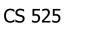
CS 525: Advanced Database Organization



01: Introduction Boris Glavic

Slides: adapted from a <u>course</u> taught by <u>Hector Garcia-Molina</u>, Stanford InfoLab







Advanced Database Organization?

- = Database Implementation
- =How to implement a database system
- ... and have fun doing it ;-)



CS 525



Isn't Implementing a Database System Simple?

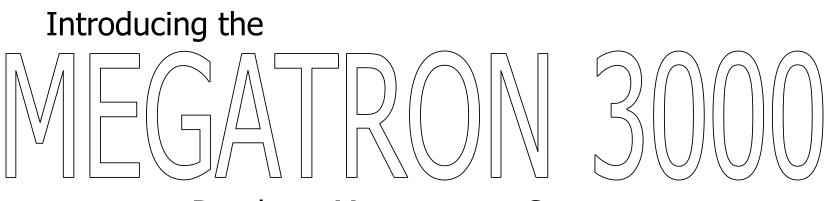




Notes 1 - Introduction



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Database Management System

- The latest from Megatron Labs
- Incorporates latest relational technology
- UNIX compatible





Megatron 3000 Implementation Details





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Megatron 3000 Implementation Details

• Relations stored in files (ASCII) e.g., relation R is in /usr/db/R

Smith Jones	••	••	



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Megatron 3000 Implementation Details

• Directory file (ASCII) in /usr/db/directory

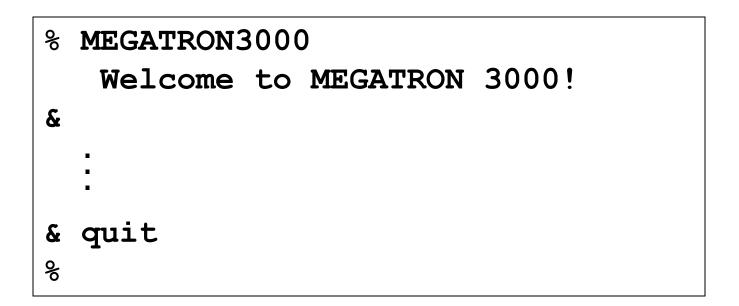
R1 # A # INT # B # STR R2 # C # STR # A # INT



Notes 1 - Introduction



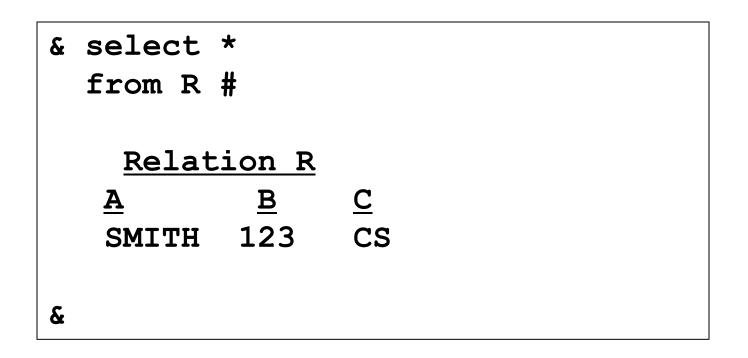
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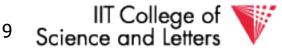
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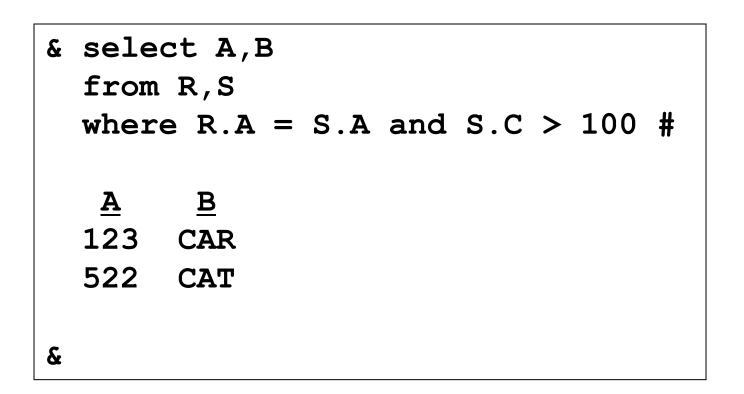




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& select * from R | LPR # &

Result sent to LPR (printer).



