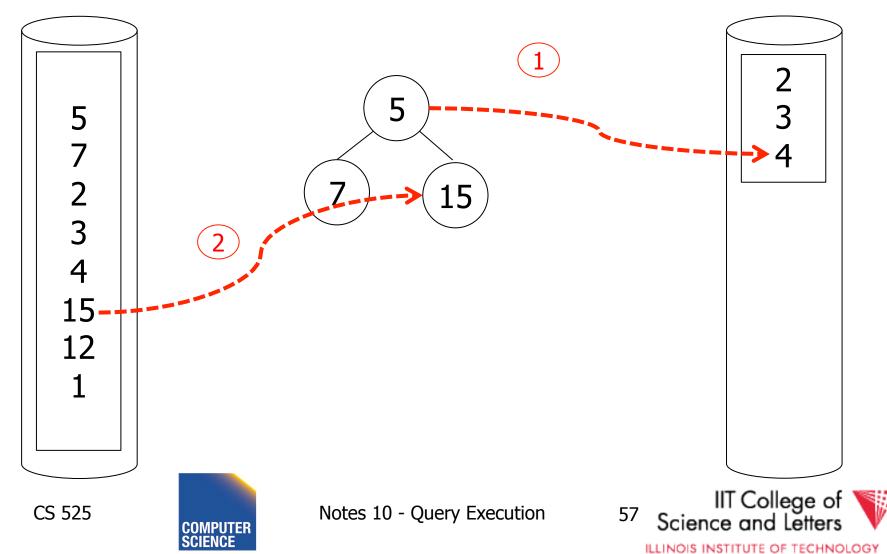


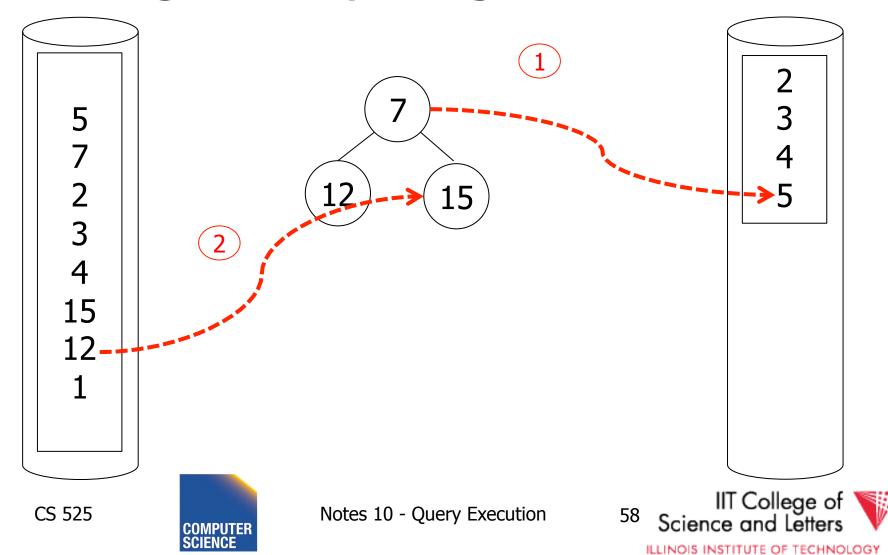


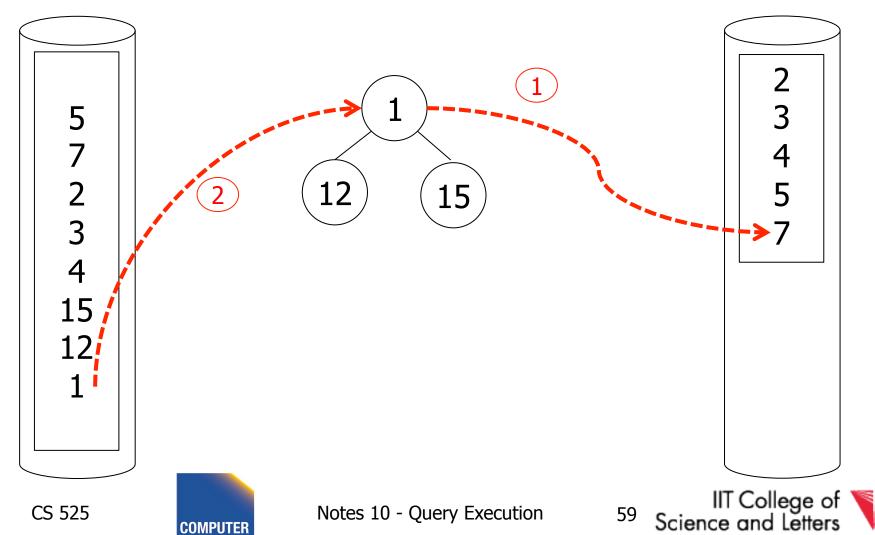
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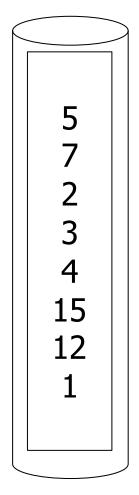


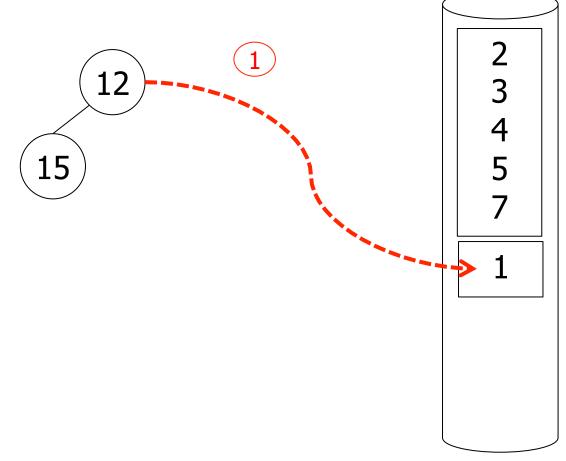






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- Increases the run-length
 - On average by a factor of 2 (see Knuth)





