

CS4XX INTRODUCTION TO COMPILER THEORY

WEEK 10

Reading:

Chapter 7 and Chapter 8 from Principles of Compiler Design, Alfred V. Aho & Jeffrey D. Ullman

Objectives:

1. To understand the concepts of Run-Time environments(Finish the previous part)
2. To learn the concepts of Intermediate Code Generations
3. To use the concepts learned in Syntax-directed translations

Concepts:

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|--|--------|
| 1. Language facilities for dynamic storage allocation----- | 1/2 hr |
| 2. Dynamic storage allocation techniques----- | 1/2 hr |
| 3. Intermediate languages----- | 1 hr |
| 4. Declarations----- | 1 hr |

Outlines:

1. Language facilities for dynamic storage allocation
 - a. Explicit and Implicit allocation of memory
 - b. Garbage Collection
2. Dynamic Storage allocation Techniques
3. Intermediate language
 - a. Graphical representations - Syntax Trees & DAG
 - b. Postfix notation
 - c. Three Address Code
4. Declarations
 - a. Translation scheme for declarations in a procedure
 - b. Keeping track of scope
 - c. Operations supporting nested STs
 - d. Translation scheme for nested procedures
 - e. Adding ST lookups to assignments

CS 4xx: Week 10 – Lecture Notes

1. Language Facilities for dynamic storage allocation

- Explicit and Implicit allocation of memory to variables
 - Most languages support dynamic allocation of memory.
 - Pascal supports new(p) and dispose(p) for pointer types.
 - C provides malloc() and free() in the standard library.
 - C++ provides the new and free operators.
 - These are all examples of EXPLICIT allocation.
 - Other languages like Python and Lisp have IMPLICIT allocation.
- Garbage – Finding variables that are not referred by the program any more
 - In languages with explicit deallocation, the programmer must be careful to free every dynamically allocated variable, or GARBAGE will accumulate.
 - Garbage is dynamically allocated memory that is no longer accessible because no pointers are pointing to it.
 - In some languages with implicit deallocation, GARBAGE COLLECTION is occasionally necessary.
 - Other languages with implicit deallocation carefully track references to allocated memory and automatically free memory when nobody refers to it any longer

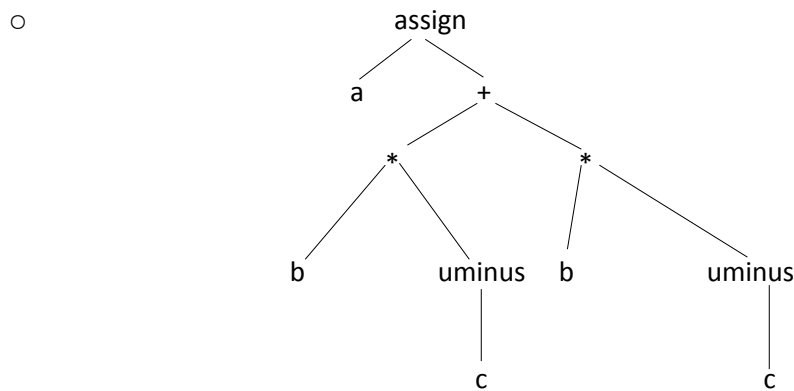
2. Dynamic storage allocation techniques

- Explicit allocation of fixed sized blocks of memory with contiguous block of memory available for usage by the program
- Explicit allocation of variable sized blocks of memory where the storage can be fragmented
- Implicit deallocation of blocks of memory that are not used any more by using reference counts and marking techniques
- We assume the heap is an initially empty block of memory.
- As memory is allocated and deallocated, fragmentation occurs.
- For allocation, we must find a HOLE large enough to hold the requested memory.
- For deallocation, we must merge adjacent holes to prevent further fragmentation.

3. Intermediate Language

- Intermediate codes are machine independent codes, but they are close to machine instructions.
- Example assignment statement $a = b * -c + b * -c$

- Syntax trees
 - A syntax tree depicts the natural hierarchical structure of a source program. A DAG (Directed Acyclic Graph) gives the same information but in a more compact way because common sub-expressions are identified.