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```
& select *
  from R
  where R.A < 100 | T #
&</pre>
```

New relation T created.



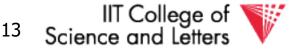
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Megatron 3000



Notes 1 - Introduction



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Megatron 3000

 To execute "select * from R where condition | T":
 (1) Process select as before
 (2) Write results to new file T
 (3) Append new line to dictionary





Megatron 3000

- - (iii) Display if OK



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Notes 1 - Introduction



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- Tuple layout on disk
- e.g., Change string from 'Cat' to 'Cats' and we have to rewrite file
 - ASCII storage is expensive
 - Deletions are expensive





- Search expensive; no indexes
- e.g., Cannot find tuple with given key quickly
 - Always have to read full relation





- Brute force query processing
- e.g., select *

from R,S

where R.A = S.A and S.B > 1000

- Do select first?
- More efficient join?





- No buffer manager
- e.g., Need caching





• No concurrency control





- No reliability
- e.g., Can lose data
 - Can leave operations half done





- No security
- e.g., File system insecure
 - File system security is coarse



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- No application program interface (API)
- e.g., How can a payroll program get at the data?





• Cannot interact with other DBMSs.



Notes 1 - Introduction



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Poor dictionary facilities



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• No GUI





• Lousy salesman!!





Course Overview

• File & System Structure

Records in blocks, dictionary, buffer management,...

Indexing & Hashing

B-Trees, hashing,...

Query Processing

Query costs, join strategies,...

• Crash Recovery

Failures, stable storage,...





Course Overview

Concurrency Control

Correctness, locks,...

Transaction Processing

Logs, deadlocks,...

Security & Integrity

Authorization, encryption,...

Advanced Topics

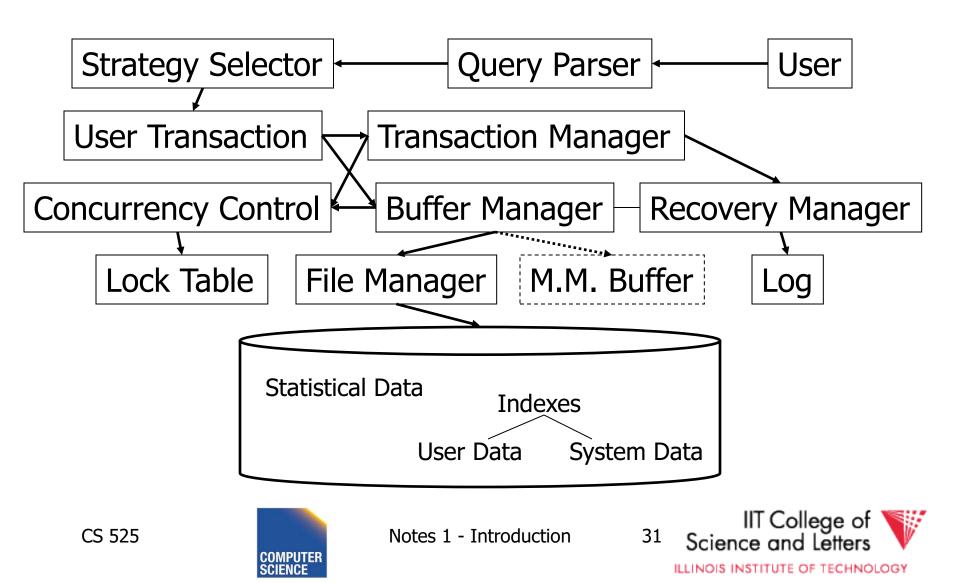
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Distribution, More Fancy Optimizations, ...





System Structure



Some Terms

- Database system
- Transaction processing system
- File access system
- Information retrieval system





Course Information

- Webpage: http://www.cs.iit.edu/~cs525/
- Instructor: Boris Glavic
 - <u>http://www.cs.iit.edu/~glavic/</u>
 - DBGroup: <u>http://www.cs.iit.edu/~dbgroup/</u>
 - Office Hours: Mondays, 12pm-1pm
 - **Office:** Stuart Building, Room 226 C
- TA: TBA

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• **Time:** Mon + Wed 1:50pm – 3:05pm





Google Group

- https://groups.google.com/forum/#!forum/cs525-2017-spring-group
- Mailing-list for announcements
- Discussion forum
 - Student Instructor/TA
 - Student Student
- ->please join the group to keep up to date





Workload and Grading

- Schedule and Important Dates
 - On webpage & updated there
- Programming Assignments (50%)
 - 4 Assignments
 - Groups of 3 students
 - Plagiarism -> 0 points and administrative action
- Quizzes (10%)
- Mid Term (20%) and Final Exam (20%)



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Notes 1 - Introduction



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Textbooks

- Elmasri and Navathe , **Fundamentals of Database Systems**, 6th Edition , Addison-Wesley , 2003
- Garcia-Molina, Ullman, and Widom, Database Systems: The Complete Book, 2nd Edition, Prentice Hall, 2008
- Ramakrishnan and Gehrke , Database Management
 Systems, 3nd Edition , McGraw-Hill , 2002
- Silberschatz, Korth, and Sudarshan, Database System
 Concepts, 6th Edition, McGraw Hill, 2010





Programming Assignments

- 4 assignments one on-top of the other
- Optional 5th assignment for extra credit
- Code has to compile & run on server account
 - Email-ID@fourier.cs.iit.edu
 - Linux machine
 - SSH with X-forwarding
- Source code managed in **git** repository on Bitbucket.org
 - Handing in assignments = submit (push) to repository
 - One repository per student
 - You should have gotten an invitation (if not, contact me/TA)
 - Git tutorials linked on course webpage!





Notes 1 - Introduction



Next:

• Hardware



Notes 1 - Introduction



CS 525: Advanced Database Organization 02: Hardware



CS 525

Boris Glavic

Slides: adapted from a <u>course</u> taught by <u>Hector Garcia-Molina</u>, Stanford InfoLab



Notes 2 - Hardware



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Outline

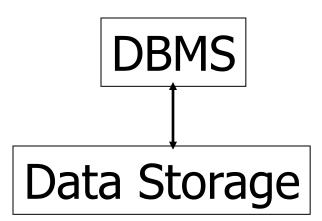
- Hardware: Disks
- Access Times
- Example Megatron 747
- Optimizations
- Other Topics:
 - Storage costs
 - Using secondary storage
 - Disk failures



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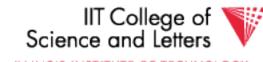




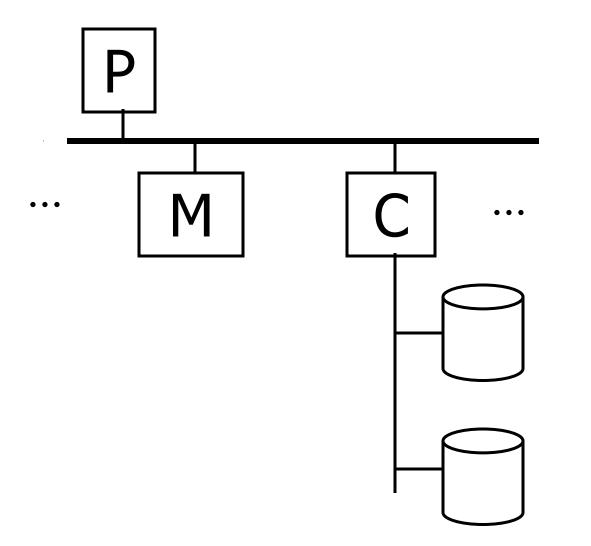
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Notes 2 - Hardware

3



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<u>Typical</u> Computer

Secondary Storage



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Notes 2 - Hardware



Processor Fast, slow, reduced instruction set, with cache, pipelined... Speed: 100 → 500 → 1000 MIPS

<u>Memory</u>

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Fast, slow, non-volatile, read-only,... Access time: $10^{-6} \rightarrow 10^{-9}$ sec. $1 \ \mu s \rightarrow 1 \ ns$



Notes 2 - Hardware



Secondary storage Many flavors: - Disk: Floppy (hard, soft) **Removable Packs** Winchester Ram disks Optical, CD-ROM... Arrays Reel, cartridge - Tape Robots



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Notes 2 - Hardware

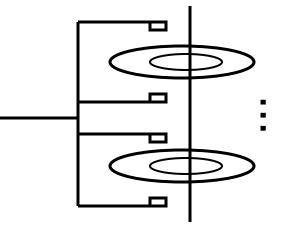
IT College of cience and Letters

6



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Focus on: "Typical Disk"



Terms: Platter, Head, Actuator Cylinder, Track Sector (physical), Block (logical), Gap



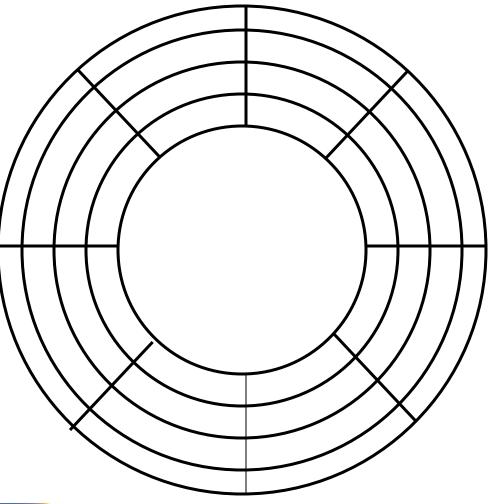
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Notes 2 - Hardware



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Notes 2 - Hardware

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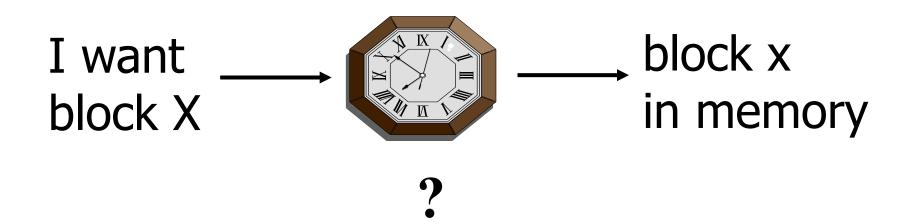
"Typical" Numbers Diameter: 1 inch \rightarrow 15 inches $100 \rightarrow 2000$ Cylinders: 1 (CDs) → Surfaces: 2 (floppies) \rightarrow 30 (Tracks/cyl) $512B \rightarrow 50K$ Sector Size: 360 KB (old floppy) Capacity: \rightarrow 1 TB (I use)



Notes 2 - Hardware



Disk Access Time





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Notes 2 - Hardware

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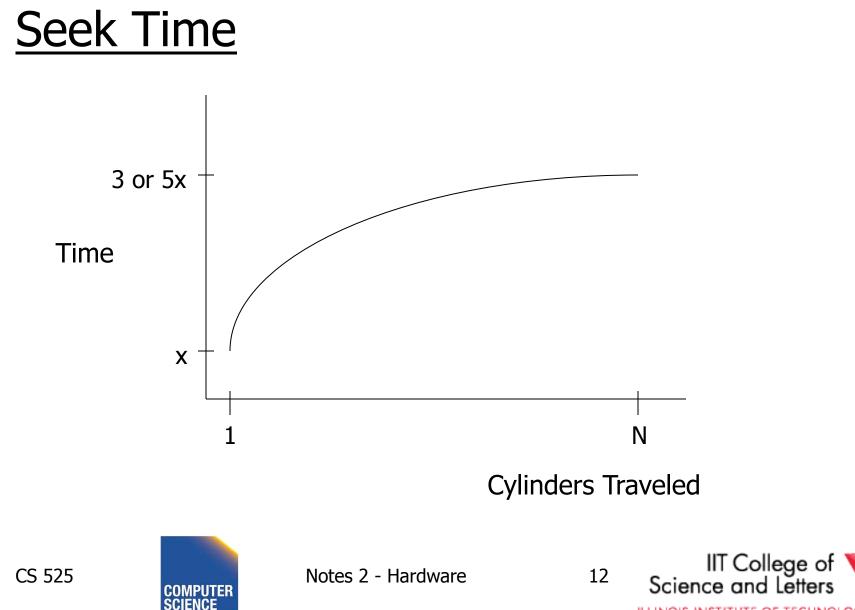
Time = Seek Time + Rotational Delay + Transfer Time + Other



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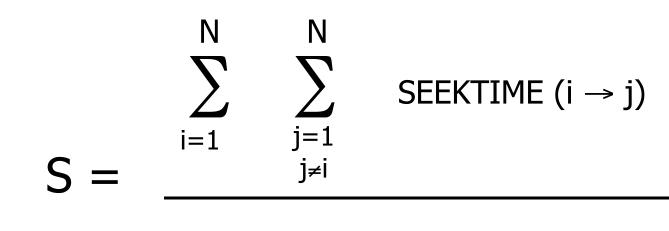
Notes 2 - Hardware





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Average Random Seek Time



N(N-1)



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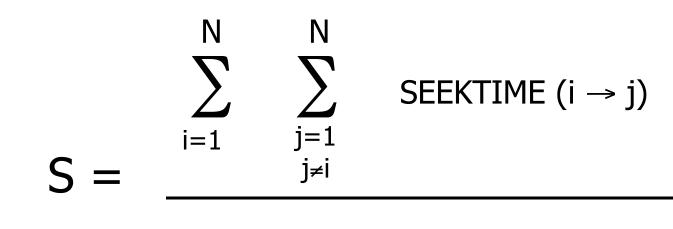
Notes 2 - Hardware

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Average Random Seek Time



N(N-1)

14

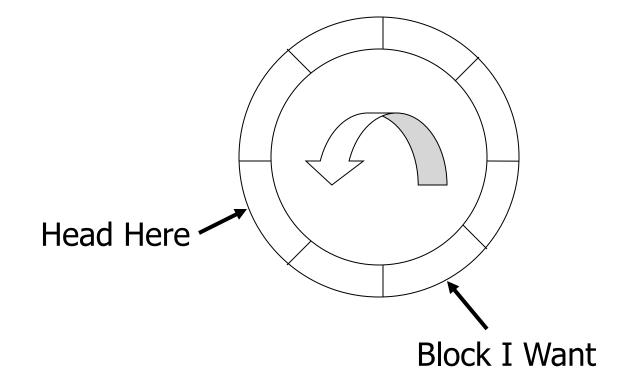
"Typical" S: 10 ms \rightarrow 40 ms



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Rotational Delay





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Average Rotational Delay

R = 1/2 revolution

"typical" R = 8.33 ms (3600 RPM)



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Notes 2 - Hardware



Transfer Rate: t

• "typical" t: 10's \rightarrow 100's MB/second

t

• transfer time: <u>block size</u>



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Notes 2 - Hardware



Other Delays

- CPU time to issue I/O
- Contention for controller
- Contention for bus, memory





Other Delays

- CPU time to issue I/O
- Contention for controller
- Contention for bus, memory

"Typical" Value: 0



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Notes 2 - Hardware



Other Delays (now and near future)

- Increasing amount of parallelism
- Contention can become a problem
- -> need rethink approach to scale



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- So far: Random Block Access
- What about: Reading "Next" block?



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<u>If we do things right</u> (e.g., Double Buffer, Stagger

Blocks...)

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Time to get = $\frac{\text{Block Size}}{\text{t}} + \text{Negligible}$

- skip gap
- switch track
- once in a while, next cylinder







Rule of
ThumbRandom I/O: Expensive
Sequential I/O: Much less

Ex: 1 KB Block
 » Random I/O: ~ 20 ms.
 » Sequential I/O: ~ 1 ms.





Cost for Writing similar to Reading

.... unless we want to verify! need to add (full) rotation + <u>Block size</u>



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Notes 2 - Hardware



• To Modify a Block?



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Notes 2 - Hardware



• To Modify a Block?

To Modify Block: (a) Read Block (b) Modify in Memory (c) Write Block [(d) Verify?]





Block Address:

- Physical Device
- Cylinder #
- Surface #
- Sector

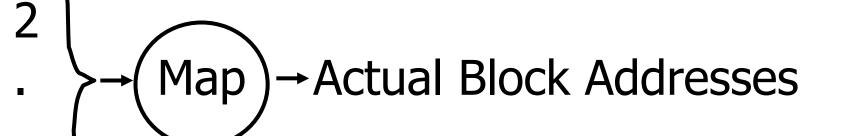






Complication: Bad Blocks

- Messy to handle
- May map via software to integer sequence









An Example Megatron 747 Disk (old)

- 3.5 in diameter
- 3600 RPM
- 1 surface
- 16 MB usable capacity (16 X 2²⁰)
- 128 cylinders
- seek time: average = 25 ms.

adjacent cyl = 5 ms.







- 1 KB blocks = sectors
- 10% overhead between blocks
- capacity = $16 \text{ MB} = (2^{20})16 = 2^{24}$
- # cylinders = $128 = 2^7$
- bytes/cyl = 2²⁴/2⁷ = 2¹⁷ = 128 KB
- blocks/cyl = 128 KB / 1 KB = 128



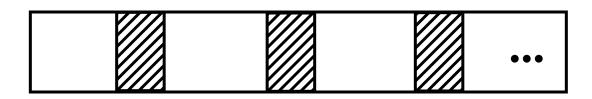
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3600 RPM \rightarrow 60 revolutions / sec \rightarrow 1 rev. = 16.66 msec.

One track:

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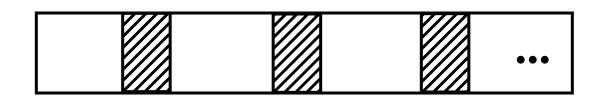
Notes 2 - Hardware



3600 RPM \rightarrow 60 revolutions / sec \rightarrow 1 rev. = 16.66 msec.

One track:

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Time over useful data:(16.66)(0.9)=14.99 ms. Time over gaps: (16.66)(0.1) = 1.66 ms. Transfer time 1 block = 14.99/128=0.117 ms. Trans. time 1 block+gap=16.66/128=0.13ms.



Notes 2 - Hardware



<u>Burst Bandwith</u> 1 KB in 0.117 ms.

BB = 1/0.117 = 8.54 KB/ms.

or

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BB =8.54KB/ms x 1000 ms/1sec x 1MB/1024KB = 8540/1024 = 8.33 MB/sec



Notes 2 - Hardware



Sustained bandwith (over track) 128 KB in 16.66 ms.

SB = 128/16.66 = 7.68 KB/ms

or

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$SB = 7.68 \times 1000/1024 = 7.50 MB/sec.$



Notes 2 - Hardware



T_1 = Time to read one random block

T_1 = seek + rotational delay + TT

= 25 + (16.66/2) + .117 = 33.45 ms.

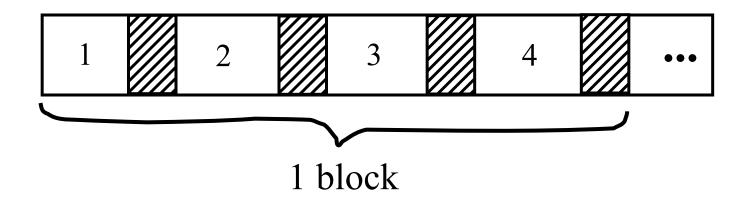


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Notes 2 - Hardware



Suppose OS deals with 4 KB blocks



$T_4 = 25 + (16.66/2) + (.117) \times 1$ $+ (.130) \times 3 = 33.83 \text{ ms}$ $[Compare to <math>T_1 = 33.45 \text{ ms}]$



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Notes 2 - Hardware





$$T_T$$
 = Time to read a full track
(start at any block)
 T_T = 25 + (0.130/2) + 16.66* = 41.73 ms
 \int_{1}^{1}
to get to first block

* Actually, a bit less; do not have to read last gap.



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Notes 2 - Hardware



The <u>NEW</u> Megatron 747

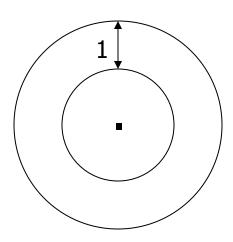
- 8 Surfaces, 3.5 Inch diameter
 - outer 1 inch used
- 2¹³ = 8192 Tracks/surface
- 256 Sectors/track
- 2⁹ = 512 Bytes/sector



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- 8 GB Disk
- If all tracks have 256 sectors
 - Outermost density: 100,000 bits/inch
 - Inner density: 250,000 bits/inch





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Notes 2 - Hardware



- Outer third of tracks: 320 sectors
- Middle third of tracks: 256
- Inner third of tracks: 192
- Density: 114,000 → 182,000 bits/inch



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Notes 2 - Hardware



Timing for <u>new</u> Megatron 747 (Ex 2.3)

- Time to read 4096-byte block:
 - MIN: 0.5 ms
 - MAX: 33.5 ms
 - AVE: 14.8 ms



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<u>Outline</u>

CS 525

- Hardware: Disks
- Access Times
- Example: Megatron 747
- Optimizations
- Other Topics
 - Storage Costs
 - Using Secondary Storage
 - Disk Failures







Optimizations (in controller or O.S.)

- Disk Scheduling Algorithms – e.g., elevator algorithm
- Track (or larger) Buffer
- Pre-fetch
- Arrays
- Mirrored Disks
- On Disk Cache







Problem: Have a File

» Sequence of Blocks B1, B2

Have a Program

- » Process B1
- » Process B2
- » Process B3





Notes 2 - Hardware



Single Buffer Solution

(1) Read B1 → Buffer
 (2) Process Data in Buffer
 (3) Read B2 → Buffer
 (4) Process Data in Buffer ...



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Say P = time to process/block

- R = time to read in 1 block
- n = # blocks

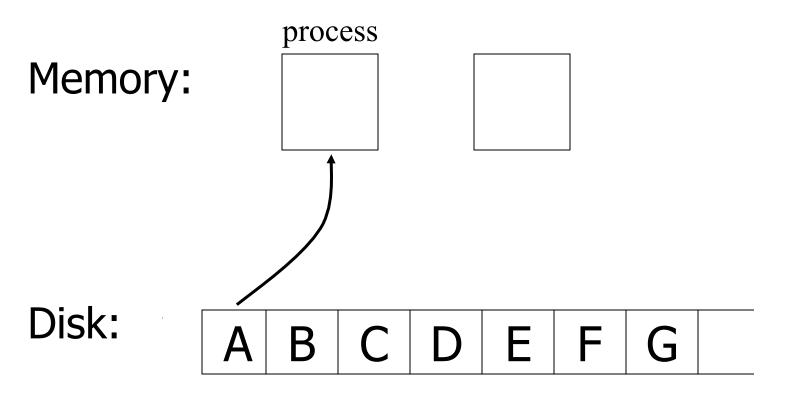
Single buffer time = n(P+R)



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Notes 2 - Hardware



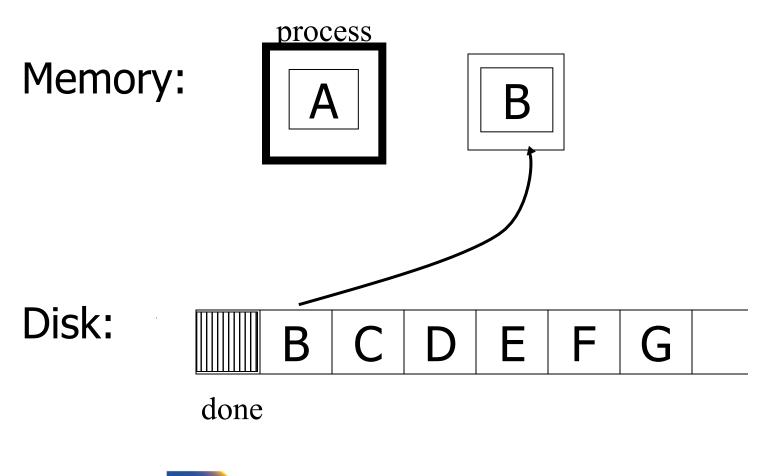




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Notes 2 - Hardware



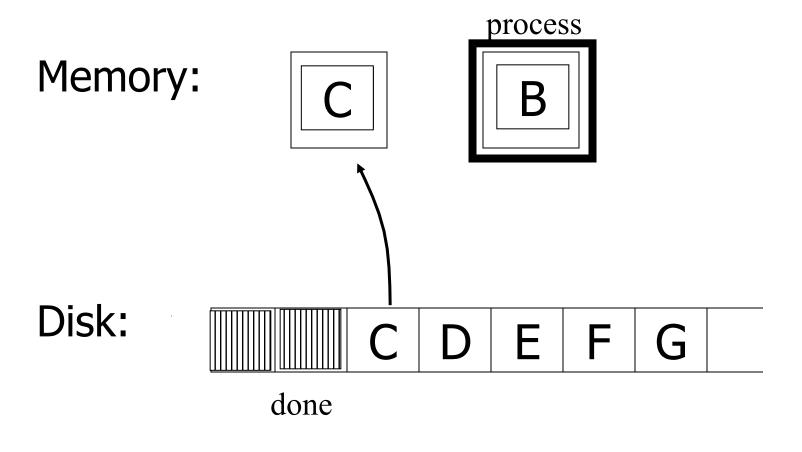






Notes 2 - Hardware



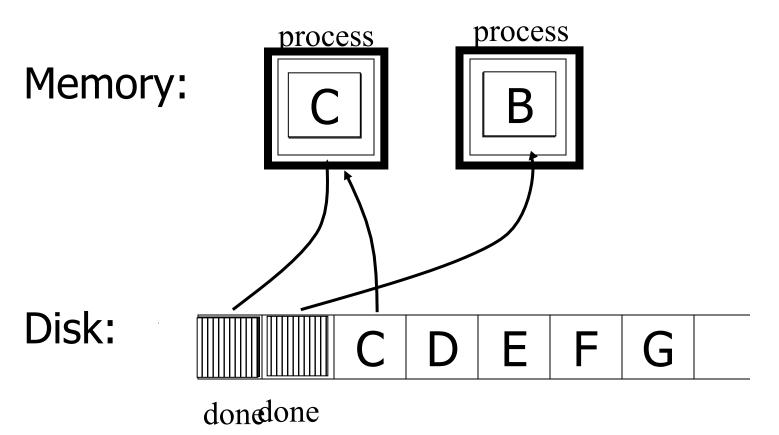




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Notes 2 - Hardware







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Notes 2 - Hardware



Say $P \ge R$

P = Processing time/block R = IO time/block n = # blocks

What is processing time?



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Notes 2 - Hardware



Say $P \ge R$

P = Processing time/block R = IO time/block n = # blocks

What is processing time?

- Double buffering time = R + nP
- Single buffering time = n(R+P)



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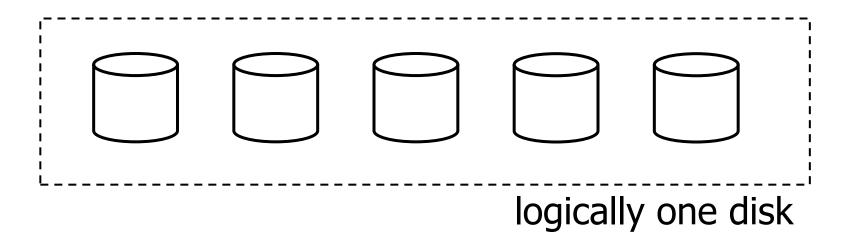
Notes 2 - Hardware



Disk Arrays

- RAIDs (various flavors)
- Block Striping
- Mirrored

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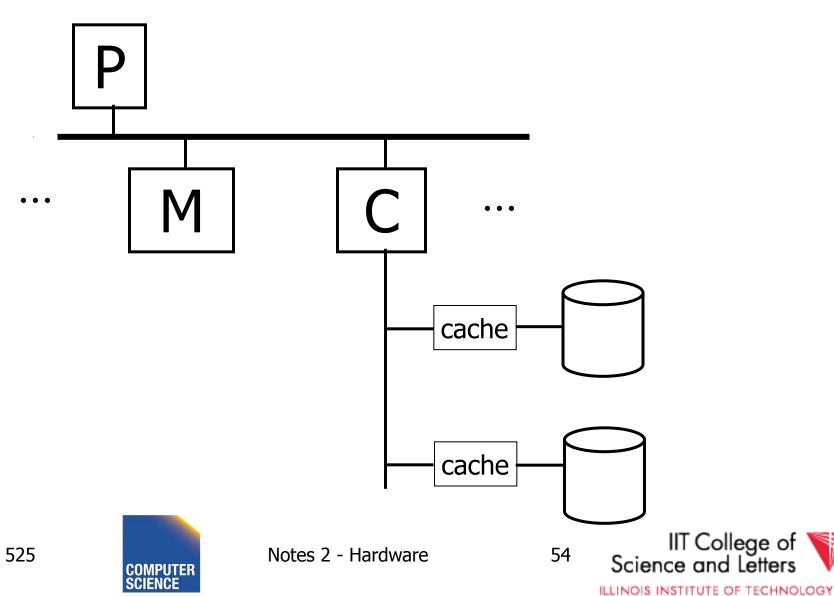




Notes 2 - Hardware



On Disk Cache



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Block Size Selection?

 Big Block → Amortize I/O Cost, Less Management Overhead

Unfortunately...

Big Block ⇒ Read in more useless stuff!
 and takes longer to read



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Notes 2 - Hardware





Trend

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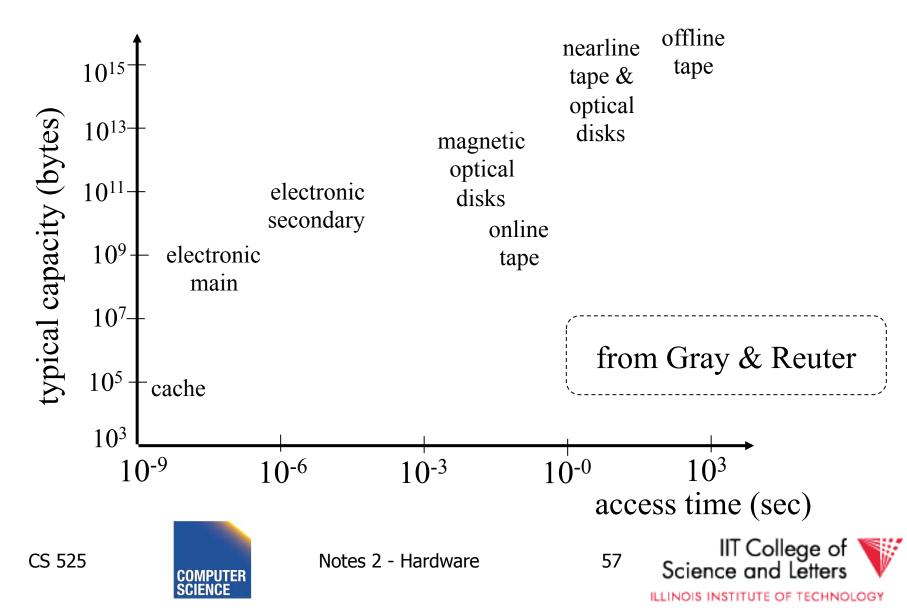
• As memory prices drop, blocks get bigger ...



Notes 2 - Hardware

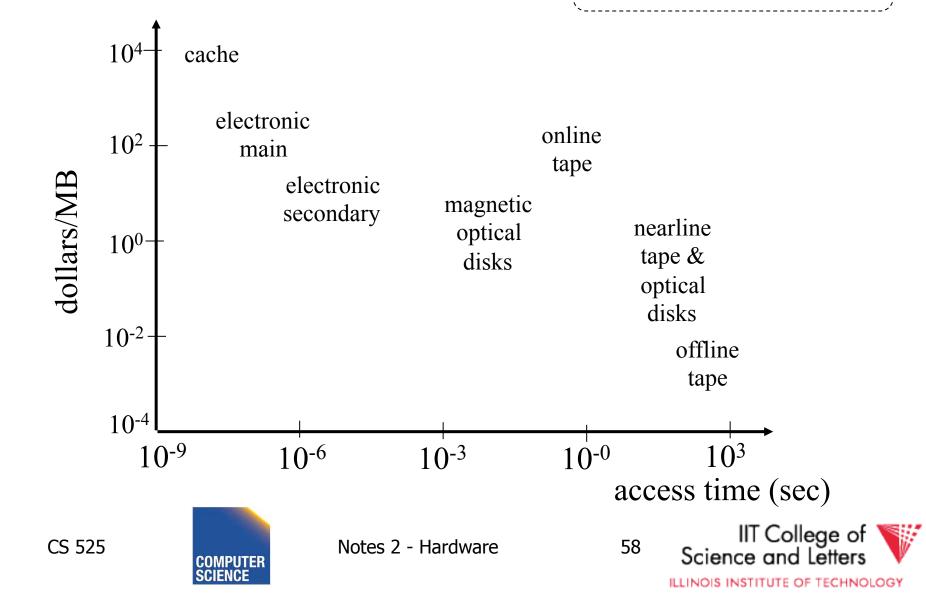


Storage Cost



Storage Cost

from Gray & Reuter



Using secondary storage effectively

- Example: Sorting data on disk
- Conclusion:
 - I/O costs dominate
 - Design algorithms to reduce I/O
- Also: How big should blocks be?



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Notes 2 - Hardware





 THE 5 MINUTE RULE FOR TRADING MEMORY FOR DISC ACCESSES
 Jim Gray & Franco Putzolu
 May 1985

 The Five Minute Rule, Ten Years Later Goetz Graefe & Jim Gray December 1997



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Notes 2 - Hardware



- Say a page is accessed every X seconds
- CD = cost if we keep that page on disk
 - \$D = cost of disk unit
 - I = numbers IOs that unit can perform per second
 - In X seconds, unit can do XI IOs
 - -So CD = \$D / XI



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- Say a page is accessed every X seconds
- CM = cost if we keep that page on RAM
 - \$M = cost of 1 MB of RAM
 - -P = numbers of pages in 1 MB RAM
 - -So CM = \$M / P



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- Say a page is accessed every X seconds
- If CD is smaller than CM,
 - keep page on disk
 - else keep in memory
- Break even point when CD = CM, or $X = \frac{\$D P}{T + M}$

$$=$$
 $\frac{1}{I \$ M}$





Using '97 Numbers

- P = 128 pages/MB (8KB pages)
- I = 64 accesses/sec/disk
- \$D = 2000 dollars/disk (9GB + controller)
- \$M = 15 dollars/MB of DRAM
- X = 266 seconds (about 5 minutes) (did not change much from 85 to 97)



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Notes 2 - Hardware



Disk Failures

- Partial \rightarrow Total
- Intermittent \rightarrow Permanent



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Notes 2 - Hardware



Coping with Disk Failures

- Detection
 - -e.g. Checksum



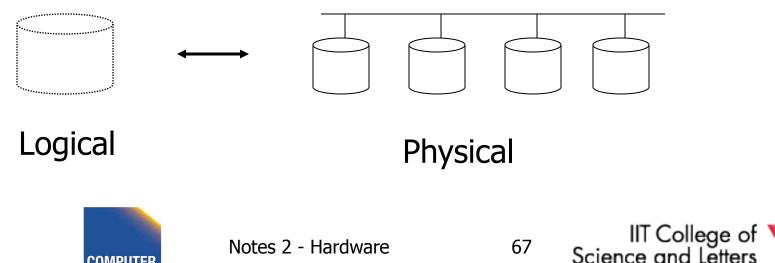
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Notes 2 - Hardware



At what level do we cope?

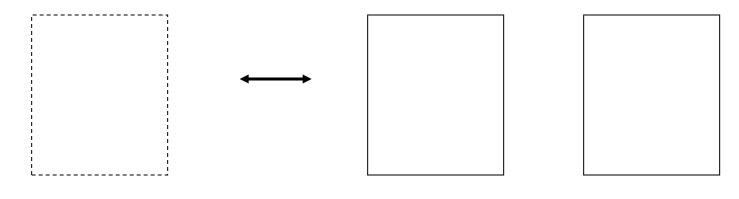
- Single Disk
 - e.g., Error Correcting Codes
- Disk Array







Operating System e.g., Stable Storage



Logical Block Copy A Copy B



Notes 2 - Hardware

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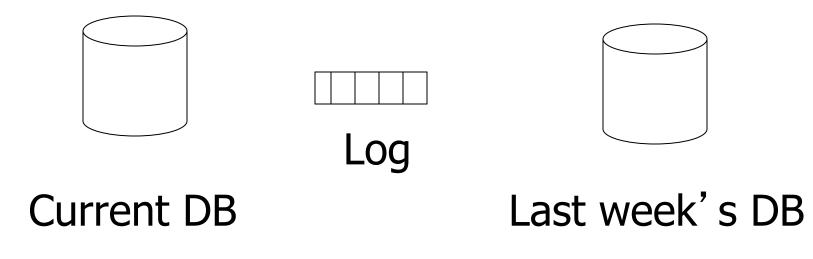


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→ Database System



CS 525





Notes 2 - Hardware



Summary