Use clustered B+-tree

- Keys in the B+-tree I are in sort order
 - If B+-tree is clustered traversing the leaf nodes is sequential I/O!
 - $-\mathbf{K} = \#\text{keys/leaf node}$
- Approach
 - Traverse from root to first leaf: HT(I)
 - Follow sibling pointers: |R| / K
 - Read data blocks: B(R)



I/O Operations

- **HT(I)** + |**R**| / **K** + **B(R)** I/Os
- Less than 2 B(R) = 1 pass external mergesort
- ->Better than external merge-sort!





Unclustered B+-tree?

- Each entry in a leaf node may point to different page of relation R
 - For each leaf page we may read up to K pages from relation R
 - Random I/O
- In worst-case we have
 - -K*B(R)
 - -K = 500
 - 500 * B(R) = 250 merge passes



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Sorting Comparison

B(R) = number of block of R

M = number of available memory blocks

#RB = records per page

HT = height of B+-tree (logarithmic)

K = number of keys per leaf node

Property	Ext. Mergesort	B+ (clustered)	B+ (unclustered)
Runtime	O (N log _{M-1} (N))	O(N)	O(N)
#I/O (random)	2 B(R) * (1 + [log _{M-1} (B(R) / M)])	HT + R / K + B(R)	HT + R / K + K * #RB
Memory	M	1 (better HT + X)	1 (better HT + X)
Disk Space	2 B(R)	0	0
Variants	 Merge with heap Run generation with heap Larger Buffer 		
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Operators Overview

- (External) Sorting
- Joins (Nested Loop, Merge, Hash, ...)
- Aggregation (Sorting, Hash)
- Selection, Projection (Index, Scan)
- Union, Set Difference
- Intersection
- Duplicate Elimination



Scan

- Implements access to a table
 - Combined with selection
 - Probably projection too
- Variants
 - Sequential
 - Scan through all tuples of relation
 - Index
 - Use index to find tuples that match selection



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<u>Options</u>

- Transformations: $R_1 \bowtie_c R_2$, $R_2 \bowtie_c R_1$
- Joint algorithms:
 - Nested loop
 - Merge join
 - Join with index
 - Hash join
- Outer join algorithms



```
Nested Loop Join (conceptually)

for each r \in R_1 do

for each s \in R_2 do

if (r,s) \models C then output (r,s)
```

Applicable to:

- Any join condition C
- Cross-product





Merge Join (conceptually)

```
(1) if R_1 and R_2 not sorted, sort them 
(2) i \leftarrow 1; j \leftarrow 1; 
While (i \le T(R_1)) \land (j \le T(R_2)) do 
if R_1{ i }.C = R_2{ j }.C then outputTuples 
else if R_1{ i }.C > R_2{ j }.C then j \leftarrow j+1 
else if R_1{ i }.C < R_2{ j }.C then i \leftarrow i+1
```

Applicable to:

C is conjunction of equalities or </></>

$$A_1 = B_1 \text{ AND } \dots \text{ AND } A_n = B_n$$



Procedure Output-Tuples

```
While (R_1\{i\}.C = R_2\{j\}.C) \land (i \le T(R_1)) do [jj \leftarrow j; while (R_1\{i\}.C = R_2\{jj\}.C) \land (jj \le T(R_2)) do [output pair R_1\{i\}, R_2\{jj\}; jj \leftarrow jj+1] i \leftarrow i+1]
```





Example

i	$R_1\{i\}.C$	$R_2\{j\}.C$	j
1	10	5	1
2	20	20	2
3	20	20	3
4	30	30	4
5	40	30	5
		50	6
		52	7



Index nested loop (Conceptually)

For each $r \in R_1$ do

Assume R₂.C index

[$X \leftarrow \text{index } (R_2, C, r.C)$ for each $s \in X$ do output (r,s) pair]

Note: $X \leftarrow index(rel, attr, value)$

then X = set of rel tuples with attr = value



Hash join (conceptual)

Hash function h, range $0 \rightarrow k$

Buckets for R_1 : G_0 , G_1 , ... G_k

Buckets for R_2 : H_0 , H_1 , ... H_k

Applicable to:

C is conjunction of equalities

$$A_1 = B_1 \text{ AND } \dots \text{ AND } A_n = B_n$$



Hash join (conceptual)

Hash function h, range $0 \rightarrow k$

Buckets for R_1 : G_0 , G_1 , ... G_k

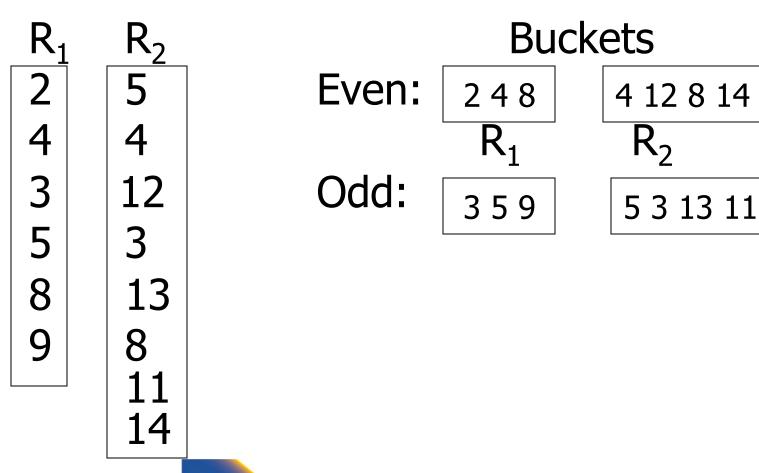
Buckets for R_2 : H_0 , H_1 , ... H_k

Algorithm

- (1) Hash R₁ tuples into G buckets
- (2) Hash R₂ tuples into H buckets
- (3) For i = 0 to k do match tuples in G_i , H_i buckets



Simple example hash: even/odd



Factors that affect performance

(1) Tuples of relation stored physically together?