- **Postfix notation**

- Postfix notation is a linearized representation of a syntax tree; it is a list of the nodes of the in which a node appears immediately after its children.
- a b c uminus * b c uminus * + assign
- postfix is convenient because it can run on an abstract STACK MACHINE

- **Three Address Code**

- A more common representation is THREE-ADDRESS CODE (3AC)
- 3AC is close to assembly language, making machine code generation easier.
- 3AC has statements of the form

$$x := y \text{ op } z$$
- To get an expression like $x + y * z$, we introduce TEMPORARIES:

$$t1 := y * z$$

$$t2 := x + t1$$
- 3AC is easy to generate from syntax trees. We associate a temporary with each interior tree node.
- Types of 3AC statements
 - Assignment statements of the form $x := y \text{ op}$, where op is a binary arithmetic or logical operation.
 - Assignment statements of the form $x := \text{op } Y$, where op is a unary operator, such as unary minus, logical negation
 - Copy statements of the form $x := y$, which assigns the value of y to x.
 - Unconditional statements goto L, which means the statement with label L is the next to be executed.
 - Conditional jumps, such as if $x \text{ relop } y$ goto L, where relop is a relational operator (<, =, >=, etc) and L is a label. (If the condition $x \text{ relop } y$ is true, the statement with label L will be executed next.)
 - Statements param x and call p, n for procedure calls, and return y, where y represents the (optional) returned value. The typical usage:

$$\begin{array}{l} \text{param } x1 \\ \text{param } x2 \\ \dots \\ \text{param } xn \\ \text{call } p, n \end{array}$$
 - Index assignments of the form $x := y[i]$ and $x[i] := y$. The first sets x to the value in the location i memory units beyond location y. The second sets the content of the location i unit beyond x to the value of y.

4. Declarations

- When we encounter declarations, we need to lay out storage for the declared variables.
- For every local name in a procedure, we create a ST entry containing:
 - The type of the name
 - How much storage the name requires
 - A relative offset from the beginning of the static data area or beginning of the activation record.
- For intermediate code generation, we try not to worry about machine-specific issues like word alignment.
- To keep track of the current offset into the static data area or the AR, the compiler maintains a global variable, OFFSET.
- OFFSET is initialized to 0 when we begin compiling.
- After each declaration, OFFSET is incremented by the size of the declared variable.

- **Translation scheme for declarations in a procedure**

```

P ->                                     { offset := 0 }
      D
D ->  D ; D
D -> id : T                             { enter( id.name, T.type, offset );
                                          offset := offset + T.width }
T -> integer                           { T.type := integer; T.width := 4 }
T -> real                              { T.type := real; T.width := 8 }
T -> array [ num ] of T1                { T.type := array( num.val, T1.type );
                                          T.width := num.val * T1.width }
T -> ^ T1                              { T.type := pointer( T1.type );
                                          T.width := 4 }

```

- **Keeping track of scope**

- When nested procedures or blocks are entered, we need to suspend processing declarations in the enclosing scope.
- Let's change the grammar:


```

P -> D
D -> D ; D | id : T | proc id ; D ; S

```
- Suppose we have a separate ST for each procedure.
- When we enter a procedure declaration, we create a new ST.
- The new ST points back to the ST of the enclosing procedure.
- The name of the procedure is a local for the enclosing procedure.
- Example: Fig. 8.12 in the text

- **Operations supporting nested STs**

- **mktable(previous)** creates a new symbol table pointing to previous, and returns a pointer to the new table.
- **enter(table,name,type,offset)** creates a new entry for name in symbol table table with the given type and offset.
- **addwidth(table,width)** records the width of ALL the entries in table.
- **enterproc(table,name,newtable)** creates a new entry for procedure name in ST table, and links it to newtable.

- **Translation scheme for nested procedures**

```

P -> M D                                { addwidth(top(tblptr), top(offset));
                                          pop(tblptr); pop(offset) }
M -> ε                                  { t := mktable(nil);
                                          push(t,tblptr); push(0,offset); }
D -> D1 ; D2
D -> proc id ; N D1 ; S                  { t := top(tblptr);
                                          addwidth(t,top(offset));
                                          pop(tblptr); pop(offset);
                                          enterproc(top(tblptr),id.name,t) }
D -> id : T                             { enter(top(tblptr),id.name,T.type,top(offset));
                                          top(offset) := top(offset)+T.width }
N -> ε                                  { t := mktable( top( tblptr ));
                                          push(t,tblptr); push(0,offset) }

```

- **Adding ST lookups to assignments**

- Let's attach our assignment grammar to the procedure declarations grammar.

$S \rightarrow id := E$	{ p := lookup(id.name); if p != nil then emit(p ':= ' E.place) else error }
$E \rightarrow E1 + E2$	{ E.place := newtemp(); emit(E.place ':= ' E1.place '+' E2.place) }
$E \rightarrow E1 * E2$	{ E.place := newtemp(); emit(E.place ':= ' E1.place '*' E2.place) }
$E \rightarrow - E1$	{ E.place := newtemp(); emit(E.place ':= ' 'uminus' E1.place) }
$E \rightarrow (E1)$	{ E.place := E1.place }
$E \rightarrow id$	{ p := lookup(id.name); if p != nil then E.place := p else error }

(Continue next week on Intermediate Code Generation)