- Secondary storage, mainly disks
- I/O times + formulas
 - Sequential vs. random
- I/Os should be avoided,

especially random ones.....

- OS optimizations
- Disk errors

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Notes 2 - Hardware

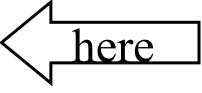


<u>Outline</u>

- Hardware: Disks
- Access Times
- Example: Megatron 747
- Optimizations
- Other Topics
 - Storage Costs
 - Using Secondary Storage
 - Disk Failures



Notes 2 - Hardware



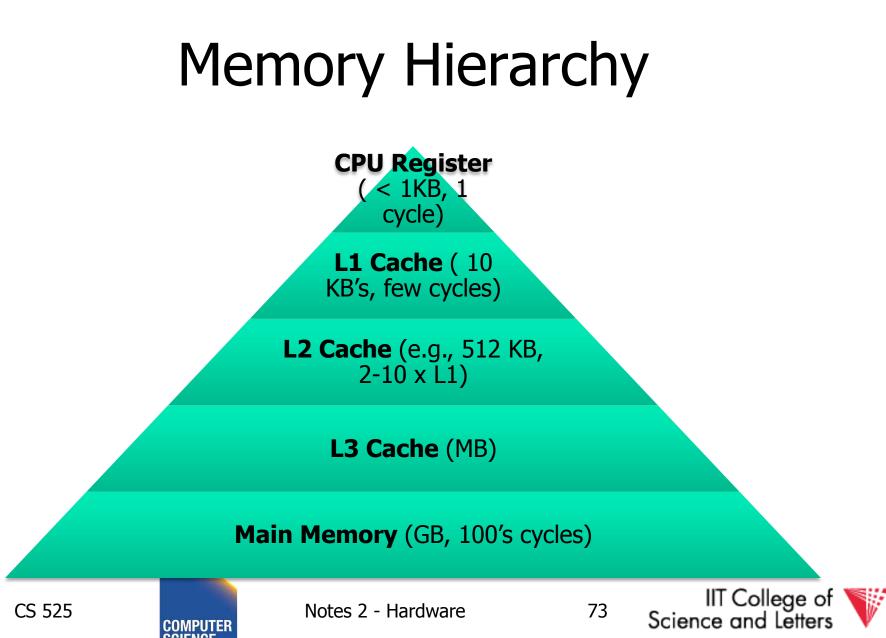


Outlook - Hardware

- Disk Access is the main limiting factor
- However, to implement fast DBMS
 - need to understand other parts of the hardware
 - Memory hierarchy
 - CPU architecture: pipelining, vector instructions, OOE, ...
 - SSD storage
 - need to understand how OS manages hardware
 - File access, VM, Buffering, ...







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Memory Hierarchy

- Compare: Disk vs. Main Memory
- Reduce accesses to main memory
- Cache conscious algorithms





Increasing Amount of Parallelism

- Contention on, e.g., Memory
- NUMA

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- Algorithmic Challenges
 - How to parallelize algorithms?
 - Sometime: Completely different approach required
 - –-> Rewrite large parts of DBMS



Notes 2 - Hardware





New Trend: Software/Hardware Co-design

- Actually, revived trend: database machines (80's)
- New goals: power consumption
- Design specific hardware and write special software for it
- E.g., Oracle Exadata, Oracle Labs



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Notes 2 - Hardware



CS 525: Advanced Database Organization 03: Disk Organization



Slides: adapted from a <u>course</u> taught by <u>Hector Garcia-Molina</u>, Stanford InfoLab



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Notes 3



Topics for today

- How to lay out data on disk
- How to move it to/from memory







What are the data items we want to store?

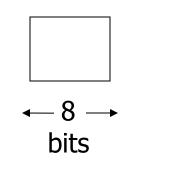
- a salary
- a name
- a date
- a picture





What are the data items we want to store?

- a salary
- a name
- a date
- a picture
- What we have available: <u>Bytes</u>







• Integer (short): 2 bytes e.g., 35 is





Endian! Could as well be

|--|



Real, floating point
 n bits for mantissa, *m* for exponent....





- Characters
 - → various coding schemes suggested, most popular is ASCII (1 byte encoding)
 - Example:
 - A: 1000001
 - a: 1100001
 - 5: 0110101
 - LF: 0001010



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• Boolean



• Application specific e.g., enumeration RED \rightarrow 1 GREEN \rightarrow 3 BLUE \rightarrow 2 YELLOW \rightarrow 4 ...





• Boolean

e.g., TRUE 1111 1111 FALSE 0000 0000

• Application specific e.g., RED \rightarrow 1 GREEN \rightarrow 3 BLUE \rightarrow 2 YELLOW \rightarrow 4 ...

➡ Can we use less than 1 byte/code?

Yes, but only if desperate...





Notes 3



- Dates
 - e.g.: Integer, # days since Jan 1, 1900
 - 8 characters, YYYYMMDD
 - 7 characters, YYYYDDD (not YYMMDD! Why?)
- Time
 - e.g. Integer, seconds since midnight
 - characters, HHMMSSFF





- String of characters
 - Null terminated

– Length given

- Fixed length





• Bag of bits









Key Point

- Fixed length items
- Variable length items - usually length given at beginning





Also

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Type of an item: Tells us how to interpret (plus size if fixed)







Data Items **Records Blocks** Files Memory



Notes 3



<u>Record</u> - Collection of related data items (called <u>FIELDS</u>)

E.g.: Employee record: name field, salary field, date-of-hire field, ...





Types of records:

- Main choices:
 - FIXED vs VARIABLE FORMAT
 - FIXED vs VARIABLE LENGTH





Fixed format

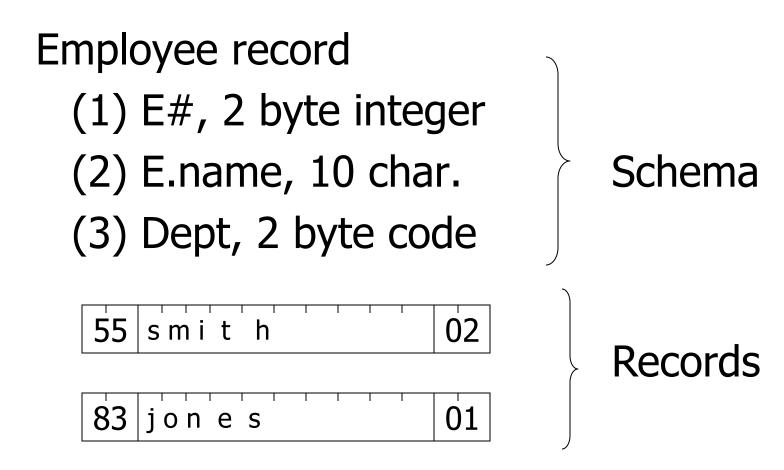
A <u>SCHEMA</u> (not record) contains following information

- # fields
- type of each field
- order in record
- meaning of each field





Example: fixed format and length





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Variable format

 Record itself contains format "Self Describing"





Example: variable format and length

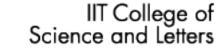
2	5	Ι	46	4	S	4	F	0	R	D
s ting	ת ן	Ť		¶e	Ť	Î				
# Fields identifvi	С Ш Ш С Щ С Щ	уре		Ena	be	f str.				
# H H H	field as E#	nteger typ		for	g type	ength of				
ude Code	fie	Inteç		Code for Enai	Strinç	-eng				

Field name codes could also be strings, i.e. TAGS



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Variable format useful for:

- "sparse" records
- repeating fields
- evolving formats

But may waste space... Additional indirection...







EXAMPLE: var format record with repeating fields Employee → one or more → children

3 E_name: Fred	Child: Sally	Child: Tom
----------------	--------------	------------



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Note: Repeating fields does not imply

- variable format, nor
- variable size

John	Sailing	Chess	
------	---------	-------	--





Note: Repeating fields does not imply

- variable format, nor
- variable size



 Key is to allocate maximum number of repeating fields (if not used → null)

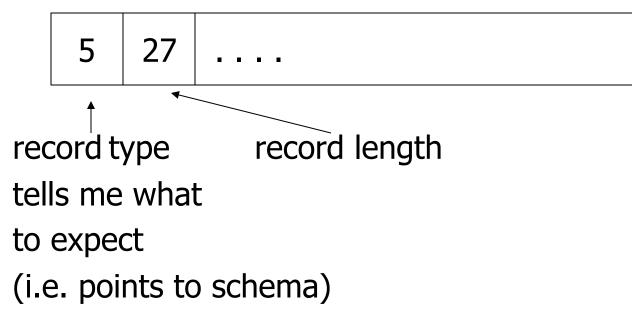


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Many variants between fixed - variable format:

Example: Include record type in record







<u>Record header</u> - data at beginning that describes record

May contain:

- record type
- record length
- time stamp
- null-value bitmap
- other stuff ...





Other interesting issues:

- Compression
 - within record e.g. code selection
 - collection of records e.g. find common patterns
- Encryption
- Splitting of large records

- E.g., image field, store pointer





Notes 3



Record Header – null-map

- SQL: NULL is special value for every data type
 - Reserve one value for each data type as NULL?
- Easier solution
 - Record header has a bitmap to store whether field is NULL
 - Only store non-NULL fields in record



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Separate Storage of Large Values

- Store fields with large values separately
 - E.g., image or binary document
 - Records have pointers to large field content
- Rationale

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- Large fields mostly not used in search conditions
- Benefit from smaller records



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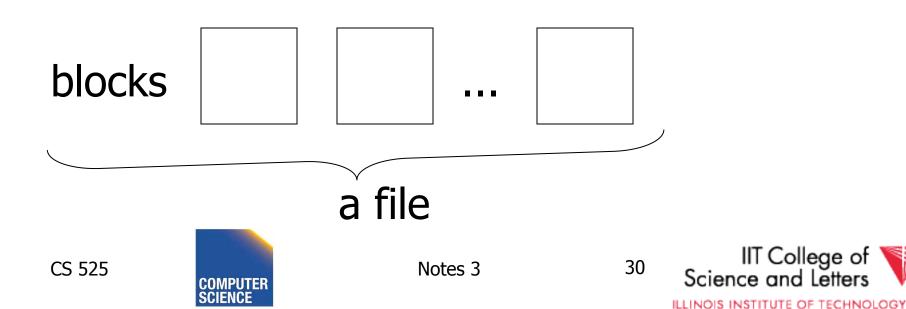
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Next: placing records into blocks

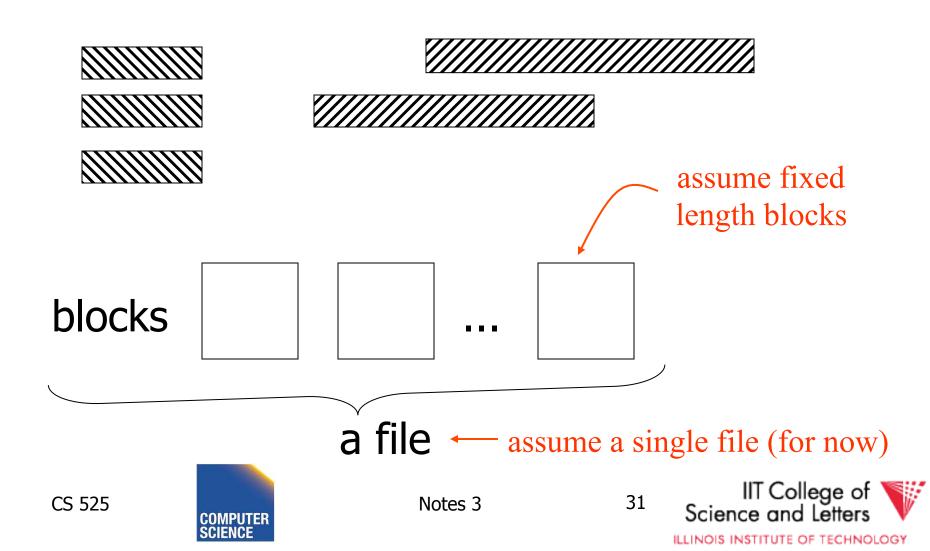








Next: placing records into blocks



Options for storing records in blocks:

- (1) separating records
- (2) spanned vs. unspanned
- (3) sequencing
- (4) indirection





(1) Separating records



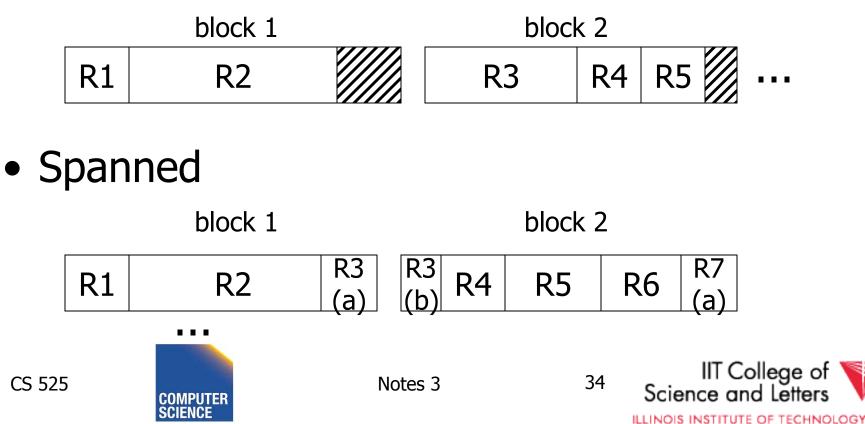
- (a) no need to separate fixed size recs.(b) special marker
- (c) give record lengths (or offsets)
 - within each record
 - in block header



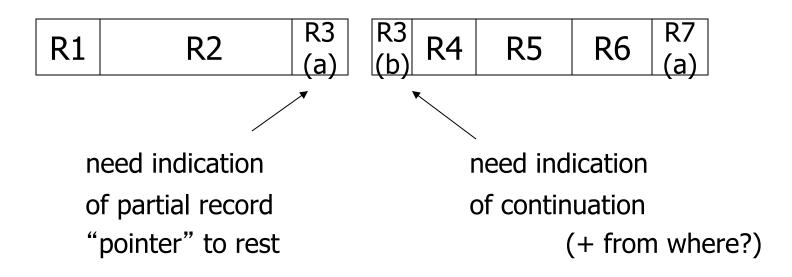


(2) Spanned vs. Unspanned

 Unspanned: records must be within one block



With spanned records:





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Spanned vs. unspanned:

- Unspanned is <u>much</u> simpler, but may waste space...
- Spanned essential if

record size > block size





(3) Sequencing

 Ordering records in file (and block) by some key value

<u>Sequential file</u> (\Rightarrow sequenced)





Why sequencing?

Typically to make it possible to efficiently read records in order

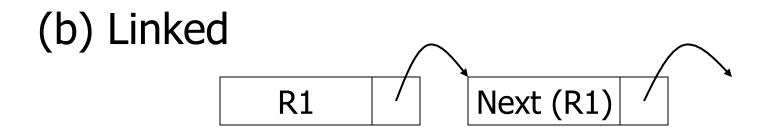
(e.g., to do a merge-join — discussed later)





Sequencing Options

(a) Next record physically contiguous









Sequencing Options

(c) Overflow area

Records in sequence

R1
R2
R3
R4
R5



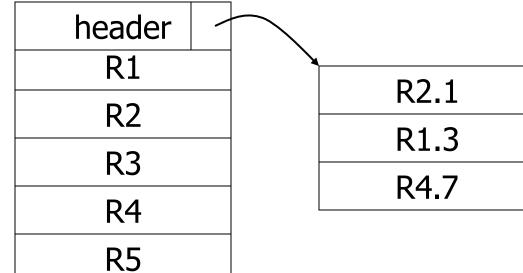




Sequencing Options

(c) Overflow area

Records Record









(4) Indirection

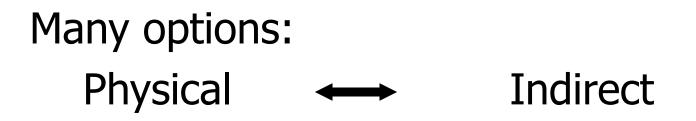
• How does one refer to records?





(4) Indirection

• How does one refer to records?





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☆ Purely Physical

E.g., Record CyAddress = $\langle Tr d$ or ID Bld

Device ID Cylinder # Track # Block # Offset in block

Block ID



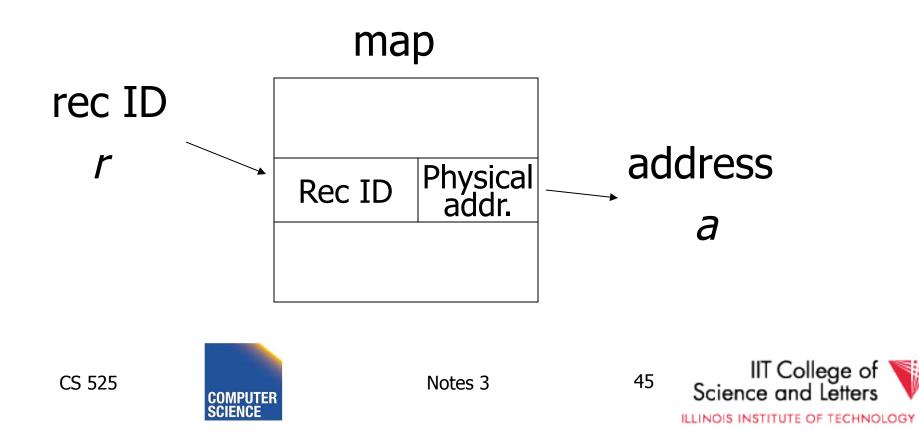
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☆ Fully IndirectE.g., Record ID is arbitrary bit string





Flexibility ---- Cost to move records of indirection

(for deletions, insertions)







Physical \longrightarrow Indirect Many options in between ...







Block header - data at beginning that describes block

May contain:

- File ID (or RELATION or DB ID)
- This block ID
- Record directory
- Pointer to free space
- Type of block (e.g. contains recs type 4;

is overflow, ...)

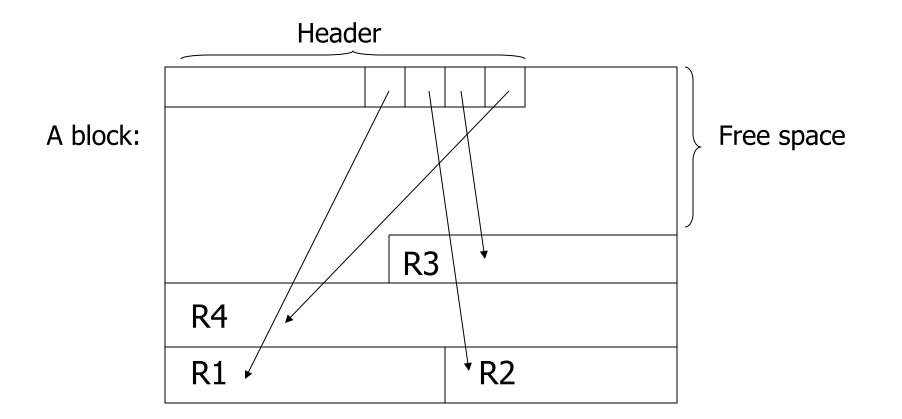
- Pointer to other blocks "like it"
- Timestamp ...







Example: Indirection in block









Tuple Identifier (TID)

• TID is

- Page identifier
- Slot number
- Slot stores either record or pointer (TID)
- TID of a record is fixed for all time





TID Operations

- Insertion
 - Set TID to record location (page, slot)
- Moving record
 - -e.g., update variable-size or reorganization
 - Case 1: TID points to record
 - Replace record with pointer (new TID)
 - Case 2: TID points to pointer (TID)
 - Replace pointer with new pointer



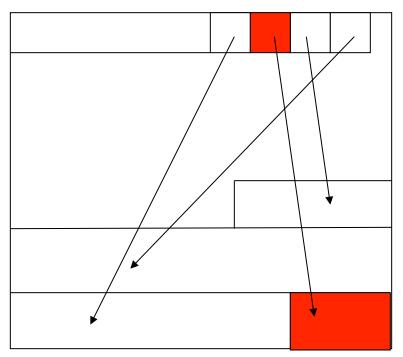
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Notes 3

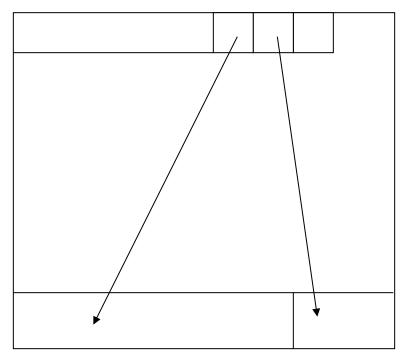
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TID: Block 1, Slot 2

Block 1



Block 2





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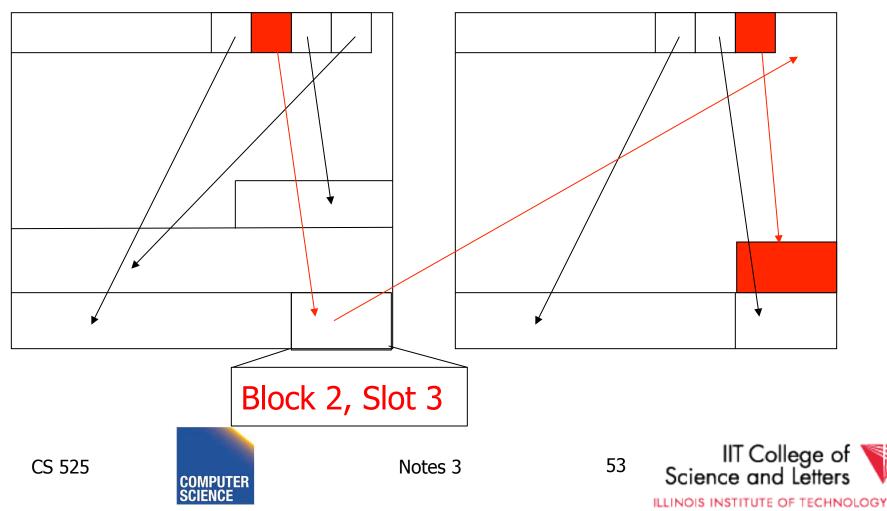


Move record to Block 2 slot 3 -> TID does not change!

TID: Block 1, Slot 2

Block 1

Block 2

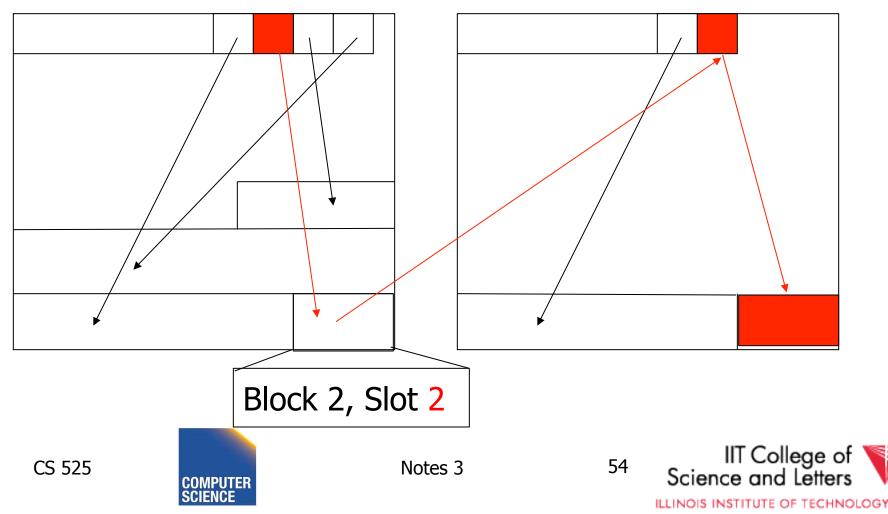


Move record again to Block 2 slot 2 -> still one level of indirection

TID: Block 1, Slot 2

Block 1

Block 2



TID Properties

- TID of record never changes
 - Can be used safely as pointer to record (e.g., in index)
- At most one level of indirection
 - Relatively efficient
 - Changes to physical address changing max 2 pages





Options for storing records in blocks:

- (1) separating records
- (2) spanned vs. unspanned
- (3) sequencing
- (4) indirection





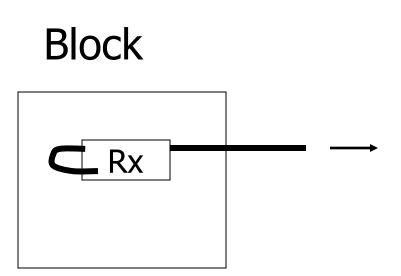
Other Topics

(1) Insertion/Deletion (2) Buffer Management (3) Comparison of Schemes















Options:

(a) Immediately reclaim space

(b) Mark deleted





Options:

(a) Immediately reclaim space

- (b) Mark deleted
 - May need chain of deleted records (for re-use)
 - Need a way to mark:
 - special characters
 - delete field
 - in map





\Rightarrow As usual, many tradeoffs...

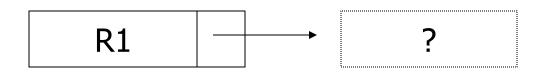
- How expensive is it to move valid record to free space for immediate reclaim?
- How much space is wasted?
 - e.g., deleted records, delete fields, free space chains,...





Concern with deletions

Dangling pointers









Solution #1: Do not worry







Solution #2: Tombstones

E.g., Leave "MARK" in map or old location

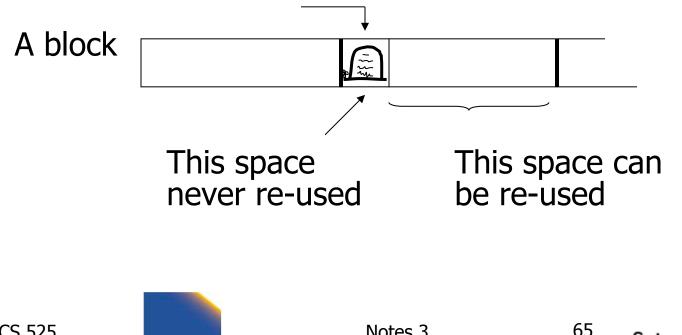




Solution #2: Tombstones

E.g., Leave "MARK" in map or old location

Physical IDs





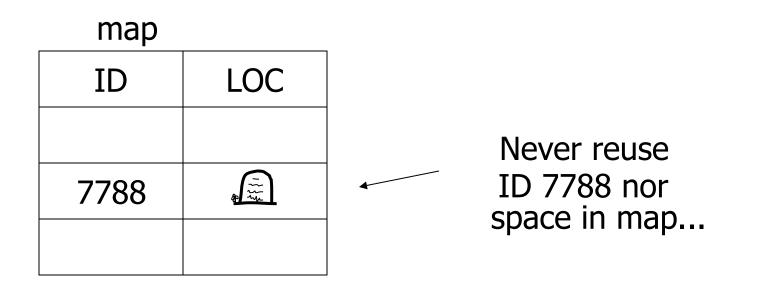




Solution #2: Tombstones

E.g., Leave "MARK" in map or old location

• Logical IDs





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Insert

Easy case: records not in sequence

- → Insert new record at end of file or in deleted slot
- → If records are variable size, not as easy...





Insert

Hard case: records in sequence → If free space "close by", not too bad… → Or use overflow idea…



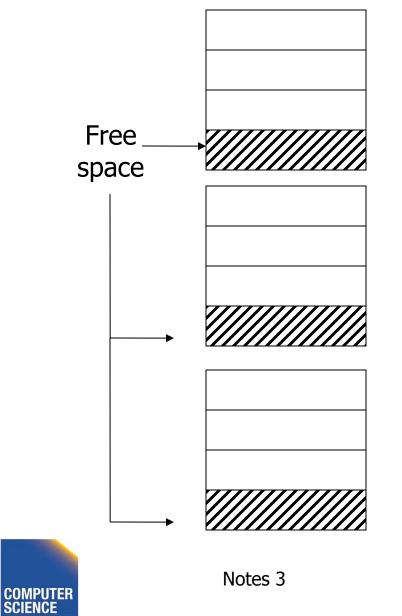


Interesting problems:

- How much free space to leave in each block, track, cylinder?
- How often do I reorganize file + overflow?











Buffer Management

- For Caching of Disk Blocks
- Buffer Replacement Strategies
 - E.g., LRU, clock
- Pinned blocks
- Forced output
- Double buffering
- Swizzling

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Notes 3

→ in Notes02



Buffer Manager

- Manages blocks cached from disk in main memory
- Usually -> fixed size buffer (M pages)
- DB requests page from Buffer Manager
 Case 1: page is in memory -> return address
 - Case 2: page is on disk -> load into memory, return address





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Goals

- Reduce the amount of I/O
- Maximize the *hit rate*
 - Ratio of number of page accesses that are fulfilled without reading from disk
- -> Need strategy to decide when to





Buffer Manager Organization

- Bookkeeping
 - Need to map (hash table) page-ids to locations in buffer (page frames)
 - Per page store fix count, dirty bit, ...
 - Manage free space
- Replacement strategy
 - If page is requested but buffer is full
 - Which page to emit remove from buffer

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FIFO

- First In, First Out
- Replace page that has been in the buffer for the longest time
- Implementation: E.g., pointer to oldest page (circular buffer)

– Pointer->next = Pointer++ % M

• Simple, but not prioritizing frequently accessed pages



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LRU

- Least Recently Used
- Replace page that has not been accessed for the longest time
- Implementation:
 - List, ordered by LRU
 - Access a page, move it to list tail
- Widely applied and reasonable performance



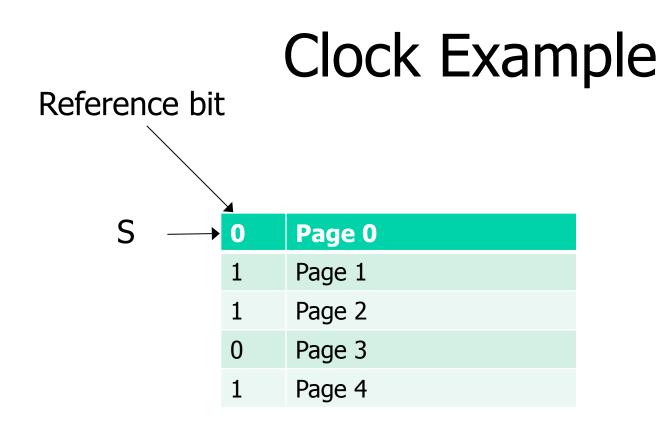


Clock

- Frames are organized clock-wise
- Pointer S to current frame
- Each frame has a reference bit
 Page is loaded or accessed -> bit = 1
- Find page to replace (advance pointer)
 - Return first frame with bit = 0
 - On the way set all bits to 0









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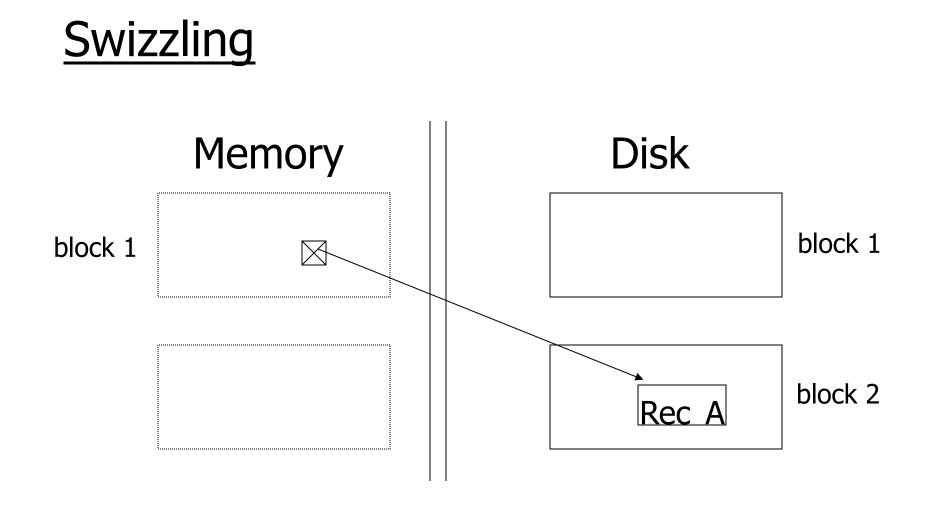


Other Replacement Strategies

- LRU-K
- GCLOCK
- Clock-Pro
- ARC
- LFU





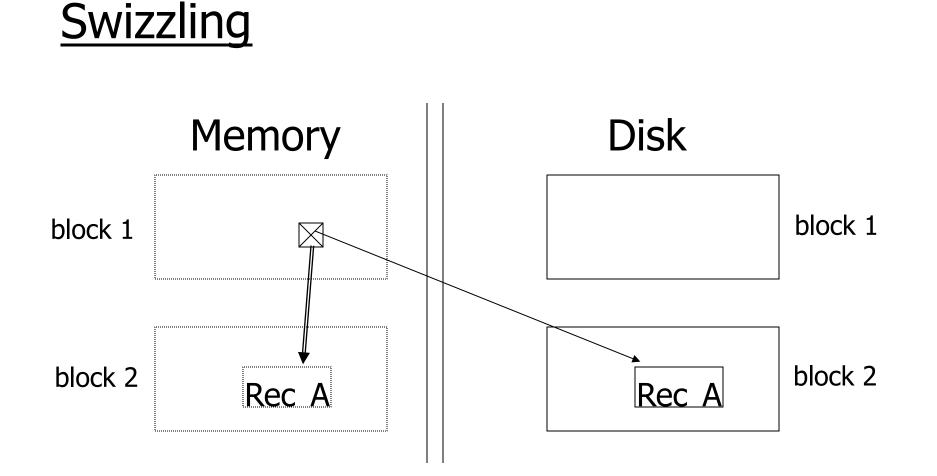


Notes 3



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Notes 3



Row vs Column Store

- So far we assumed that fields of a record are stored contiguously (row store)...
- Another option is to store all values of a field together (column store)





Row Store

- Example: Order consists of
 - id, cust, prod, store, price, date, qty

id1	cust1	prod1	store1	price1	date1	qty1
id2	cust2	prod2	store2	price2	date2	qty2
id3	cust3	prod3	store3	price3	date3	qty3







Column Store

- Example: Order consists of
 - id, cust, prod, store, price, date, qty

id1	cust1
id2	cust2
id3	cust3
id4	cust4
	•••

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id1	prod1	
id2	prod2	
id3	prod3	
id4	prod4	

id1	price1	qty1
id2	price2	qty2
id3	price3	qty3
id4	price4	qty4
		•••

_____ids may or may not be stored explicitly



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Row vs Column Store

- Advantages of Column Store
 - more compact storage (fields need not start at byte boundaries)
 - Efficient compression, e.g., RLE
 - efficient reads on data mining operations
- Advantages of Row Store
 - writes (multiple fields of one record)more efficient
 - efficient reads for record access (OLTP)



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Comparison

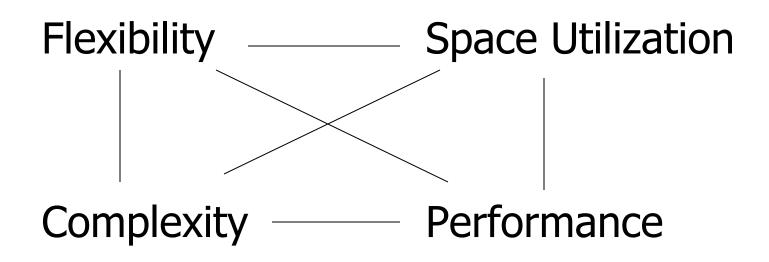
• There are 10,000,000 ways to organize my data on disk...

Which is right for me?





Issues:





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To evaluate a given strategy, compute following parameters:

- -> space used for expected data
- -> expected time to
 - fetch record given key
 - fetch record with next key
 - insert record
 - append record
 - delete record
 - update record
 - read complete file
 - reorganize file





<u>Example</u>

How would you design Megatron 3000 storage system? (for a relational DB, low end)

- Variable length records?
- Spanned?
- What data types?
- Fixed format?
- Record IDs ?
- Sequencing?
- How to handle deletions?





Summary

• How to lay out data on disk

Data Items **Records Blocks Files** Memory **DBMS**



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How to find a record quickly, given a key



Notes 3

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CS 525: Advanced Database Organization 04: Indexing

Boris Glavic

Slides: adapted from a <u>course</u> taught by <u>Hector Garcia-Molina</u>, Stanford InfoLab



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Notes 4 - Indexing



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Part 04 Indexing & Hashing record value value ?



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Query Types:

• Point queries:

- Input: value **v** of attribute **A**
- Output: all objects (tuples) with that value in attribute A

• Range queries:

- Input: value interval [low,high] of attr A
- Output: all tuples with a value

low <= v < high in attribute A



Notes 4 - Indexing



Index Considerations:

- Supported Query Types
- Secondary-storage capable
- Storage size
 - Index Size / Data Size
- Complexity of Operations

 E.g., insert is O(log(n)) worst-case
- Efficient Concurrent Operations?



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<u>Topics</u>

- Conventional indexes
- B-trees

- Hashing schemes
- Advanced Index Techniques