(2) Relations sorted by join attribute?

(3) Indexes exist?



Example 1(a) NL Join $R_1 \bowtie R_2$

Relations <u>not</u> contiguous

• Recall
$$\{ T(R_1) = 10,000 \ T(R_2) = 5,000 \ S(R_1) = S(R_2) = 1/10 \text{ block} \}$$

MEM=101 blocks





Example 1(a)

Nested Loop Join $R_1 \bowtie R_2$

Relations <u>not</u> contiguous

• Recall
$$\{T(R_1) = 10,000 \ T(R_2) = 5,000 \ S(R_1) = S(R_2) = 1/10 \text{ block} \}$$

MEM=101 blocks

Cost: for each R₁ tuple:

Total = 10,000 [1+500]=5,010,000 IOs



Can we do better?



Can we do better?

Use our memory

- (1) Read 100 blocks of R_1
- (2) Read all of R_2 (using 1 block) + join
- (3) Repeat until done

Cost: for each R₁ chunk:

Read chunk: 100 IOs

Read R₂: 500 IOs

600



Cost: for each R₁ chunk:

Read chunk: 100 IOs

Read R_2 : 500 IOs

600

Total =
$$\frac{1,000}{100}$$
 x 600 = 6,000 IOs



Can we do better?





Can we do better?

• Reverse join order: $R_2 > R_1$

Total =
$$500 \times (100 + 1,000) = 100$$

$$5 \times 1,100 = 5,500 IOs$$



Cost of Block Nested Loop

◆ Reverse join order: R₁ R₂

Total =
$$[B(R1)]$$
 x (min(B(R1), M-1) + B(R2))



Block-Nested Loop Join (conceptual) for each M-1 blocks of R₁ do read M-1 blocks of R₁ into buffer for each block of R₂ do read next block of R₂ for each tuple r in R₁ block for each tuple s in R₂ block if $(r,s) \models C$ then output (r,s)



Note

- How much memory for buffering inner and for outer chunks?
 - 1 for inner would minimize I/O
 - But, larger buffer better for I/O



 R_1

M - k M - k	M - k
-------------	-------

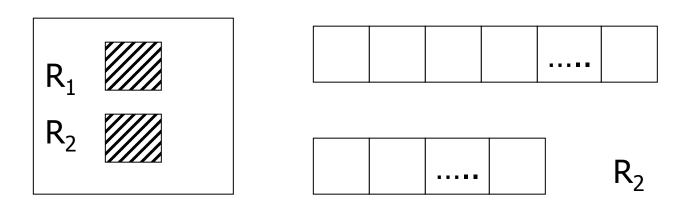
 R_2

|--|



Example 1(b) Merge Join

Both R₁, R₂ ordered by C; relations contiguous
 Memory

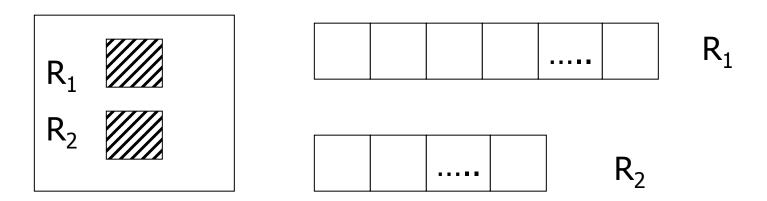




 R_1

Example 1(b) Merge Join

Both R₁, R₂ ordered by C; relations contiguous
 Memory



Total cost: Read R_1 cost + read R_2 cost = 1000 + 500 = 1,500 IOs



$$R > \subset_{B=C} S$$

Output: (a,1,1,X)

R

S

A	В			C	D
а	1	\leftarrow Z _R	Z_S —	→ 1	X
b	1			2	У
а	2			2	е
С	3			6	q
d	4			7	d
е	5				



$$R > \subset_{B=C} S$$

Output: (b,1,1,X)

R

A	В	
a	1	
b	1	\leftarrow Z_R
a	2	
С	3	
d	4	

 $Z_S \longrightarrow \begin{array}{c|c} \mathbf{C} & \mathbf{D} \\ 1 & x \\ 2 & y \\ 2 & e \\ 6 & q \\ 7 & d \end{array}$



5

e

$$R \bowtie_{B=C} S$$

R.B > S.C: advance Z_S

R

S

A	В			C	D
а	1		$Z_S \longrightarrow$	1	X
b	1			2	У
а	2	\leftarrow Z_R		2	е
С	3			6	q
d	4			7	d
е	5				



$$R > \subset_{B=C} S$$

Output: (a,2,2,y)

R

A B
 a 1
 b 1
 a 2
 c 3
 d 4
 e 5

	C	D
	1	X
$Z_S \longrightarrow$	2	У
	2	е
	6	q
	7	d





Output: (a,2,2,e)

R

A	В			C	D
a	1			1	X
b	1			2	У
а	2	\leftarrow Z_R	Z_S —	> 2	е
С	3	1		6	q
d	4			7	d
е	5				