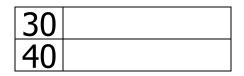




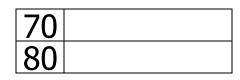


Sequential File









90	
100	

6



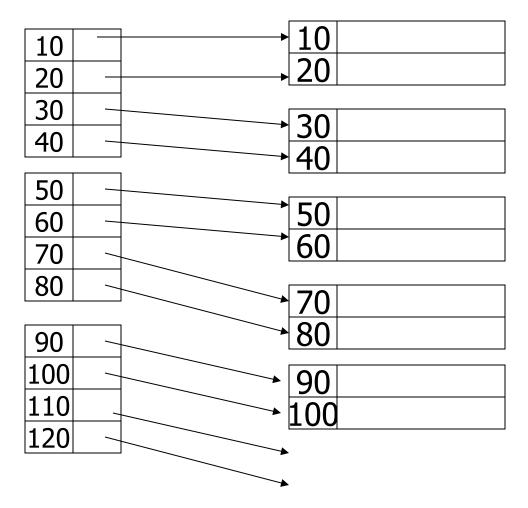
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Dense Index

Sequential File



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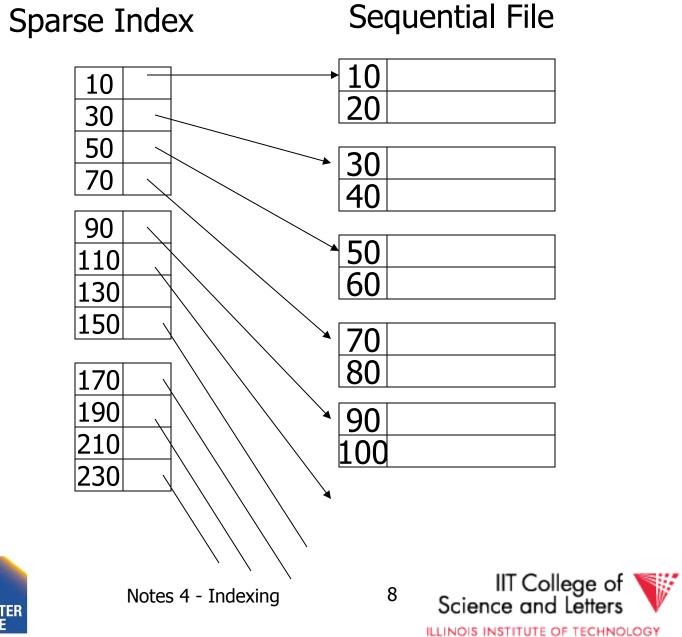


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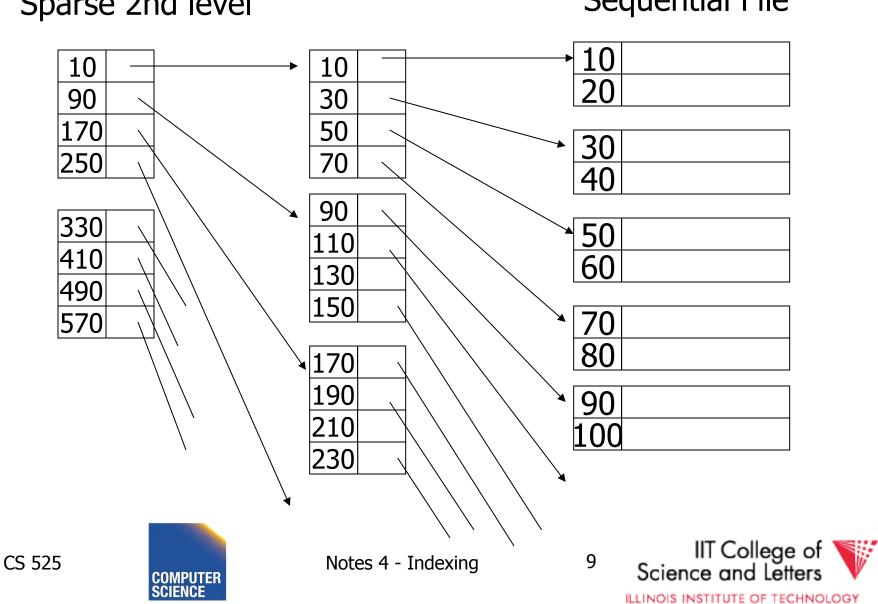
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Sparse 2nd level

Sequential File

Comment: {FILE,INDEX} may be contiguous or not (blocks chained)



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• Can we build a dense, 2nd level index for a dense index?



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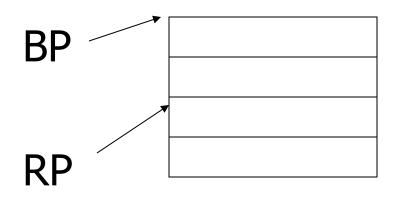
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Notes on pointers:

(1) Block pointer (sparse index) can be smaller than record pointer





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Notes on pointers:

(2) If file is contiguous, then we can omit pointers (i.e., compute them)



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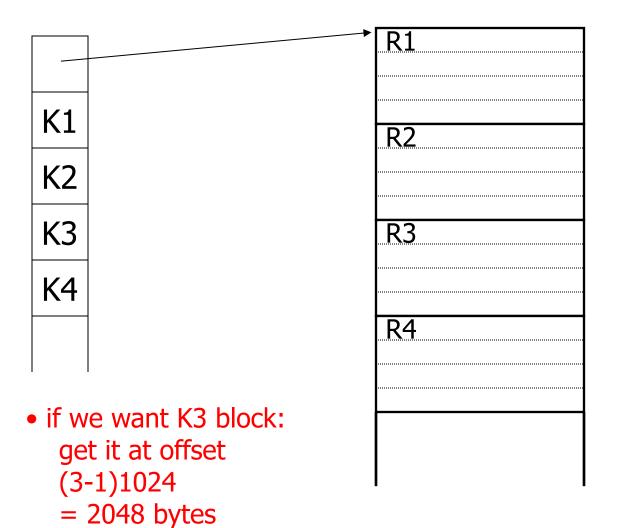
	→ R1
K1	R2
K2	
K3	R3
K4	
	R4
I I	



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say: 1024 B per block

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Sparse vs. Dense Tradeoff

• <u>Sparse:</u> Less index space per record can keep more of index

in memory

• <u>Dense</u>: Can tell if any record exists without accessing file

(Later:

- sparse better for insertions
- dense needed for secondary indexes)

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Notes 4 - Indexing



<u>Terms</u>

- Index sequential file
- Search key (≠ primary key)
- Primary index (on Sequencing field)
- Secondary index
- Dense index (all Search Key values in)
- Sparse index

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• Multi-level index





Next:

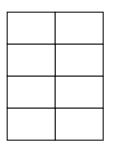
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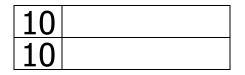
- Duplicate keys
- Deletion/Insertion
- Secondary indexes

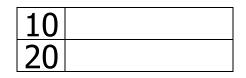


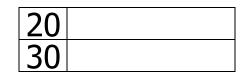
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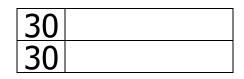












40	
45	



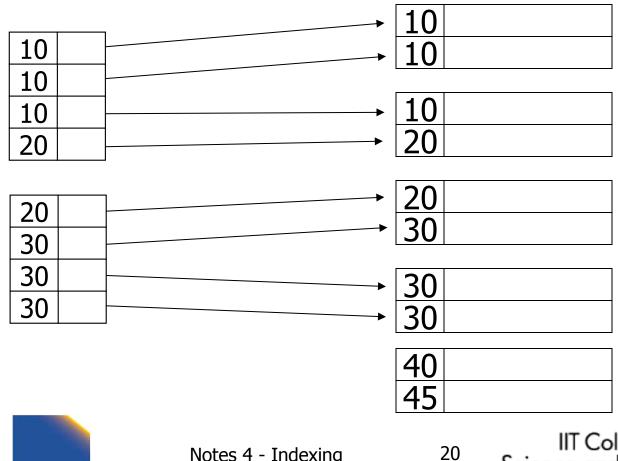
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Dense index, one way to implement?





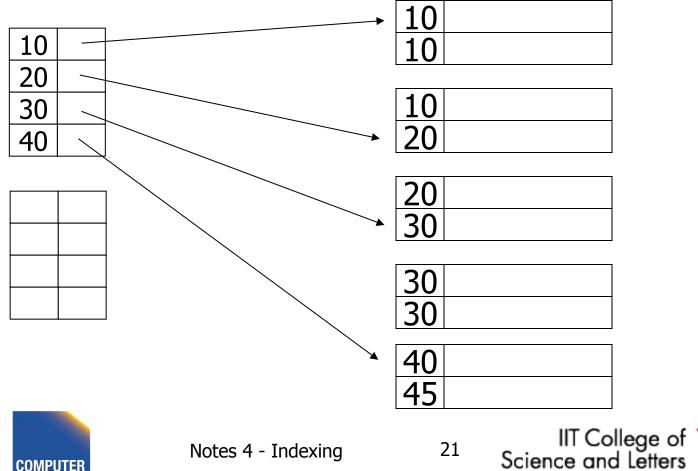
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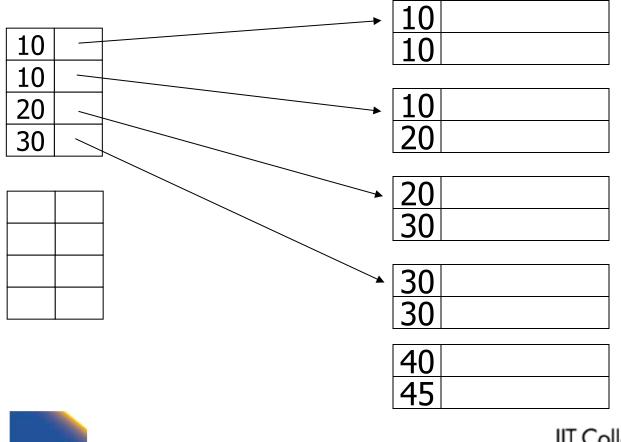
Dense index, better way?







Sparse index, one way?





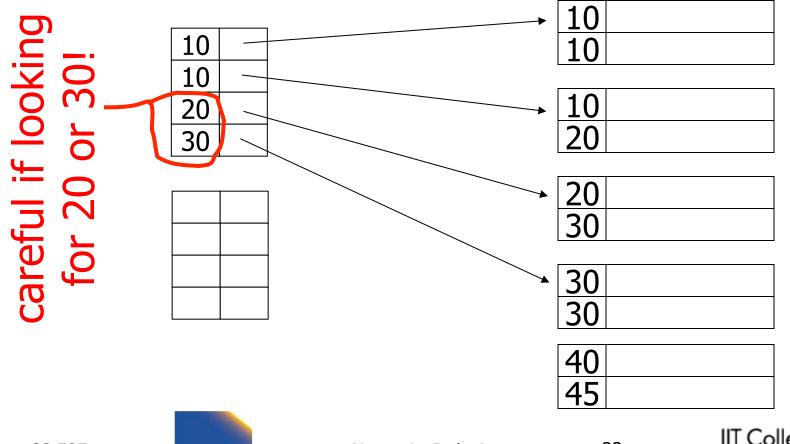
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Sparse index, one way?



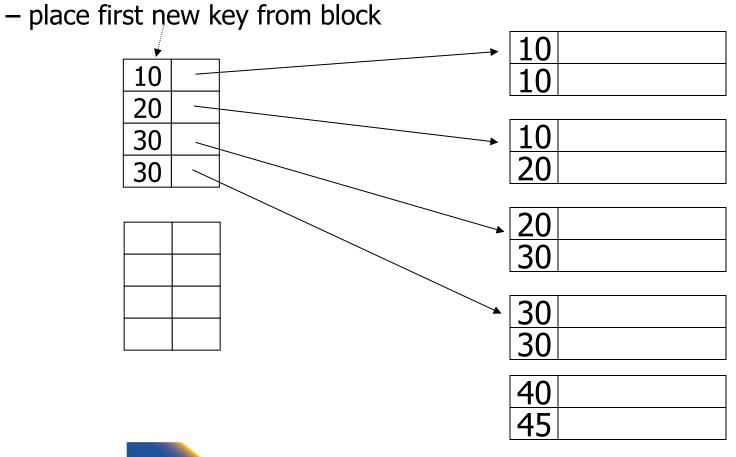




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Sparse index, another way?





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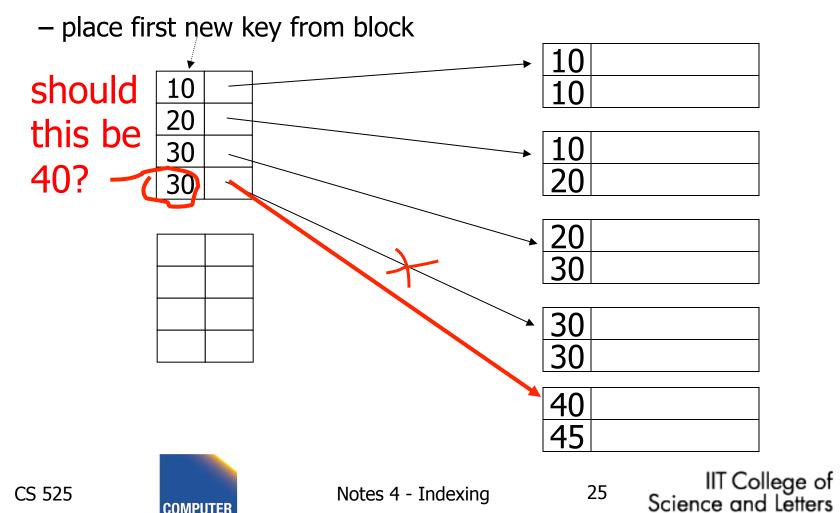
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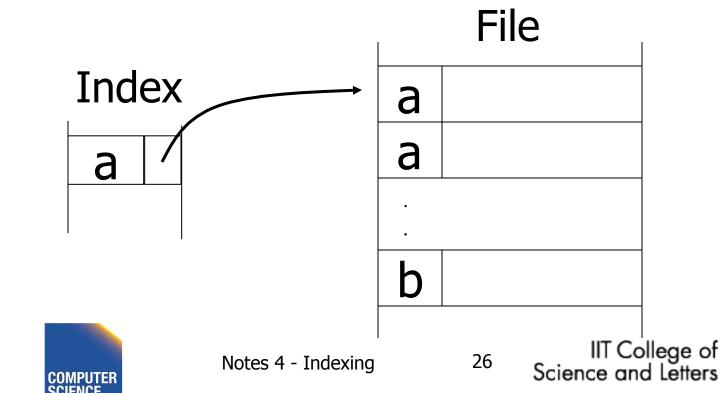
Sparse index, another way?

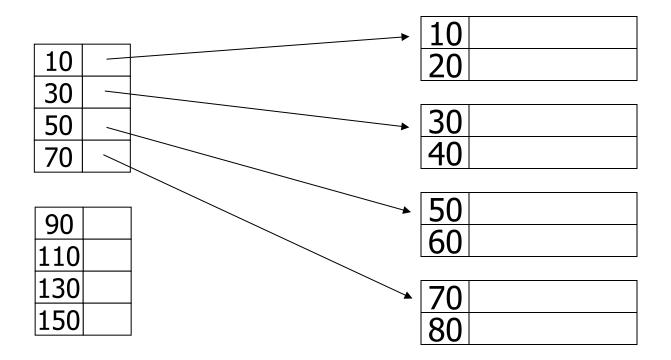


Summary Duplicate values, primary index

 Index may point to <u>first</u> instance of each value only

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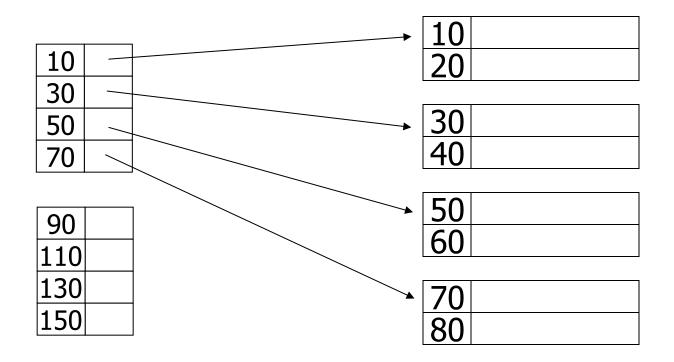




Notes 4 - Indexing



- delete record 40



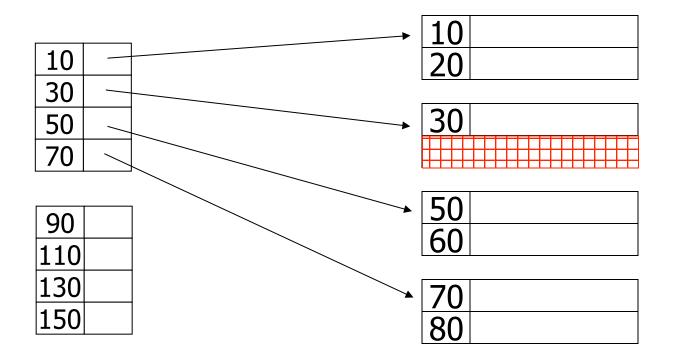


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Notes 4 - Indexing



- delete record 40



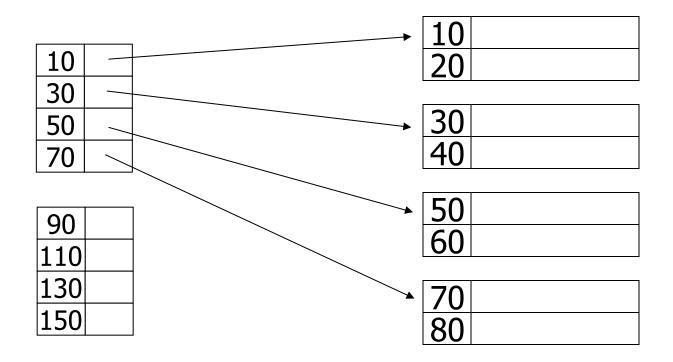


CS 525

Notes 4 - Indexing



- delete record 30



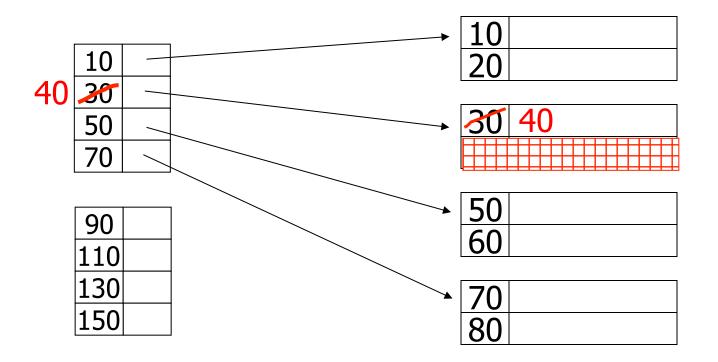


CS 525

Notes 4 - Indexing



- delete record 30



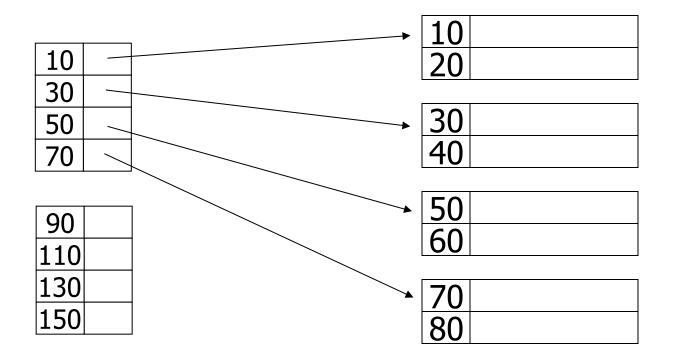


CS 525

Notes 4 - Indexing



– delete records 30 & 40



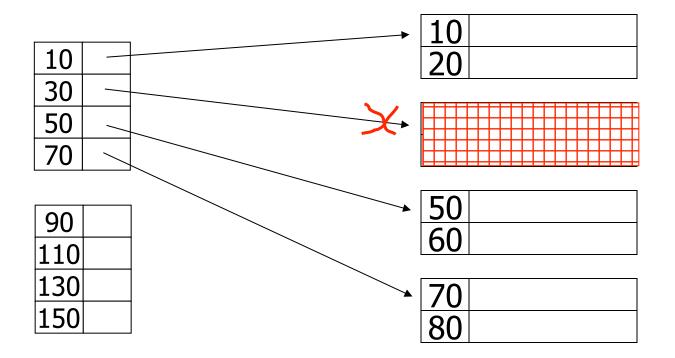


CS 525

Notes 4 - Indexing



– delete records 30 & 40



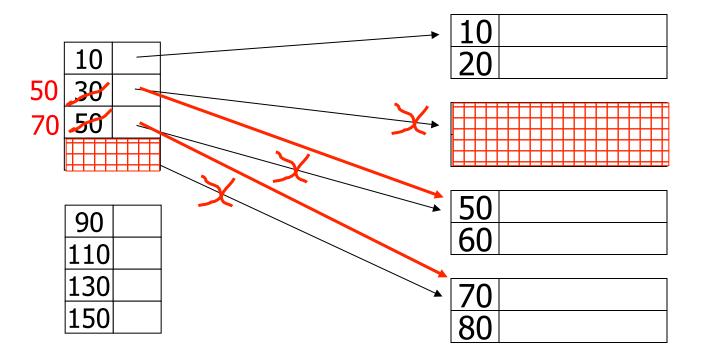


CS 525

Notes 4 - Indexing



- delete records 30 & 40

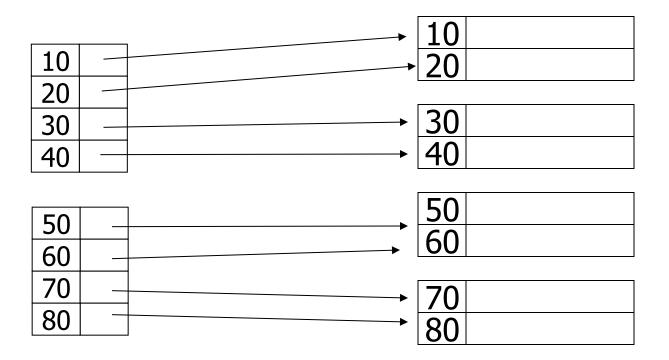




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Notes 4 - Indexing





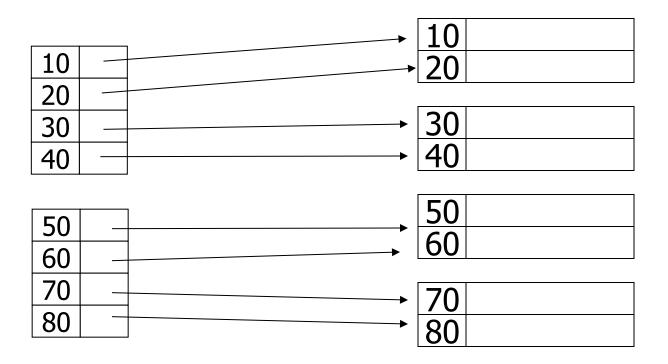


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Notes 4 - Indexing



- delete record 30



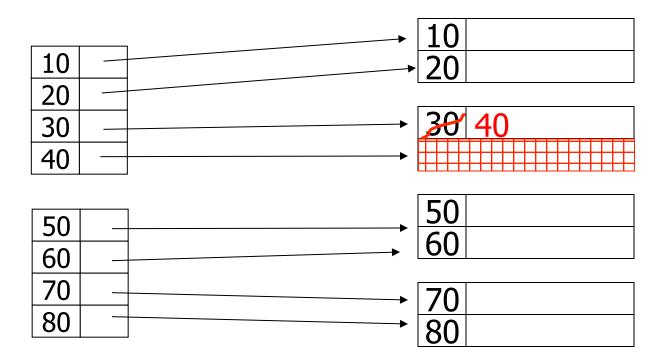


CS 525

Notes 4 - Indexing



- delete record 30



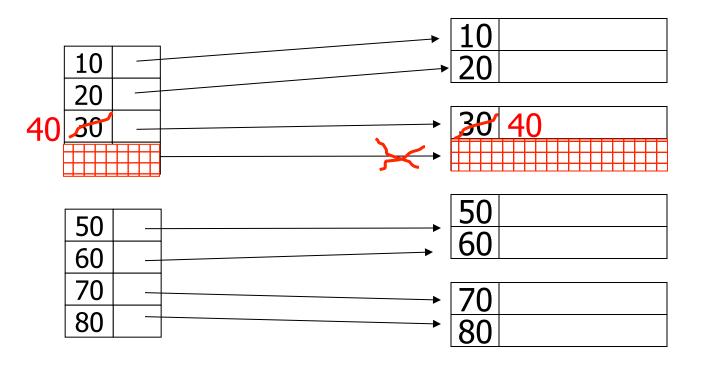


CS 525

Notes 4 - Indexing



- delete record 30

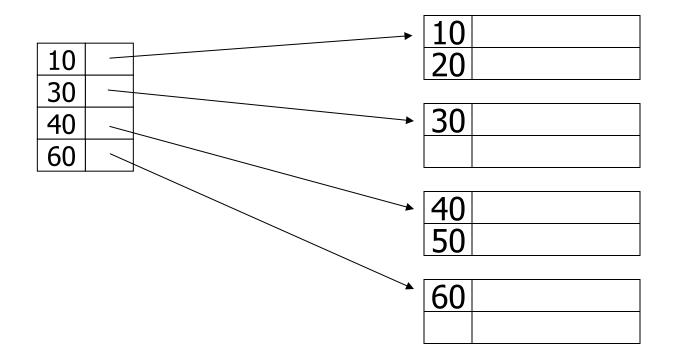




CS 525

Notes 4 - Indexing







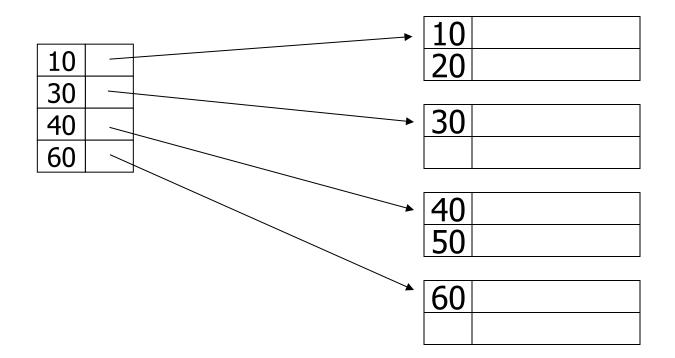
Notes 4 - Indexing

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- insert record 34



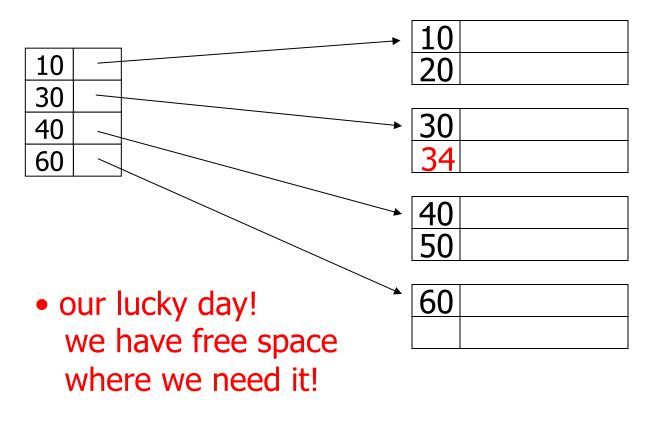


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- insert record 34





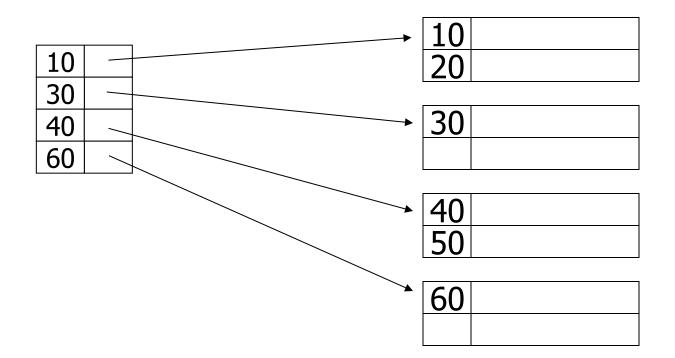
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- insert record 15



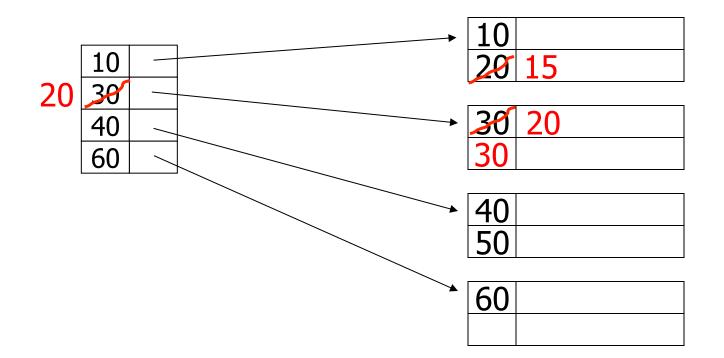


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Notes 4 - Indexing



- insert record 15



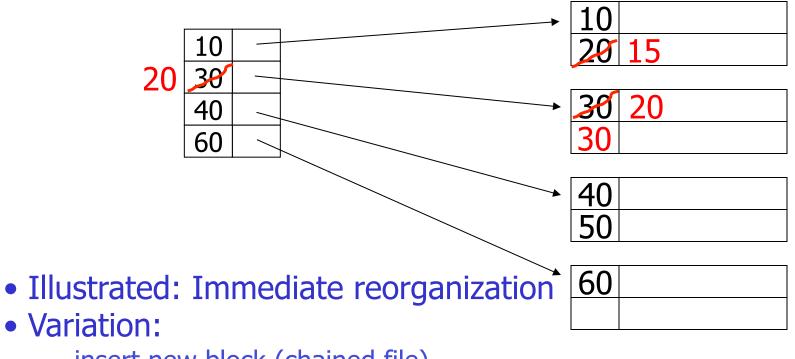


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- insert record 15



- insert new block (chained file)
- update index

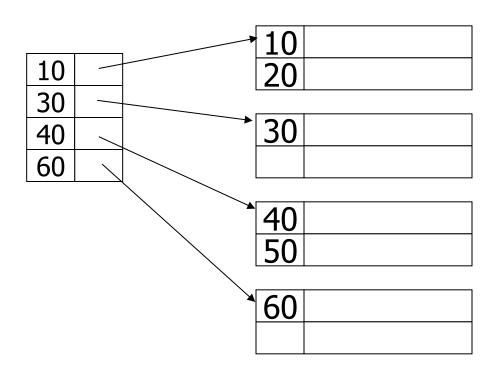
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- insert record 25

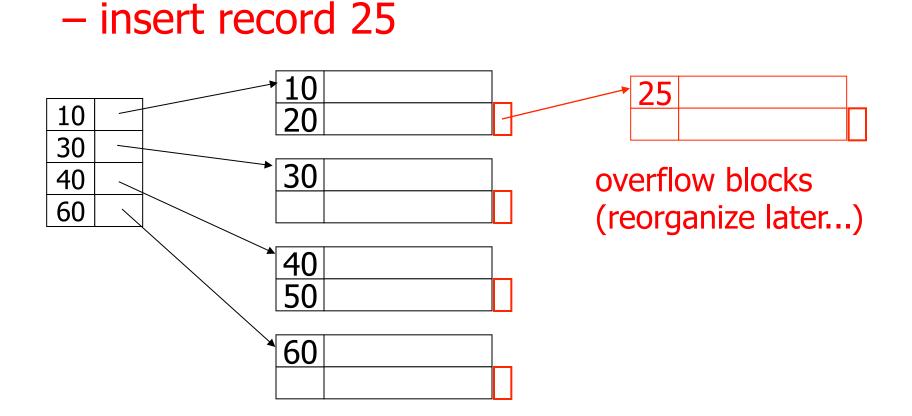




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Insertion, dense index case

- Similar
- Often more expensive . . .

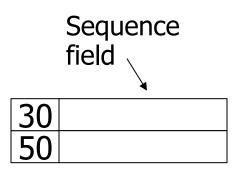


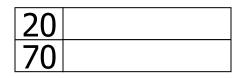
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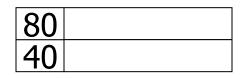
Notes 4 - Indexing



Secondary indexes









90	
60	

48



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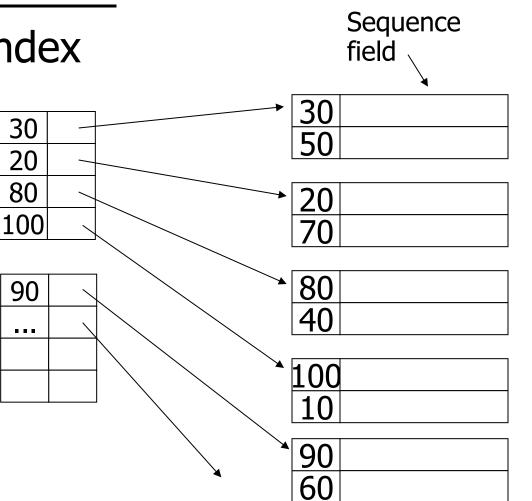
Notes 4 - Indexing







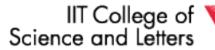
• Sparse index





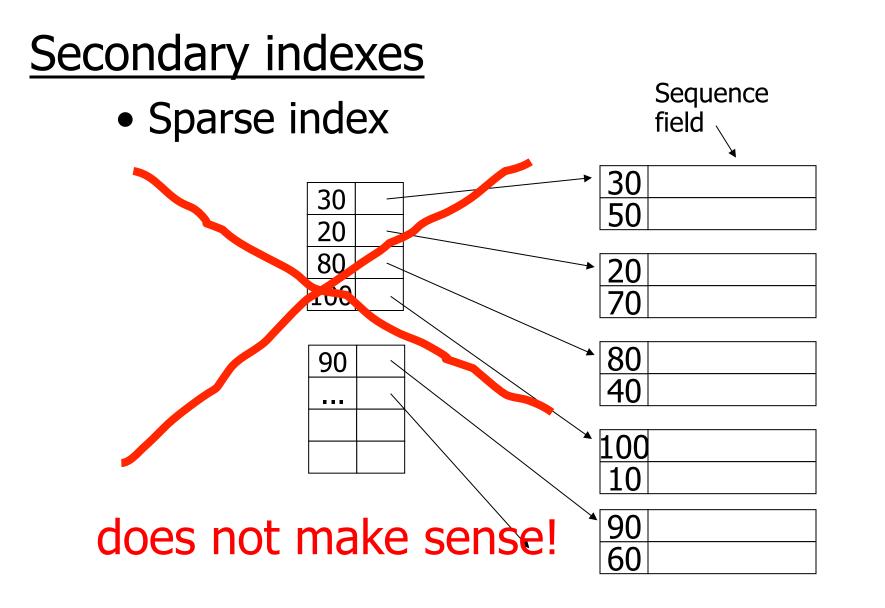
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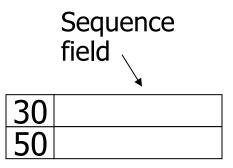
Notes 4 - Indexing

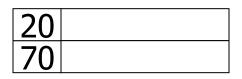
50



Secondary indexes

• Dense index









90	
60	



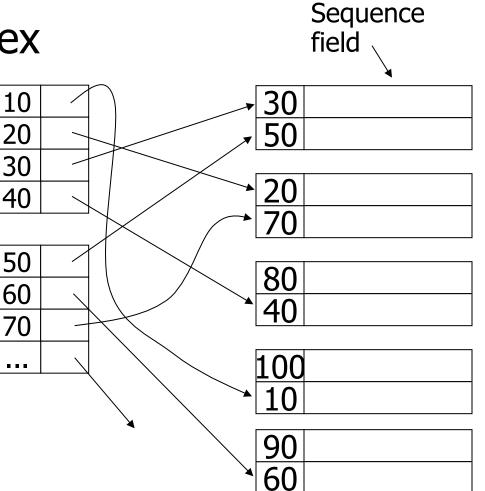
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Secondary indexes

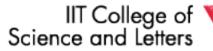
• Dense index





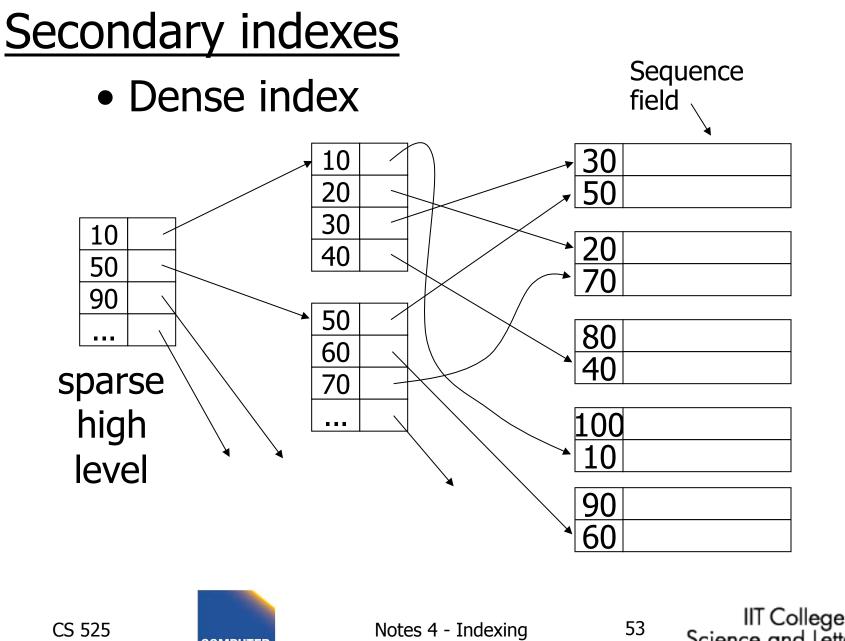
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COMPUTE



With secondary indexes:

- Lowest level is dense
- Other levels are sparse

<u>Also:</u> Pointers are record pointers (not block pointers; not computed)

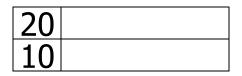


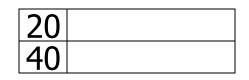
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30	
40	



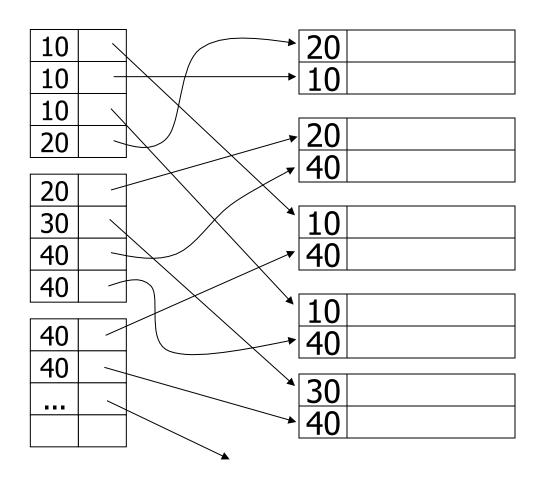
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Notes 4 - Indexing





one option...





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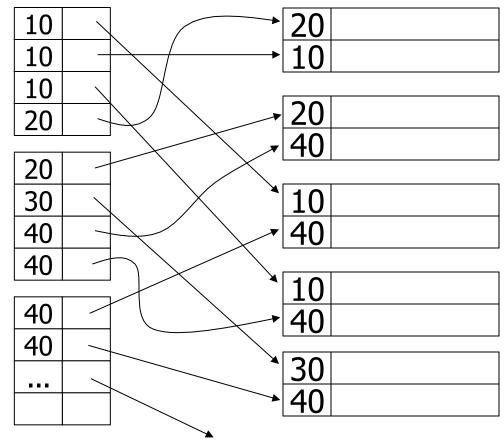
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one option...

Problem: excess overhead!

- disk space
- search time

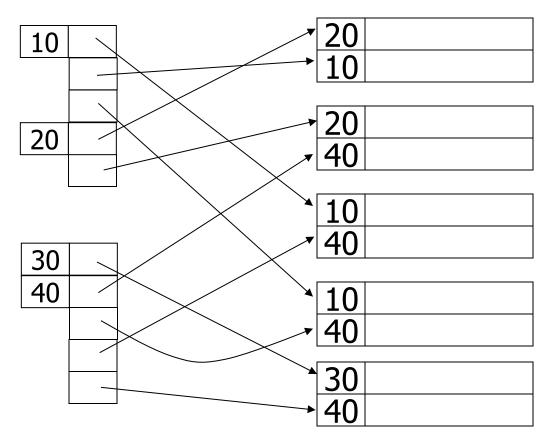




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another option...





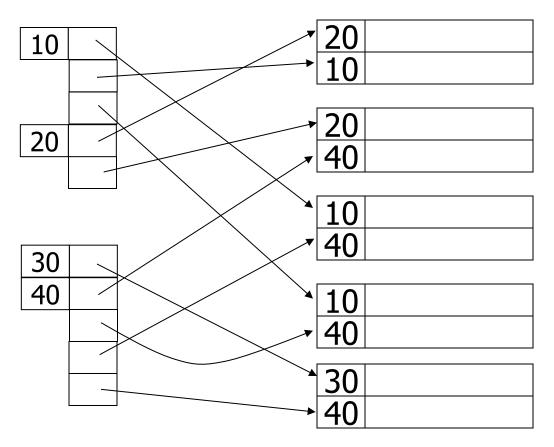
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another option...

Problem: variable size records in index!

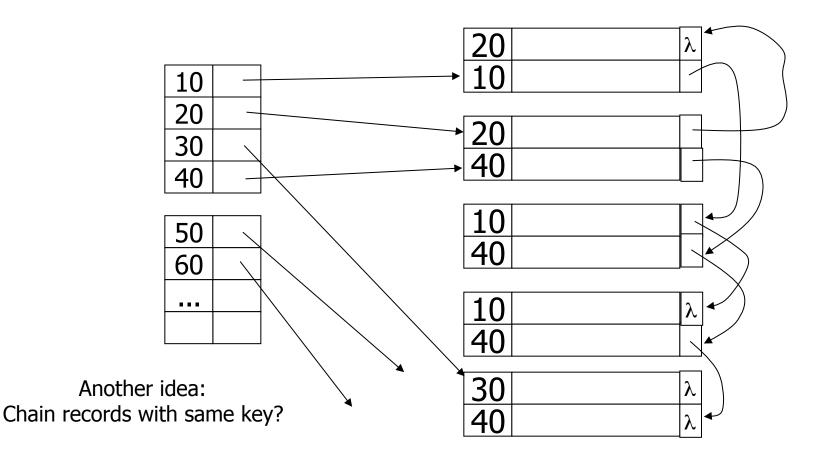
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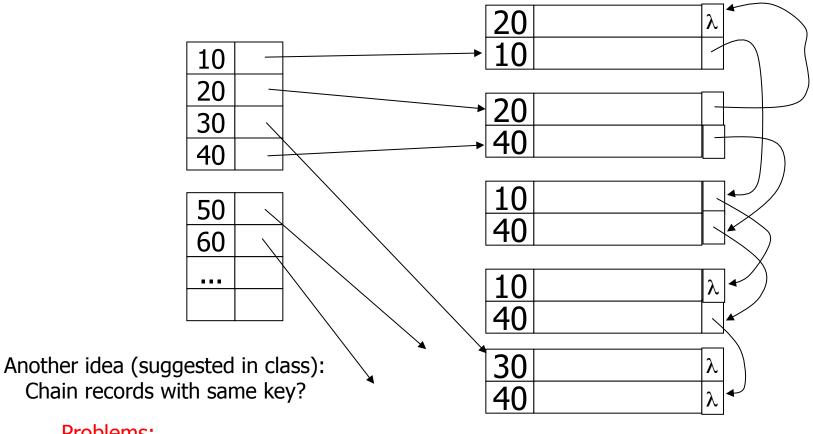




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Problems:

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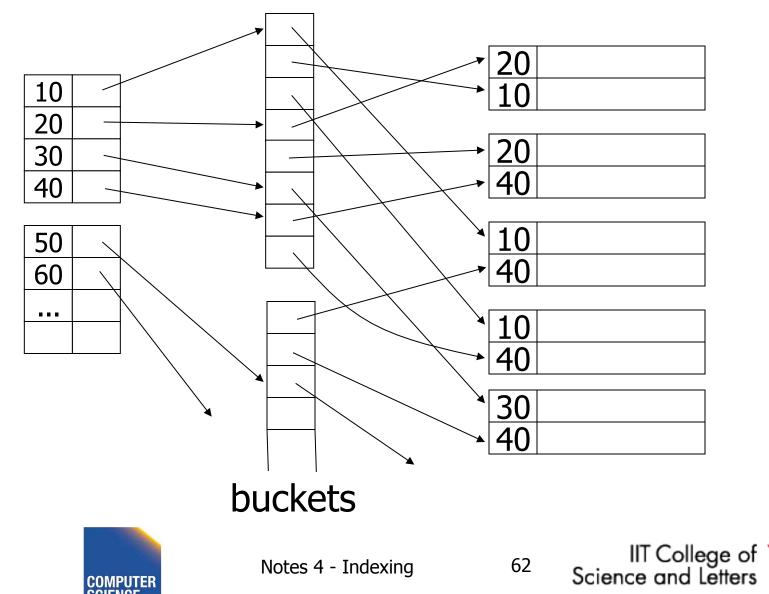
- Need to add fields to records
- Need to follow chain to know records



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Why "bucket" idea is useful

IndexesRecordsName: primaryEMP (name,dept,floor,...)Dept: secondaryFloor: secondary

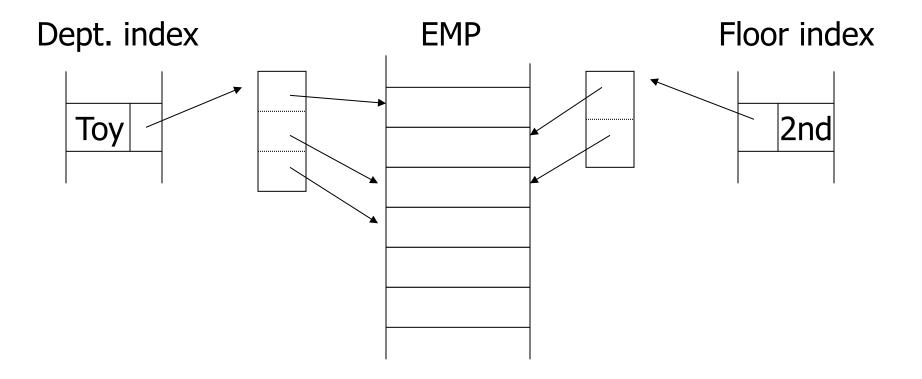


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Query: Get employees in (Toy Dept) $_{\wedge}$ (2nd floor)



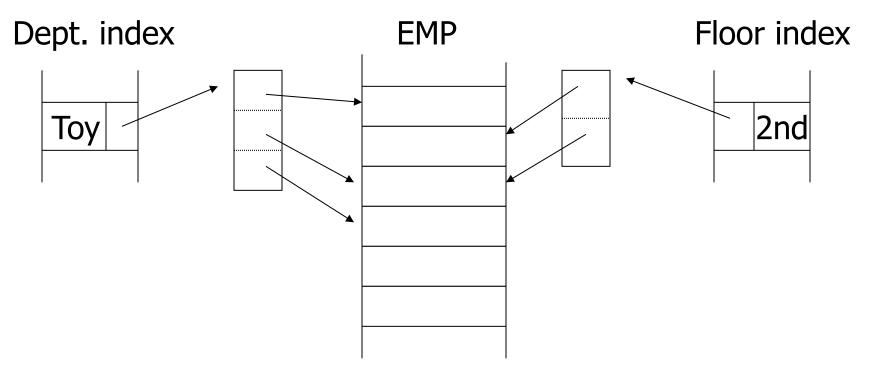


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Query: Get employees in (Toy Dept) $_{\wedge}$ (2nd floor)



→ Intersect toy bucket and 2nd Floor bucket to get set of matching EMP's

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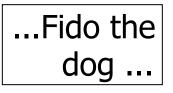
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This idea used in text information retrieval

Documents

...the cat is fat ...

...was raining cats and dogs...





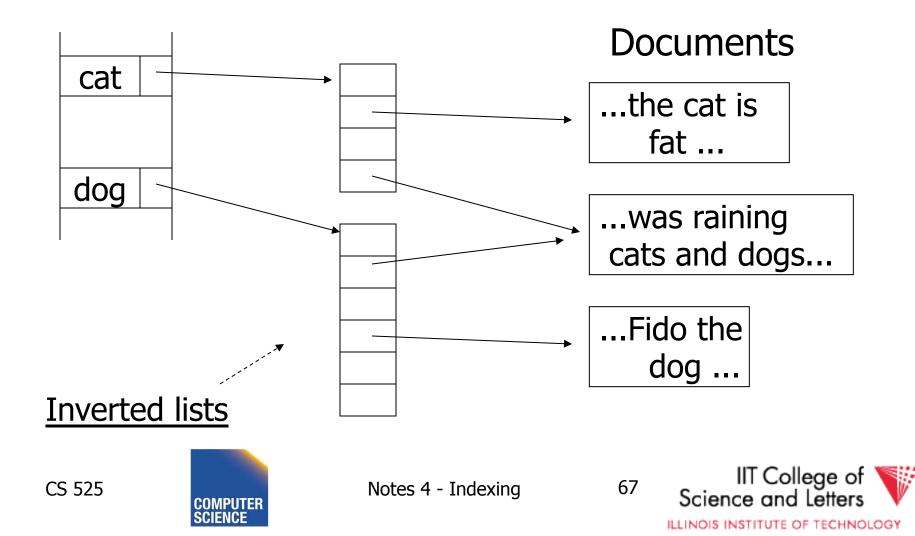
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This idea used in text information retrieval



IR QUERIES

- Find articles with "cat" and "dog"
- Find articles with "cat" or "dog"
- Find articles with "cat" and not "dog"



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Summary so far

- Conventional index
 - Basic Ideas: sparse, dense, multi-level...
 - Duplicate Keys
 - Deletion/Insertion
 - Secondary indexes
 - Buckets of Postings List



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Conventional indexes

Advantage:

- Simple
- Index is sequential file good for scans

Disadvantage:

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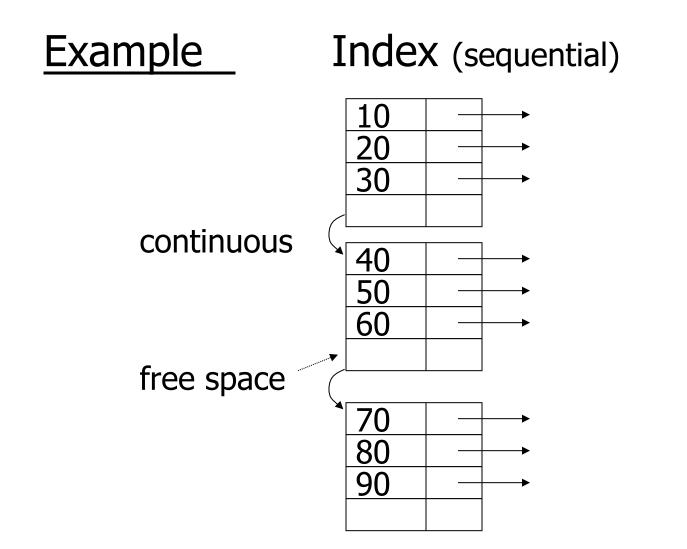
- Inserts expensive, and/or
- Lose sequentiality & balance



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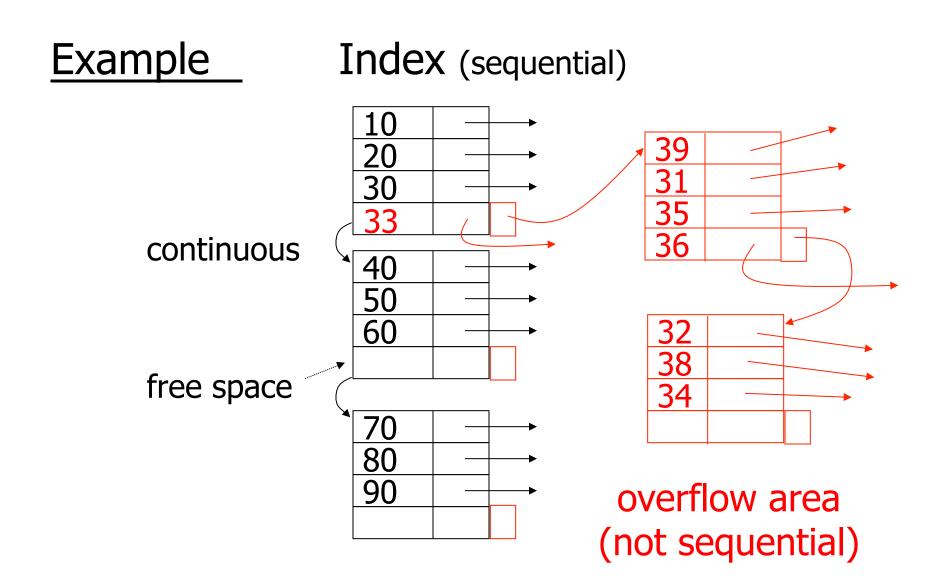




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Outline:

- Conventional indexes
- B-Trees \Rightarrow NEXT
- Hashing schemes
- Advanced Index Techniques



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- NEXT: Another type of index
 - Give up on sequentiality of index
 - Try to get "balance"



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B+-tree Motivation

- Tree indices are pretty efficient
 - E.g., binary search tree
 - Average case O(log(n)) lookup
- However

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- Unclear how to map to disk (index larger than main memory, loading partial index)
- Worst-case O(n) lookup



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B+-tree Properties

- Large nodes:
 - Node size is multiple of block size
 - -> small number of levels
 - -> simple way to map index to disk
 - -> many keys per node
- Balance:

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- Require all nodes to be more than X% full
- -> for n records guaranteed only logarithmically many levels
- --> log(n) worst-case performance



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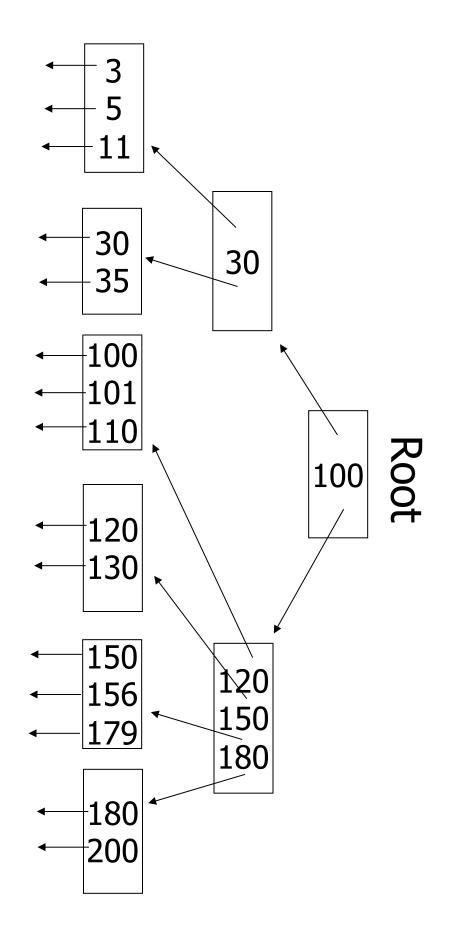


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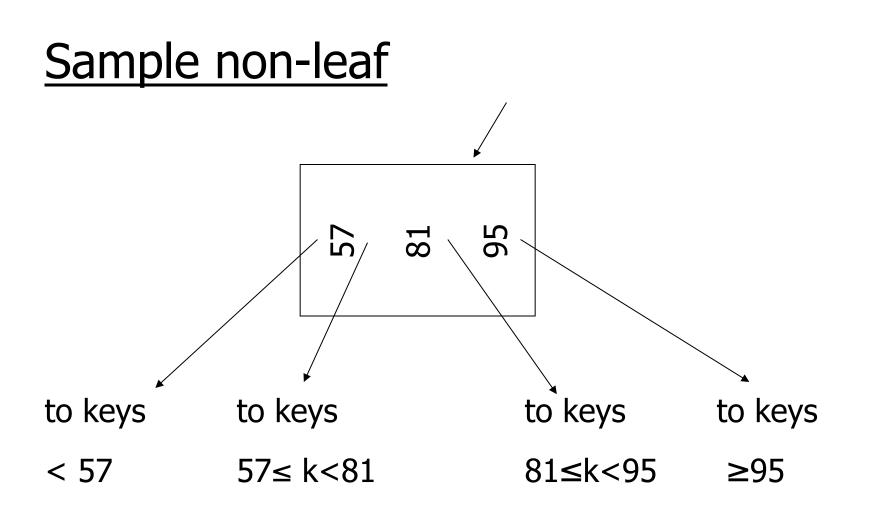


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B+Tree Example

n=3



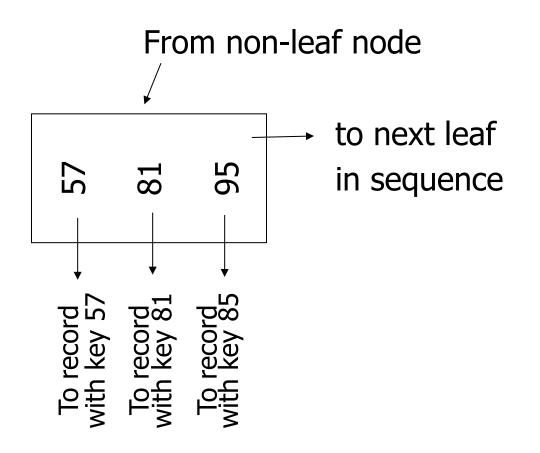


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Sample leaf node:





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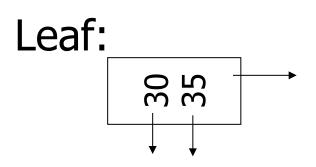
79



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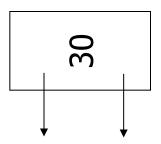
In textbook's notation

n=3



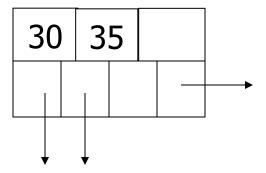
Non-leaf:

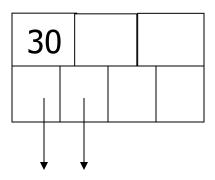
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Size of nodes:

n+1 pointers n keys



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Don't want nodes to be too empty

• Use at least (balance)

Non-leaf: [(n+1)/2] pointers

Leaf: $\lfloor (n+1)/2 \rfloor$ pointers to data



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n=3 Full node min. node Non-leaf 120 150 180 30 counts even if null Leaf 30 35 11 u u



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B+tree rules tree of order n

(1)All leaves at same lowest level (balanced tree)

-> guaranteed worst-case complexity for operations on the index

(2) Pointers in leaves point to records except for "sequence pointer"



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(3) Number of pointers/keys for B+tree

	Max ptrs	Max keys	Min ptrs→data	Min keys
Non-leaf (non-root)	n+1	n	[(n+1)/2]	[(n+1)/2]- 1
Leaf (non-root)	n+1	n	[(n+1)/2]	[(n+1)/2]
Root	n+1	n	1	1



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Search Algorithm

- Search for key k
- Start from root until leaf is reached
- For current node find i so that
 - $-\text{Key}[i] \le \mathbf{k} \le \text{Key}[i + 1]$
 - Follow i+1th pointer
- If current node is leaf return pointer to record or fail (no such record in tree)



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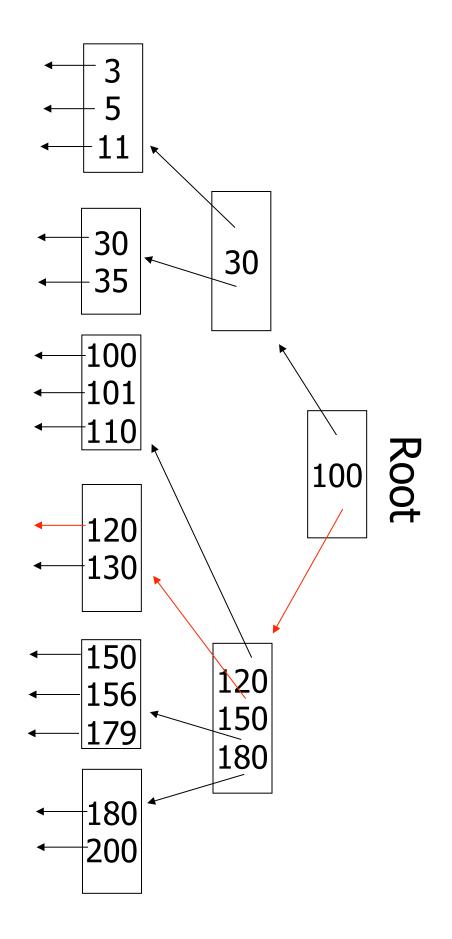




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Search Example

k= 120

Remarks Search

- If **n** is large, e.g., 500
- Keys inside node are sorted
- -> use binary search to find **I**
- Performance considerations
 - Linear search O(n)
 - Binary search $O(\log_2(n))$



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Insert into B+tree

(a) simple case
– space available in leaf
(b) leaf overflow
(c) non-leaf overflow
(d) new root

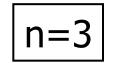


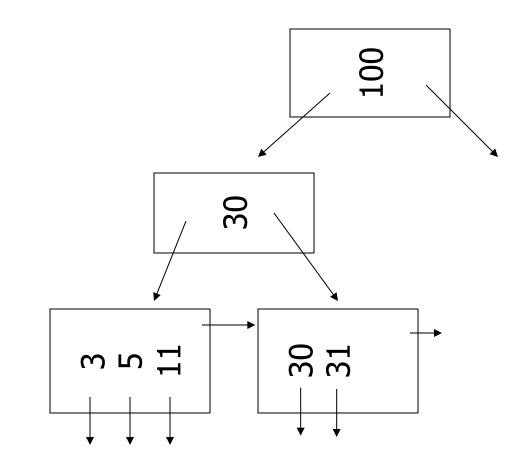
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(a) Insert key = 32





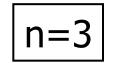


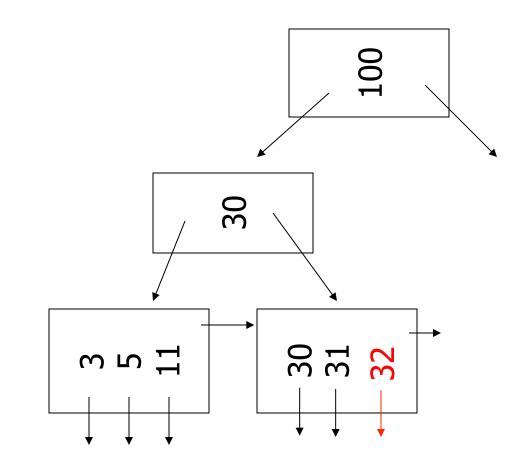
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(a) Insert key = 32





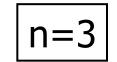


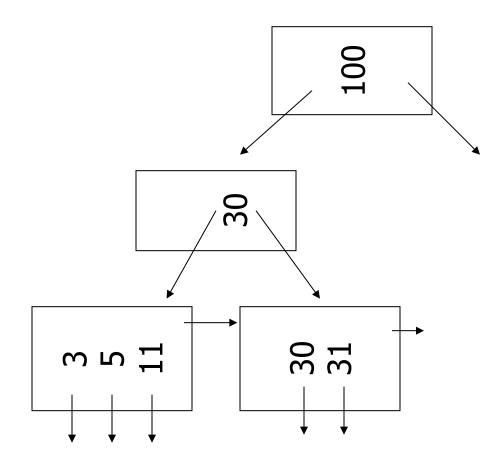
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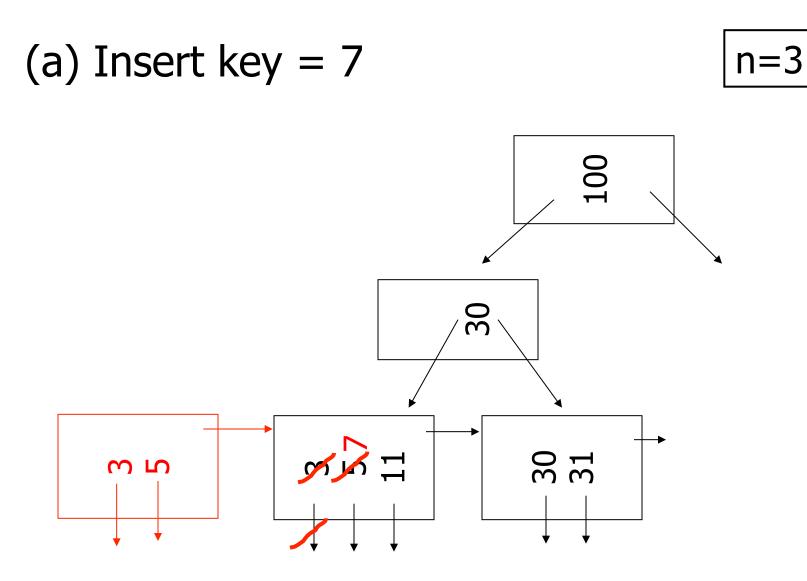






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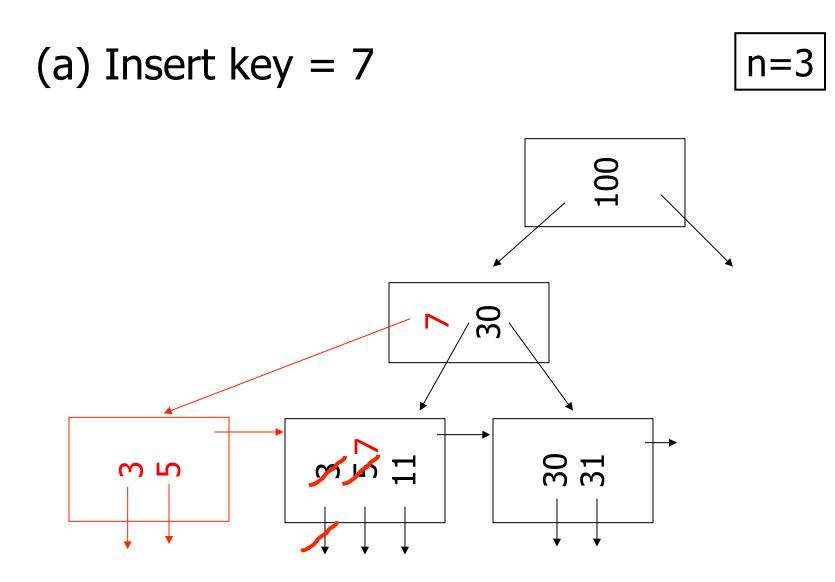






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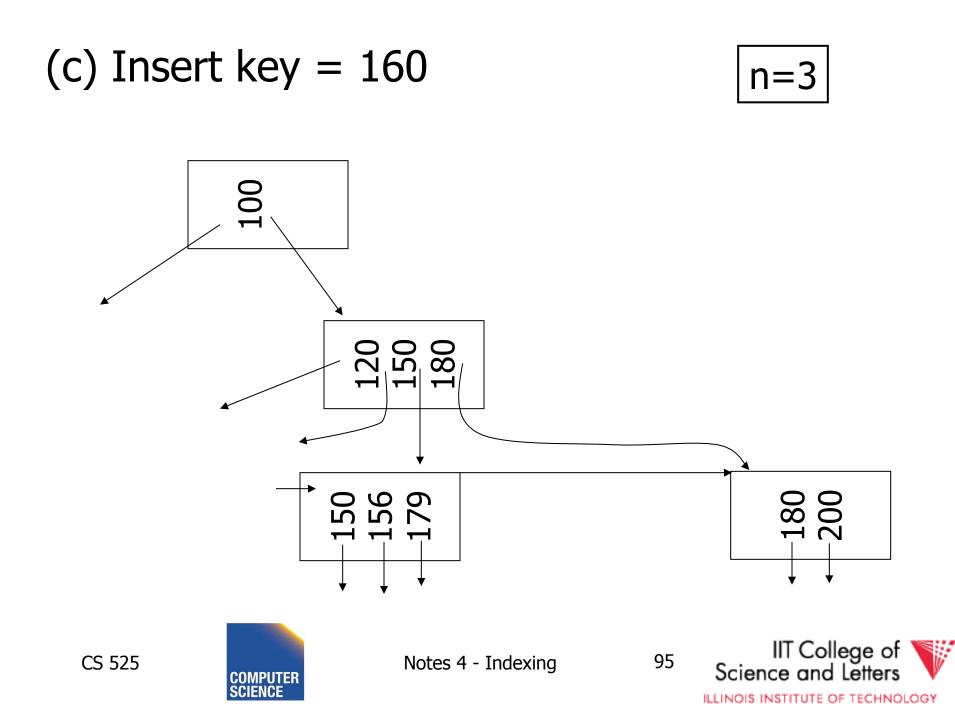


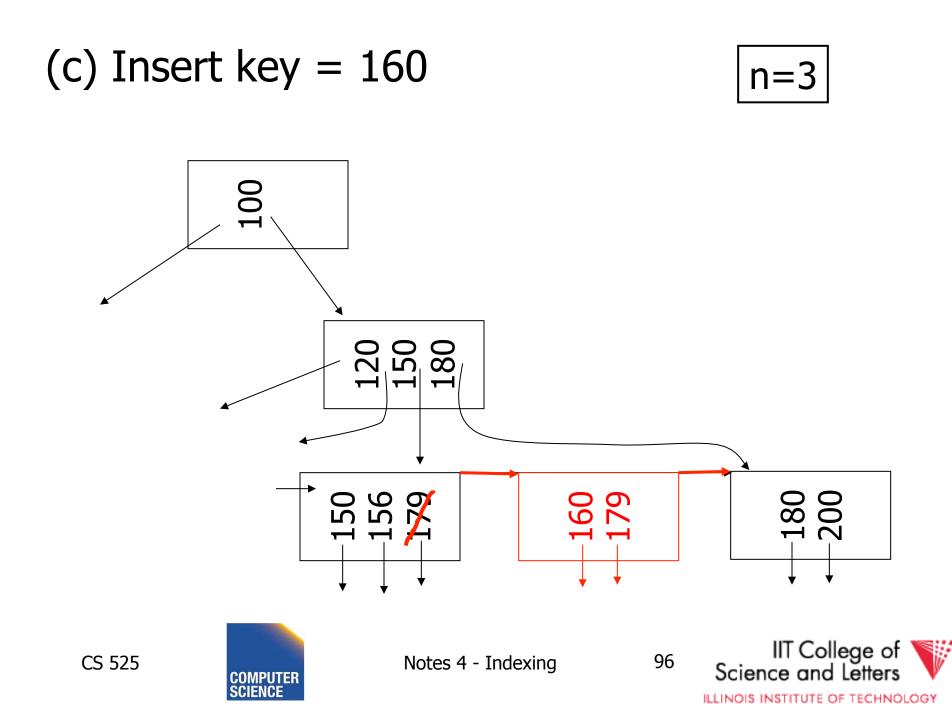


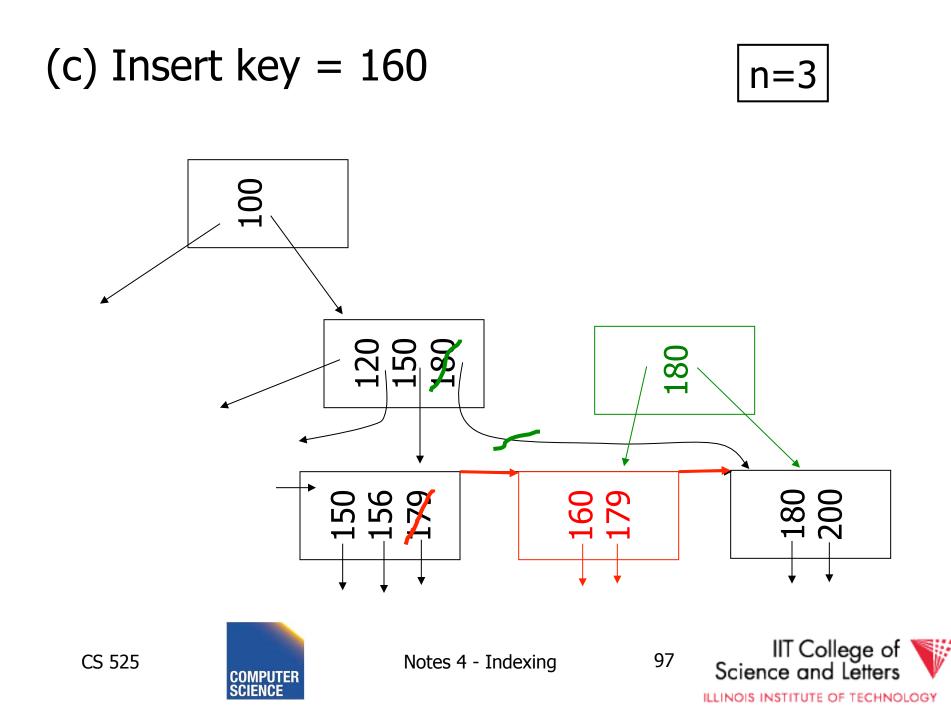


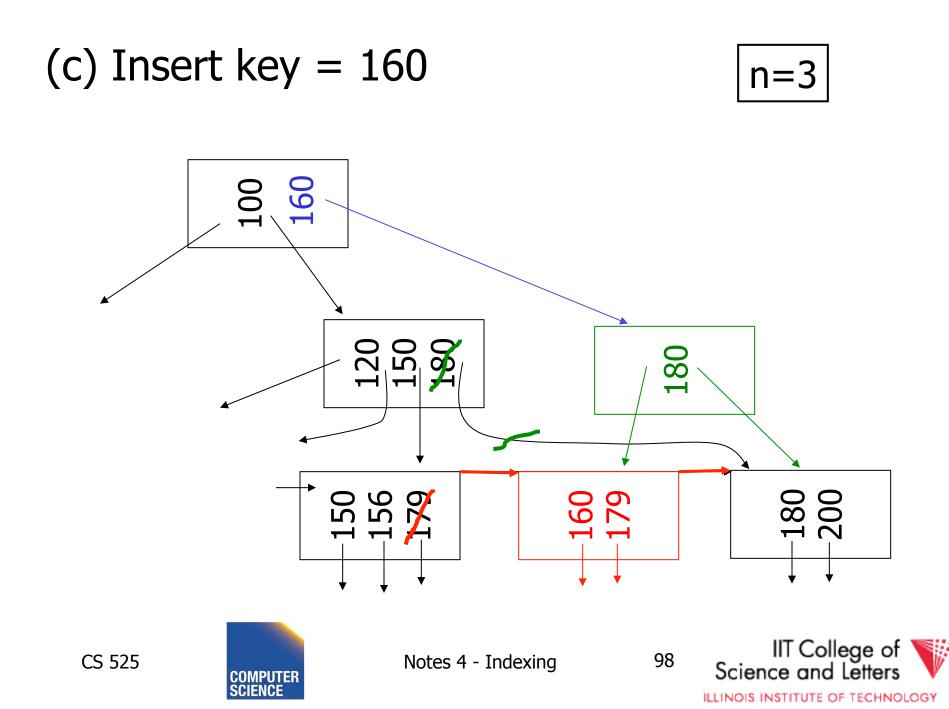
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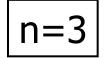


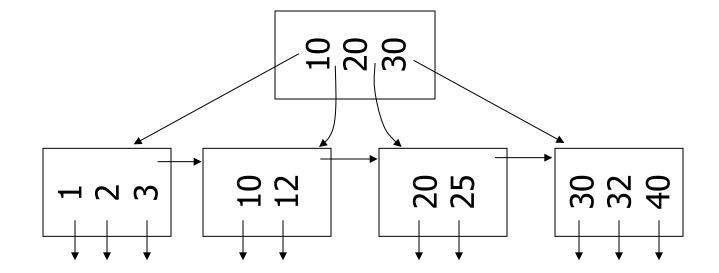






(d) New root, insert 45







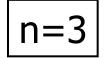
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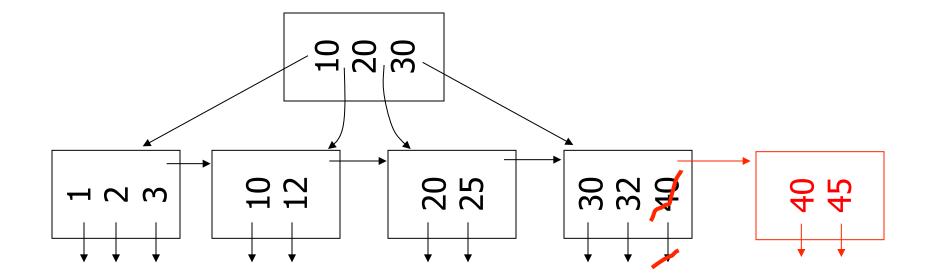
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(d) New root, insert 45







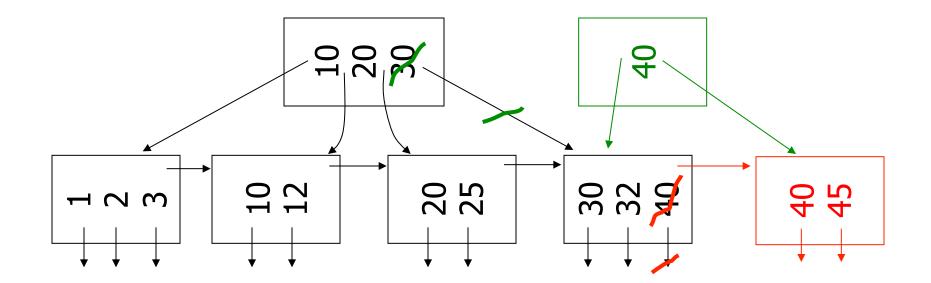
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(d) New root, insert 45

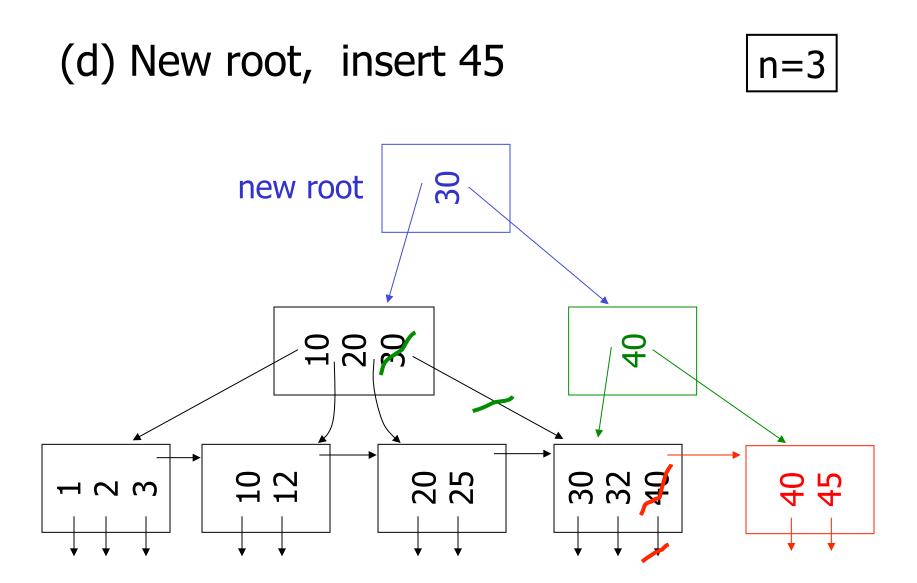




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Insertion Algorithm

- Insert Record with key ${\bf k}$
- Search leaf node for ${\boldsymbol k}$
 - Leaf node has at least one space
 - Insert into leaf
 - Leaf is full
 - Split leaf into two nodes (new leaf)
 - Insert new leaf's smallest key into parent



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Insertion Algorithm cont.

Non-leaf node is full

- Split parent
- Insert median key into parent
- Root is full
 - Split root
 - Create new root with two pointers and single key
- -> B-trees grow at the root



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Deletion from B+tree

(a) Simple case - no example
(b) Coalesce with neighbor (sibling)
(c) Re-distribute keys
(d) Cases (b) or (c) at non-leaf

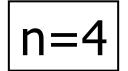


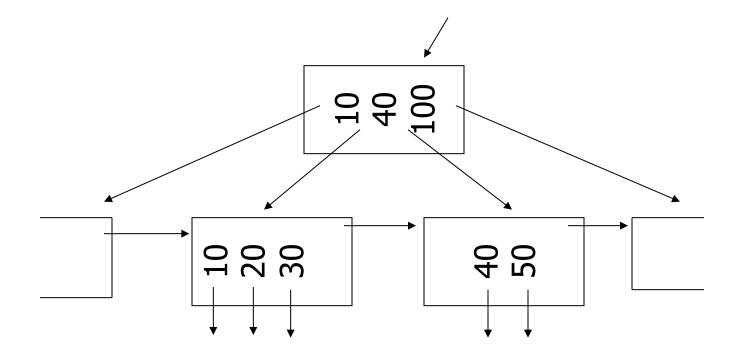
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(b) Coalesce with sibling – Delete 50





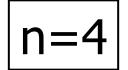


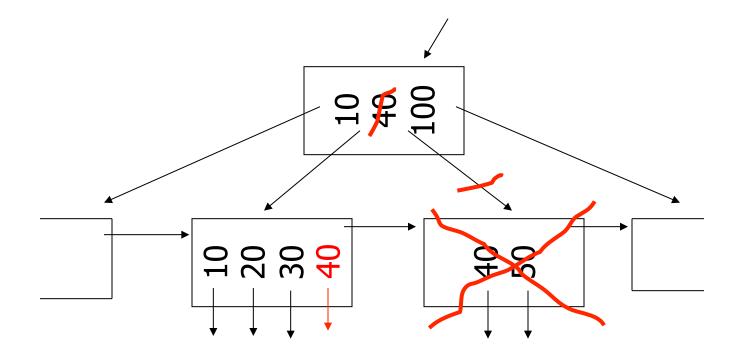
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(b) Coalesce with sibling – Delete 50



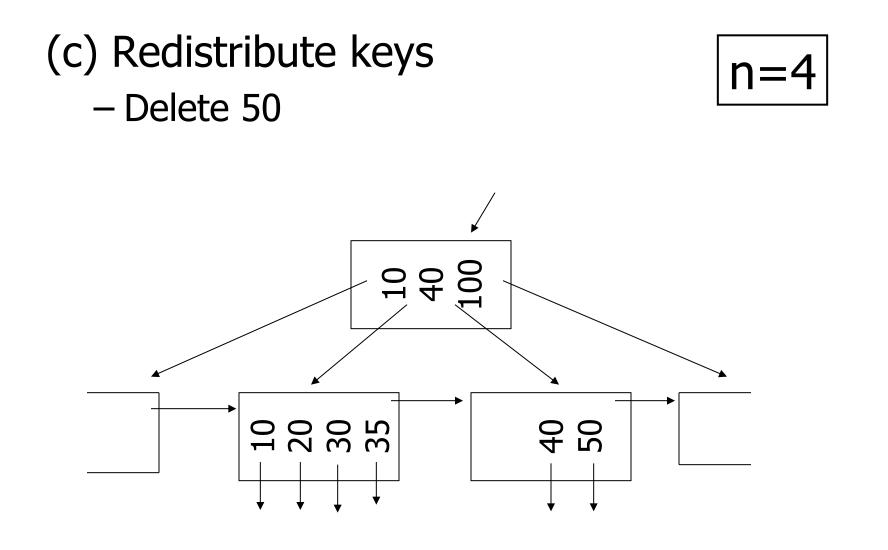




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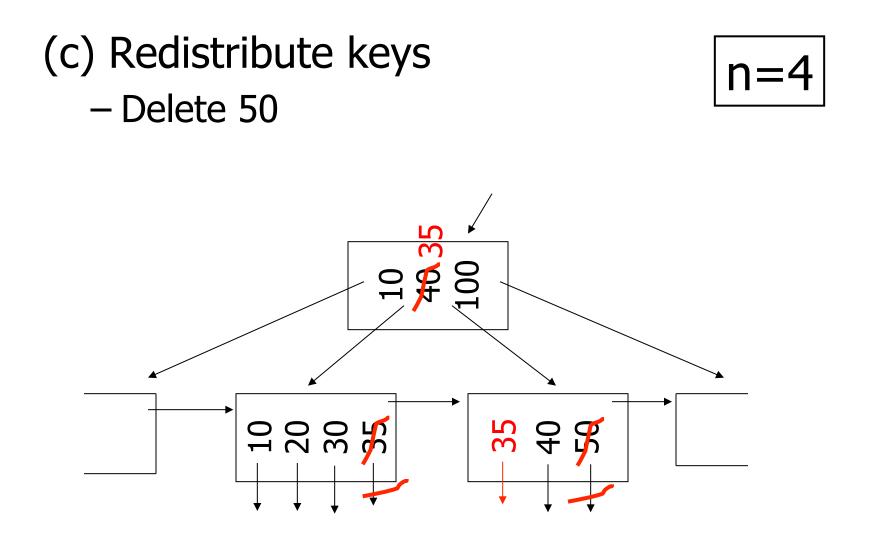






Notes 4 - Indexing

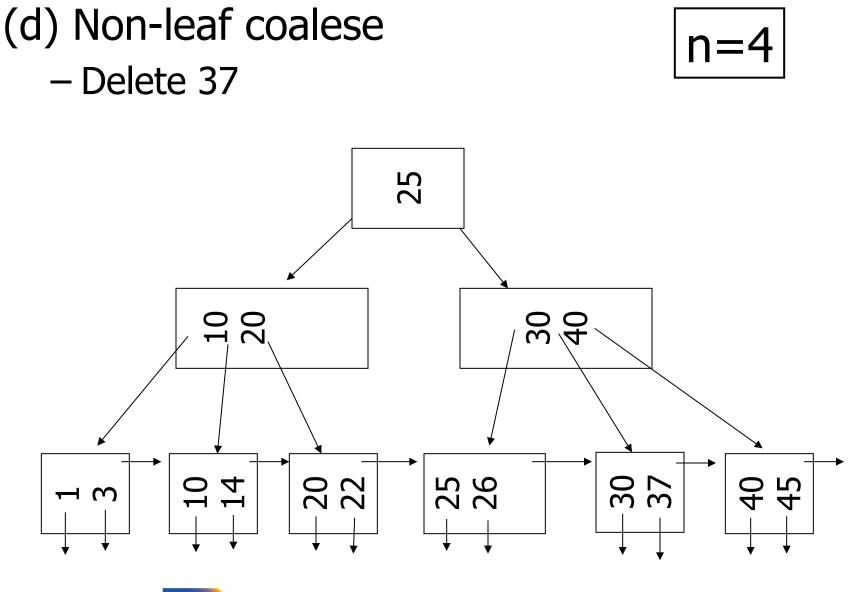






Notes 4 - Indexing

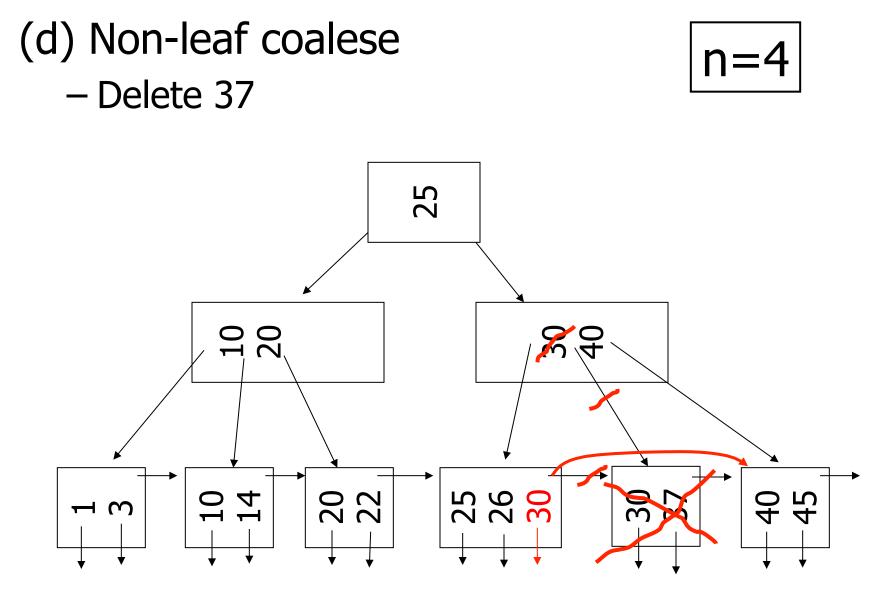






Notes 4 - Indexing

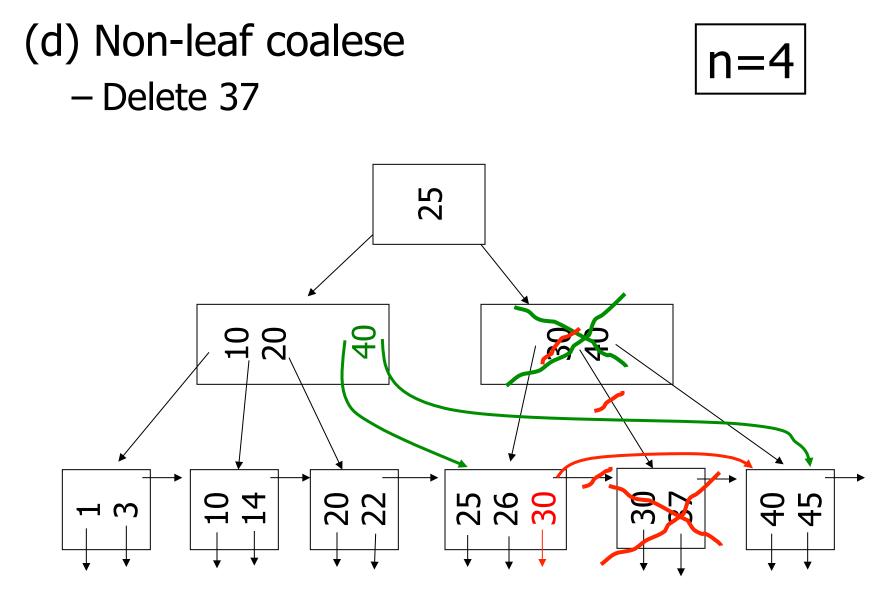






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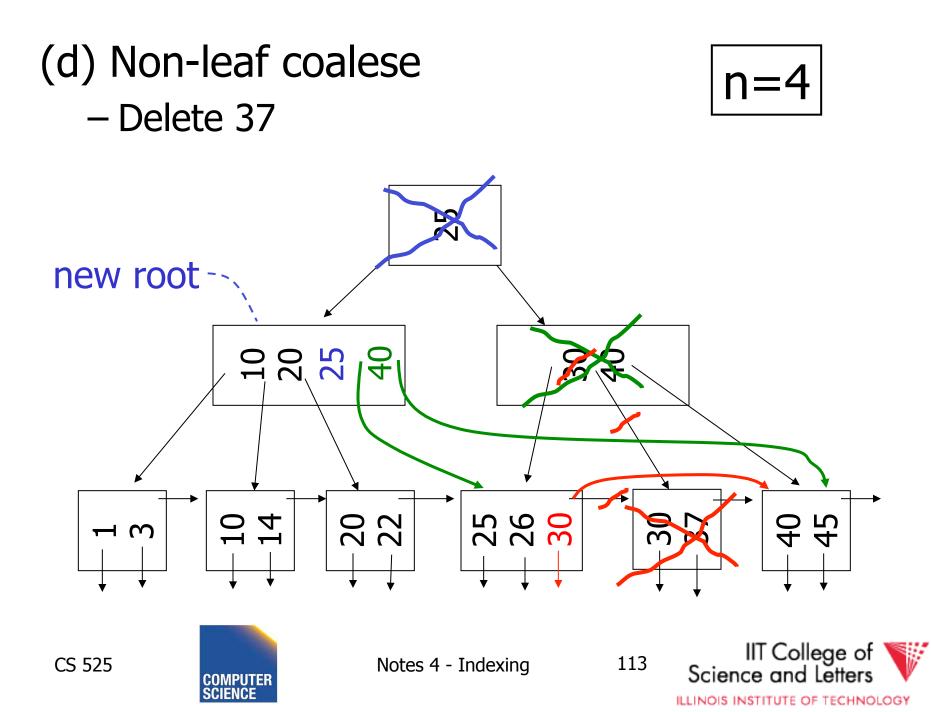
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Deletion Algorithm

- Delete record with key ${\bf k}$
- Search leaf node for ${\boldsymbol k}$
 - Leaf has more than min entries
 - Remove from leaf
 - Leaf has min entries
 - Try to borrow from sibling
 - One direct sibling has more min entries
 - Move entry from sibling and adapt key in parent



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Deletion Algorithm cont.

- Both direct siblings have min entries
 - Merge with one sibling
 - Remove node or sibling from parent
 - ->recursive deletion
- Root has two children that get merged – Merged node becomes new root



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<u>B+tree deletions in practice</u>

– Often, coalescing is not implemented

- Too hard and not worth it!
- Assumption: nodes will fill up in time again



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Comparison: B-trees vs. static indexed sequential file

Ref #1:Held & Stonebraker"B-Trees Re-examined"CACM, Feb. 1978



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Ref # 1 claims:

- Concurrency control harder in B-Trees
 - B-tree consumes more space

```
For their comparison:
block = 512 bytes
key = pointer = 4 bytes
4 data records per block
```

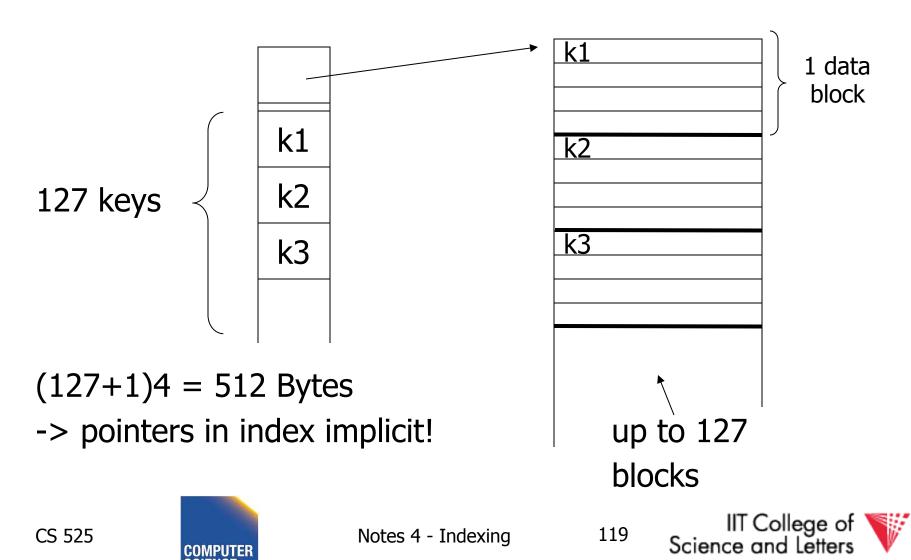


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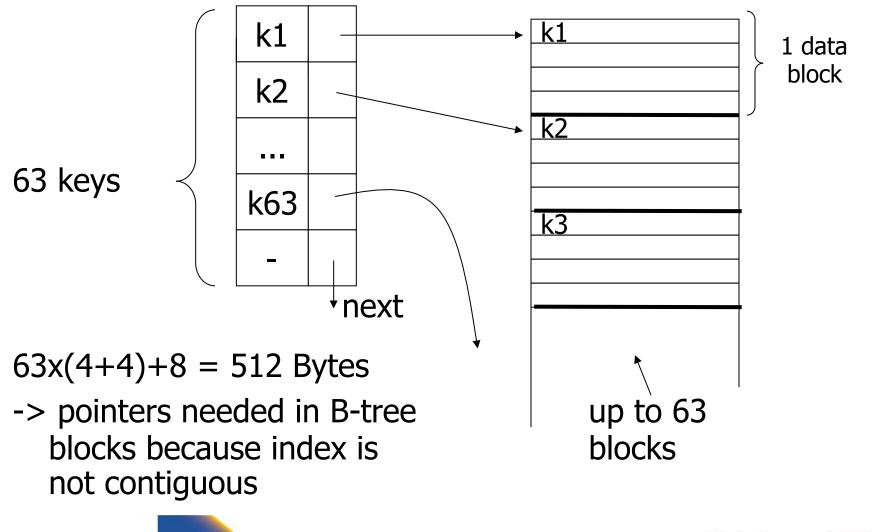
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Example: 1 block static index



Example: 1 block B-tree



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Size comp	arison	Ref. #1		
<u>Static 1</u> # data blocks	I <u>ndex</u> height	B-tree # data blocks	height	
2 -> 127 128 -> 16,129 16,130 -> 2,048	2 3 ,383 4	2 -> 63 64 -> 3968 3969 -> 250,047 250,048 -> 15,752,96	2 3 4 1 5	



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Ref. #1 analysis claims

- For an 8,000 block file, $\begin{cases} after 32,000 \text{ inserts} \\ after 16,000 \text{ lookups} \\ \Rightarrow \text{ Static index saves enough accesses} \end{cases}$
 - to allow for reorganization



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Ref. #1 analysis claims

- For an 8,000 block file, $\begin{cases} after 32,000 \text{ inserts} \\ after 16,000 \text{ lookups} \\ \Rightarrow \text{ Static index saves enough accesses} \end{cases}$
 - to allow for reorganization



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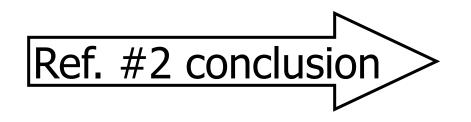
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Ref #2: M. Stonebraker,

"Retrospective on a database system," TODS, June 1980



B-trees better!!



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- DBA does not know when to reorganize
- DBA does not know <u>how full</u> to load pages of new index



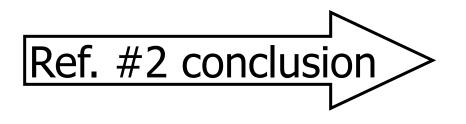
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B-trees better!!





B-trees better!!

- Buffering
 - B-tree: has fixed buffer requirements
 - Static index: must read several overflow blocks to be efficient (large & variable size

size needed for this)



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• Speaking of buffering... Is LRU a good policy for B+tree buffers?



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- Speaking of buffering... Is LRU a good policy for B+tree buffers?
 - \rightarrow Of course not!
 - → Should try to keep root in memory at all times

(and perhaps some nodes from second level)



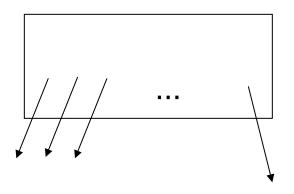
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Interesting problem:

For B+tree, how large should *n* be?



n is number of keys / node



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Sample assumptions:

(1) Time to read node from disk is (S+T*n*) msec.



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Sample assumptions:

(1) Time to read node from disk is (S+T*n*) msec.

(2) Once block in memory, use binary search to locate key: (a + b LOG₂ n) msec.

For some constants *a*,*b*; Assume a << S



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Sample assumptions:

(1) Time to read node from disk is (S+T*n*) msec.

(2) Once block in memory, use binary search to locate key:
 (a + b LOG₂ n) msec.

For some constants *a*,*b*; Assume a << S

(3) Assume B+tree is full, i.e.,
 # nodes to examine is LOG_n N
 where N = # records



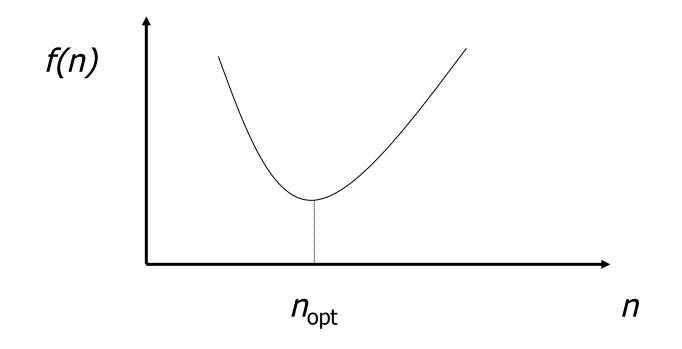
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➤Can get: f(n) = time to find a record





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► FIND n_{opt} by f'(n) = 0

Answer is $n_{opt} =$ "few hundred"



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► FIND n_{opt} by f'(n) = 0

Answer is $n_{opt} =$ "few hundred"

\rightarrow What happens to n_{opt} as

- Disk gets faster?
- CPU get faster?
- Memory hierarchy?



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Variation on B+tree: B-tree (no +)

• Idea:

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Avoid duplicate keys

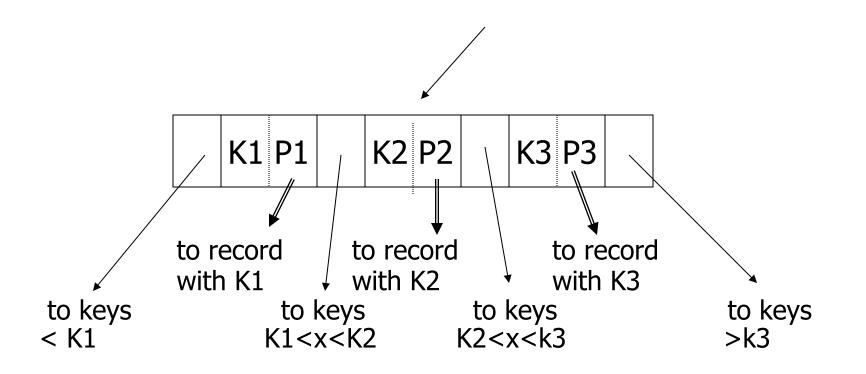
- Have record pointers in non-leaf nodes



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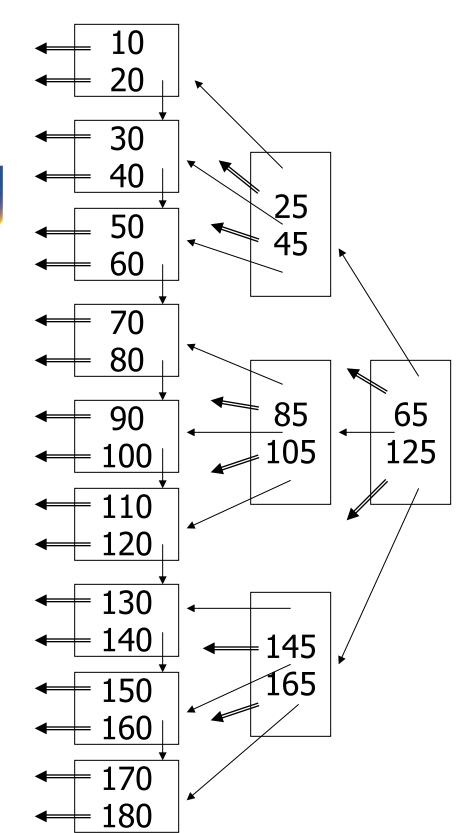


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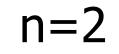
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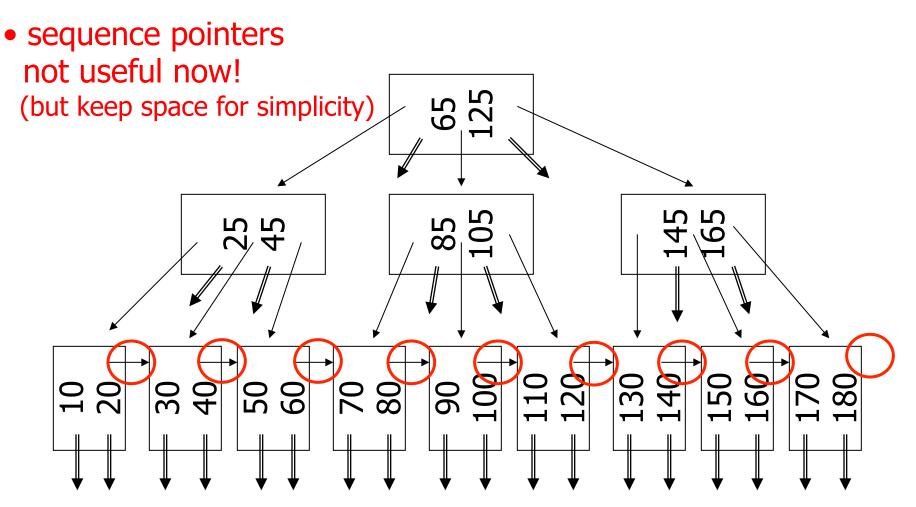


<u>B-tree example</u>

n=2

B-tree example







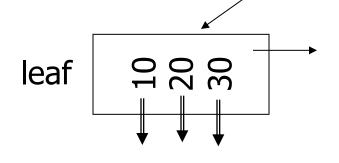
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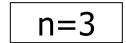
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Note on inserts

• Say we insert record with key = 25







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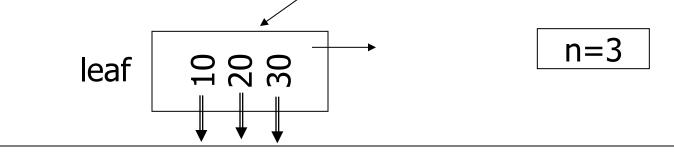
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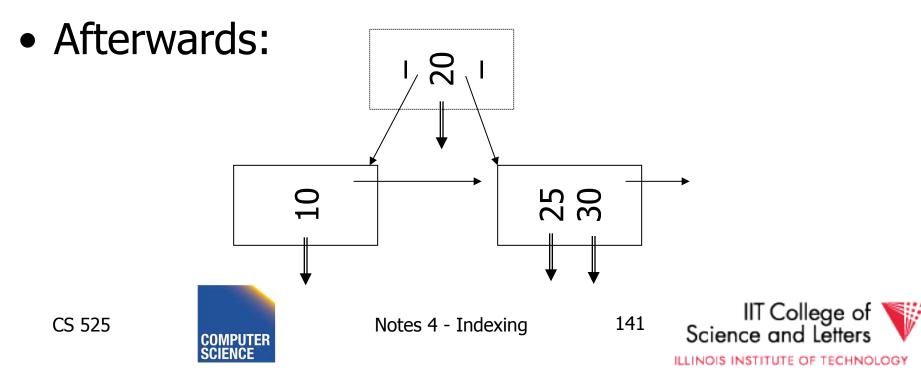
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Note on inserts

• Say we insert record with key = 25





So, for B-trees:

	MAX			MIŅ		
	Tree Ptrs	Rec Ptrs	Keys	Tree Ptrs	Rec Ptrs	Keys
Non-leaf non-root	n+1	n	n		[(n+1)/2]-1	[(n+1)/2]-1
Leaf non-root	1	n	n	1	[n/2]	[n/2]
Root non-leaf	n+1	n	n	2	1	1
Root Leaf	1	n	n	1	1	1



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Tradeoffs:

☺ B-trees have faster lookup than B+trees

⊗ in B-tree, non-leaf & leaf different sizes⊗ in B-tree, deletion more complicated



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Tradeoffs:

☺ B-trees have faster lookup than B+trees

⊗ in B-tree, non-leaf & leaf different sizes⊗ in B-tree, deletion more complicated

➡ B+trees preferred!



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But note:

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• If blocks are fixed size

(due to disk and buffering restrictions) Then lookup for B+tree is actually better!!



Notes 4 - Indexing



Example:

- Pointers 4 bytes
- Keys 4 bytes
- Blocks 100 bytes (just example)
- Look at full 2 level tree



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B-tree:

Root has 8 keys + 8 record pointers + 9 son pointers = 8x4 + 8x4 + 9x4 = 100 bytes



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B-tree:

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Root has 8 keys + 8 record pointers + 9 son pointers = 8x4 + 8x4 + 9x4 = 100 bytes

Each of 9 sons: 12 rec. pointers (+12 keys) = 12x(4+4) + 4 = 100 bytes



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B-tree:

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Root has 8 keys + 8 record pointers + 9 son pointers = 8x4 + 8x4 + 9x4 = 100 bytes

Each of 9 sons: 12 rec. pointers (+12 keys) = 12x(4+4) + 4 = 100 bytes

<u>2-level B-tree, Max # records</u> = 12x9 + 8 = 116



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<u>Root</u> has 12 keys + 13 son pointers = 12x4 + 13x4 = 100 bytes



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B+tree:

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<u>Root</u> has 12 keys + 13 son pointers = 12x4 + 13x4 = 100 bytes

Each of 13 sons: 12 rec. ptrs (+12 keys) = 12x(4 + 4) + 4 = 100 bytes



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B+tree:

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<u>Root</u> has 12 keys + 13 son pointers = 12x4 + 13x4 = 100 bytes

Each of 13 sons: 12 rec. ptrs (+12 keys) = 12x(4 + 4) + 4 = 100 bytes

$\frac{2 \text{-level B+tree, Max # records}}{= 13 \text{x} 12 = 156}$



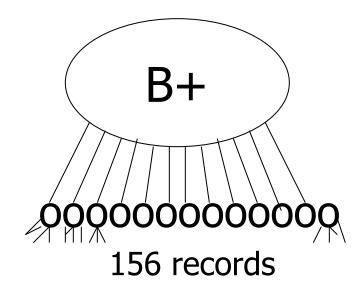
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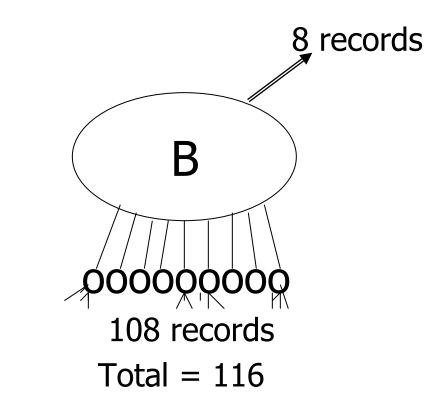
152



So...

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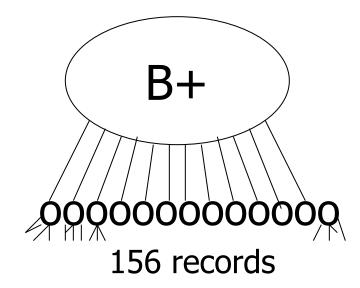


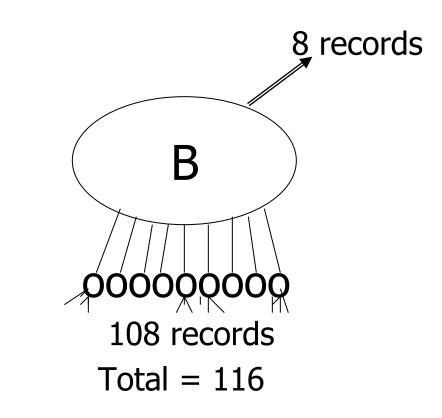


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So...





- Conclusion:
 - For fixed block size,
 - B+ tree is better because it is bushier





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Additional B-tree Variants

• B*-tree

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- Internal notes have to be 2/3 full



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An Interesting Problem...

- What is a good index structure when:
 - records tend to be inserted with keys that are larger than existing values? (e.g., banking records with growing data/time)
 - we want to remove older data



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One Solution: Multiple Indexes

• Example: I1, I2

day	days indexed I1	days indexed I2
10	1,2,3,4,5	6,7,8,9,10
11	11,2,3,4,5	6,7,8,9,10
12	11,12,3,4,5	6,7,8,9,10
13	11,12,13,4,5	6,7,8,9,10

advantage: deletions/insertions from smaller index
disadvantage: query multiple indexes

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Another Solution (Wave Indexes)

day	I1	I2	I3	I4
10	1,2,3	4,5,6	7,8,9	10
11	1,2,3	4,5,6	7,8,9	10,11
12	1,2,3	4,5,6	7,8,9	10,11, 12
13	13	4,5,6	7,8,9	10,11, 12
14	13,14	4,5,6	7,8,9	10,11, 12
15	13,14,15	4,5,6	7,8,9	10,11, 12
16	13,14,15	16	7,8,9	10,11, 12

advantage: no deletionsdisadvantage: approximate windows



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Concurrent Access To B-trees

- Multiple processes/threads accessing the B-tree
 - Can lead to corruption
- Serialize access to complete tree for updates
 - Simple
 - Unnecessary restrictive
 - Not feasible for high concurrency





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Lock Nodes

• One solution

- ReadWriteReadXWrite-
- Safe and unsafe updates of nodes
 - **Safe:** No ancestor of node will be effected by update
 - Unsafe: Ancestor may be affected
 - Can be determined locally

- Read and exclusive locks

– E.g., deletion is safe is node has more than n/2



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Lock Nodes

- Reading
 - Use standard search algorithm
 - Hold lock on current node
 - Release when navigating to child
- Writing
 - Lock each node on search for key
 - Release all locks on parents of node if the node is safe





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Improvements?

- Try locking only the leaf for update
 - Let update use read locks and only lock leaf node with write lock
 - If leaf node is unsafe then use previous protocol
- Many more locking approaches have been proposed



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Outline/summary

- Conventional Indexes
 - Sparse vs. dense
 - Primary vs. secondary
- B trees

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- B+trees vs. B-trees
- B+trees vs. indexed sequential
- Hashing schemes --> Next
- Advanced Index Techniques



Notes 4 - Indexing



CS 525: Advanced Database Organization **05: Hashing and More** Boris Glavic

Slides: adapted from a <u>course</u> taught by <u>Hector Garcia-Molina</u>, Stanford InfoLab



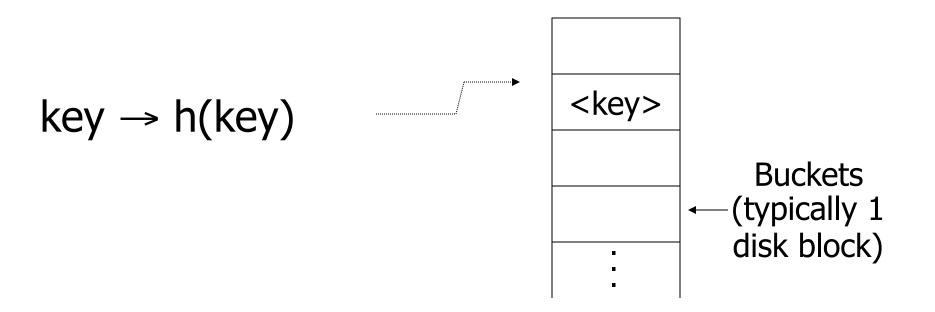
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Notes 5 - Hashing

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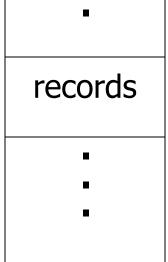


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Two alternatives

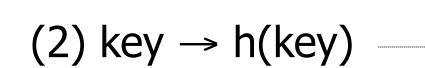
(1) key \rightarrow h(key)

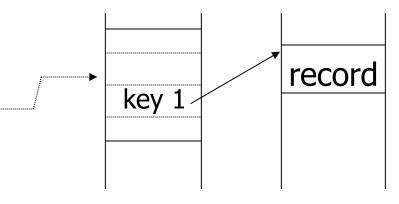






Two alternatives





Index

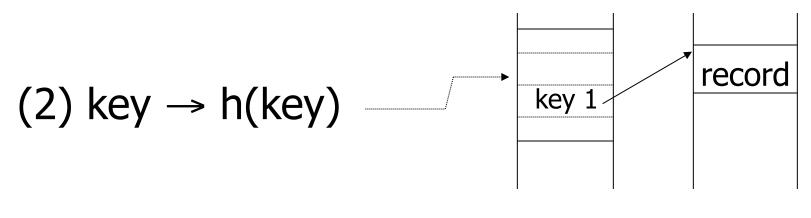


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Two alternatives



Index

• Alt (2) for "secondary" search key



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Notes 5 - Hashing



Example hash function

- Key = 'x₁ x₂ ... x_n' *n* byte character string
- Have *b* buckets
- h: add x₁ + x₂ + x_n
 - compute sum modulo b





➡ This may not be best function ...

Read Knuth Vol. 3 if you really need to select a good function.





➡ This may not be best function ...

Read Knuth Vol. 3 if you really need to select a good function.

Good hash See Expected number of function: keys/bucket is the same for all buckets



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Within a bucket:

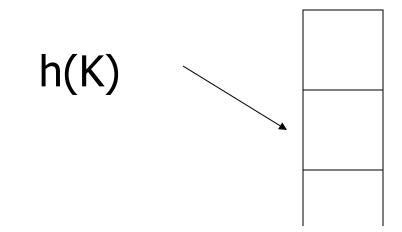
- Do we keep keys sorted?
- Yes, if CPU time critical
 & Inserts/Deletes not too frequent





<u>Next:</u> example to illustrate inserts,

overflows, deletes

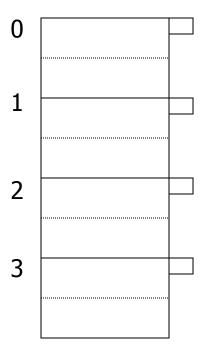






EXAMPLE 2 records/bucket

INSERT: h(a) = 1h(b) = 2h(c) = 1h(d) = 0

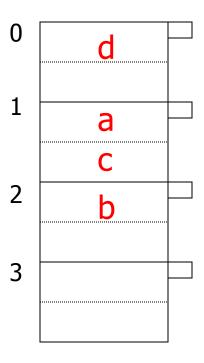






EXAMPLE 2 records/bucket

INSERT: h(a) = 1h(b) = 2h(c) = 1h(d) = 0h(e) = 1



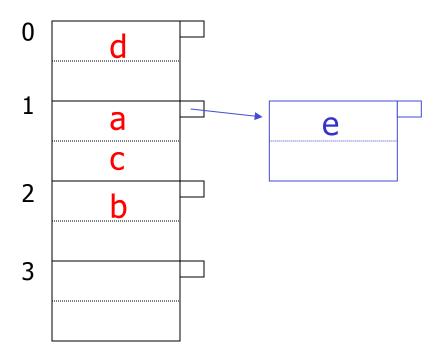






EXAMPLE 2 records/bucket

INSERT: h(a) = 1h(b) = 2h(c) = 1h(d) = 0h(e) = 1

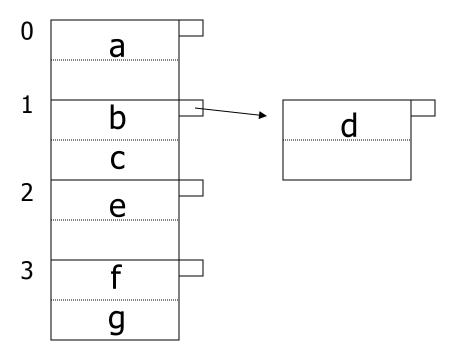






EXAMPLE: deletion

Delete: e f

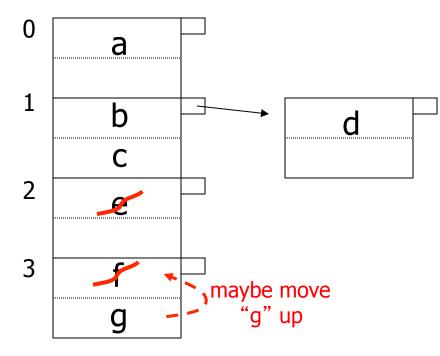






EXAMPLE: deletion

Delete: e f C



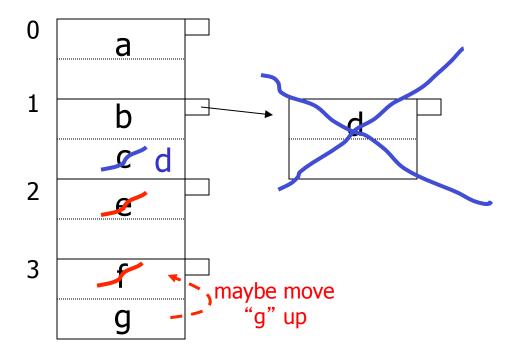


Notes 5 - Hashing



EXAMPLE: deletion

Delete: e f C





Notes 5 - Hashing



Rule of thumb:

 Try to keep space utilization
 between 50% and 80%
 Utilization = <u># keys used</u> total # keys that fit





Rule of thumb:

- Try to keep space utilization
 between 50% and 80%
 Utilization = <u># keys used</u> total # keys that fit
- If < 50%, wasting space
- If > 80%, overflows significant
 depends on how good hash function is & on # keys/bucket





How do we cope with growth?

- Overflows and reorganizations
 Dynamic hashing





How do we cope with growth?

- Overflows and reorganizations
 Dynamic hashing

- Extensible
 Linear





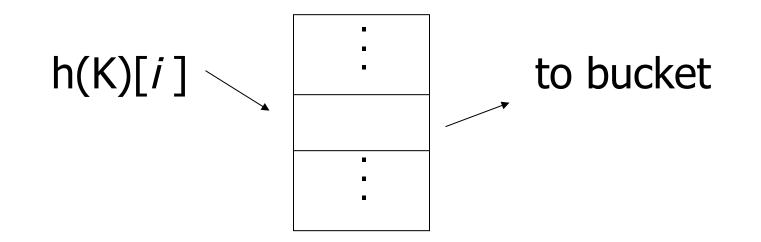
Extensible hashing: two ideas

(a) Use *i* of *b* bits output by hash function $\begin{array}{c} \leftarrow & b & \longrightarrow \\ h(K) \rightarrow & 00110101 \\ & & & \\ use i \rightarrow \text{ grows over time....} \end{array}$





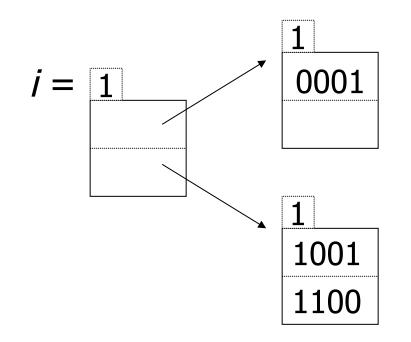
(b) Use directory







Example: h(k) is 4 bits; 2 keys/bucket

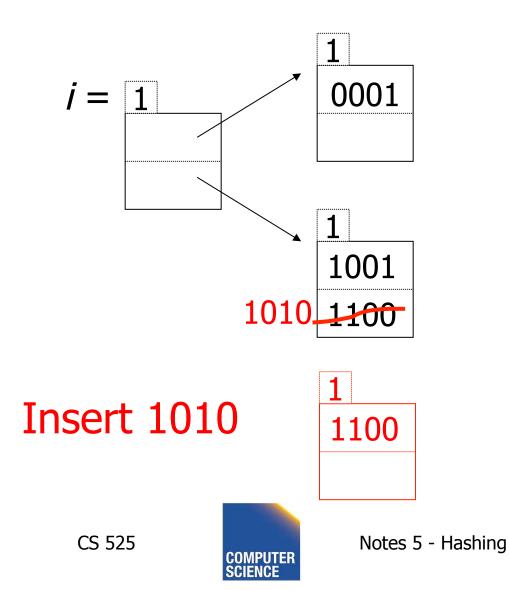


Insert 1010



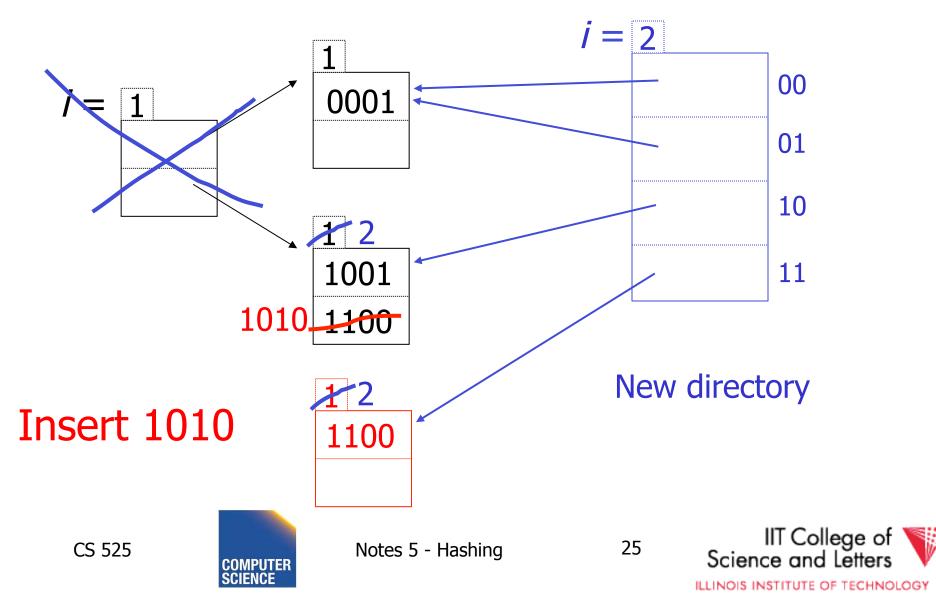


Example: h(k) is 4 bits; 2 keys/bucket

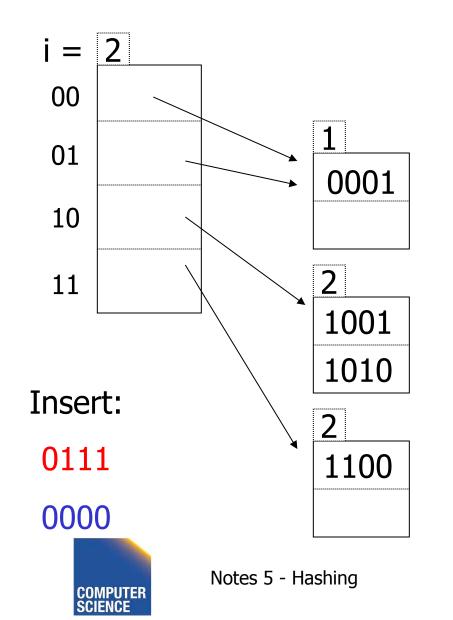




Example: h(k) is 4 bits; 2 keys/bucket

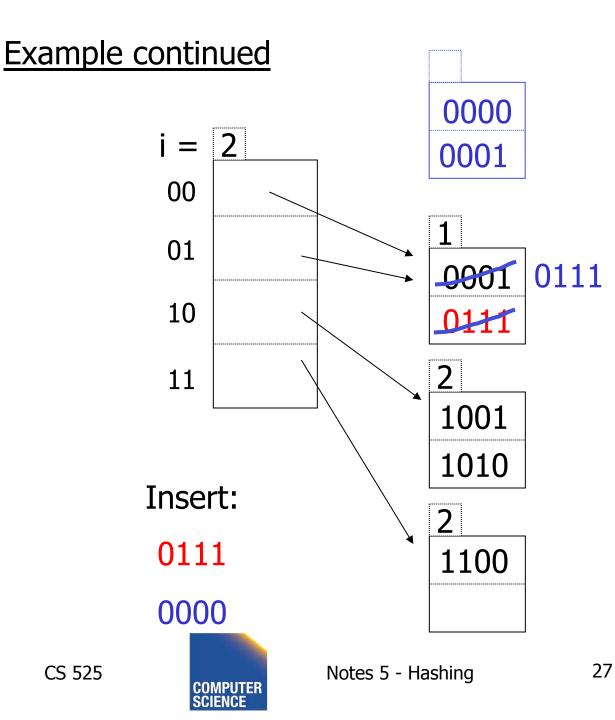


Example continued

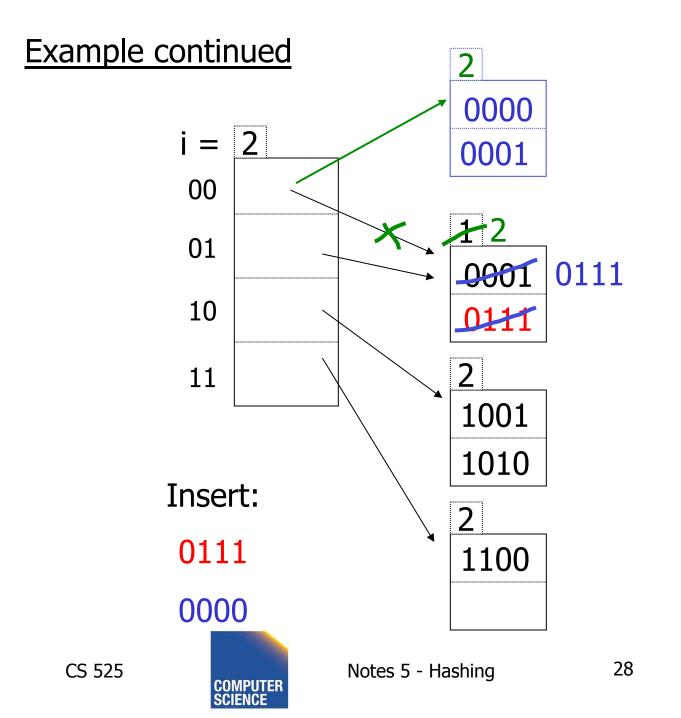


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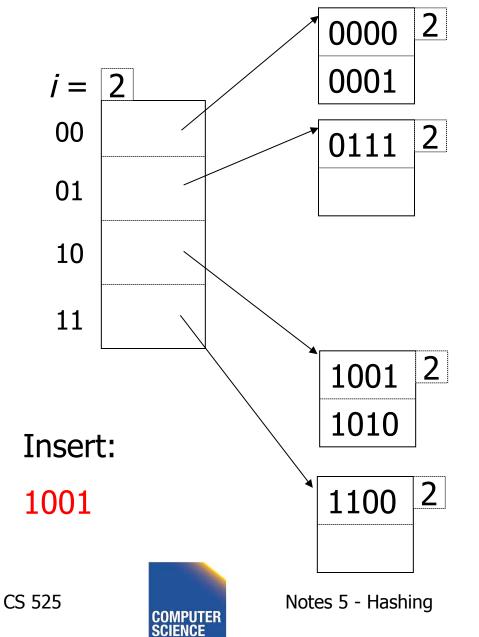






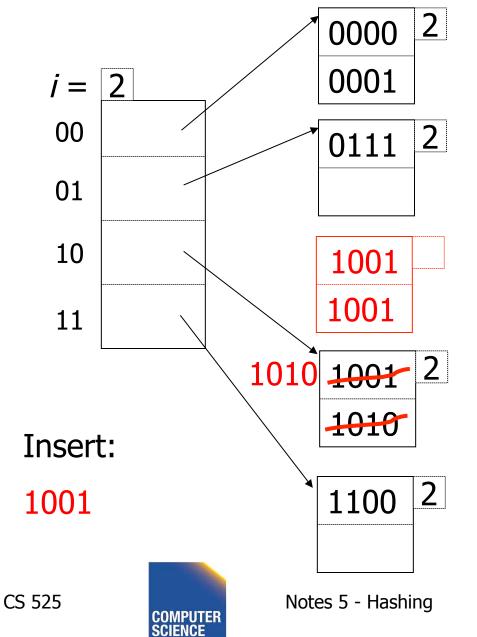


Example continued

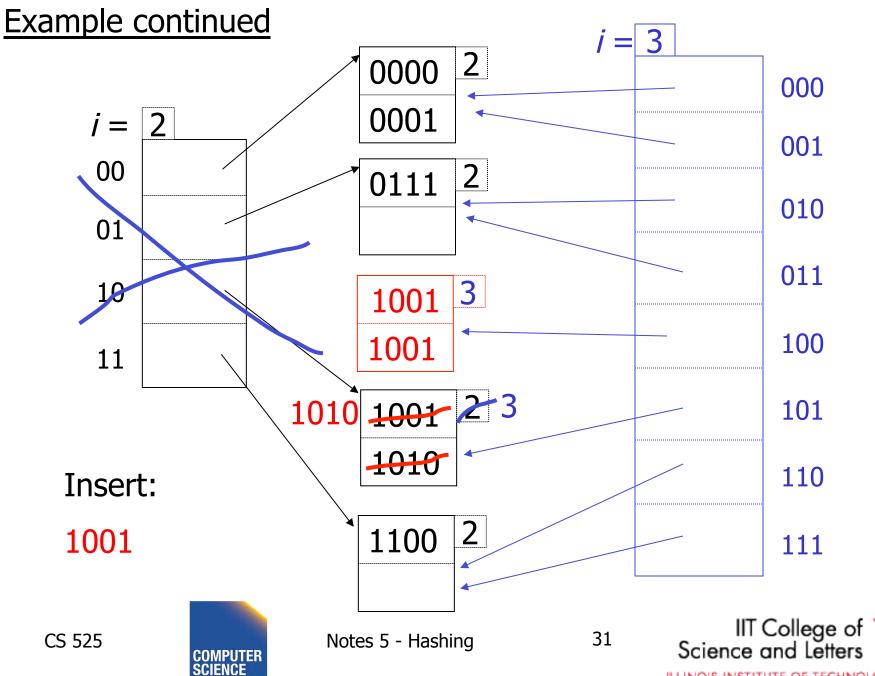


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Example continued



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Extensible hashing: <u>deletion</u>

- No merging of blocks
- Merge blocks and cut directory if possible (Reverse insert procedure)





Deletion example:

• Run thru insert example in reverse!



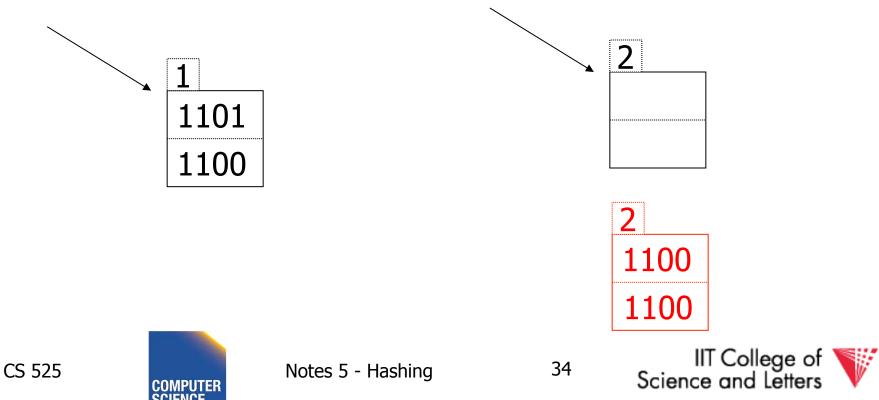


Note: Still need overflow chains

• Example: many records with duplicate keys

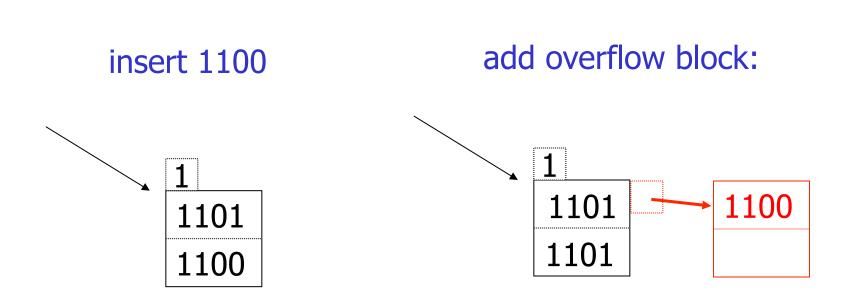
insert 1100

if we split:



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Solution: overflow chains







Summary Extensible hashing

+ Can handle growing files

- with less wasted space
- with no full reorganizations





Summary Extensible hashing

+ Can handle growing files

- with less wasted space
- with no full reorganizations

- Indirection

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(Not bad if directory in memory)

- Directory doubles in size

(Now it fits, now it does not)



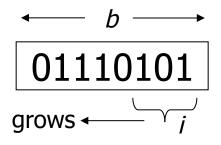


Linear hashing

Another dynamic hashing scheme

Two ideas:

(a) Use *i* low order bits of hash





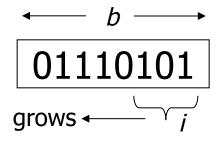


Linear hashing

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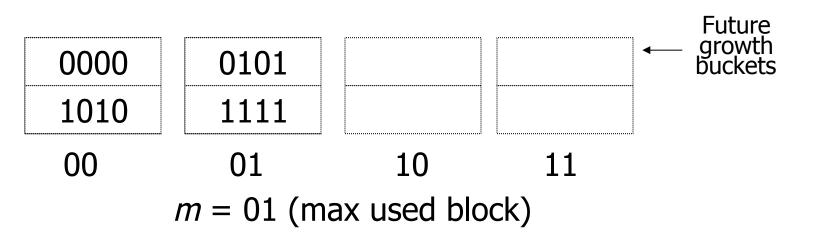


(b) File grows linearly



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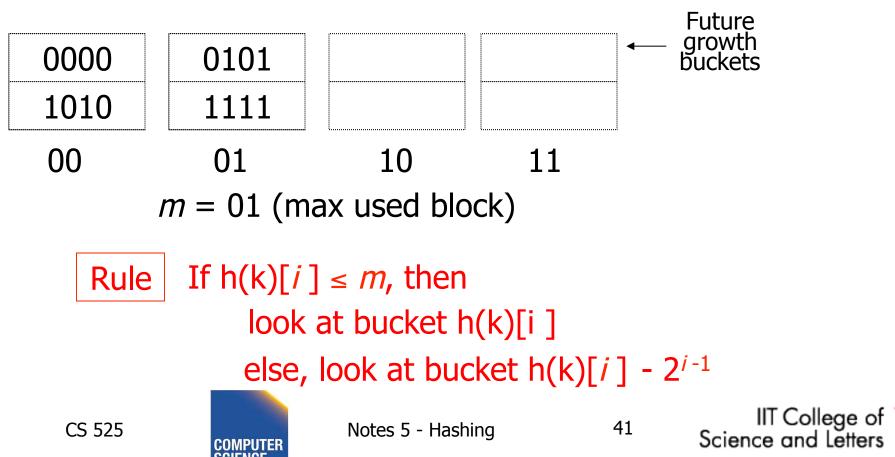




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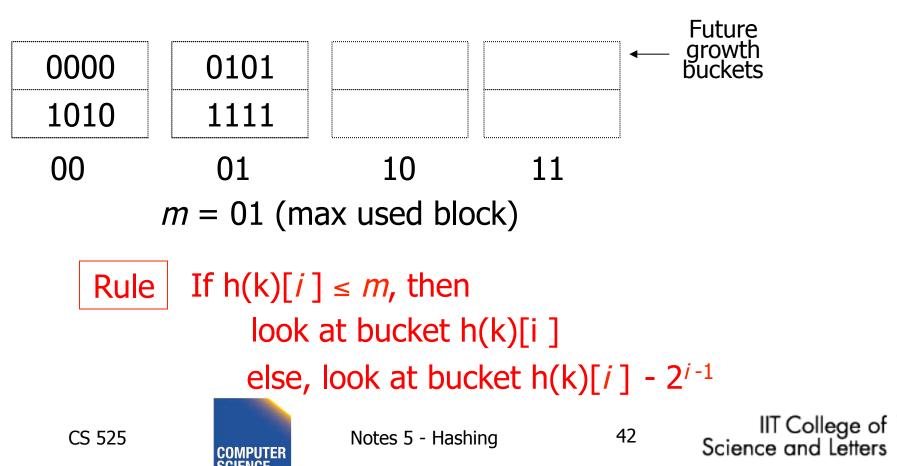
Notes 5 - Hashing



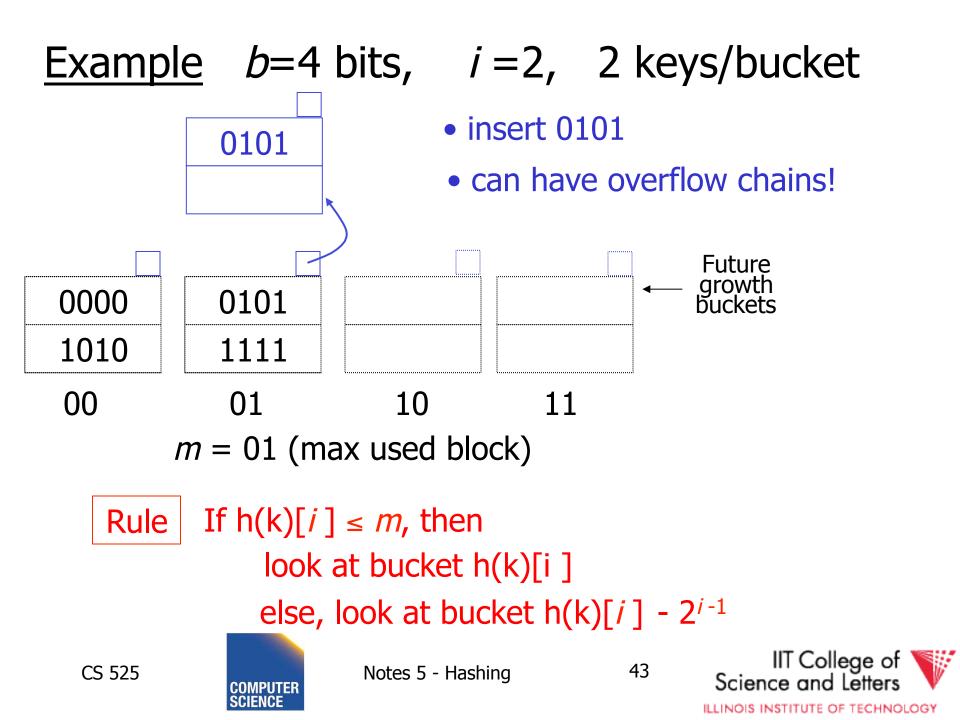


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• insert 0101

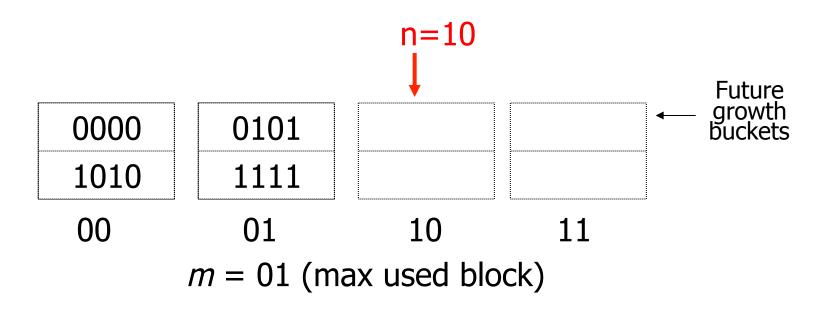


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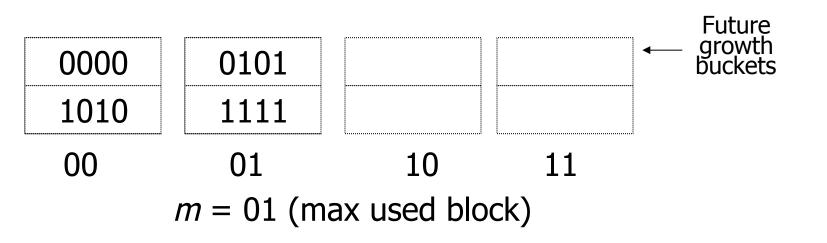
<u>Note</u>

- In textbook, n is used instead of m
- n=m+1





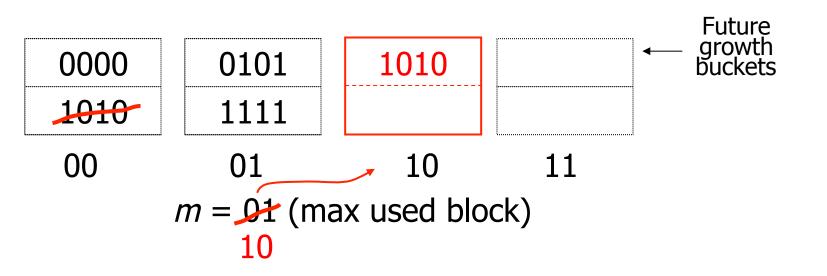






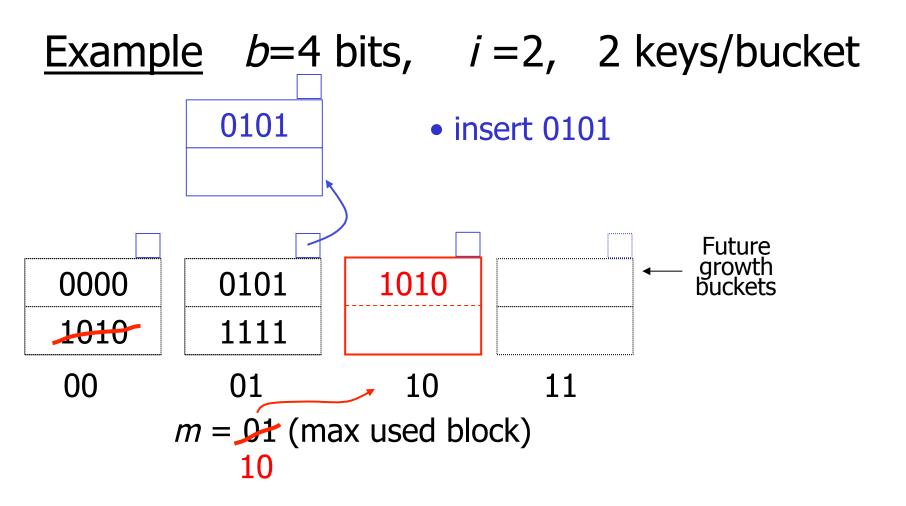
CS 525







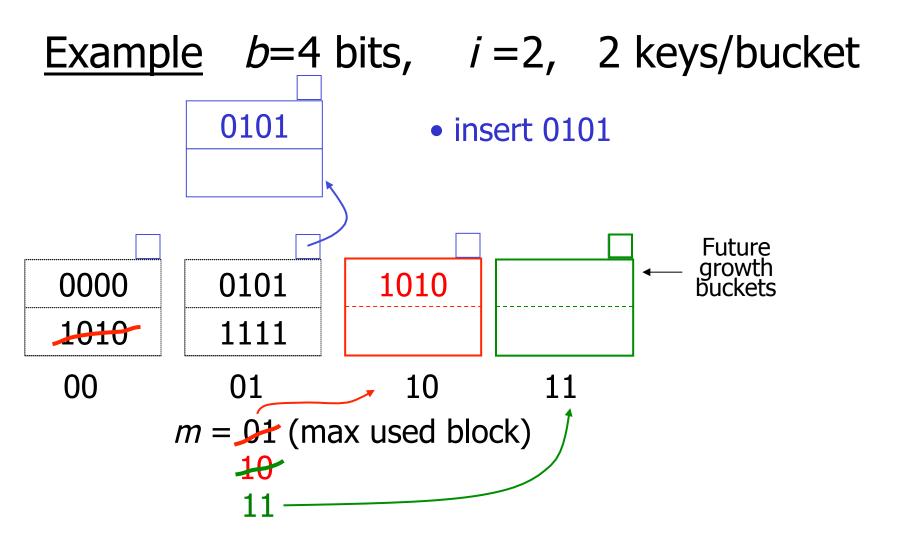






CS 525

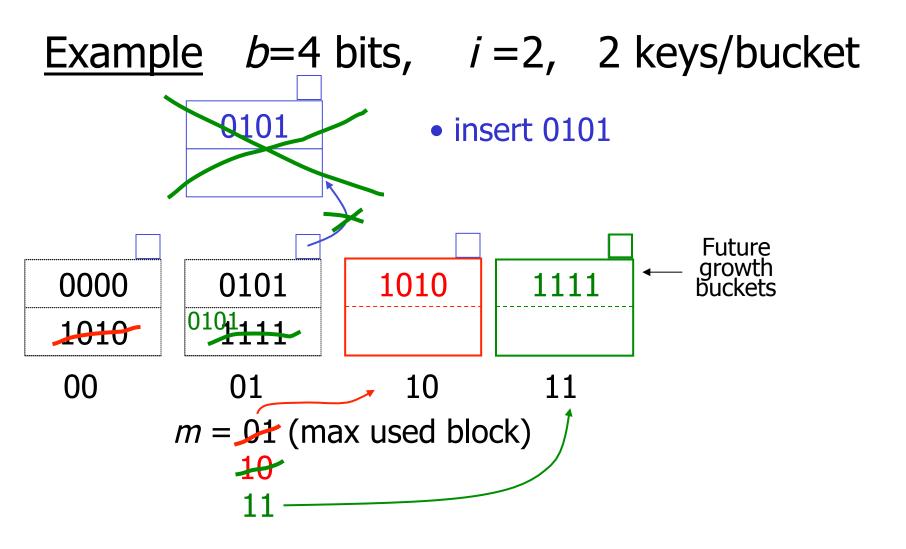






CS 525



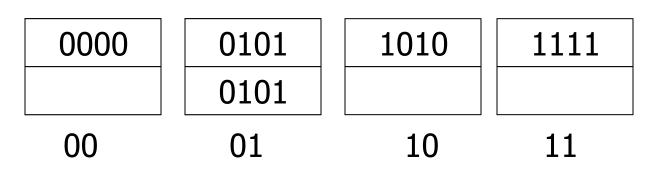




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i = 2

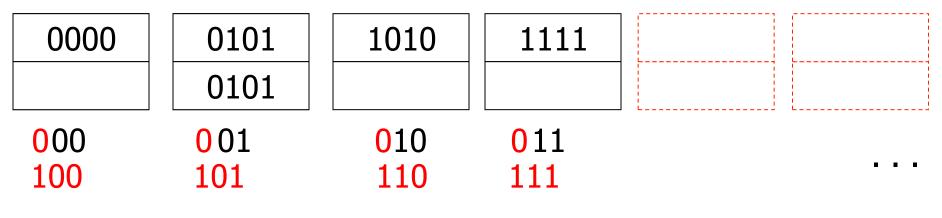


m = 11 (max used block)





i = 🔁 3

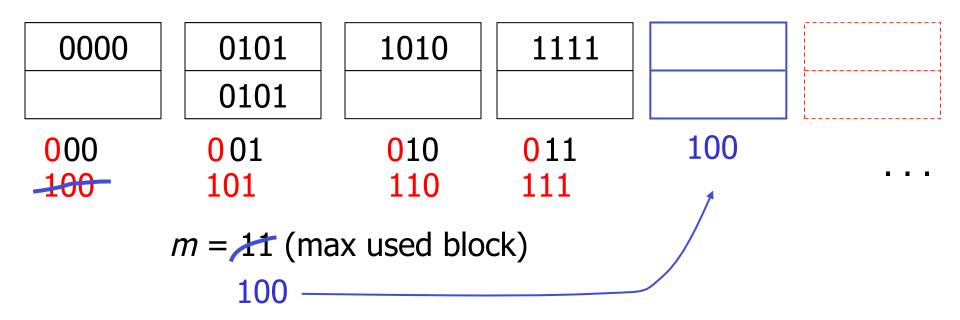


m = 11 (max used block)





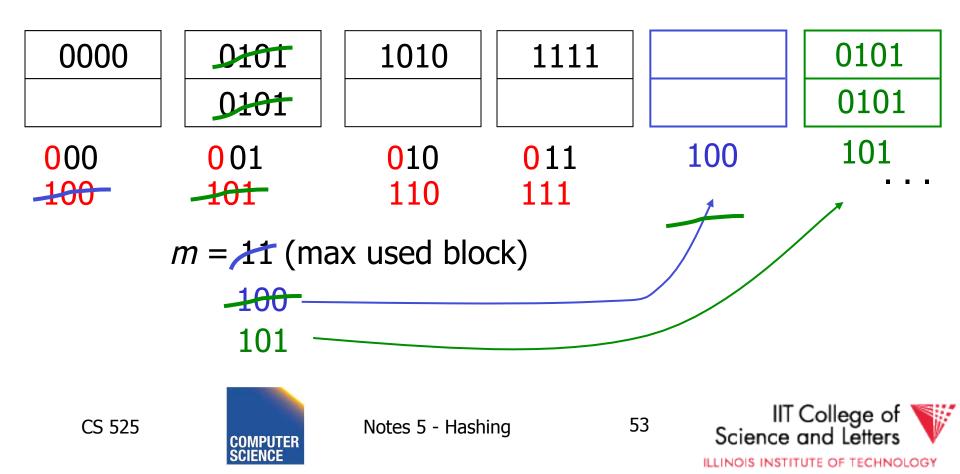
i = 🔁 3







i = 🔁 3



When do we expand file?

• Keep track of: <u># used slots</u> _ = U total # of slots



Notes 5 - Hashing

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When do we expand file?

• Keep track of: <u># used slots</u> _ = U total # of slots

 If U > threshold then increase m (and maybe i)



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Notes 5 - Hashing



Summary Linear Hashing

- Can handle growing files
 - with less wasted space
 - with no full reorganizations
 - No indirection like extensible hashing

Can still have overflow chains

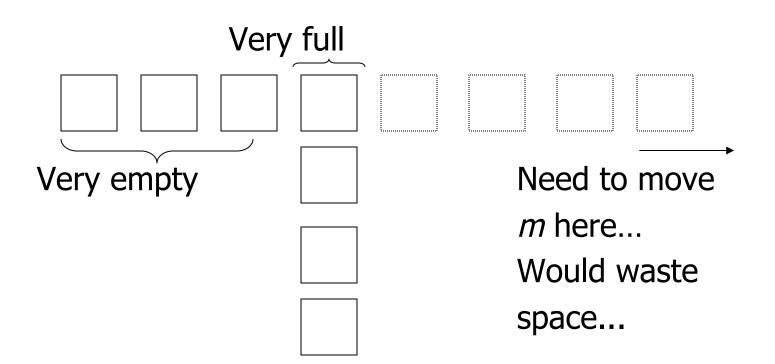


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Notes 5 - Hashing



Example: BAD CASE





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Notes 5 - Hashing



Summary

<u>Hashing</u>

- How it works
- Dynamic hashing
 - Extensible
 - Linear





Next:

- Indexing vs Hashing
- Index definition in SQL
- Multiple key access





Indexing vs Hashing

- Hashing good for probes given key

 e.g.,
 SELECT ...
 FROM R
 WHERE R.A = 5
- -> Point Queries



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Notes 5 - Hashing



Indexing vs Hashing

- INDEXING (Including B Trees) good for Range Searches:
 - e.g., SELECT

FROM R

WHERE R.A > 5

-> Range Queries

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Notes 5 - Hashing



Index definition in SQL

- <u>Create index name on rel (attr)</u>
- Create unique index name on rel (attr)

→ defines candidate key

• **Drop** INDEX name





Note CANNOT SPECIFY TYPE OF INDEX (e.g. B-tree, Hashing, ...) OR PARAMETERS (e.g. Load Factor, Size of Hash,...) ... at least in standard SQL...

Vendor specific extensions allow that



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Notes 5 - Hashing



Note ATTRIBUTE <u>LIST</u> \Rightarrow MULTIKEY INDEX (next) e.g., <u>CREATE INDEX</u> foo <u>ON</u> R(A,B,C)



Notes 5 - Hashing

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Multi-key Index

Motivation: Find records where DEPT = "Toy" AND SAL > 50k



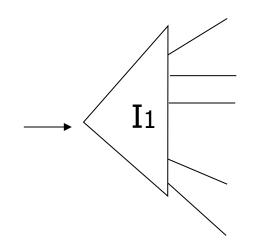
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Notes 5 - Hashing



Strategy I:

- Use one index, say Dept.
- Get all Dept = "Toy" records and check their salary

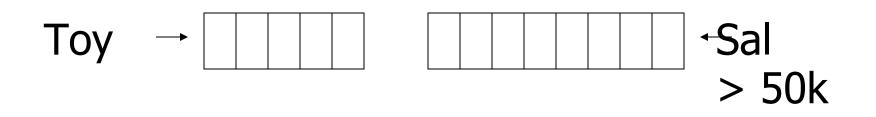






Strategy II:

• Use 2 Indexes; Manipulate Pointers