R.B > S.C: advance Z_s

R

5

A	В			С	D
а	1			1	X
b	1			2	У
a	2		$Z_S \longrightarrow$	2	е
С	3	\leftarrow Z_R		6	q
d	4			7	d
е	5				



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R.B < S.C: advance Z_R

R

S

A	В			C	D
а	1			1	X
b	1			2	У
a	2			2	е
С	3	\leftarrow Z_R	Z_S —	6	q
d	4	, and the second		7	d
е	5				



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R.B < S.C: advance Z_R

R

S

A	В			C	D
а	1			1	X
b	1			2	У
a	2			2	е
С	3		Z_S —	→ 6	q
d	4	\leftarrow Z_R		7	d
е	5				

$$R \bowtie_{B=C} S$$

R.B < S.C: **DONE**

R

S

A	В	
a	1	
b	1	
a	2	
С	3	
d	4	
е	5	<

	C	D
	1	X
	2	У
	2	е
$Z_S \longrightarrow$	6	q
	7	d



 Z_{R}

Example 1(c) Merge Join

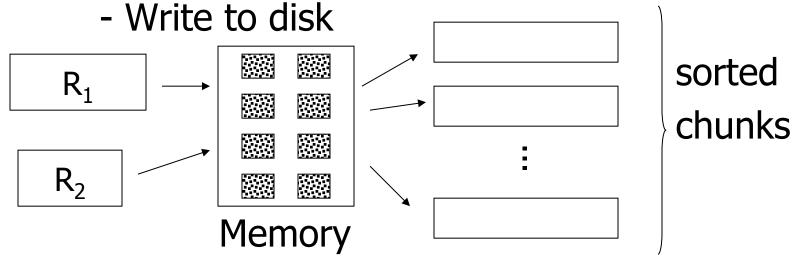
• R₁, R₂ not ordered, but contiguous

--> Need to sort R₁, R₂ first



One way to sort: Merge Sort

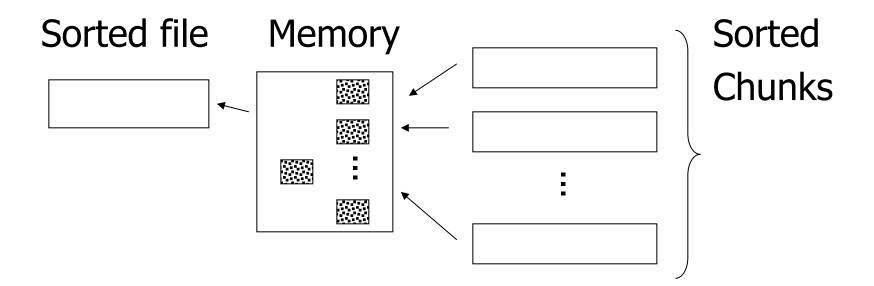
- (i) For each 100 blk chunk of R:
 - Read chunk
 - Sort in memory





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(ii) Read all chunks + merge + write out





Cost: Sort

Each tuple is read, written, read, written

SO...

Sort cost R_1 : $4 \times 1,000 = 4,000$

Sort cost R_2 : $4 \times 500 = 2,000$





Example 1(d) Merge Join (continued)

R₁,R₂ contiguous, but unordered

Total cost = sort cost + join cost
=
$$6,000 + 1,500 = 7,500$$
 IOs



Example 1(c) Merge Join (continued)

R₁,R₂ contiguous, but unordered

Total cost = sort cost + join cost
=
$$6,000 + 1,500 = 7,500$$
 IOs

But: Iteration cost = 5,500 so merge joint does not pay off!





But say $R_1 = 10,000$ blocks contiguous $R_2 = 5,000$ blocks not ordered

Iterate: $5000 \times (100+10,000) = 50 \times 10,100$ 100 = 505,000 IOs

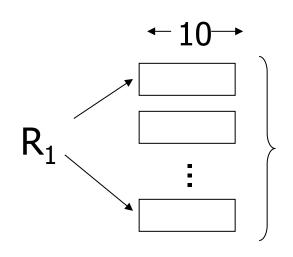
Merge join: 5(10,000+5,000) = 75,000 IOs

Merge Join (with sort) WINS!



How much memory do we need for merge sort?

E.g: Say I have 10 memory blocks



100 chunks ⇒ to merge, need 100 blocks!





In general:

Say k blocks in memory x blocks for relation sort # chunks = (x/k) size of chunk = k





<u>In general:</u>

Say k blocks in memory x blocks for relation sort # chunks = (x/k) size of chunk = k

chunks < buffers available for merge





<u>In general:</u>

Say k blocks in memory
x blocks for relation sort
chunks = (x/k) size of chunk = k

chunks < buffers available for merge

so...
$$(x/k) \le k$$

or $k^2 \ge x$ or $k \ge \sqrt{x}$





In our example

 R_1 is 1000 blocks, $k \ge 31.62$

 R_2 is 500 blocks, $k \ge 22.36$

Need at least 32 buffers

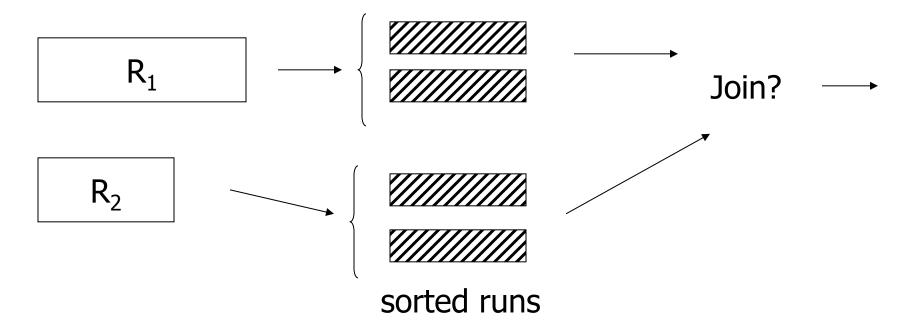
Again: in practice we would not want to use only one buffer per run!





Can we improve on merge join?

Hint: do we really need the fully sorted files?





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Cost of improved merge join:

- $C = Read R_1 + write R_1 into runs$
 - + read R₂ + write R₂ into runs
 - + join
 - = 2,000 + 1,000 + 1,500 = 4,500

--> Memory requirement?





Example 1(d) Index Join

- Assume R₁.C index exists; 2 levels
- Assume R₂ contiguous, unordered

Assume R₁.C index fits in memory





Cost: Reads: 500 IOs for each R₂ tuple:

- probe index free
- if match, read R₁ tuple: 1 IO



What is expected # of matching tuples?

- (a) say R_1 .C is key, R_2 .C is foreign key then expect = 1
- (b) say $V(R_1,C) = 5000$, $T(R_1) = 10,000$ with uniform assumption expect = 10,000/5,000 = 2



What is expected # of matching tuples?

(c) Say DOM(
$$R_1$$
, C)=1,000,000
 $T(R_1) = 10,000$
with alternate assumption
 $Expect = 10,000 = 1$
 $1,000,000 = 100$



Total cost with index join

(a) Total cost =
$$500+5000(1)1 = 5,500$$

(b) Total cost =
$$500+5000(2)1 = 10,500$$

(c) Total cost =
$$500+5000(1/100)1=550$$





What if index does not fit in memory?

Example: say R₁.C index is 201 blocks

- Keep root + 99 leaf nodes in memory
- Expected cost of each probe is

$$E = (0)\underline{99} + (1)\underline{101} \approx 0.5$$

$$200 \quad 200$$



Total cost (including probes)

- = 500+5000 [Probe + get records]
- =500+5000 [0.5+2] uniform assumption
- = 500+12,500 = 13,000 (case b)



Total cost (including probes)

- = 500+5000 [Probe + get records]
- = 500+5000 [0.5+2] uniform assumption
- = 500+12,500 = 13,000 (case b)

For case (c):

- $= 500+5000[0.5 \times 1 + (1/100) \times 1]$
- = 500+2500+50 = 3050 IOs



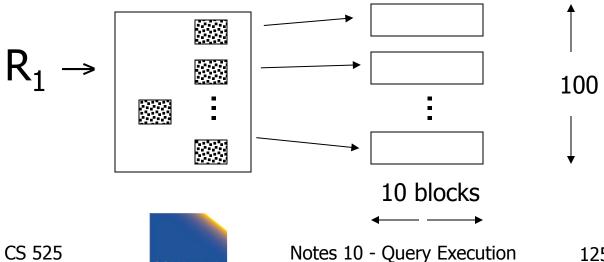
So far

	Nested Loop	5500
	Merge join	1500
1	Sort+Merge Join	7500 → 4500
	R ₁ .C Index	$5500 \rightarrow 3050 \rightarrow 550$
	R ₂ .C Index	



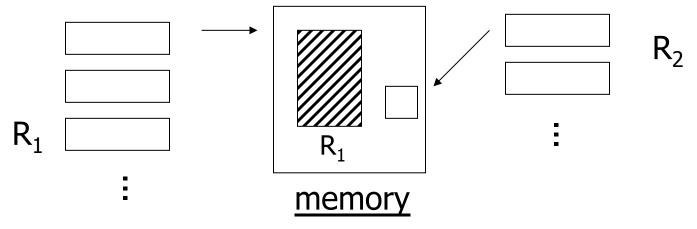
Example 1(e) Partition Hash Join

- R₁, R₂ contiguous (un-ordered)
- → Use 100 buckets
- → Read R₁, hash, + write buckets





- -> Same for R₂
- -> Read one R₁ bucket; build memory hash table
 -using different hash function h'
- -> Read corresponding R₂ bucket + hash probe



Then repeat for all buckets



Cost:

"Bucketize:" Read R₁ + write

Read R₂ + write

Join: Read R₁, R₂

Total cost = $3 \times [1000+500] = 4500$



Cost:

"Bucketize:" Read R₁ + write

Read R₂ + write

Join: Read R₁, R₂

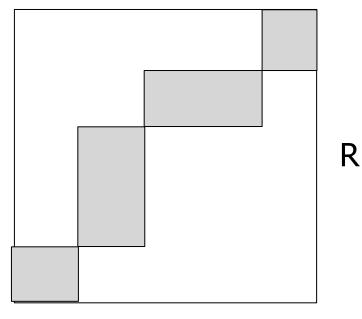
Total cost = $3 \times [1000+500] = 4500$

Note: this is an approximation since buckets will vary in size and we have to round up to blocks



Why is Hash Join good?