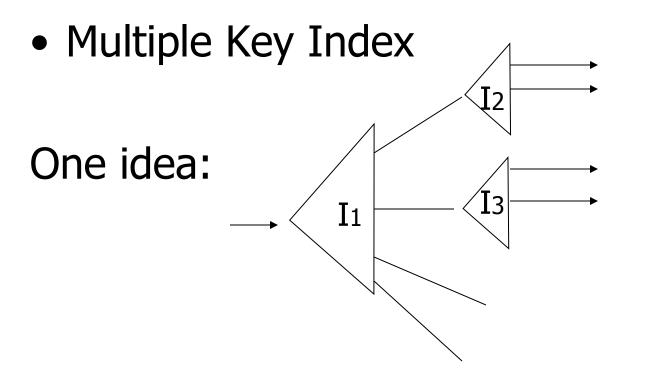


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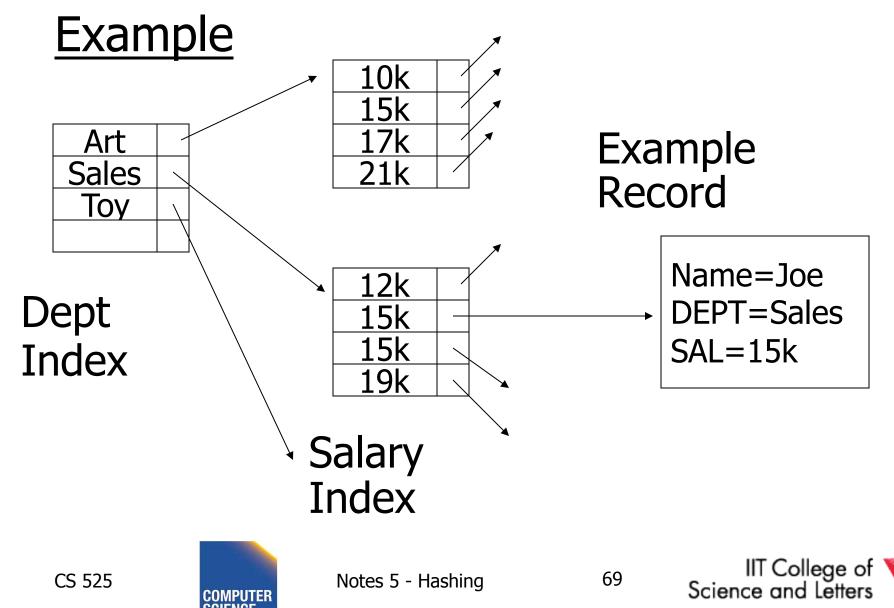


Strategy III:









For which queries is this index good?

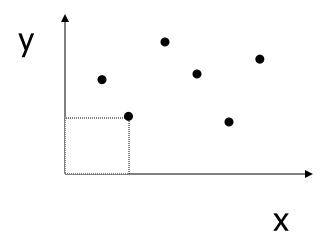
□ Find RECs Dept = "Sales" ∧ SAL=20k
□ Find RECs Dept = "Sales" ∧ SAL ≥ 20k
□ Find RECs Dept = "Sales"
□ Find RECs SAL = 20k





Interesting application:

• Geographic Data



DATA: <X1,Y1, Attributes> <X2,Y2, Attributes>



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Notes 5 - Hashing



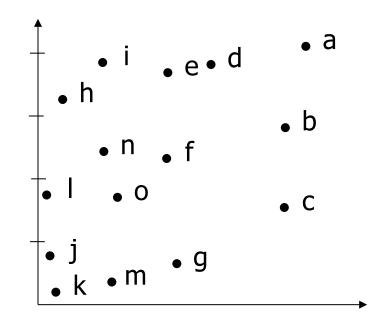
Queries:

- What city is at <Xi,Yi>?
- What is within 5 miles from <Xi,Yi>?
- Which is closest point to <Xi,Yi>?





Example





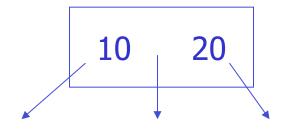
Notes 5 - Hashing

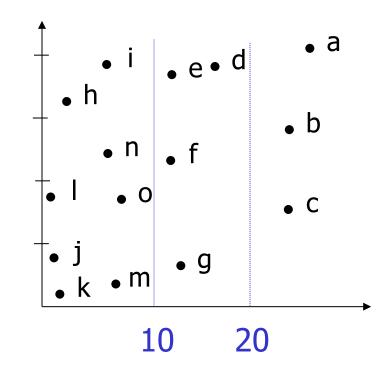
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Example

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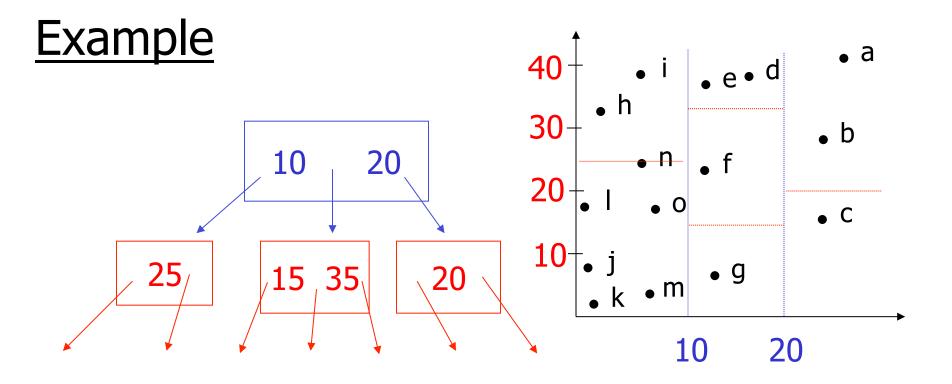


Notes 5 - Hashing

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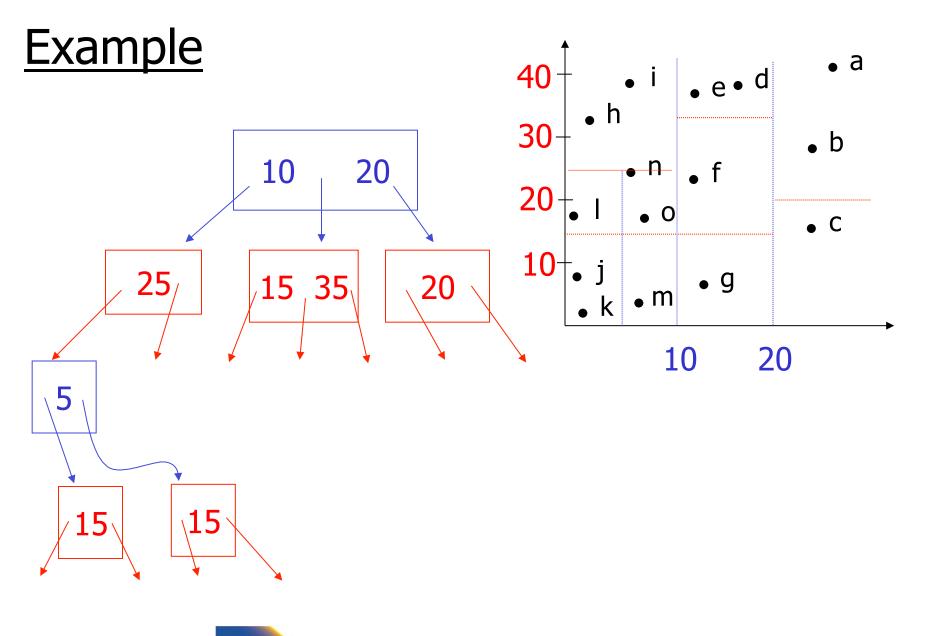




Notes 5 - Hashing

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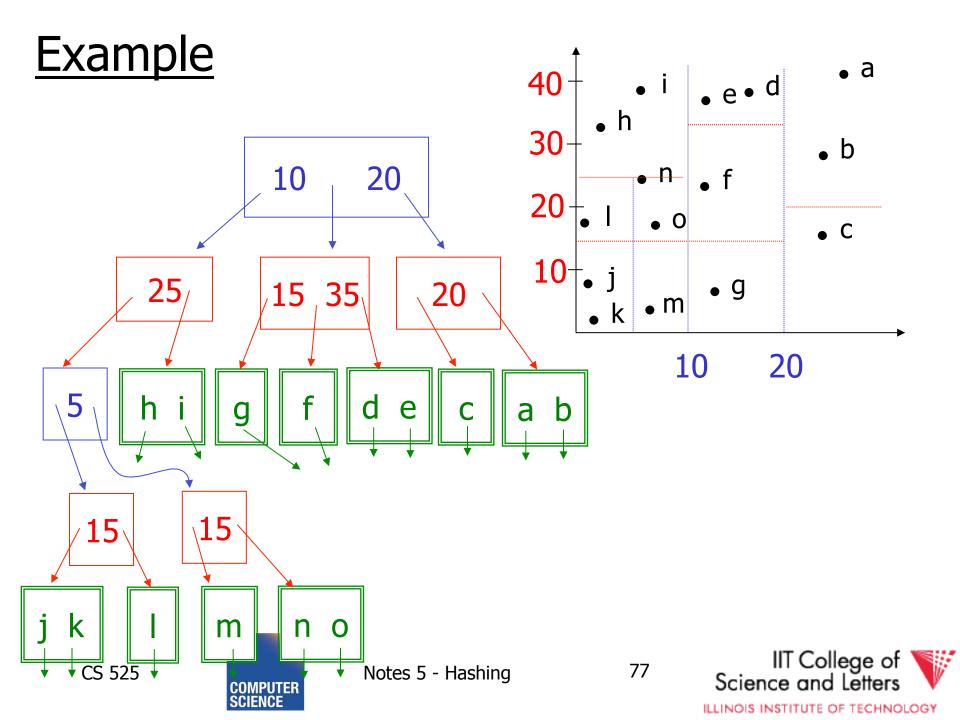


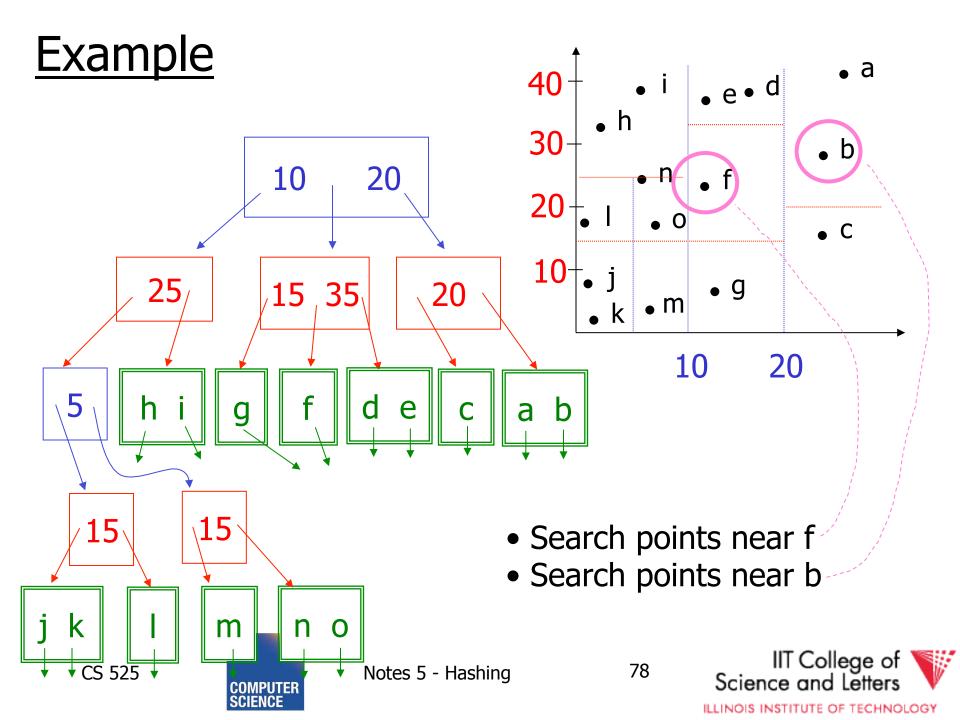




Notes 5 - Hashing







Queries

- Find points with Yi > 20
- Find points with Xi < 5
- Find points "close" to $i = \langle 12, 38 \rangle$
- Find points "close" to $b = \langle 7, 24 \rangle$





Next

• Even more index structures ③



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Notes 5 - Hashing

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CS 525: Advanced Database Organization 06: Even more index structures

Boris Glavic

Slides: adapted from a <u>course</u> taught by <u>Hector Garcia-Molina</u>, Stanford InfoLab





Notes 6 - More Indices

Recap

- We have discussed
 - Conventional Indices
 - B-trees
 - Hashing
 - Trade-offs
 - Multi-key indices
 - Multi-dimensional indices
 - ... but no example





Today

- Multi-dimensional index structures
 - kd-Trees (very similar to example before)
 - Grid File (Grid Index)
 - Quad Trees
 - R Trees
 - Partitioned Hash

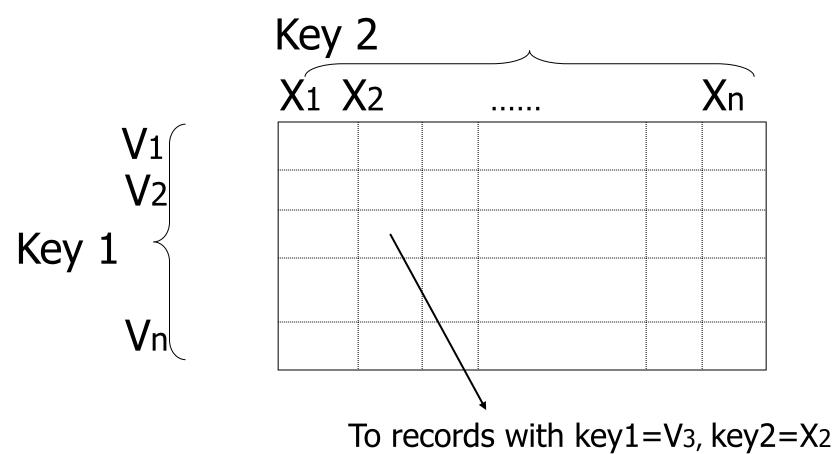
- ...

- Bitmap-indices
- Tries





Grid Index





Notes 5 - Hashing



<u>CLAIM</u>

Can quickly find records with

$$- \text{key } 1 = V_i \wedge \text{Key } 2 = X_i$$
$$- \text{key } 1 = V_i$$
$$- \text{key } 2 = X_j$$





<u>CLAIM</u>

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Can quickly find records with

$$- \text{key } 1 = V_i \wedge \text{Key } 2 = X_j$$
$$- \text{key } 1 = V_i$$
$$- \text{key } 2 = X_j$$

• And also ranges....

- E.g., key $1 \ge V_i \land key 2 < X_j$

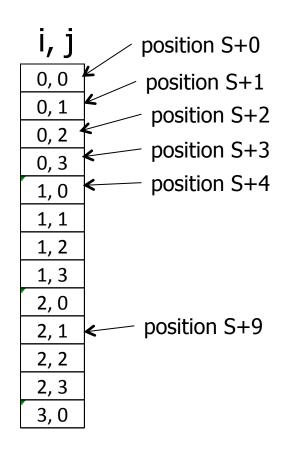




• How do we find entry i,j in linear structure?

max number of i values N=4

pos(i, j) =





Notes 5 - Hashing

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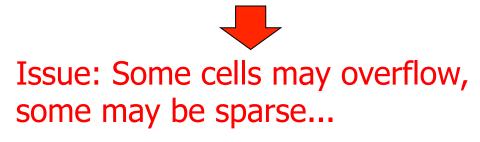


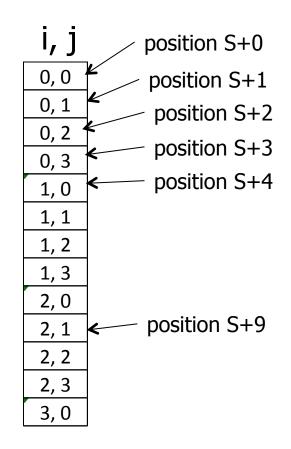
• How do we find entry i,j in linear structure?

max number of i values N=4

pos(i, j) = S + iN + j

Issue: Cells must be same size, and N must be constant!



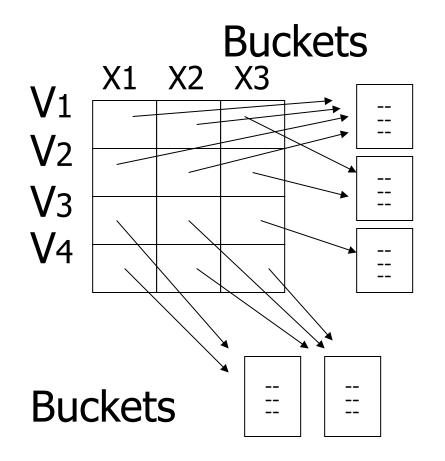




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Solution: Use Indirection



*Grid only contains pointers to buckets





With indirection:

- Grid can be regular without wasting space
- We do have price of indirection

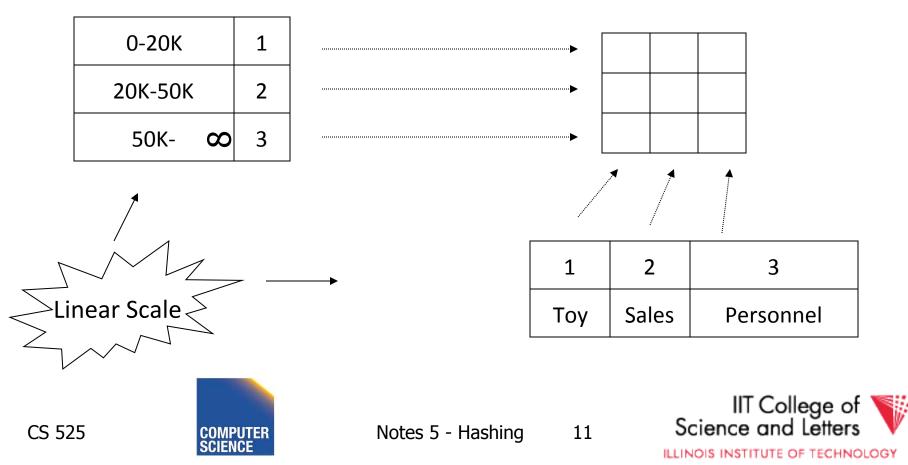


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Can also index grid on value ranges

Salary Grid



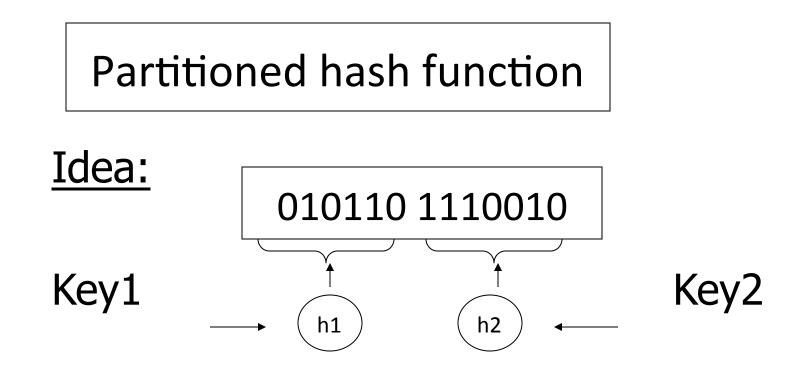


 Good for multiple-key search
 Space, management overhead (nothing is free)
 Need partitioning ranges that evenly split keys



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h1(toy) =0	000
h1(sales) = 1	001
h1(art) =1	010
	011
•	100
h2(10k) =01	101
h2(20k) =11	110
h2(30k) =01	111

h2(40k) =00

Insert

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<Fred,toy,10k>,<Joe,sales,10k> <Sally,art,30k>





h1(toy) =	0 0)00	
h1(sales) =	1 0	001 <fred></fred>	
h1(art) =	ſ	010	
iii (ai c)	C)11	
		.00	
		.01 <joe><sally></sally></joe>	
		.10	
h2(30k) =	01]	.11	
	• •		

h2(40k) =00

<Fred,toy,10k>,<Joe,sales,10k>





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h1(toy)	=0	000	<fred></fred>
h1(sales)	=1	001	<joe><jan></jan></joe>
h1(art)	=1	010	<mary></mary>
III (arc)	-	011	
	•	100	<sally></sally>
h2(10k)	=01	101	
h2(20k)	=11	110	<tom><bill></bill></tom>
h2(30k)	=01	111	<andy></andy>
h2(40k)	=00		

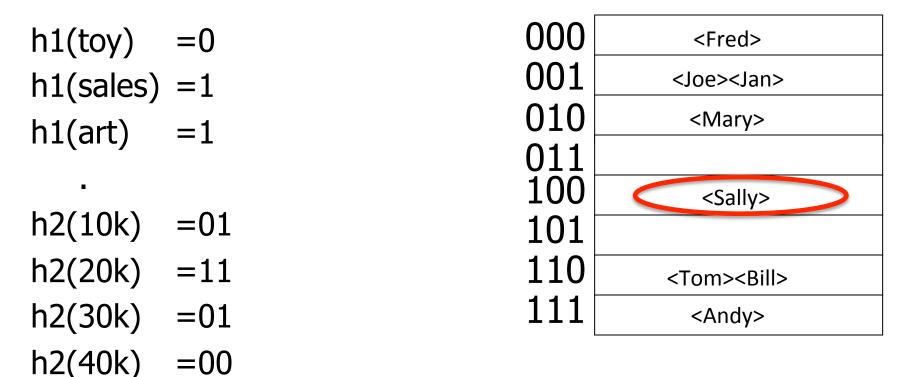
Find Emp. with Dept. = Sales \land Sal=40k



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Find Emp. with Dept. = Sales \land Sal=40k





h2(40k)

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h1(toy)	=0	000	<fred></fred>
h1(sales)	=1	001	<joe><jan></jan></joe>
	=1	010	<mary></mary>
	-	011	
•	•	100	<sally></sally>
h2(10k)	=01	101	
h2(20k)	=11	110	<tom><bill></bill></tom>
h2(30k)	=01	111	<andy></andy>

Find Emp. with Sal=30k



=00



EX:

h1(toy) =0 h1(sales) = 1h1(art) =1 h2(10k) =01h2(20k) = 11h2(30k) = 01h2(40k)

000 <Fred> 001 <Joe><Jan> 010 <Mary> 011 100 <Sally> 101 110<Tom><Bill> 111<Andy>

Find Emp. with Sal=30k



=00

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h1(toy)	=0	000	<fred></fred>
h1(sales)	=1	001	<joe><jan></jan></joe>
h1(art)	=1	010	<mary></mary>
in t (ar c)	-	011	
•		100	<sally></sally>
h2(10k)	=01	101	
h2(20k)	=11	110	<tom><bill></bill></tom>
h2(30k)	=01	111	<andy></andy>
h2(40k)	=00		

Find Emp. with Dept. = Sales



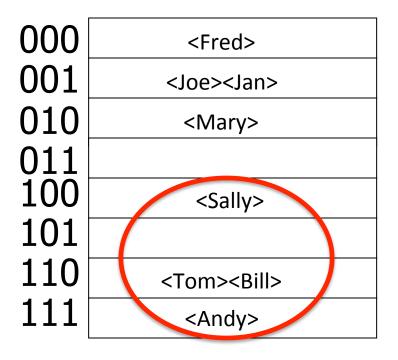


<u>EX:</u>

h1(toy) = 0 h1(sales) = 1 h1(art) = 1 . h2(10k) = 01 h2(20k) = 11h2(30k) = 01

h2(40k)

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Find Emp. with Dept. = Sales



=00

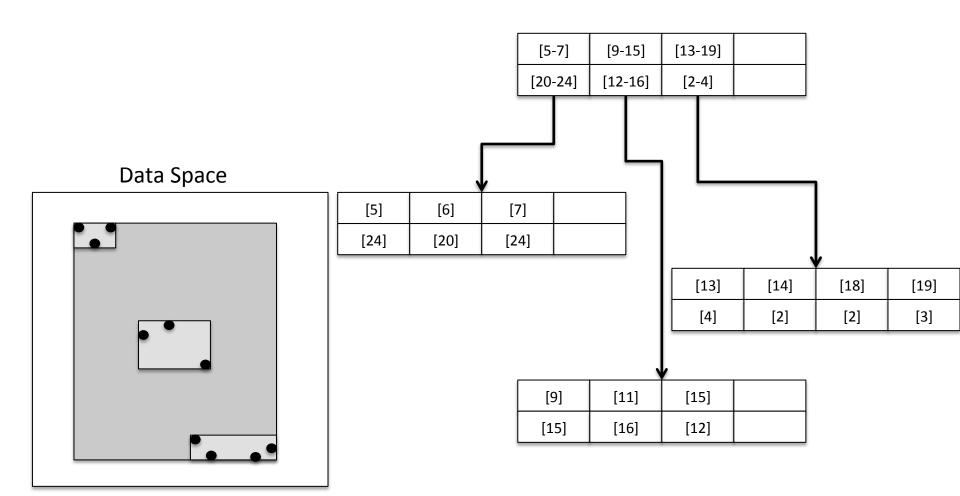


R-tree

- Nodes can store up to M entries
 Minimum fill requirement (depends on variant)
- Each node rectangle in **n**-dimensional space
 - Minimum Bounding Rectangle (MBR) of its children
- MBRs of siblings are allowed to overlap
 Different from B-trees
- balanced





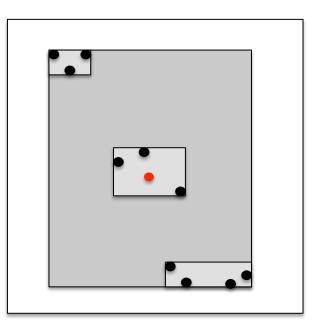






R-tree - Search

- Point Search
 - Search for $p = \langle x_i, y_i \rangle$
 - Keep list of potential nodes
 - Needed because of overlap
 - Traverse to child if MBR of child contains p

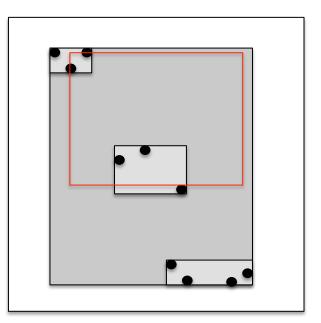






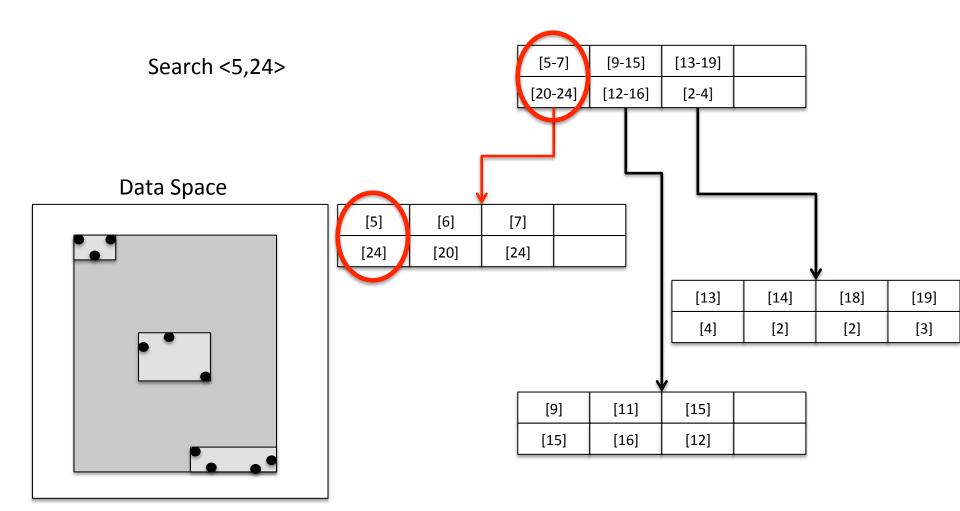
R-tree - Search

- Point Search
 - Search for points in region =
 - <[x_{min}- x_{max}], [y_{min} -y_{max}]>
 - Keep list of potential nodes
 - Traverse to child if MBR of child overlaps with query region













R-tree - Insert

- Similar to B-tree, but more complex
 - Overlap -> multiple choices where to add entry
 - Split harder because more choice how to split node (compare B-tree = 1 choice)
- 1) Find potential subtrees for current node
 - Choose one for insert (heuristic, e.g., the one the would grow the least)
 - Continue until leaf is found





R-tree - Insert

- 2) Insert into leaf
- 3) Leaf is full? -> split
 - Find best split (minimum overlap between new nodes) is hard (O(2^M))
 - Use linear or quadratic heuristics (original paper)
- 4) Adapt parents if necessary





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R-tree - Delete

- 1) Find leaf node that contains entry
- 2) Delete entry
- 3) Leaf node underflow?
 - Remove leaf node and cache entries
 - Adapt parents
 - Reinsert deleted entries





Bitmap Index

Domain of values D = {d₁, ..., d_n}

– Gender {male, female}

- Age {1, ..., 120?}

- Use one vector of bits for each value
 - One bit for each record
 - 0: record has different value in this attribute
 - 1: record has this value





Bitmap Index Example

Age

1	2	3
1	0	0
0	1	0
1	0	0
0	0	1

Todlers

Name	Age	Gender
Peter	1	male
Gertrud	2	female
Joe	1	male
Marry	3	female

Gender

male	female
1	0
0	1
1	0
0	1





Bitmap Index Example

ļ	Age			Todlers			Ger	nder
1	2	3		Name	Age	Gender	male	female
1	0	0		Peter	1	male	1	0
0	1	0		Gertrud	2	female	0	1
1	0	0		Joe	1	male	1	0
0	0	1		Marry	3	female	0	1

Find all todlers with age **2** and sex female: Bitwise-and between vectors





0

1

0

Bitmap Index Example

ŀ	Age			Todlers			Gei	nder
1	2	3		Name	Age	Gender	male	female
1	0	0		Peter	1	male	1	0
0	1	0		Gertrud	2	female	0	1
1	0	0		Joe	1	male	1	0
0	0	1		Marry	3	female	0	1

Find all todlers with age **2 or** sex **female**: Bitwise-or between vectors



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0

1

0

Compression

- Observation:
 - Each record has one value in indexed attribute
 - For N records and domain of size |D|
 - Only 1/|D| bits are 1
 - -> waste of space
- Solution
 - Compress data
 - Need to make sure that and and or is still fast





Run length encoding (RLE)

- Instead of actual 0-1 sequence encode length of 0 or 1 runs
- One bit to indicate whether 0/1 run + several bits to encode run length
- But how many bits to use to encode a run length?
 - Gamma codes or similar to have variable number of bits





RLE Example

- 0001 0000 1110 1111 (2 bytes)
- 3, 1,4, 3, 1,4 (6 bytes)
- -> if we use one byte to encode a run we have
 7 bits for length = max run length is 128(127)





Elias Gamma Codes

• $X = 2^{N} + (x \mod 2^{N})$

- Write N as N zeros followed by one 1

- Write (x mod 2^N) as N bit number
- $18 = 2^4 + 2 = 000010010$
- 0001 0000 1110 1111 (2 bytes)
- 3, 1,4, 3, 1,4
- **0111 0010 0**011 **1**001 00



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(6 bytes)

(3 bytes)



Hybrid Encoding

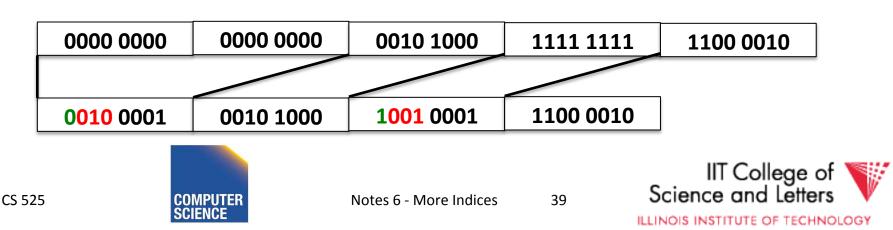
- Run length encoding
 - Can waste space
 - And/or run length not aligned to byte/word boundaries
- Encode some bytes of sequence as is and only store long runs as run length
 - EWAH
 - BBC (that's what Oracle uses)





Extended Word aligned Hybrid (EWAH)

- Segment sequence in machine words (64bit)
- Use two types of words to encode
 - Literal words, taken directly from input sequence
 - Run words
 - ¹/₂ word is used to encode a run
 - ¹/₂ word is used to encode how many literals follow



Bitmap Indices

- Fast for read intensive workloads
 Used a lot in datawarehousing
- Often build on the fly during query processing

As we will see later in class



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Trie

- From Retrieval
- Tree index structure
- Keys are sequences of values from a domain D
 D = {0,1}
 D = {a,b,c,...,z}
- Key size may or may not be fixed
 - Store 4-byte integers using D = {0,1} (32 elements)
 - Strings using D={a,...,z} (arbitrary length)





Trie

- Each node has pointers to |D| child nodes
 One for each value of D
- Searching for a key k = [d₁, ..., d_n]
 - Start at the root
 - Follow child for value d_i

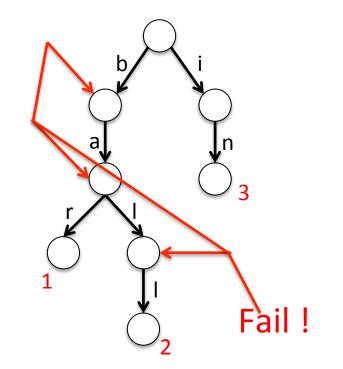




Trie Example

Words: bar, ball, in

Search for **bald**





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Tries Implementation

- 1) Each node has an array of child pointers
- 2) Each node has a list or hash table of child pointers
- 3) array compression schemes derived from compressed DFA representations



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Summary

Discussion:

- Conventional Indices
- B-trees
- Hashing (extensible, linear)
- SQL Index Definition
- Index vs. Hash
- Multiple Key Access
- Multi Dimensional Indices Variations: Grid, R-tree,
- Partitioned Hash
- Bitmap indices and compression
- Tries

CS 525





CS 525: Advanced Database Organisation



CS 525

07: Query Processing Overview

Boris Glavic

Slides: adapted from a <u>course</u> taught by <u>Hector Garcia-Molina</u>, Stanford InfoLab





Query Processing

$Q \rightarrow Query Plan$



Notes 7 - Query Processing



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Query Processing

$Q \rightarrow Query Plan$

Focus: Relational Systems

• Others?





Example

Select B,D From R,S Where R.A = "c" \land S.E = 2 \land R.C=S.C

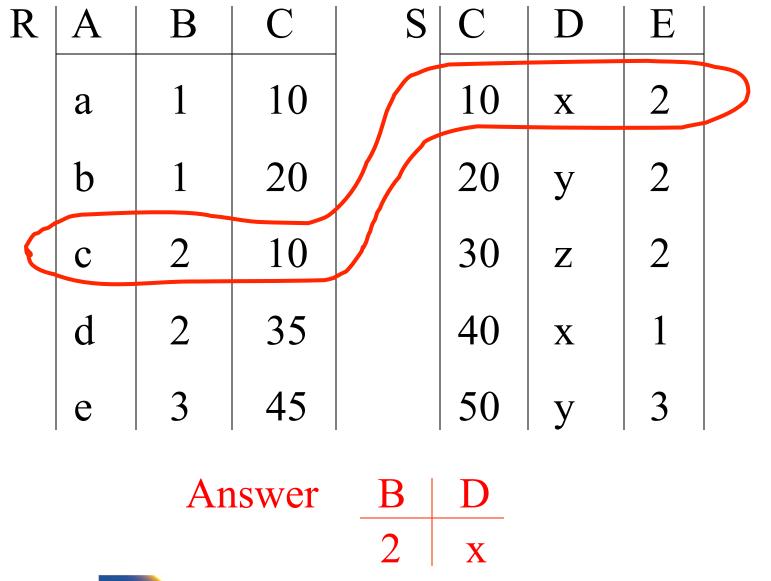




R	A	В	С	S	С	D	E
	a	1	10		10	X	2
	b	1	20		20	У	2
	c	2	10		30	Ζ	2
	d	2	35		40	X	1
	e	3	45		50	У	3









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Notes 7 - Query Processing

6 Science and Letters

• How do we execute query?



- Do Cartesian product
- Select tuples
- Do projection



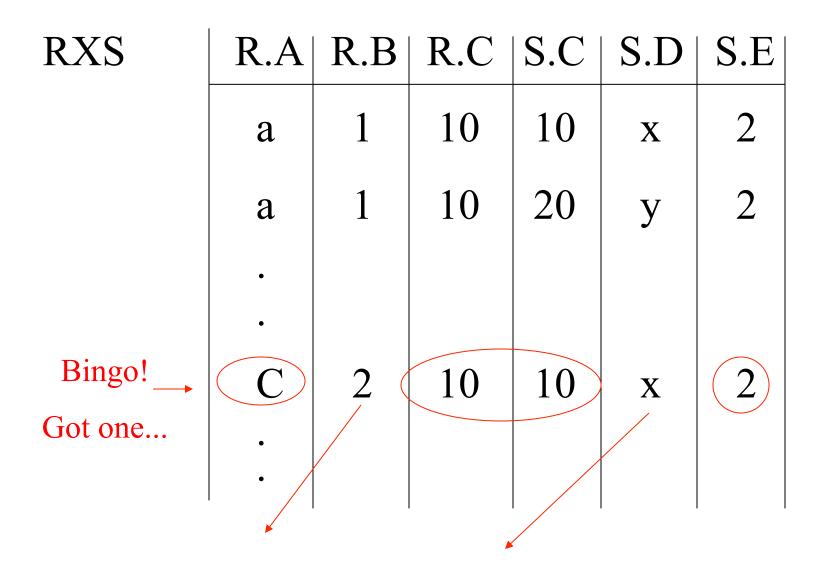


RXS

R.A	R.B	R.C	S.C	S.D	S.E
a	1	10	10	X	2
a	1	10	20	У	2
•					
•					
C	2	10	10	X	2
•					
•					









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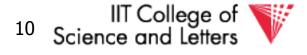


Relational Algebra - can be used to describe plans... Ex: Plan I $\Pi_{\mathsf{B},\mathsf{D}}$ $O_{R.A="c" \land S.E=2 \land R.C=S.C}$

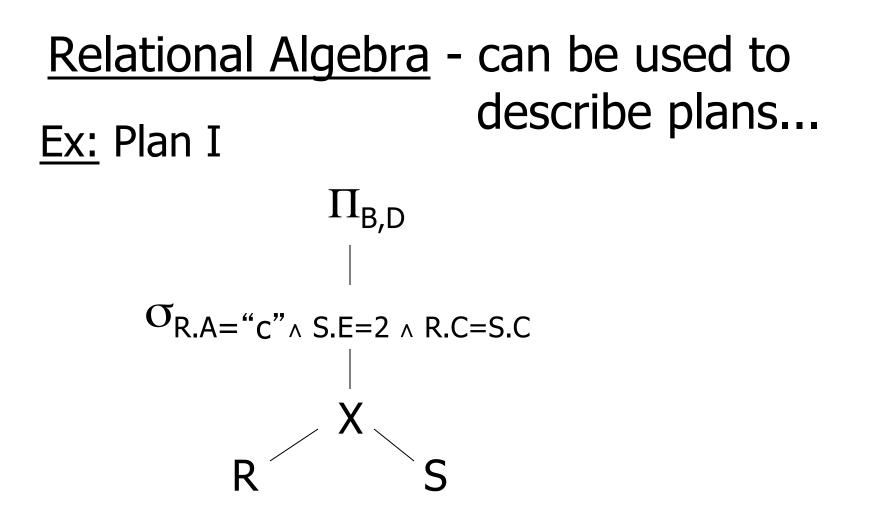


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Notes 7 - Query Processing



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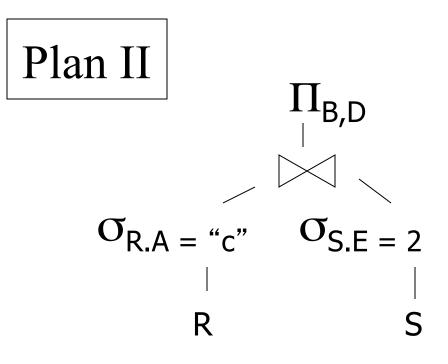
<u>OR:</u> $\Pi_{B,D}$ [$\sigma_{R,A="c" \land S,E=2 \land R,C=S,C}$ (RXS)]



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Another idea:



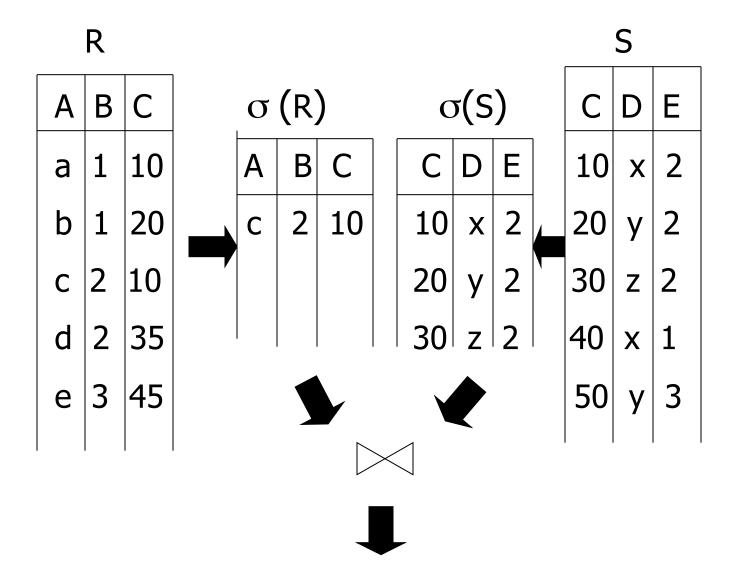


natural join



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Notes 7 - Query Processing



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<u>Plan III</u>

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Use R.A and S.C Indexes (1) Use R.A index to select R tuples with R.A = "c" (2) For each R.C value found, use S.C index to find matching tuples





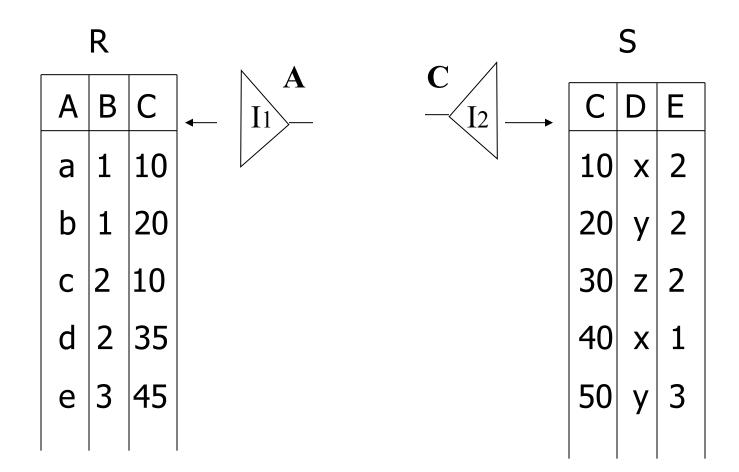
<u>Plan III</u>

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Use R.A and S.C Indexes (1) Use R.A index to select R tuples with $R_{A} = c^{*}$ (2) For each R.C value found, use S.C index to find matching tuples (3) Eliminate S tuples S.E \neq 2 (4) Join matching R,S tuples, project B,D attributes and place in result

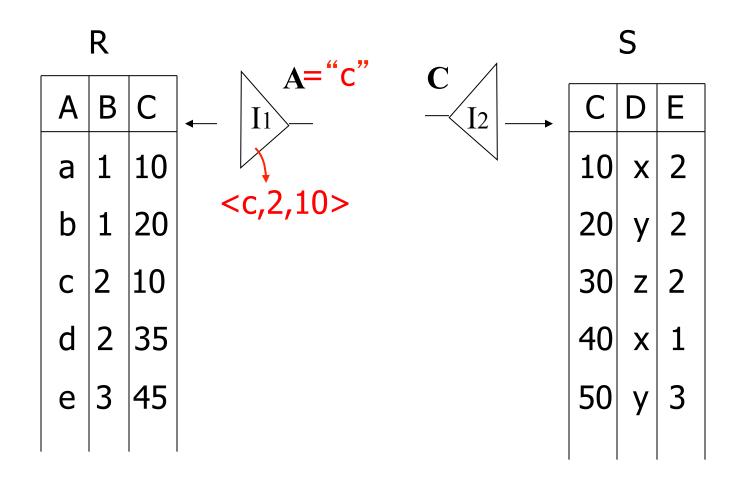






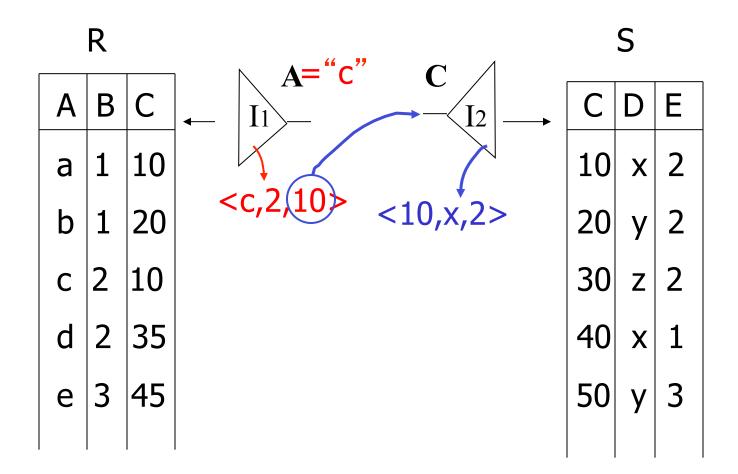






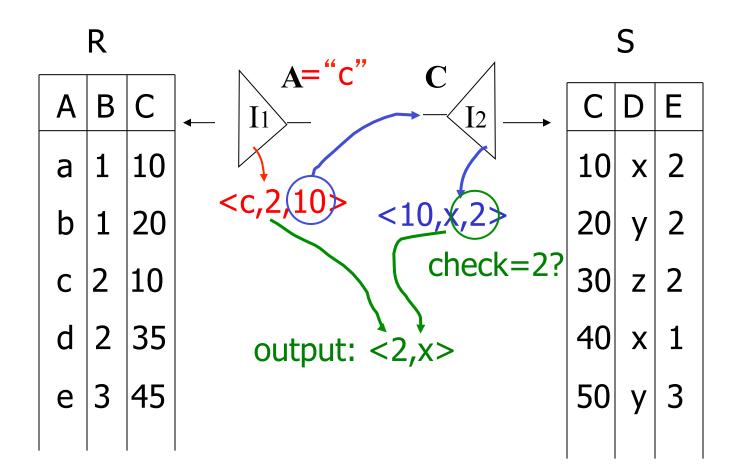






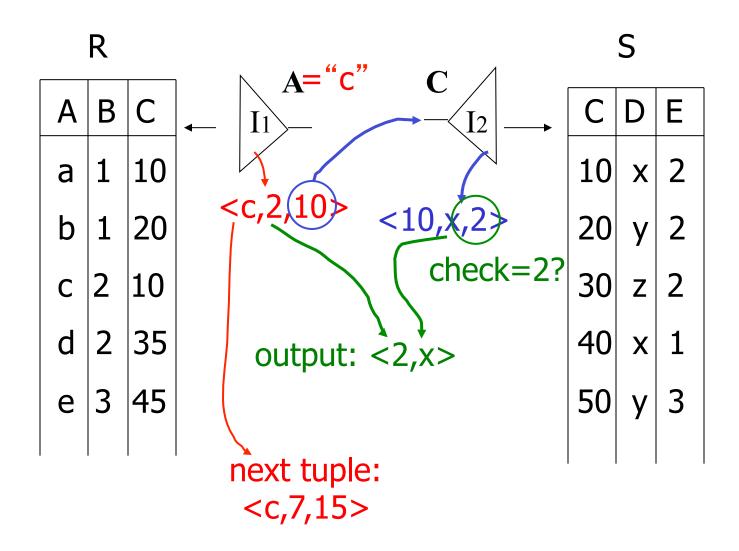














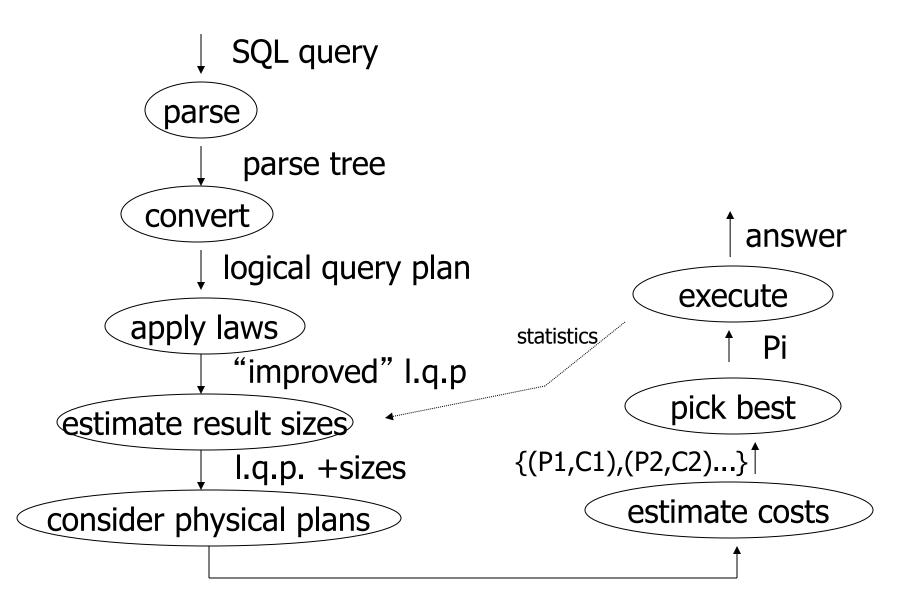


Overview of Query Optimization



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{P1,P2,....}

Notes 7 - Query Processing



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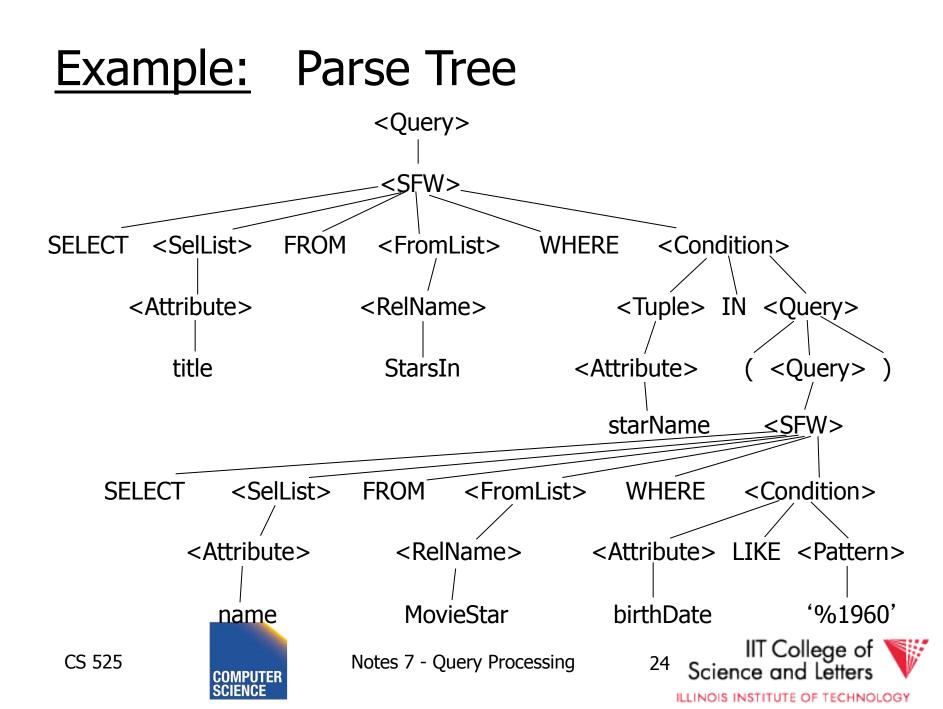
SELECT title FROM StarsIn WHERE starName IN (SELECT name FROM MovieStar WHERE birthdate LIKE '%1960');

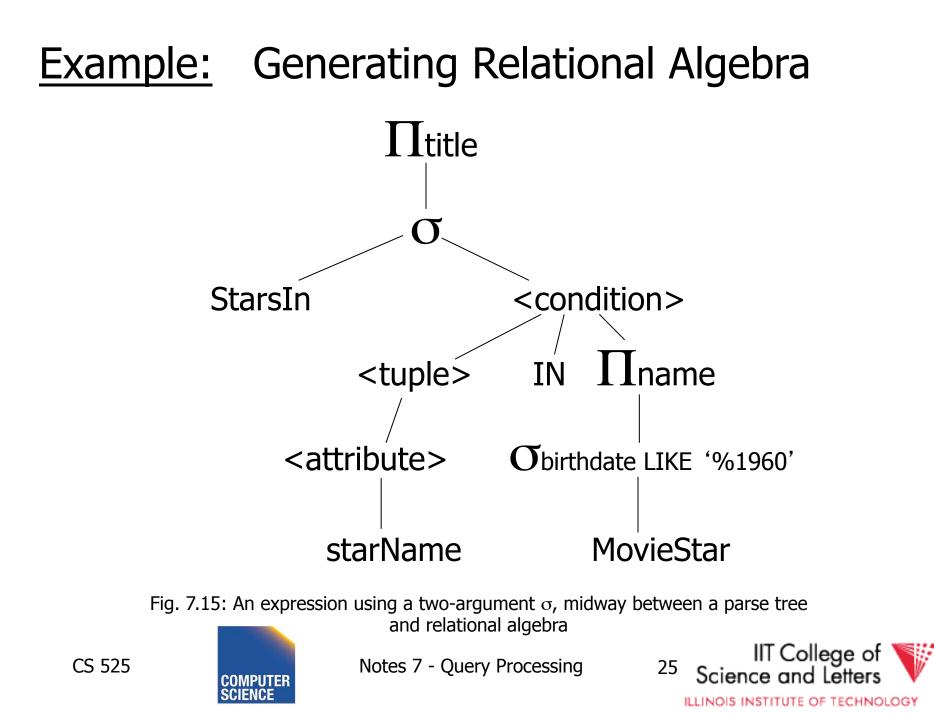
(Find the movies with stars born in 1960)



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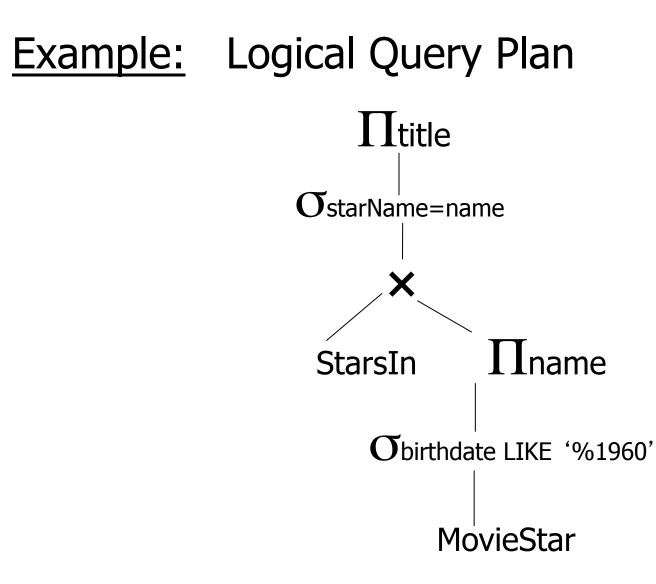


Fig. 7.18: Applying the rule for IN conditions



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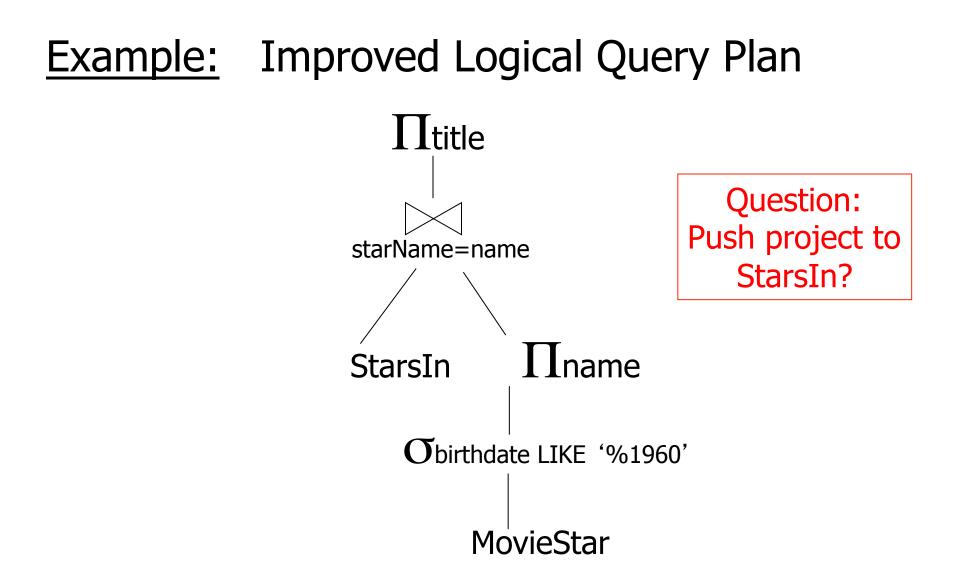
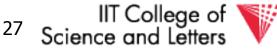


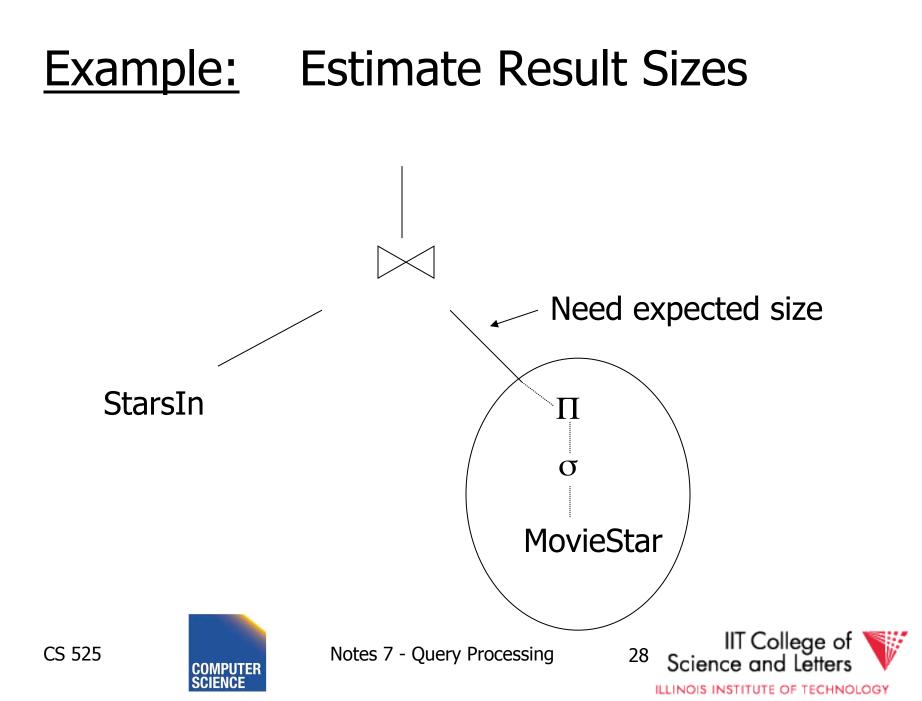
Fig. 7.20: An improvement on fig. 7.18.



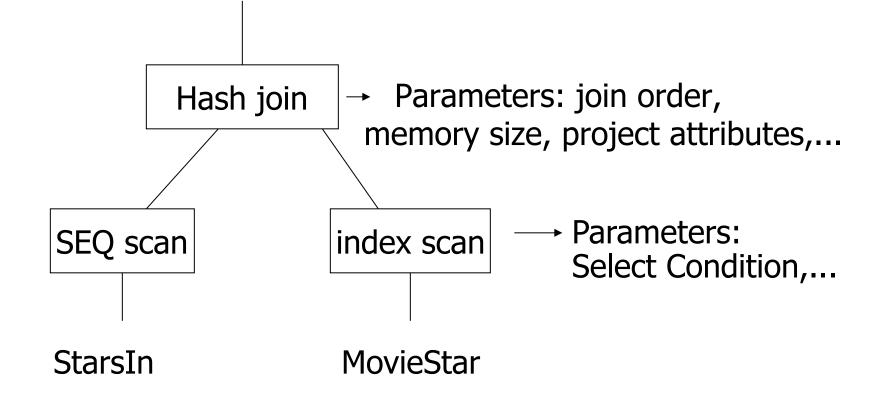
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Example: One Physical Plan

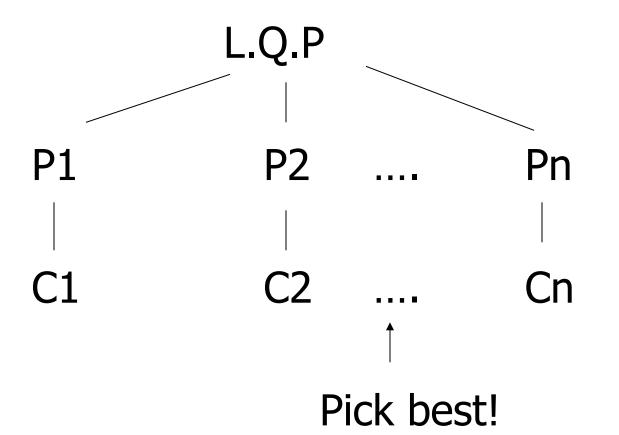




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Example: Estimate costs





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CS 525: Advanced Database Organisation



08: Query Processing Parsing and Analysis Boris Glavic

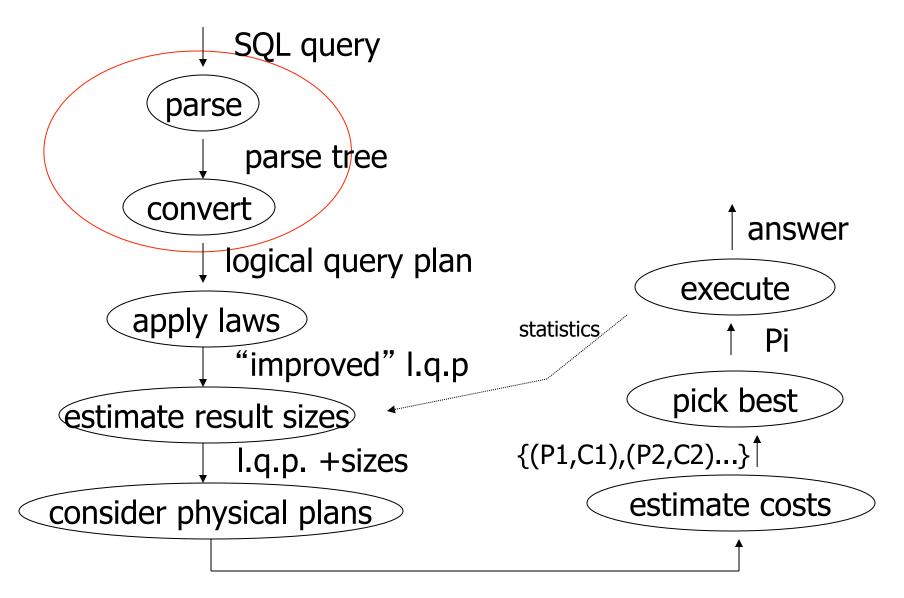
Slides: adapted from a <u>course</u> taught by <u>Hector Garcia-Molina</u>, Stanford InfoLab



Notes 8 - Parsing and Analysis

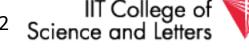


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{P1,P2,....}

Notes 8 - Parsing and Analysis



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Parsing, Analysis, Conversion

- 1. Parsing
 - Transform SQL text into syntax tree
- 2. Analysis
 - Check for semantic correctness
 - Use database catalog
 - E.g., unfold views, lookup functions and attributes, check scopes
- 3. Conversion
 - Transform into internal representation
 - Relational algebra or QBM





Analysis and Conversion

- Usually intertwined
- The internal representation is used to store analysis information
- Create an initial representation and complete during analysis





Parsing, Analysis, Conversion

1. Parsing

- 2. Analysis
- 3. Conversion





Parsing

- SQL -> Parse Tree
- Covered in compiler courses and books
- Here only short overview





SQL Standard

- Standardized language
 86, 89, 92, 99, 03, 06, 08, 11
- DBMS vendors developed their own dialects





Example: SQL query

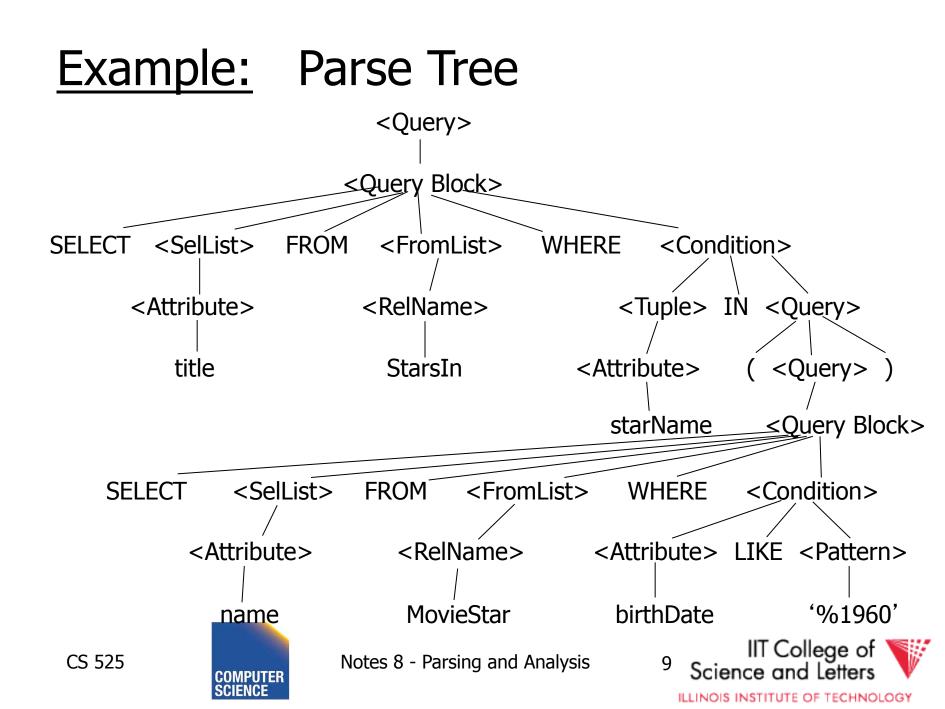
SELECT title
FROM StarsIn
WHERE starName IN (
 SELECT name
 FROM MovieStar
 WHERE birthdate LIKE '%1960'
);

(Find the movies with stars born in 1960)



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SQL Query Structure

• Organized in Query blocks **SELECT** <select_list> **FROM** <from list> **WHERE** <where condition> **GROUP BY** <group_by_expressions> **HAVING** <having_condition> **ORDER BY** <order by expressions>



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Notes 8 - Parsing and Analysis

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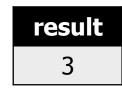
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10

Query Blocks

Only SELECT clause is mandatory Some DBMS require FROM

SELECT (1 + 2) AS result







SELECT clause

- List of expressions and optional name assignment + optional **DISTINCT**
 - Attribute references: R.a, b
 - Constants: 1, 'hello', '2008-01-20'
 - Operators: (R.a + 3) * 2
 - Functions (maybe UDF): substr(R.a, 1,3)
 - Single result or **set functions**
 - Renaming: (R.a + 2) AS x

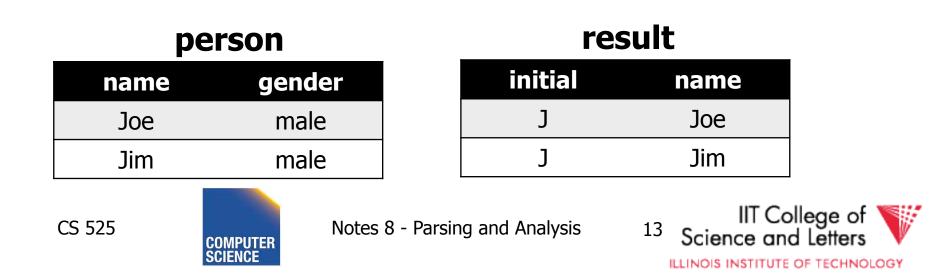


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SELECT clause - example

SELECT substring(p.name,1,1) AS initial p.name FROM person p



SELECT clause – set functions

Function extrChar(string)

SELECT extrChar(p.name) AS n FROM person p

person

_	
name	gender
Joe	male
Jim	male



Notes 8 - Parsing and Analysis



result

n

]

0

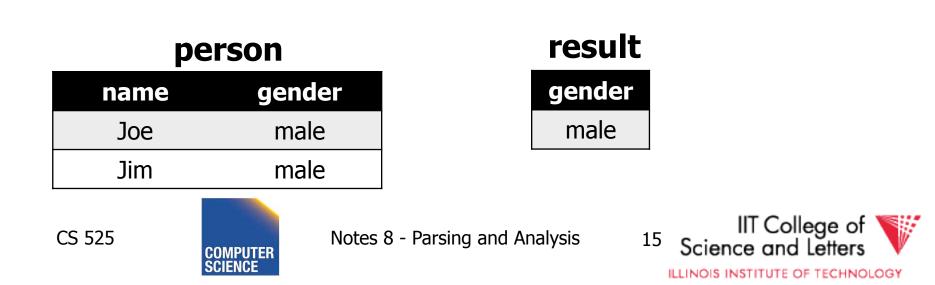
e

]

m

SELECT clause – DISTINCT

SELECT DISTINCT gender FROM person p



FROM clause

- List of table expressions
 - Access to relations
 - Subqueries (need alias)
 - Join expressions
 - Table functions
 - Renaming of relations and columns



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FROM clause examples

FROM R -access table R FROM R, S -access tables R and S FROM R JOIN S ON $(R_a = S_b)$ -join tables R and S on condition (R.a = S.b) FROM R x FROM R AS x

-Access table R and assign alias 'x'



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```
FROM R x(c,d)
FROM R AS x(c,d)
     -using aliases x for R and c,d for its attribues
FROM (R JOIN S t ON (R.a = t.b)), T
     -join R and S, and access T
FROM (R JOIN S ON (R.a = S.b)) JOIN T
     -join tables R and S and result with T
FROM create_sequence(1,100) AS seq(a)
     -call table function
```