R



5



Minimum memory requirements:

Size of R_1 bucket = (x/k)

k = number of memory buffers

 $x = number of R_1 blocks$

So... (x/k) < k

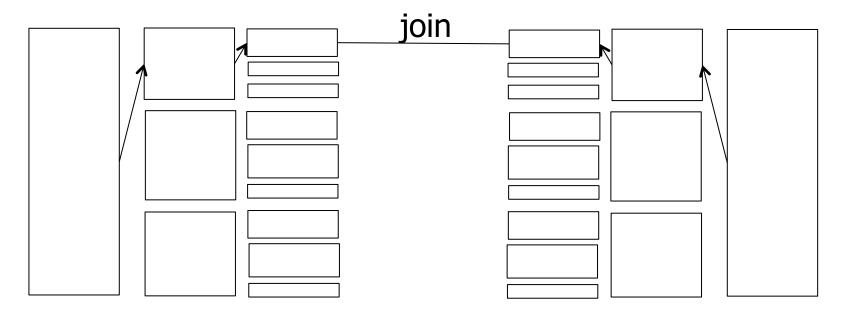
 $k > \sqrt{x}$

need: k+1 total memory buffers



Can we use Hash-join when buckets do not fit into memory?:

 Treat buckets as relations and apply Hash-join recursively





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Duality Hashing-Sorting

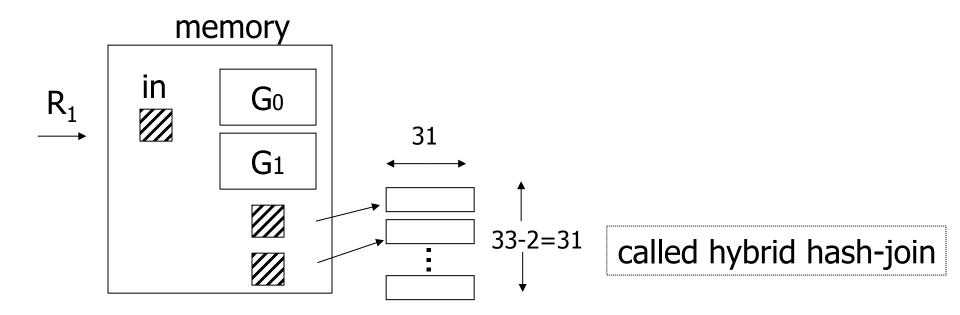
- Both partition inputs
- Until input fits into memory
- Logarithmic number of phases in memory size





Trick: keep some buckets in memory

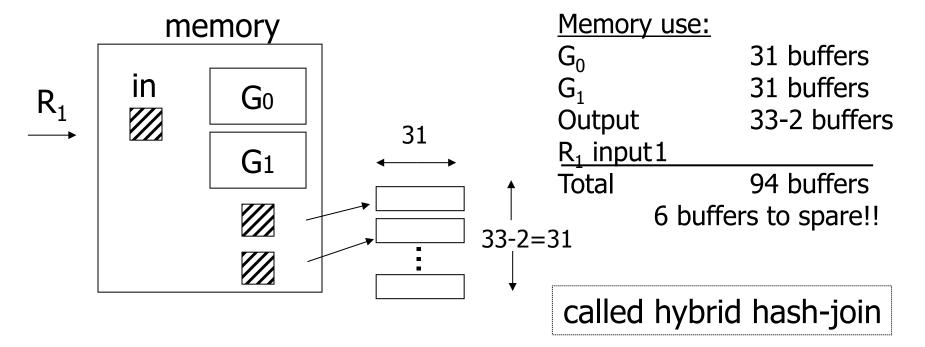
E.g., k' = 33 R₁ buckets = 31 blocks keep 2 in memory





Trick: keep some buckets in memory

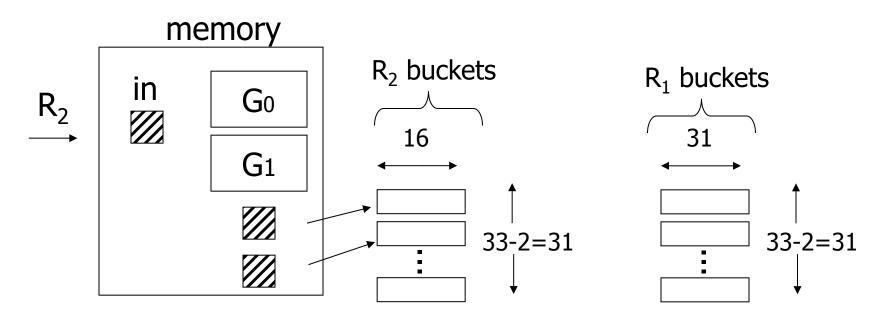
E.g., k' = 33 R₁ buckets = 31 blocks keep 2 in memory





Next: Bucketize R₂

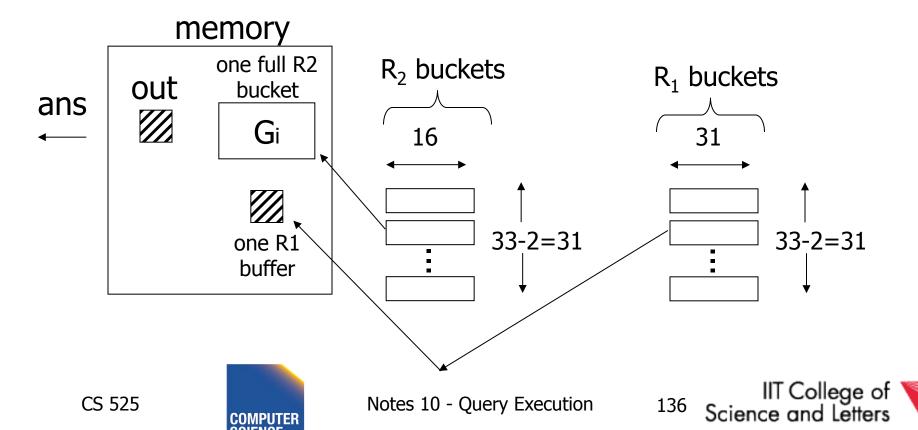
- $-R_2$ buckets =500/33= 16 blocks
- Two of the R₂ buckets joined immediately with G₀,G₁