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Notes 8 - Parsing and Analysis



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FROM

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(SELECT count(*) FROM employee) AS empcnt(cnt)

-count number of employee in subquery





SELECT * FROM create_sequence(1,3) AS seq(a)

result

а
1
2
3





SELECT dep, headcnt
FROM (SELECT count(*) AS headcnt, dep
 FROM employee
 GROUP BY dep)
WHERE headcnt > 100

employee

name	dep
Joe	IT
Jim	Marketing

result

dep	headcnt
IT	103
Support	2506





Notes 8 - Parsing and Analysis



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FROM clause - correlation

Correlation

- Reference attributes from other FROM clause item
- Attributes of i^{th} entry only available in j > i
- Semantics:
 - For each row in result of ith entry:
 - Substitute correlated attributes with value from current row and evaluate query





Correlation - Example

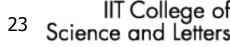
SELECT name, chr FROM employee AS e, extrChar(e.name) AS c(chr)

result

employee

name	dep
Joe	IT
Jim	Marketing

name	chr
Joe	J
Joe	0
Joe	e
Jim	J
Jim	i





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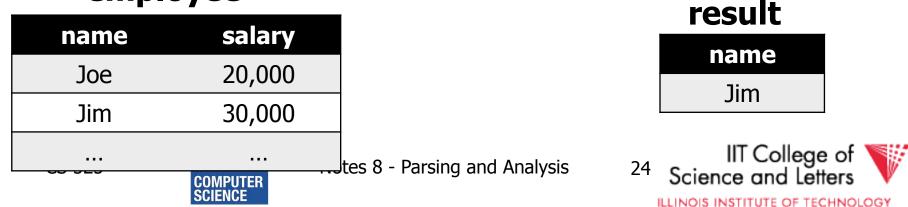




Correlation - Example

SELECT name
FROM (SELECT max(salary) maxsal
 FROM employee) AS m,
 (SELECT name
 FROM employee x
 WHERE x.salary = m.maxsal) AS e

employee



WHERE clause

- A condition
 - Attribute references
 - Constants
 - Operators (boolean)
 - Functions
 - Nested subquery expressions
- Result has to be boolean



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WHERE clause examples





Nested Subqueries

- Nesting a query within an expression
- Correlation allowed
 - Access FROM clause attributes
- Different types of nesting
 - Scalar subquery
 - Existential quantification
 - Universal quantification



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Nested Subqueries Semantics

- For each tuple produced by the FROM clause execute the subquery
 - If correlated attributes replace them with tuple values



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Scalar subquery

- Subquery that returns one result tuple – How to check?
 - --> Runtime error

SELECT * FROM R WHERE R.a = (SELECT count(*) FROM S)



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Existential Quantification

- <expr> IN <subquery>
 - Evaluates to true if <expr> equal to at least one of the results of the subquery

SELECT *
FROM users
WHERE name IN (SELECT name FROM
 blacklist)

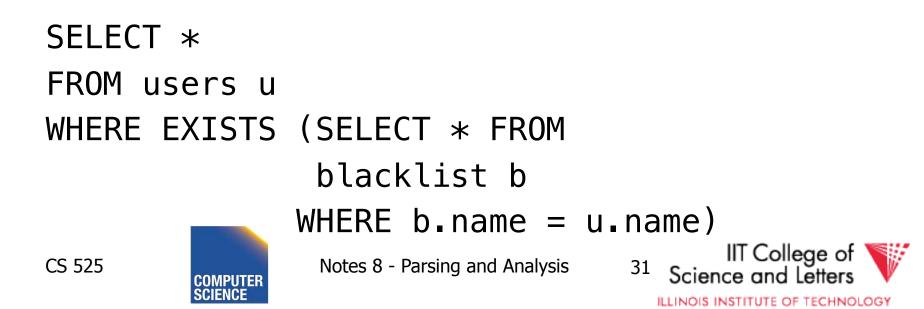


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Existential Quantification

- EXISTS <subquery>
 - Evaluates to true if <subquery> returns at least one tuple



Existential Quantification

- <expr> <op> ANY <subquery>
 - Evaluates to true if <expr> <op> <tuple>
 evaluates to true for **at least one** result
 tuple

– Op is any comparison operator: =, <, >, ...
SELECT *

FROM users

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WHERE name = ANY (SELECT name FROM

blacklist)



Universal Quantification

• <expr> <op> ALL <subquery>

Evaluates to true if <expr> <op> <tuple>
 evaluates to true for **all** result tuples

– Op is any comparison operator: =, <, >, ...
SELECT *

FROM nation

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WHERE nname = ALL (SELECT nation FROM blacklist)





Nested Subqueries Example

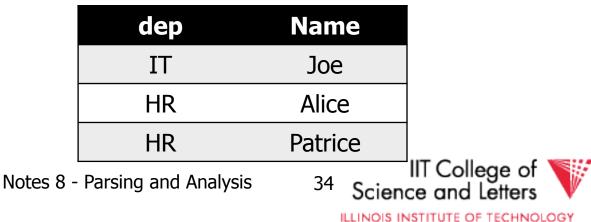
SELECT dep,name
FROM employee e
WHERE salary >= ALL (SELECT salary

employee

name	dep	salary
Joe	IT	2000
Jim	IT	300
Bob	HR	100
Alice	HR	10000
Patrice	HR	10000

FROM employee d WHERE e.dep = d.dep)

result



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GROUP BY clause

- A list of expressions
 - Same as WHERE
 - No restriction to boolean
 - DBMS has to know how to compare = for data type
- Results are grouped by values of the expressions
- -> usually used for aggregation







GROUP BY restrictions

- If group-by is used then
 - SELECT clause can only use group by expressions or aggregation functions



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GROUP BY clause examples

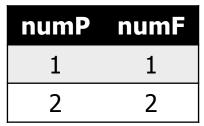
GROUP BY R.a -group on single attribute GROUP BY (1+2) -allowed but useless (single group) GROUP BY salary / 1000 -groups of salary values in buckets of 1000 GROUP BY R.a, R.b -group on two attributes





SELECT count(*) AS numP, (SELECT count(*) FROM friends o WHERE $o_with = f_name$) AS numF FROM (SELECT DISTINCT name FROM friends) f GROUP BY (SELECT count(*) FROM friends o WHERE $o_with = f_name$

result



friends

name	with
Joe	Jim
Joe	Peter
Jim	Joe
Jim	Peter
Peter	Joe





HAVING clause

- A boolean expression
- Applied after grouping and aggregation
 - Only references aggregation expressions and group by expressions



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HAVING clause examples

...

HAVING sum(R.a) > 100 -only return tuples with sum bigger than 100

...

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GROUP BY dep HAVING dep = 'IT' AND sum(salary) > 1000000 -only return group 'IT' and sum threshold





ORDER BY clause

- A list of expressions
- Semantics: Order the result on these expressions



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ORDER BY clause examples

ORDER BY R.a ASC ORDER BY R.a -order ascending on R.a ORDER BY R.a DESC -order descending on R.a ORDER BY salary + bonus -order by sum of salary and bonus





New and Non-standard SQL features (excerpt)

- LIMIT / OFFSET
 - Only return a fix maximum number of rows
 - FETCH FIRST n ROWS ONLY (DB2)
 - row_number() (Oracle)
- Window functions
 - More flexible grouping
 - Return both aggregated results and input values



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Parsing, Analysis, Conversion

- 1. Parsing
- 2. Analysis
- 3. Conversion





Analysis Goals

- Semantic checks
 - Table column exists
 - Operator, function exists
 - Determine type casts
 - Scope checks
- Rewriting
 - Unfolding views





Semantic checks

SELECT *

FROM R

WHERE $R_a + 3 > 5$

- Table R exists?
- Expand *: which attributes in R?
- R.a is a column?
- Type of constants 3, 5?
- Operator + for types of R.a and 3 exists?
- Operator > for types of result of + and 5 exists?





Database Catalog

- Stores information about database objects
- Aliases:
 - Information Schema
 - System tables
 - Data Dictionary





Typical Catalog Information

- Tables
 - Name, attributes + data types, constraints
- Schema, DB
 - Hierarchical structuring of data
- Data types

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- Comparison operators
- physical representation
- Functions to (de)serialize to string





Typical Catalog Information

- Functions (including aggregate/set)
 - Build-in
 - User defined (UDF)
- Triggers

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Stored Procedures

COMPUTER



Type Casts

- Similar to automatic type conversion in programming languages
- Expression: R.a + 3.0
 - Say R.a is of type integer
 - Search for a function +(int,float)
 - Does not exist?
 - Try to find a way to cast R.a, 3.0 or both to new data type
 - So that a function + exists for new types



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Scope checks

- Check that references are in correct scope
- E.g., if GROUP BY is present then SELECT clause expression can only reference group by expressions or aggregated values



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View Unfolding

- SQL allows for stored queries using CREATE VIEW
- Afterwards a view can be used in queries
- If view is not materialized, then need to replace view with its definition



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View Unfolding Example

CREATE VIEW totalSalary AS SELECT name, salary + bonus AS total FROM employee

SELECT * FROM totalSalary WHERE total > 10000



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View Unfolding Example

CREATE VIEW totalSalary AS SELECT name, salary + bonus AS total FROM employee



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Analysis Summary

- Perform semantic checks
 - Catalog lookups (tables, functions, types)
 - Scope checks
- View unfolding
- Generate internal representation during analysis





Parsing, Analysis, Conversion

- 1. Parsing
- 2. Analysis
- 3. Conversion





Conversion

- Create an internal representation
 - Should be useful for analysis
 - Should be useful optimization
- Internal representation
 - Relational algebra
 - Query tree/graph models
 - E.g., QGM (Query Graph Model) in Starburst



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Relational Alegbra

- Formal language
- Good for studying logical optimization and query equivalence (containment)
- Not informative enough for analysis
 - No datatype representation in algebra expressions
 - No meta-data



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Other Internal Representations

- Practical implementations
 - Mostly following structure of SQL query blocks
 - Store data type and meta-data (where necessary)



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Canonical Translation to Relational Algebra

- TEXTBOOK version of conversion
- Given an SQL query
- Return an equivalent relational algebra expression



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Relational Algebra Recap

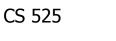
- Formal query language
- Consists of operators
 - Input(s): relation
 - Output: relation
 - --> Composable
- Set and Bag semantics version



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- Relation Schema
 - A set of attribute name-datatype pairs
- Relation (instance)
 - A (multi-)set of tuples with the same schema
- Tuple
 - List of attribute value pairs (or function from attribute name to value)







Set-vs. Bag semantics

- Set semantics:
 - Relations are Sets
 - Used in most theoretical work
- Bag semantics
 - Relations are Multi-Sets
 - Each element (tuple) can appear more than once
 - SQL uses bag semantics



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Bag semantics notation

 We use t^m to denote tuple t appears with multiplicity m



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Set- vs. Bag semantics

Set

Name	Purchase
Peter	Guitar
Joe	Drum
Alice	Bass

Ba	ag
Name	Purchase
Peter	Guitar
Peter	Guitar
Joe	Drum
Alice	Bass
Alice	Bass



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Operators

- Selection
- Renaming
- Projection
- Joins

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- Theta, natural, cross-product, outer, anti

- Aggregation
- Duplicate removal
- Set operations





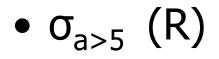
Selection

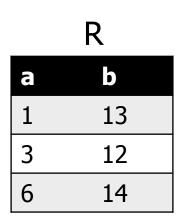
- Syntax: $\sigma_{c}(R)$
 - R is input
 - C is a condition
- Semantics:
 - Return all tuples that match condition C
 - Set: { t | t εR AND t fulfills C }
 - Bag: { tⁿ | tⁿεR AND t fulfills C }





Selection Example





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Renaming

- Syntax: $\rho_A(R)$
 - R is input
 - A is list of attribute renamings b ← a
- Semantics:

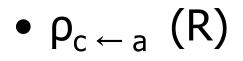
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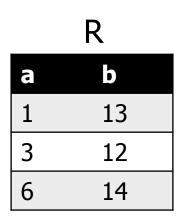
- Applies renaming from A to inputs
- Set: { t.A | t εR }
- Bag: { (t.A)ⁿ | tⁿεR }



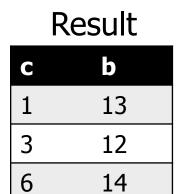


Renaming Example





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Projection

- Syntax: $\Pi_A(R)$
 - R is input
 - A is list of projection expressions
 - Standard: only attributes in A

– Semantics:

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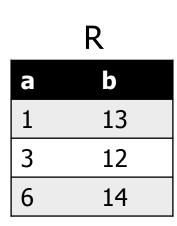
- Project all inputs on projection expressions
- Set: { t.A | t εR }
- Bag: { (t.A)ⁿ | tⁿεR }





Projection Example

• Π_b (R)



Result

12

14





Cross Product

- Syntax: R X S
 - R and S are inputs
- Semantics:
 - All combinations of tuples from R and S
 - = mathematical definition of cross product
 - Set: { (t,s) | t εR AND sεS }
 - Bag: { (t,s)^{n*m} | tⁿεR AND s^mεS }

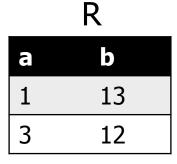


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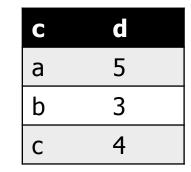


Cross Product Example

• R X S









а	b	С	d	
1	13	а	5	
1	13	b	3	
1	13	С	4	
3	12	а	5	
3	12	b	3	
3	12	С	4	





Join

- − Syntax: R ▷ C S
 - R and S are inputs
 - C is a condition
- Semantics:

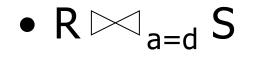
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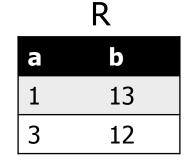
- All combinations of tuples from R and S that match C
- Set: { (t,s) | t εR AND sεS AND (t,s) matches C}
- Bag: { (t,s)^{n*m} | tⁿεR AND s^mεS AND (t,s) matches C}



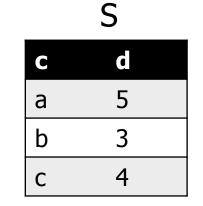


Join Example





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	Re	esult		
a	b	С	d	
3	12	b	3	

. .





Natural Join

- Syntax: R 🖂 S
 - R and S are inputs
- Semantics:
 - All combinations of tuples from R and S that match on common attributes
 - A = common attributes of R and S
 - C = exclusive attributes of S
 - Set: { (t,s.C) | t εR AND sεS AND t.A=s.A}
 - Bag: { (t,s.C)^{n*m} | tⁿεR AND s^mεS AND t.A=s.A}

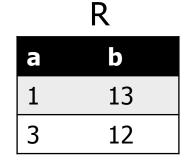


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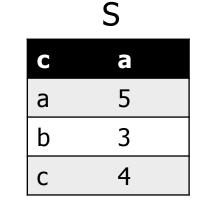


Natural Join Example





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а	b	С	
3	12	b	





Left-outer Join



- R and S are inputs
- C is condition

– Semantics:

- R join S
- t εR without match, fill S attributes with NULL

{ (t,s) | t ER AND SES AND (t,s) matches C} union

{ (t, NULL(S)) | t ɛR AND NOT exists sɛS: (t,s) matches C }





Left-outer Join Example

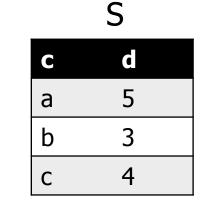
 R

 a
 b

 1
 13

 3
 12

CS 525



Result	
--------	--

	a	b	C	d
,	1	13	NULL	NULL
	3	12	b	3





Right-outer Join

– Syntax: R C S

- R and S are inputs
- C is condition

– Semantics:

• R join S

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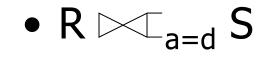
s εS without match, fill R attributes with NULL
 { (t,s) | t εR AND sεS AND (t,s) matches C}
 union

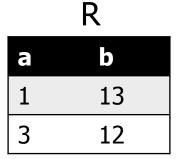
{ (NULL(R),s) | s ɛS AND NOT exists tɛR: (t,s) matches C }



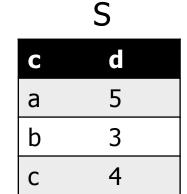


Right-outer Join Example





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	I	1C3	uit
а	b	С	d
NULL	NULL	а	5
3	12	b	3
NULL	NULL	С	4

Recult





Full-outer Join

- Syntax: $R \supset C_C S$
 - R and S are inputs and C is condition
- Semantics:

{ (t,s) | t ER AND SES AND (t,s) matches C} union

{ (NULL(R),s) | s ɛS AND NOT exists tɛR: (t,s) matches C }

union

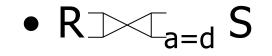
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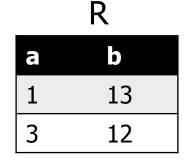
{ (t, NULL(S)) | t ɛR AND NOT exists sɛS: (t,s) matches C }



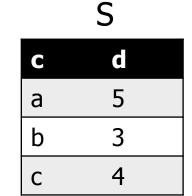


Full-outer Join Example





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а	b	С	d
1	13	NULL	NULL
NULL	NULL	а	5
3	12	b	3
NULL	NULL	С	4





Semijoin

- Syntax: $R \ltimes S$ and $R \rtimes S$
 - R and S are inputs

– Semantics:

• All tuples from R that have a matching tuple from relation S on the common attributes A

{ t | t ϵ R AND exists s ϵ S: t.A = s.A}

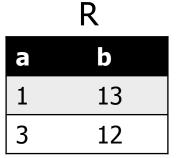


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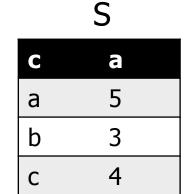


Semijoin Example





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а	b
3	12





Antijoin

- Syntax: R ▷ S
 - R and S are inputs

– Semantics:

• All tuples from R that have no matching tuple from relation S on the common attributes A

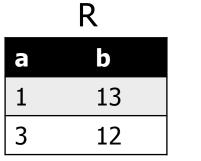
{ t | t ϵ R AND NOT exists s ϵ S: t.A = s.A}



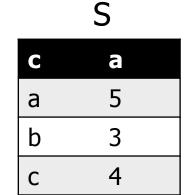


Antijoin Example





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а	b
1	13





Aggregation

- Syntax: $_{G}a_{A}(R)$

- A is list of aggregation functions
- G is list of group by attributes

– Semantics:

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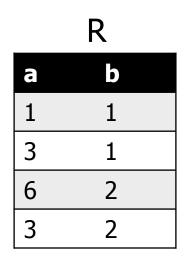
- Build groups of tuples according G and compute the aggregation functions from each group
- { (t.G, agg(G(t)) | tɛR }
- G(t) = { t' | t' εR AND t'.G = t.G }





Aggregation Example

• _ba_{sum(a)} (R)



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Result

sum(a)	b
4	1
9	2





Duplicate Removal

- Syntax:δ(R)
 - R is input

– Semantics:

- Remove duplicates from input
- Set: N/A
- Bag: { t¹ | tⁿεR }

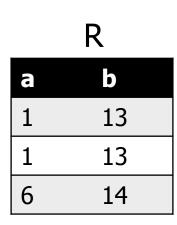




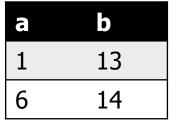
Duplicate Removal Example

• δ(R)

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Set operations

– Input: R and S

- Have to have the same schema
 - Union compatible
- Modulo attribute names
- Types
 - Union
 - Intersection
 - Set difference





Union

- Syntax: R U S
 - R and S are union-compatible inputs

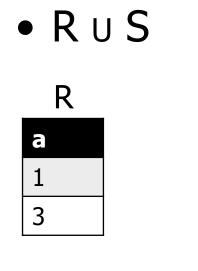
– Semantics:

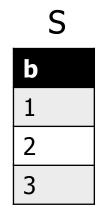
- Set: { (t) | t εR OR tεS}
- Bag: { (t,s)^{n+m} | tⁿεR AND s^mεS }
 - Assumption t^n with n < 1 for tuple not in relation



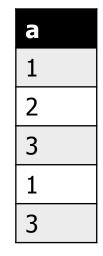


Union Example





Result





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Intersection

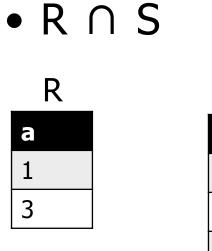
- Syntax: $R \cap S$
 - R and S are union-compatible inputs
- Semantics:
 - Set: { (t) | t εR AND tεS}
 - Bag: { (t,s)^{min(n,m)} | tⁿεR AND s^mεS }



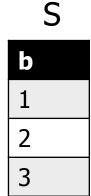
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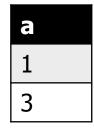
Intersection Example



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Result







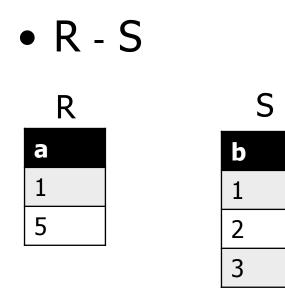
Set Difference

- Syntax: R S
 - R and S are union-compatible inputs
- Semantics:
 - Set: { (t) | t εR AND NOT tεS}
 - Bag: { (t,s)^{n m} | tⁿεR AND s^mεS }





Set Difference Example



Result





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Canonical Translation to Relational Algebra

- TEXTBOOK version of conversion
- Given an SQL query
- Return an equivalent relational algebra expression



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Canonical Translation

- FROM clause into joins and crossproducts
 - Cross-product between list items
 - Joins into their algebra counter-part
- WHERE clause into selection
- **SELECT** clause into projection and renaming
 - If it has aggregation functions use aggreation

– **DISTINCT** into duplicate removal



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Canonical Translation

- **GROUP BY** clause into aggregation
- HAVING clause into selection
- ORDER BY no counter-part
- Then turn joins into crossproducts and selections



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Set Operations

- UNION ALL into union
- **UNION** duplicate removal over union
- INTERSECT ALL into intersection
- INTERSECT add duplicate removal
- **EXCEPT ALL** into set difference
- **EXCEPT** apply duplicate removal to inputs and then apply set difference



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Example: Relational Algebra Translation

SELECT sum(R.a) FROM R GROUP BY b

> Π_{sum(a)} Bα_{sum(a)} | R



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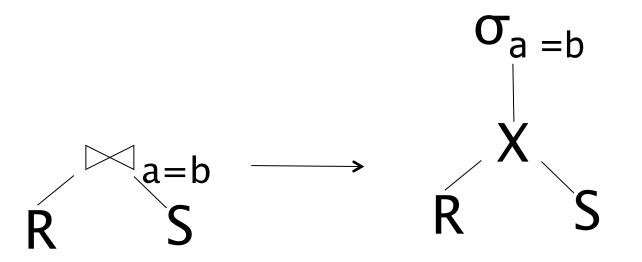