Finally: Join remaining buckets

- for each bucket pair:
 - read one of the buckets into memory
 - join with second bucket



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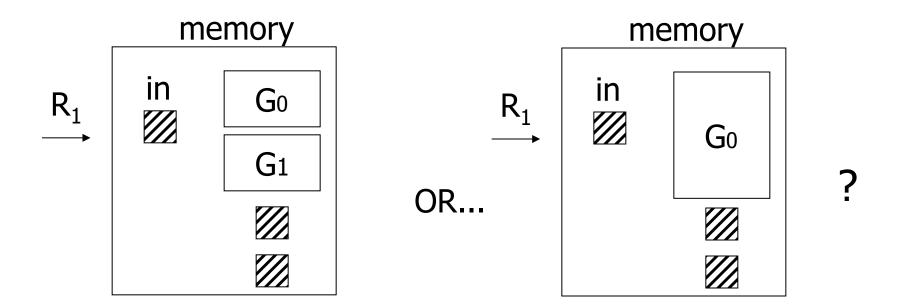
Cost

- Bucketize $R_1 = 1000 + 31 \times 31 = 1961$
- To bucketize R₂, only write 31 buckets:
 so, cost = 500+31×16=996
- To compare join (2 buckets already done)
 read 31×31+31×16=1457

Total cost = 1961+996+1457 = 4414



How many buckets in memory?



See textbook for answer...





Another hash join trick:

- Only write into buckets<val,ptr> pairs
- When we get a match in join phase, must fetch tuples



- To illustrate cost computation, assume:
 - 100 <val,ptr> pairs/block
 - expected number of result tuples is 100



- To illustrate cost computation, assume:
 - 100 <val,ptr> pairs/block
 - expected number of result tuples is 100
- Build hash table for R_2 in memory 5000 tuples \rightarrow 5000/100 = 50 blocks
- Read R₁ and match
- Read ~ 100 R₂ tuples



- To illustrate cost computation, assume:
 - 100 <val,ptr> pairs/block
 - expected number of result tuples is 100
- Build hash table for R_2 in memory 5000 tuples \rightarrow 5000/100 = 50 blocks
- Read R₁ and match
- Read ~ 100 R₂ tuples

Total cost =	Read R ₂ :	500
	Read R_1 :	1000
	Get tuples:	100
	•	1600



So far:

Iterate	5500
Merge join	1500
Sort+merge joint	7500
R ₁ .C index	$5500 \rightarrow 550$
R_2 .C index	
Build R₁.C index	
Build R ₂ .C index	
Hash join	4500+
with trick, R ₁ first	4414
with trick, R ₂ first	
Hash join, pointers	1600



Yet another hash join trick:

- Combine the ideas of
 - block nested-loop with hash join
- Use memory to build hash-table for one chunk of relation
- Find join partners in O(1) instead of O(M)
- Trade-off
 - Space-overhead of hash-table
 - Time savings from look-up



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<u>Summary</u>

- Nested Loop ok for "small" relations (relative to memory size)
 - Need for complex join condition
- For equi-join, where relations not sorted and no indexes exist, hash join usually best



- Sort + merge join good for non-equi-join (e.g., R₁.C > R₂.C)
- If relations already sorted, use merge join
- If index exists, it <u>could</u> be useful (depends on expected result size)



Join Comparison

 N_i = number of tuples in R_i $B(R_i)$ = number of blocks of R_i **#P** = number of partition steps for hash join

 P_{ii} = average number of join partners

Algorithm	#I/O	Memory	Disk Space
Nested Loop (block)	B(R ₁) / (M-1) * [min(B(R),M-1) + B(R ₂)]	3	0
Index Nested Loop	$B(R_1) + N_1 * P_{12}$	B(Index) + 2	0
Merge (sorted)	$B(R_1) + B(R_2)$	Max tuples =	0
Merge (unsorted)	$B(R_1) + B(R_2) +$ (sort – 1 pass)	sort	$B(R_1) + B(R_2)$
Hash	$(2#P + 1) (B(R_1) + B(R_2))$	root(max(B(R_1), B(R_2)), #P + 1)	$\sim B(R_1) + B(R_2)$





Why do we need nested loop?

 Remember not all join implementations work for all types of join conditions

Algorithm	Type of Condition	Example
Nested Loop	any	a LIKE '%hello%'
Index Nested Loop	Supported by index: Equi-join (hash) Equi or range (B-tree)	a = b a < b
Merge	Equalities and ranges	a < b, $a = b$ AND $c = d$
Hash	Equi-join	a = b

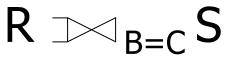


Outer Joins

- How to implement (left) outer joins?
- Nested Loop and Merge
 - Use a flag that is set to true if we find a match for an outer tuple
 - If flag is false fill with NULL
- Hash
 - If no matching tuple fill with NULL



Merge Left Outer Join



Output: (a,1,1,X)

R

A	В	
а	1	\leftarrow Z _R
d	4	
е	5	

	C	D
$Z_S \longrightarrow$	1	X
	2	У
	2	е
	6	q
	7	d

Merge Left Outer Join



R

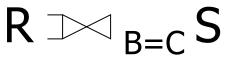
No match for (d,4)
Output: (d,4,NULL,NULL)

A	В	
а	1	
d	4	\leftarrow Z_R
е	5	

	C	D
	1	X
	2	У
	2	е
$Z_S \longrightarrow$	6	q
	7	d



Merge Left Outer Join



R

No match for (e,5) Output: (e,5,NULL,NULL)

A	В	
а	1	
d	4	
е	5	\leftarrow Z_R

	C	D
	1	X
	2	У
	2	е
$Z_S \longrightarrow$	6	q
	7	d



Operators Overview

- (External) Sorting
- Joins (Nested Loop, Merge, Hash, ...)
- Aggregation (Sorting, Hash)
- Selection, Projection (Index, Scan)
- Union, Set Difference
- Intersection
- Duplicate Elimination



Aggregation

- Have to compute aggregation functions
 - for each group of tuples from input
- Groups
 - Determined by equality of group-by attributes



SELECT sum(a),b
FROM R
GROUP BY b

a	b
3	1
4	2
3	1
1	2
1	2

sum(a)	b
6	1
6	2





Aggregation Function Interface

- init()
 - Initialize state
- update(tuple)
 - Update state with information from tuple
- close()
 - Return result and clean-up



Implementation SUM(A)

```
init()
-sum := 0
update(tuple)
-sum += tuple.A
close()
-return sum
```



Aggregation Implementations

Sorting

- Sort input on group-by attributes
- On group boundaries output tuple

Hashing

- Store current aggregated values for each group in hash table
- Update with newly arriving tuples
- Output result after processing all inputs



Grouping by sorting

- Similar to Merge join
- Sort R on group-by attribute
- Scan through sorted input
 - If group-by values change
 - Output using close() and call init()
 - Otherwise
 - Call update()



SELECT sum(a),b
FROM R
GROUP BY b

init()





SELECT sum(a),b
FROM R
GROUP BY b

a	b	
3	1	
3	1	
4	2	
1	2	
1	2	

update(3,1)





SELECT sum(a),b
FROM R
GROUP BY b

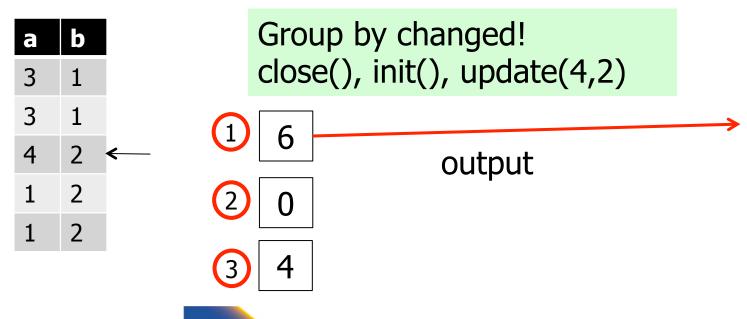
a	b	
3	1	
3	1	
4	2	
1	2	
1	2	

update(3,1)





SELECT sum(a),b FROM R GROUP BY b



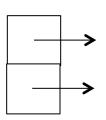
Grouping by Hashing

- Create in-memory hash-table
- For each input tuple probe hash table with group by values
 - If no entry exists then call init(), update(), and add entry
 - Otherwise call update() for entry
- Loop through all entries in hash-table and ouput calling close()



SELECT sum(a),b
FROM R
GROUP BY b

a	b
3	1
4	2
3	1
1	2
1	2

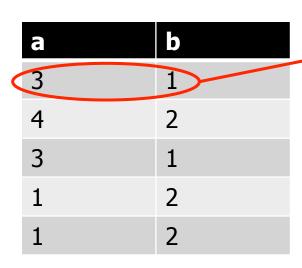


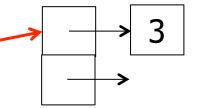




SELECT sum(a), b
FROM R
GROUP BY b
Init(

Init() and update(3,1)



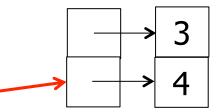




SELECT sum(a),b FROM R GROUP BY b

Init() and update(4,2)

	a	b
	3	1
(4	2
	3	1
	1	2
	1	2





SELECT sum(a), b
FROM R
GROUP BY b

update(3,1)

	a	b	
	3	1	
	4	2	
(3	1	
	1	2	
	1	2	



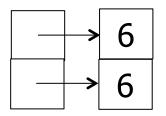


SELECT sum(a),b

FROM R
GROUP BY b

- Loop through hash table entries
- Output tuples

a	b
3	1
4	2
3	1
1	2
1	2





Aggregation Summary

Hashing

- No sorting -> no extra I/O
- Hash table has to fit into memory
- No outputs before all inputs have been processed
- Sorting
 - No memory required
 - Output one group at a time



Operators Overview

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Duplicate Elimination

- Equivalent to group-by on all attributes
- -> Can use aggregation implementations
- Optimization
 - Hash
 - Directly output tuple and use hash table only to avoid outputting duplicates



Operators Overview

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- Joins (Nested Loop, Merge, Hash, ...)
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- Union, Set Difference
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Set Operations

- Can be modeled as join
 - with different output requirements
- As aggregation/group by on all columns
 - with different output requirements



Union

- Bag union
 - Append the two inputs
 - E.g., using three buffers
- Set union
 - Apply duplicate removal to result



Intersection

- Set version
 - Equivalent to join + project + duplicate removal
 - 3-state aggregate function (found left, found right, found both)
- Bag version
 - Join + project + min(i,j)
 - Aggegate min(count(i),count(j))



Set Difference

- Using join methods
 - Find matching tuples
 - If no match found, then output
- Using aggregation
 - count(i) count(j) (bag)
 - true(i) AND false(j) (set)



Summary

- Operator implementations
 - Joins!
 - Other operators
- Cost estimations
 - -I/O
 - memory
- Query processing architectures



Next

- Query Optimization Physical
- -> How to efficiently choose an efficient plan