Example: Relational Algebra Translation

```
SELECT dep, headcnt
FROM (SELECT count(*) AS headcnt, dep
       FROM employee
       GROUP BY dep)
                                        <sup>11</sup>dep, headcnt
WHERE headcnt > 100
                                         \sigma_{headcnt > 100}
                                   \rho_{headcnt} \leftarrow count(*)
                                         dep<sup>X<sup>|</sup><sub>count(*)</sub></sup>
                                        Employee
                                                              College of
   CS 525
                          Notes 8 - Parsing and Analysis
                                                   105
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```

Example: Relational Algebra Translation

SELECT *
FROM R JOIN S ON (R.a = S.b)





Notes 8 - Parsing and Analysis



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Parsing and Analysis Summary

- SQL text -> Internal representation
- Semantic checks
- Database catalog
- View unfolding



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CS 525: Advanced Database Organisation



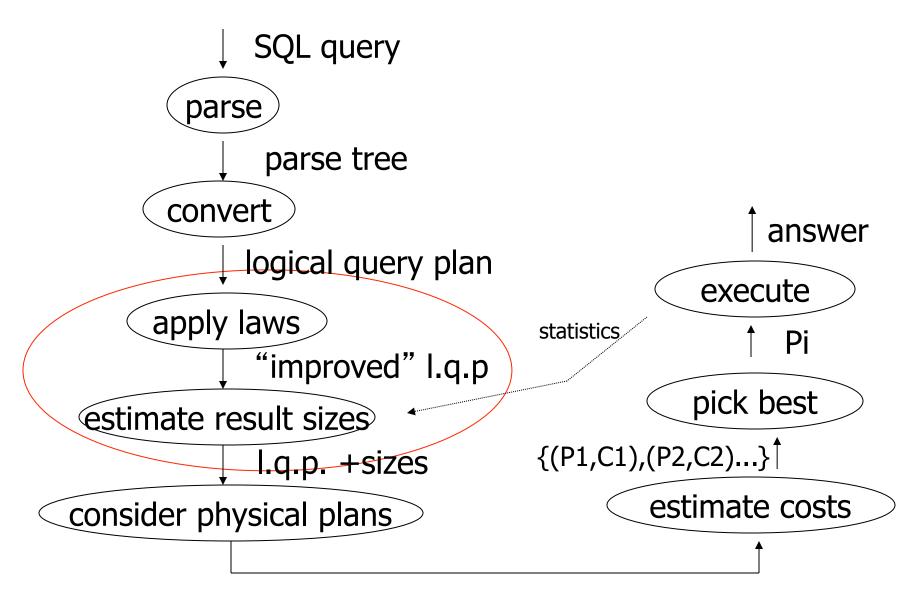
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09: Query Optimization -Logical Boris Glavic

Slides: adapted from a <u>course</u> taught by <u>Hector Garcia-Molina</u>, Stanford InfoLab

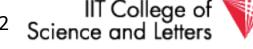






{P1,P2,....}

Notes 8 - Parsing and Analysis



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Query Optimization

- Relational algebra level
- Detailed query plan level



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Query Optimization

- Relational algebra level
- Detailed query plan level
 - Estimate Costs
 - without indexes
 - with indexes
 - Generate and compare plans





Relational algebra optimization

- Transformation rules (preserve equivalence)
- What are good transformations?
 - Heuristic application of transformations





Query Equivalence

- Two queries q and q' are equivalent:
 - If for every database instance I
 - Contents of all the tables
 - Both queries have the same result

 $q \equiv q' \text{ iff } \forall I: q(I) = q'(I)$





Rules: Natural joins & cross products & union

- $\mathsf{R} \bowtie \mathsf{S} = \mathsf{S} \bowtie \mathsf{R}$
- $(\mathsf{R} \bowtie \mathsf{S}) \bowtie \mathsf{T} = \mathsf{R} \bowtie (\mathsf{S} \bowtie \mathsf{T})$

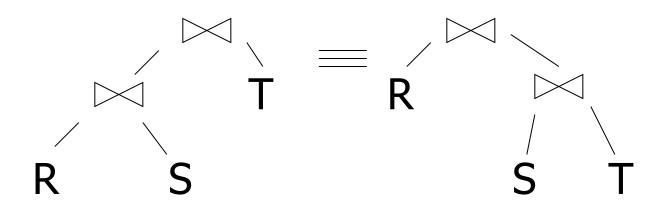




Note:

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- Carry attribute names in results, so order is not important
- Can also write as trees, e.g.:







Rules: Natural joins & cross products & union

- $\mathsf{R} \bowtie \mathsf{S} = \mathsf{S} \bowtie \mathsf{R}$
- $(\mathsf{R} \bowtie \mathsf{S}) \bowtie \mathsf{T} = \mathsf{R} \bowtie (\mathsf{S} \bowtie \mathsf{T})$
- $R \times S = S \times R$ ($R \times S$) $\times T = R \times (S \times T)$

R U S = S U R R U (S U T) = (R U S) U T



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Rules: Selects

$O_{p1 \wedge p2}(R) =$

$\mathbf{O}_{p1vp2}(\mathsf{R}) =$

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Rules: Selects



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Bags vs. Sets

R = {a,a,b,b,b,c} S = {b,b,c,c,d} RUS = ?





Bags vs. Sets

- R = {a,a,b,b,b,c} S = {b,b,c,c,d} RUS = ?
- <u>Option 1</u> SUM RUS = $\{a,a,b,b,b,b,c,c,c,d\}$
- <u>Option 2</u> MAX RUS = $\{a,a,b,b,b,c,c,d\}$



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Option 2 (MAX) makes this rule work:

$\mathcal{O}_{p1vp2}(R) = \mathcal{O}_{p1}(R) \cup \mathcal{O}_{p2}(R)$ Example: R={a,a,b,b,c}

P1 satisfied by a,b; P2 satisfied by b,c



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Option 2 (MAX) makes this rule work:

 $\mathbf{O}_{p1\mathbf{v}p2}(R) = \mathbf{O}_{p1}(R) \cup \mathbf{O}_{p2}(R)$ Example: R={a,a,b,b,b,c} P1 satisfied by a,b; P2 satisfied by b,c $O_{p1vp2}(R) = \{a,a,b,b,b,c\}$ $O_{p1}(R) = \{a,a,b,b,b\}$ $O_{p2}(R) = \{b, b, b, c\}$ $O_{p1}(R) \cup O_{p2}(R) = \{a,a,b,b,b,c\}$ College of

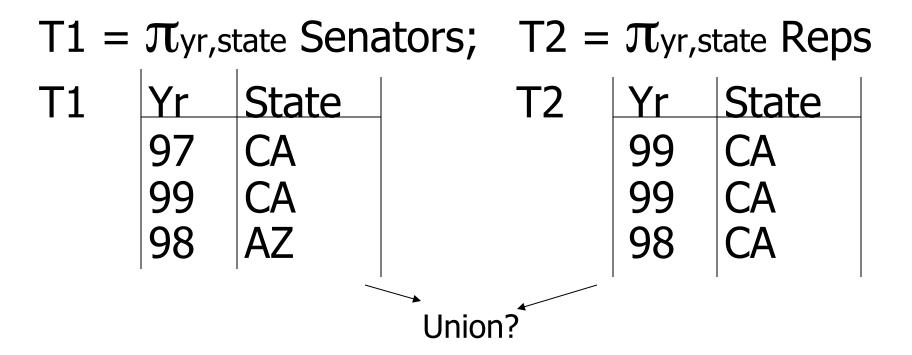
Notes 9 - Logical Optimization



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"Sum" option makes more sense:





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Executive Decision

- -> Use "SUM" option for bag unions
- -> Some rules cannot be used for bags



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Rules: Project

Let: X = set of attributes Y = set of attributesXY = X U Y

$\pi_{xy}(R) =$





Rules: Project

Let: X = set of attributes Y = set of attributesXY = X U Y

$\pi_{xy}(R) = \pi_x[\pi_y(R)]$



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Rules: Project

Let: X = set of attributes
Y = set of attributes
XY = X U Y
$$\pi_{xy}(R) = \pi_x[\pi_x(R)]$$



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<u>Rules:</u> σ + \bowtie combined

Let p = predicate with only R attribs

- q = predicate with only S attribs
- m = predicate with only R,S attribs

$\sigma_{p} (R \bowtie S) =$ $\sigma_{q} (R \bowtie S) =$

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<u>Rules:</u> σ + \bowtie combined

Let p = predicate with only R attribs

- q = predicate with only S attribs
- m = predicate with only R,S attribs

$\mathcal{O}_{p}(R \bowtie S) = [\mathcal{O}_{p}(R)] \bowtie S$ $\mathcal{O}_{q}(R \bowtie S) = R \bowtie [\mathcal{O}_{q}(S)]$



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<u>Rules:</u> σ + \bowtie combined (continued)

Some Rules can be Derived:

Op∧q (R ▷ S) =

Op∧q∧m (R ▷<< S) =

Opvq (R ▷< S) =



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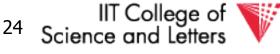
$$\begin{split} & \boldsymbol{\sigma}_{p \wedge q} \left(\mathsf{R} \bowtie \mathsf{S} \right) = \left[\boldsymbol{\sigma}_{p} \left(\mathsf{R} \right) \right] \bowtie \left[\boldsymbol{\sigma}_{q} \left(\mathsf{S} \right) \right] \\ & \boldsymbol{\sigma}_{p \wedge q \wedge m} \left(\mathsf{R} \bowtie \mathsf{S} \right) = \\ & \boldsymbol{\sigma}_{m} \left[\left(\boldsymbol{\sigma}_{p} \, \mathsf{R} \right) \bowtie \left(\boldsymbol{\sigma}_{q} \, \mathsf{S} \right) \right] \end{aligned}$$

Opvq (R ▷< S) =

$\left[(\sigma_{P} R) \bowtie S \right] U \left[R \bowtie (\sigma_{q} S) \right]$



Notes 9 - Logical Optimization



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--> Derivation for first one:

$O_{pAq}(R \bowtie S) =$ $\sigma_{p}[\sigma_{q}(R \bowtie S)] =$ $\mathcal{O}_p \left[R \bowtie \mathcal{O}_q (S) \right] =$ $[\mathbf{O}_{\mathsf{P}}(\mathsf{R})] \bowtie [\mathbf{O}_{\mathsf{q}}(\mathsf{S})]$



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<u>Rules:</u> π,σ combined

Let x = subset of R attributes z = attributes in predicate P (subset of R attributes)

$\pi x[\sigma_{P}(R)] =$

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<u>Rules:</u> π,σ combined

Let x = subset of R attributes z = attributes in predicate P (subset of R attributes)

$\pi_{x}[\sigma_{p}(R)] = \{\sigma_{p}[\pi_{x}(R)]\}$



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<u>Rules:</u> π,σ combined

Let x = subset of R attributes z = attributes in predicate P (subset of R attributes)

$$\pi_{x}[\sigma_{p(R)}] = \pi_{x} \{\sigma_{p}[\pi_{x}(R)]\}$$



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<u>Rules:</u> π , \bowtie combined

Let x = subset of R attributes y = subset of S attributes z = intersection of R,S attributes

 π_{xy} (R \bowtie S) =



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<u>Rules:</u> π , \bowtie combined

Let x = subset of R attributes y = subset of S attributes z = intersection of R,S attributes

π_{xy} (R \bowtie S) =

$\pi_{xy}\{[\pi_{xz}(R)] \bowtie [\pi_{yz}(S)]\}$



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$\pi_{xy} \{ \sigma_p \ (R \bowtie S) \} =$



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$\pi_{xy} \{ \sigma_{p} (R \bowtie S) \} =$ $\pi_{xy} \{ \sigma_{p} [\pi_{xz'} (R) \bowtie \pi_{yz'} (S)] \}$ $z' = z \cup \{ \text{attributes used in P} \}$



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<u>Rules</u> for σ , π combined with X

similar...

e.g., $\sigma_{p}(R X S) = ?$



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<u>Rules</u> σ , U combined:

$\sigma_{p}(R \cup S) = \sigma_{p}(R) \cup \sigma_{p}(S)$ $\sigma_{p}(R - S) = \sigma_{p}(R) - S = \sigma_{p}(R) - \sigma_{p}(S)$



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Which are "good" transformations?

$\Box \ \mathfrak{O}_{p1 \wedge p2} (\mathsf{R}) \to \mathfrak{O}_{p1} [\mathfrak{O}_{p2} (\mathsf{R})]$ $\Box \ \mathfrak{O}_{p} (\mathsf{R} \bowtie \mathsf{S}) \to [\mathfrak{O}_{p} (\mathsf{R})] \bowtie \mathsf{S}$

- $\Box \mathsf{R} \bowtie \mathsf{S} \twoheadrightarrow \mathsf{S} \bowtie \mathsf{R}$
- $\Box \ \pi_{x}[\sigma_{p}(R)] \rightarrow \pi_{x} \{\sigma_{p}[\pi_{xz}(R)]\}$



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Conventional wisdom: do projects early

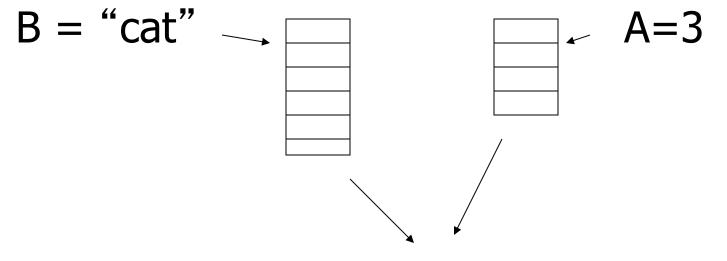
$\pi_x \{ \sigma_p(R) \}$ vs. $\pi_E \{ \sigma_p \{ \pi_{ABE}(R) \} \}$



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But What if we have A, B indexes?



Intersect pointers to get pointers to matching tuples e.g., using bitmaps



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Bottom line:

- No transformation is <u>always</u> good
- Usually good: early selections
 - Exception: expensive selection conditions
 - E.g., UDFs



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More transformations

- Eliminate common sub-expressions
- Detect constant expressions
- Other operations: duplicate elimination



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Pushing Selections

• Idea:

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- Join conditions equate attributes
- For parts of algebra tree (scope) store which attributes have to be the same
 - Called Equivalence classes
- Example: R(a,b), S(c,d)

$\mathbf{O}_{b=3} (\mathsf{R} \Join_{b=c} \mathsf{S}) = \mathbf{O}_{b=3} (\mathsf{R}) \Join_{b=c} \mathbf{O}_{c=3} (\mathsf{S})$





Outer-Joins

- Not commutative $-R \bowtie S \neq S \bowtie R$
- p condition over attributes in A
- A list of attributes from R

 $\begin{array}{l} \sigma_{p} \left(\mathsf{R} \bowtie_{\mathsf{A}=\mathsf{B}} \mathsf{S}\right) \equiv \sigma_{p} \left(\mathsf{R}\right) \bowtie_{\mathsf{A}=\mathsf{B}} \mathsf{S} \\ \text{Not} \, \sigma_{p} \left(\mathsf{R} \bowtie_{\mathsf{A}=\mathsf{B}} \mathsf{S}\right) \equiv \mathsf{R} \bowtie_{\mathsf{A}=\mathsf{B}} \sigma_{p} \left(\mathsf{S}\right) \end{array}$



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Summary Equivalences

- Associativity: $(R \circ S) \circ T \equiv R \circ (S \circ T)$
- Commutativity: $R \circ S \equiv S \circ R$
- Distributivity: $(R \circ S) \otimes T \equiv (R \otimes T) \circ (S \otimes T)$
- Difference between Set and Bag Equivalences
- Only some equivalence are useful





Outline - Query Processing

- Relational algebra level
 - transformations
 - good transformations
- Detailed query plan level
 - estimate costs
 - generate and compare plans





- Estimating cost of query plan
- (1) Estimating <u>size</u> of results(2) Estimating # of IOs



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Estimating result size

- Keep statistics for relation R
 - -T(R): # tuples in R
 - S(R) : # of bytes in each R tuple
 - B(R): # of blocks to hold all R tuples
 - V(R, A) : # distinct values in R for attribute A





Example

R

Α	В	С	D
cat	1	10	а
cat	1	20	b
dog	1	30	а
dog	1	40	С
bat	1	50	d

A: 20 byte stringB: 4 byte integerC: 8 byte dateD: 5 byte string





Example

R

A	В	С	D
cat	1	10	а
cat	1	20	b
dog	1	30	а
dog	1	40	С
bat	1	50	d

- A: 20 byte string
- B: 4 byte integer
- C: 8 byte date
- D: 5 byte string

$$T(R) = 5$$
 $S(R) = 37$ $V(R,A) = 3$ $V(R,C) = 5$ $V(R,B) = 1$ $V(R,D) = 4$



Notes 9 - Logical Optimization



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<u>Size estimates</u> for $W = R1 \times R2$

T(W) =

S(W) =





<u>Size estimates</u> for $W = R1 \times R2$

$T(W) = T(R1) \times T(R2)$

S(W) = S(R1) + S(R2)





<u>Size estimate</u> for $W = \sigma_{A=a}(R)$

S(W) = S(R)

T(W) = ?





Example

R

A	В	С	D
cat	1	10	а
cat	1	20	b
dog	1	30	а
dog	1	40	С
bat	1	50	d

V(R,A)=3V(R,B)=1V(R,C)=5V(R,D)=4

 $W = \sigma_{z=val}(R) T(W) =$



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Example

R

Α	В	С	D
cat	1	10	а
cat	1	20	b
dog	1	30	а
dog	1	40	С
bat	1	50	d

V(R,A)=3 V(R,B)=1 V(R,C)=5 V(R,D)=4

$$W = \sigma_{z=val}(R) \quad T(W) = \frac{T(R)}{V(R,Z)}$$



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Assumption:

Values in select expression Z = valare <u>uniformly distributed</u> over possible V(R,Z) values.



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<u>Alternate Assumption:</u>

Values in select expression Z = valare <u>uniformly distributed</u> over domain with DOM(R,Z) values.





<u>Example</u> R

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Α	В	С	D
cat	1	10	а
cat	1	20	b
dog	1	30	а
dog	1	40	С
bat	1	50	d

Alternate assumption V(R,A)=3 DOM(R,A)=10 V(R,B)=1 DOM(R,B)=10 V(R,C)=5 DOM(R,C)=10 V(R,D)=4 DOM(R,D)=10

$$W = \sigma_{z=val}(R) \quad T(W) = ?$$





C=val ⇒ T(W) = (1/10)1 + (1/10)1 + ...= (5/10) = 0.5

$B=val \Rightarrow T(W) = (1/10)5 + 0 + 0 = 0.5$

$A=val \Rightarrow T(W) = (1/10)2 + (1/10)2 + (1/10)1 = 0.5$



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<u>Example</u> R

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Α	В	С	D
cat	1	10	а
cat	1	20	b
dog	1	30	а
dog	1	40	С
bat	1	50	d

Alternate assumption V(R,A)=3 DOM(R,A)=10 V(R,B)=1 DOM(R,B)=10 V(R,C)=5 DOM(R,C)=10 V(R,D)=4 DOM(R,D)=10

$$W = \sigma_{z=val}(R) \quad T(W) = \frac{T(R)}{DOM(R,Z)}$$





Selection cardinality

SC(R,A) = average # records that satisfyequality condition on R.A V(R,A) SC(R,A) T(R)DOM(R,A)



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What about $W = \sigma_{z \ge val}(R)$?

T(W) = ?



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What about
$$W = \sigma_{z \ge val} (R)$$
 ?

$$T(W) = ?$$

 Solution # 1: T(W) = T(R)/2



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What about
$$W = \sigma_{z \ge val} (R)$$
 ?

T(W) = ?

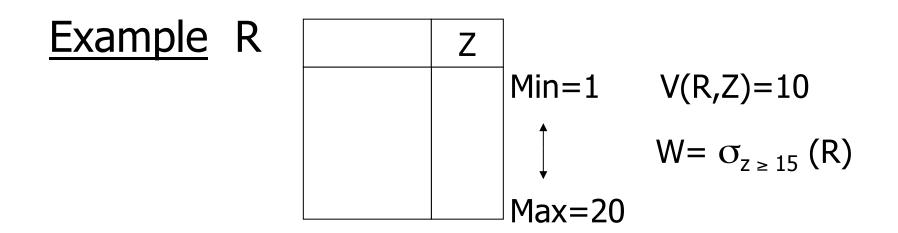
- Solution # 1: T(W) = T(R)/2
- Solution # 2:
 T(W) = T(R)/3



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• Solution # 3: Estimate values in range





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• Solution # 3: Estimate values in range

ExampleRZ
$$Min=1$$
 $V(R,Z)=10$ \downarrow $W=\sigma_{z \ge 15}(R)$ $Max=20$

f = 20-15+1 = 6 (fraction of range) 20-1+1 20

$T(W) = f \times T(R)$







Equivalently:

$f \times V(R,Z) = fraction of distinct values$ T(W) = [f × V(Z,R)] × T(R) = f × T(R) V(Z,R)



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<u>Size estimate</u> for $W = R1 \bowtie R2$

Let x = attributes of R1 y = attributes of R2



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<u>Size estimate</u> for $W = R1 \bowtie R2$

Let x = attributes of R1 y = attributes of R2



Same as R1 x R2

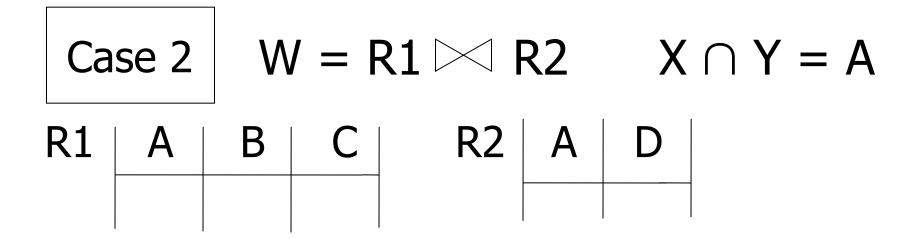


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Notes 9 - Logical Optimization



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Case 2W = R1 \bowtie R2X \cap Y = AR1ABCR2AD

Assumption:

 $V(R1,A) \leq V(R2,A) \Rightarrow$ Every A value in R1 is in R2 $V(R2,A) \leq V(R1,A) \Rightarrow$ Every A value in R2 is in R1

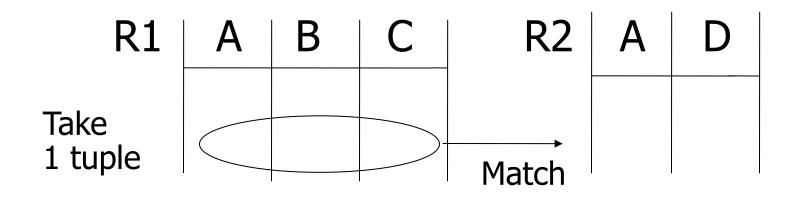


Notes 9 - Logical Optimization



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<u>Computing T(W)</u> when $V(R1,A) \leq V(R2,A)$

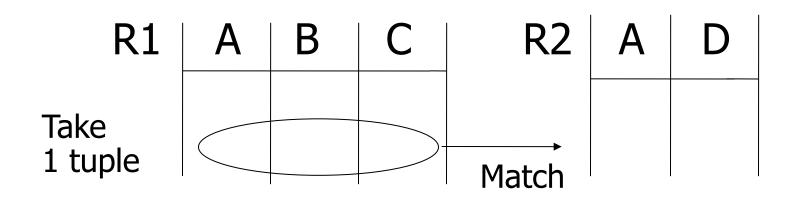




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<u>Computing T(W)</u> when $V(R1,A) \leq V(R2,A)$



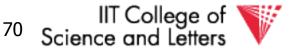
1 tuple matches with T(R2) tuples... V(R2,A)

so $T(W) = \frac{T(R2)}{V(R2, A)} \times T(R1)$



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Notes 9 - Logical Optimization



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• $V(R1,A) \leq V(R2,A) \quad T(W) = \frac{T(R2) T(R1)}{V(R2,A)}$

• $V(R2,A) \leq V(R1,A) T(W) = \frac{T(R2) T(R1)}{V(R1,A)}$

[A is common attribute]



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Notes 9 - Logical Optimization



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<u>In general</u> $W = R1 \bowtie R2$

T(W) = T(R2) T(R1) $max{ V(R1,A), V(R2,A) }$



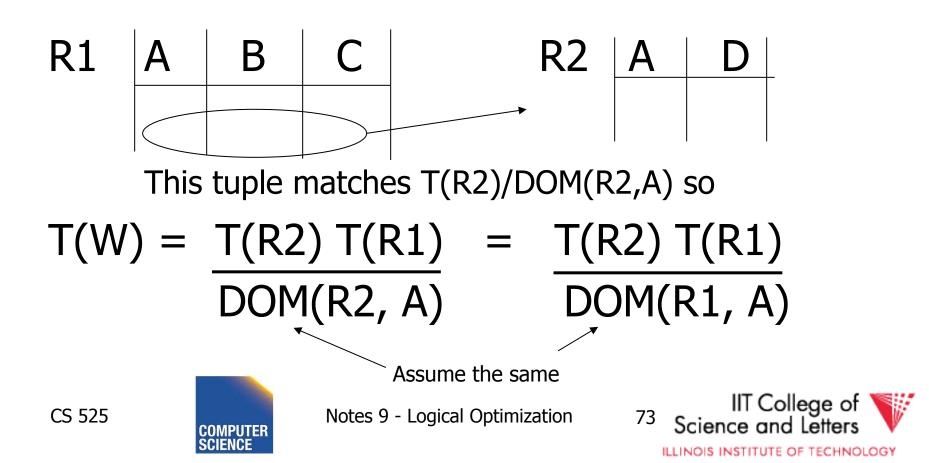
Notes 9 - Logical Optimization



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Case 2 with alternate assumption

Values uniformly distributed over domain



In all cases:

$S(W) = S(R1) + S(R2) - S(A)_{\text{size of attribute A}}$



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<u>Using similar ideas,</u> we can estimate sizes of:

 $\Pi_{AB}(R)$

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 $\mathcal{O}_{A=a \wedge B=b}(R)$ R > S with common attribs. A,B,C Union, intersection, diff,





<u>Note:</u> for complex expressions, need intermediate T,S,V results.

E.g.
$$W = [O_{A=a}(R1)] \bowtie R2$$

Treat as relation U
 $T(U) = T(R1)/V(R1,A)$ $S(U) = S(R1)$

Also need V (U, *) !!



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To estimate Vs

E.g., $U = \sigma_{A=a}(R1)$ Say R1 has attribs A,B,C,D V(U, A) =V(U, B) =V(U, C) =V(U, D) =



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R1

A	В	С	D
cat	1	10	10
cat	1	20	20
dog	1	30	10
dog	1	40	30
bat	1	50	10

V(R1,A)=3 V(R1,B)=1 V(R1,C)=5 V(R1,D)=3

U = O A=a (R1)



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R1

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A	В	С	D
cat	1	10	10
cat	1	20	20
dog	1	30	10
dog	1	40	30
bat	1	50	10

V(R1,A)=3 V(R1,B)=1 V(R1,C)=5 V(R1,D)=3

U = O A=a (R1)

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 $V(U,A) = 1 \quad V(U,B) = 1 \quad V(U,C) = \frac{T(R1)}{V(R1,A)}$

V(D,U) ... somewhere in between

Notes 9 - Logical Optimization

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Possible Guess $U = \sigma_{A=a}(R)$

V(U,A) = 1V(U,B) = V(R,B)





<u>For Joins</u> $U = R1(A,B) \bowtie R2(A,C)$

$V(U,A) = min \{ V(R1, A), V(R2, A) \}$ V(U,B) = V(R1, B)V(U,C) = V(R2, C)

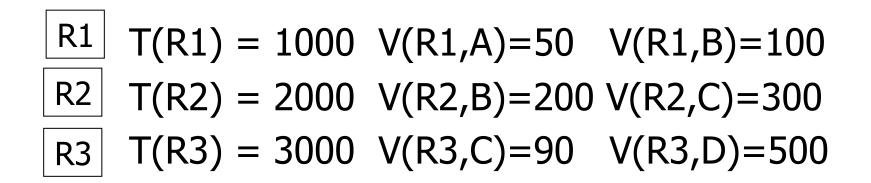


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Example:

$Z = R1(A,B) \bowtie R2(B,C) \bowtie R3(C,D)$





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Partial Result: $U = R1 \bowtie R2$

$T(U) = \frac{1000 \times 2000}{200} V(U,A) = 50$ V(U,B) = 100V(U,C) = 300



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Z = U ⋈ R3

$T(Z) = \frac{1000 \times 2000 \times 3000}{200 \times 300} \quad V(Z,A) = 50$ V(Z,B) = 100V(Z,C) = 90V(Z,D) = 500



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Approximating Distributions

- Summarize the distribution
 - Used to better estimate result sizes
 - Without the need to look at all the data
- Concerns

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- Error metric: How to measure preciseness
- Memory consumption
- Computational Complexity





Approximating Distributions

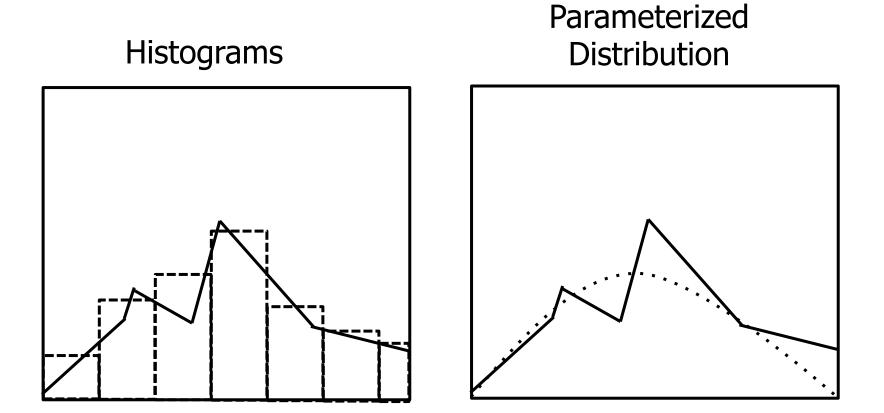
- Parameterized distribution
 - E.g., gauss distribution
 - Adapt parameters to fit data
- Histograms

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- Divide domain into ranges (buckets)
- Store the number of tuples per bucket
- Both need to be maintained









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Maintaining Statistics

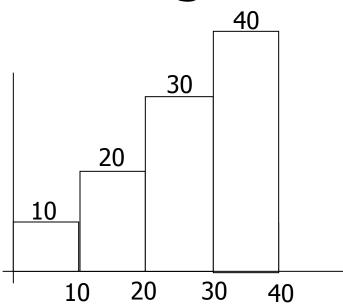
- Use separate command that triggers statistics collection
 - Postgres: ANALYZE
- During query processing
 - Overhead for queries
- Use Sampling?



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Estimating Result Size using Histograms



number of tuples in R with A value in given range

```
\sigma_{A=val}(R) = ?
```



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Estimating Result Size using Histograms

- $\sigma_{A=val}(R) = ?$
- |B| number of values per bucket
- #B number of records in bucket

#B |B|

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Join Size using Histograms

- R ⋈ S
- Use

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$T(W) = \frac{T(R2) T(R1)}{max\{ V(R1,A), V(R2,A) \}}$

• Apply for each bucket





Join Size using Histograms

• V(R1,A) = V(R2,A) = bucket size |B|





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Equi-width vs. Equi-depth

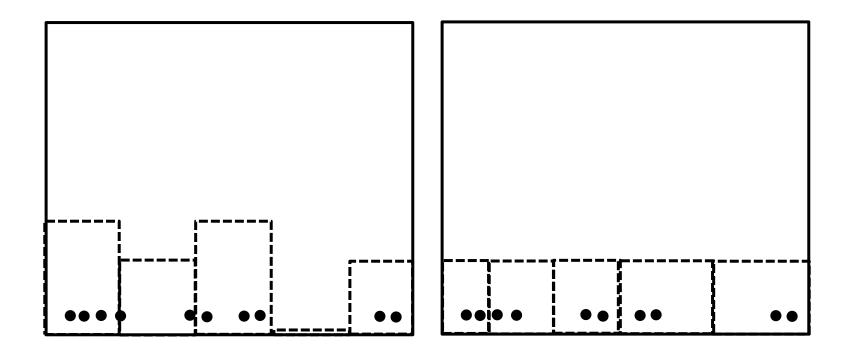
- Equi-width
 - All buckets contain the same number of values
 - Easy, but inaccurate
- Equi-depth (used by most DBMS)
 - All buckets contain the same number of tuples
 - Better accuracy, need to sort data to compute



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Equi-width vs. Equi-depth





Notes 9 - Logical Optimization



Construct Equi-depth Histograms

- Sort input
- Determine size of buckets
 - #bucket / #tuples
- Example 3 buckets
- 1, 5,44, 6,10,12, 3, 6, 7
- 1, 3, 5, 6, 6, 7,10,12,44 [1-5][6-8][9-44]





Advanced Techniques

- Wavelets
- Approximate Histograms
- Sampling Techniques
- Compressed Histograms





<u>Summary</u>

• Estimating size of results is an "art"

 Don't forget:
 Statistics must be kept up to date... (cost?)



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<u>Outline</u>

- Estimating cost of query plan
 - Estimating size of results —— done!
 - Estimating # of IOs
 - Operator Implementations
- Generate and compare plans



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next...

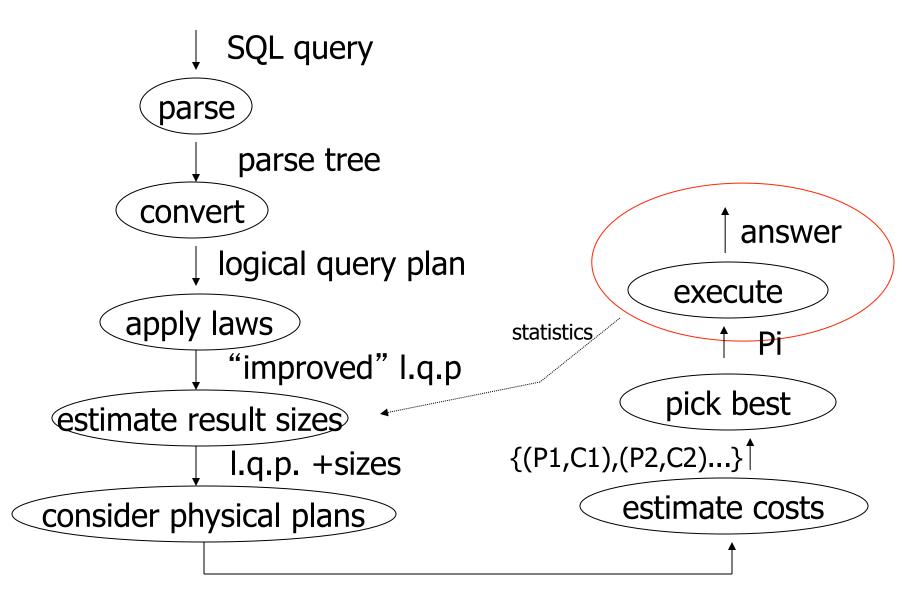
CS 525: Advanced Database Organization **10: Query Execution** Boris Glavic

Slides: adapted from a <u>course</u> taught by <u>Hector Garcia-Molina</u>, Stanford InfoLab



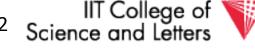
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{P1,P2,....}

Notes 10 - Query Execution



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Query Execution

- Here only:
 - how to implement operators
 - what are the costs of implementations
 - how to implement queries
 - Data flow between operators
- Next part:
 - How to choose good plan





Execution Plan

- A tree (DAG) of physical operators that implement a query
- May use indices
- May create temporary relations
- May create indices on the fly
- May use auxiliary operations such as sorting





How to estimate costs

- If everything fits into memory
 - Standard computational complexity
- If not

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- Assume fixed memory available for buffering pages
- Count I/O operations
- Real systems combine this with CPU estimations





Estimating IOs:

 Count # of disk blocks that must be read (or written) to execute query plan





To estimate costs, we may have additional parameters:

B(R) = # of blocks containing R tuplesf(R) = max # of tuples of R per block M = # memory blocks available





To estimate costs, we may have additional parameters:

B(R) = # of blocks containing R tuples f(R) = max # of tuples of R per block

M = # memory blocks available

HT(i) = # levels in index i LB(i) = # of leaf blocks in index i

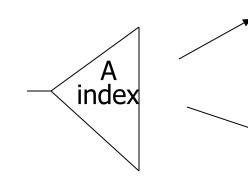


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Clustered index

Index that allows tuples to be read in an order that corresponds to physical order



A	
10	
15	

Λ

19	
35	
37	



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Operators Overview

- (External) Sorting
- Joins (Nested Loop, Merge, Hash, ...)
- Aggregation (Sorting, Hash)
- Selection, Projection (Index, Scan)
- Union, Set Difference
- Intersection
- Duplicate Elimination

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Operator Profiles

- Algorithm
- In-memory complexity: e.g., O(n²)
- Memory requirements
 - Runtime based on available memory
- #I/O if operation needs to go to disk
- Disk space needed
- Prerequisites

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 Conditions under which the operator can be applied





Execution Strategies

- Compiled
 - Translate into C/C++/Assembler code
 - Compile, link, and execute code
- Interpreted

- Generic operator implementations
- Generic executor
 - Interprets query plan





Virtual Machine Approach

- Implement virtual machine of low-level DBMS operations
- Compile query into machine-code for that machine



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Notes 10 - Query Execution



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Iterator Model

- Need to be able to combine operators in different ways
 - E.g., join inputs may be scans, or outputs of other joins, ...
 - -> define generic interface for operators
 - be able to arbitrarily compose complex plans from a small set of operators



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Iterator Model - Interface

• Open

- Prepare operator to read inputs

• Close

- Close operator and clean up

• Next

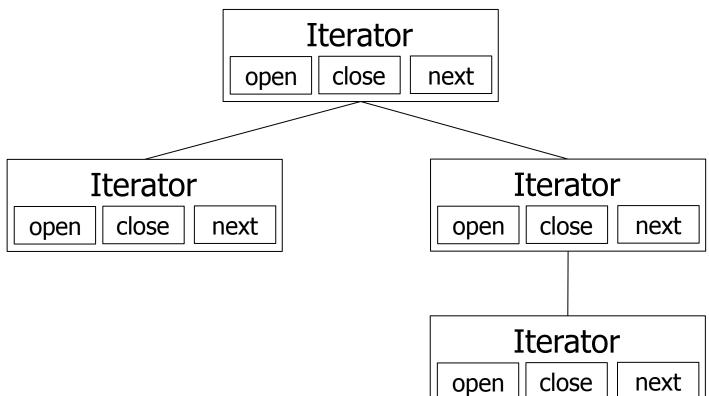
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Return next result tuple





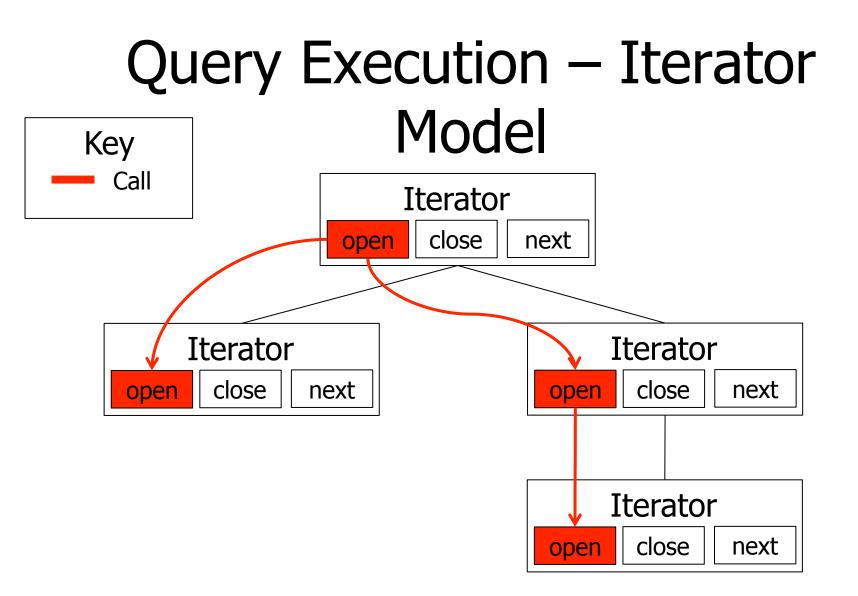
Query Execution – Iterator Model





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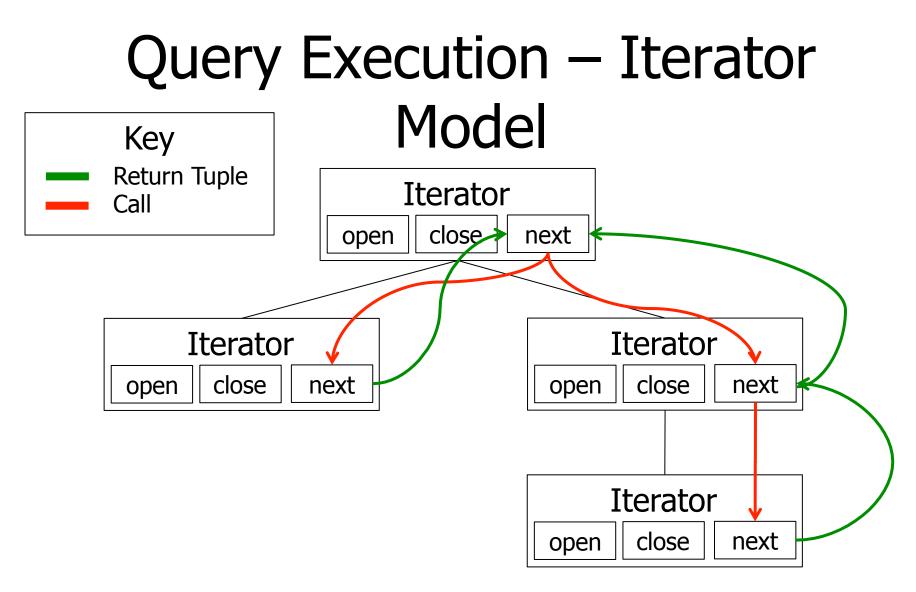


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Notes 10 - Query Execution



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Parallelism

- Iterator Model
 - Pull-based query execution
- Potential types of parallelism
 - Inter-query (every multiuser system)
 - Intra-operator
 - Inter-operator





Intra-Operator Parallelism

- Execute portions of an operator in parallel
 - Merge-Sort
 - Assign a processor to each merge phase
 - Scan

- Partition tables
- Each process scans one partition





Inter-Operator Parallelism

- Each process executes one or more operators
- Pipelining
 - Push-based query execution
 - Chain operators to directly produce results
 - Pipeline-breakers
 - Operators that need to consume the whole input (or large parts) before producing outputs



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Notes 10 - Query Execution



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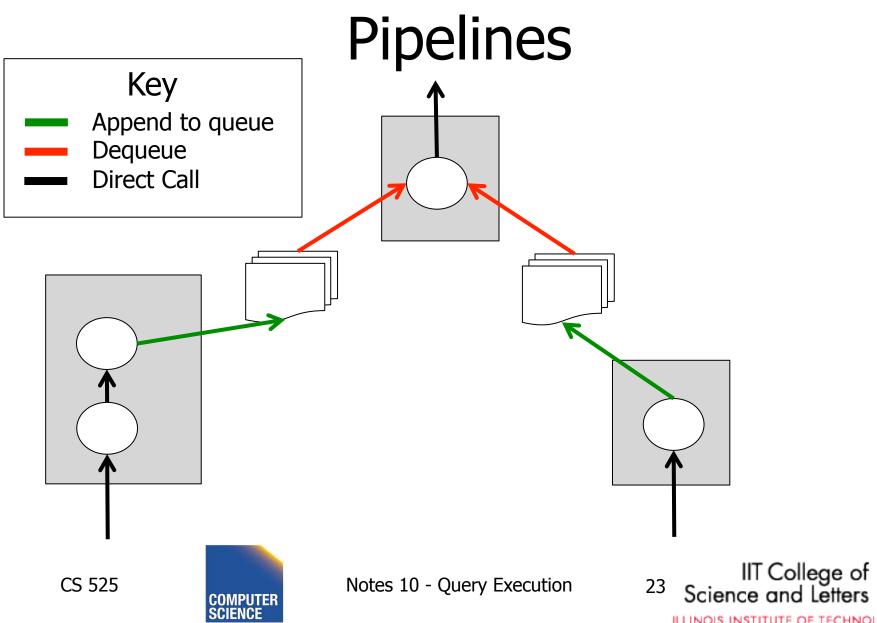
Pipelining Communication

• Queues

- Operators push their results to queues
- Operators read their inputs from queues
- Direct call
 - Operator calls its parent in the tree with results
 - Within one process







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Pipeline-breakers

- Sorting
 - All operators that apply sorting
- Aggregation
- Set Difference
- Some implementations of
 - Join

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– Union





Operators Overview

- (External) Sorting
- Joins (Nested Loop, Merge, Hash, ...)
- Aggregation (Sorting, Hash)
- Selection, Projection (Index, Scan)
- Union, Set Difference
- Intersection
- Duplicate Elimination

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Sorting

- Why do we want/need to sort
 - Query requires sorting (ORDER BY)
 - Operators require sorted input
 - Merge-join
 - Aggregation by sorting
 - Duplicate removal using sorting





In-memory sorting

- Algorithms from data structures 101
 - Quick sort
 - Merge sort
 - Heap sort
 - Intro sort





External sorting

- Problem:
 - Sort N pages of data with M pages of memory
- Solutions?

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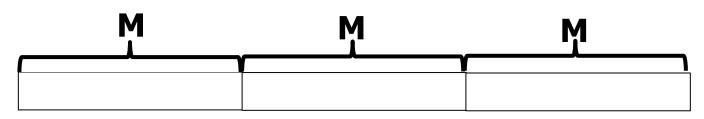




First Idea

- Split data into runs of size **M**
- Sort each run in memory and write back to disk
 - [N/M] sorted runs of size M
- Now what?

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Merging Runs

- Need to create bigger sorted runs out of sorted smaller runs
 - Divide and Conquer
 - Merge Sort?
- How to merge two runs that are bigger than M?



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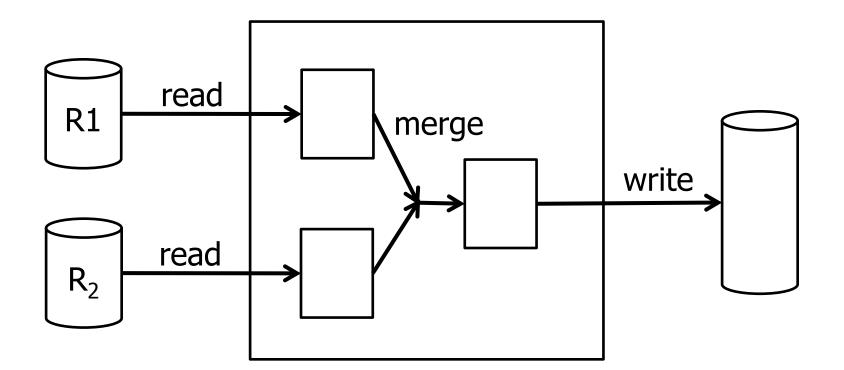
Merging Runs using 3 pages

- Merging sorted runs R₁ and R₂
- Need 3 pages
 - One page to buffer pages from R_1
 - One page to buffer pages from R_2
 - One page to buffer the result
 - Whenever this buffer is full, write it to disk





Merging Runs





Notes 10 - Query Execution



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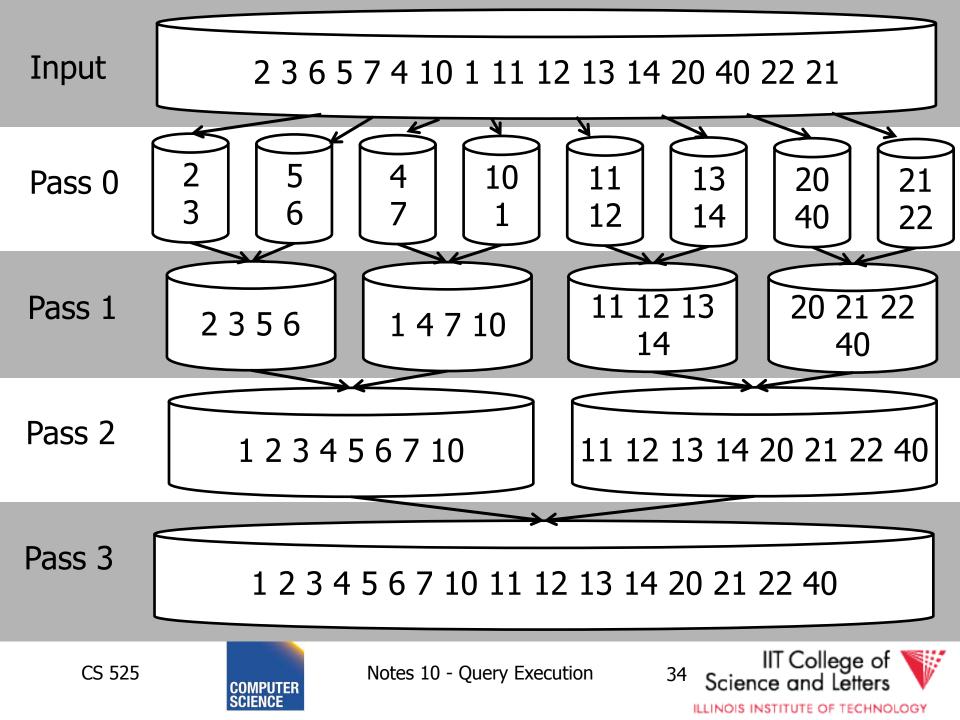
2-Way External Mergesort

- Repeat process until we have one sorted run
- Each iteration (pass) reads and writes the whole table once: 2 B(R) I/Os
- Each pass doubles the run size
 - 1 + [log₂ (B(R) / M)] runs
 - 2 B(R) * (1 + [log₂ (B(R) / M)]) I/Os



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N-Way External Mergesort

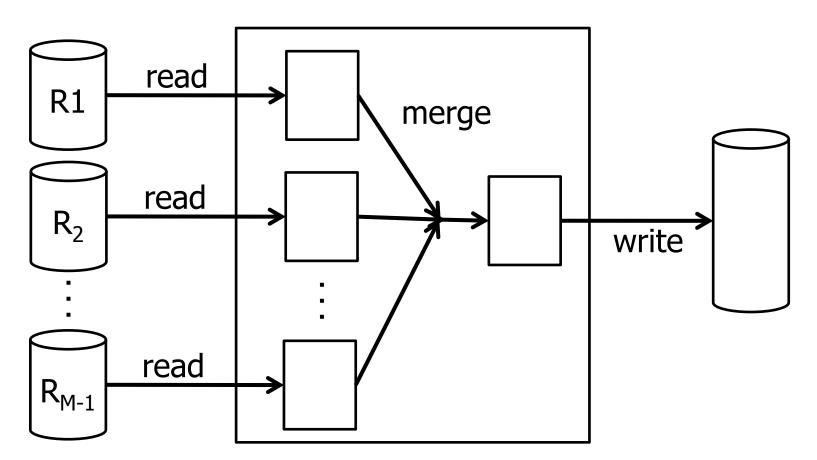
- How to utilize **M** buffer during merging?
- Each pass merges M-1 runs at once
 One memory page as buffer for each run
- #I/Os

1 + [log_{M-1} (B(R) / M)] runs 2 B(R) *(1 + [log_{M-1} (B(R) / M)]) I/Os





Merging Runs







How many passes do we need?

Ν	M=17	M=129	M=257	M=513	M=1025
100	2	1	1	1	1
1,000	3	2	2	2	1
10,000	4	2	2	2	2
100,000	5	3	3	2	2
1,000,000	5	3	3	3	2
10,000,000	6	4	3	3	3
100,000,000	7	4	4	3	3
1,000,000,000	8	5	4	4	3



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To put into perspective

- Scenario
 - Page size 4KB
 - 1TB of data (250,000,000)
 - 10MB of buffer for sorting (250)
- Passes
 - -4 passes





Merge

- In practice would want larger I/O buffer for each run
- Trade-off between number of runs and efficiency of I/O



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Improving in-memory merging

- Merging **M** runs
 - To choose next element to output
 - Have to compare **M** elements
 - --> complexity linear in M: O(M)
- How to improve that?
 - Use priority queue to store current element from each run
 - --> O(log₂(M))



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Priority Queue

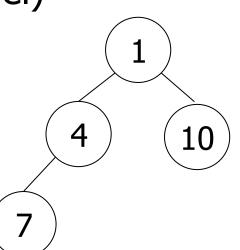
- Queue for accessing elements in some given order
 - -pop-smallest = return and remove
 smallest element in set
 - -Insert(e) = insert element into queue





Min-Heap

- Implementation of priority queue
 - Store elements in a binary tree
 - All levels are full (except leaf level)
 - Heap property
 - Parent is smaller than child
- Example: { 1, 4, 7, 10 }







Min-Heap Insertion

- insert(e)
 - 1. Add element at next free leaf node
 - This may invalidate heap property
 - 2. If node smaller than parent then
 - Switch node with parent
 - 3. Repeat until 2) cannot be applied anymore





Min-Heap Dequeue

• pop-smallest

- 1. Return Root and use right-most leaf as new root
 - This may invalidate heap property
- 2. If node smaller than child then
 - Switch node with smaller child
- 3. Repeat until 2) cannot be applied anymore

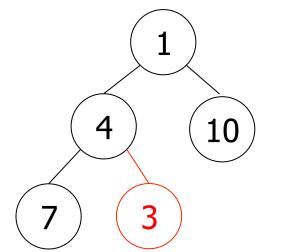




Insertion

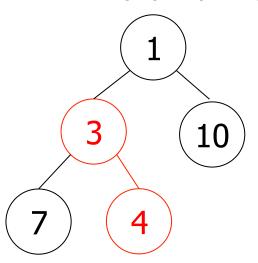
• Insert 3





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Restore heap property







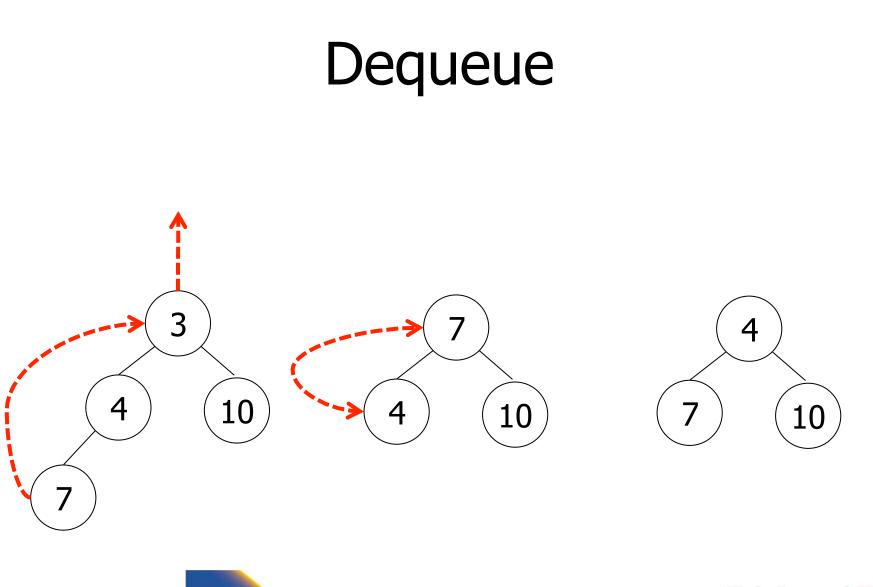
Dequeue $\mathbf{\Lambda}$



Notes 10 - Query Execution



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Min/Max-Heap Complexity

- Heap is a complete tree
 Height is O(log₂(n))
- Insertion
 - Maximal height of the tree switches
 - $--> O(log_{2}(n))$
- Dequeue
 - Maximal height of the tree switches
 - --> O(log₂(n))

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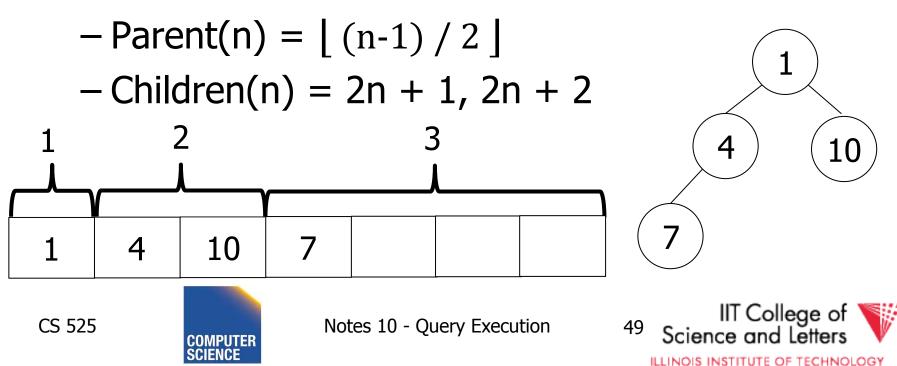


Min-Heap Implementation

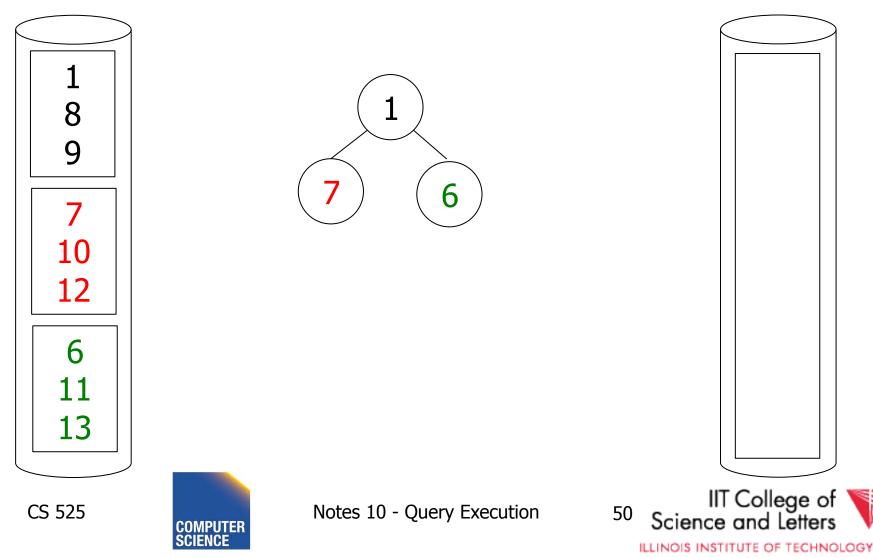
• Full tree

– Use array to implement tree

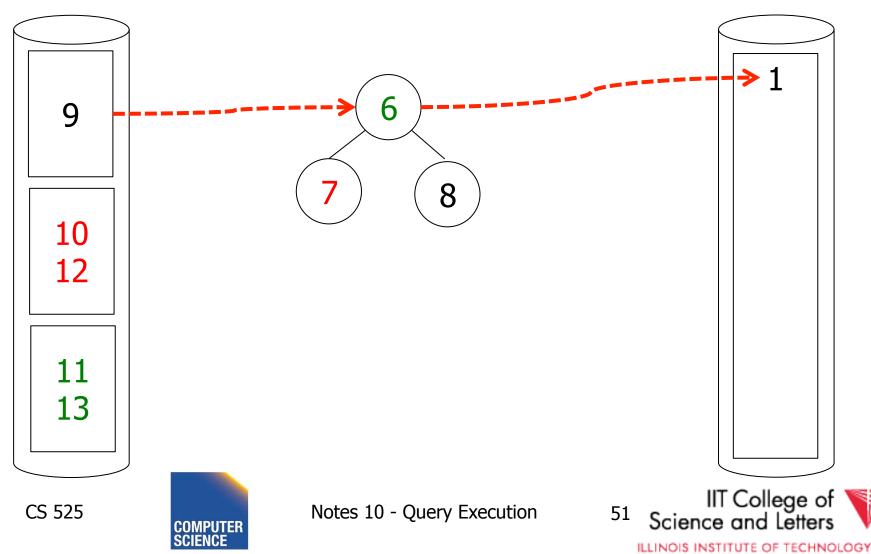
Compute positions



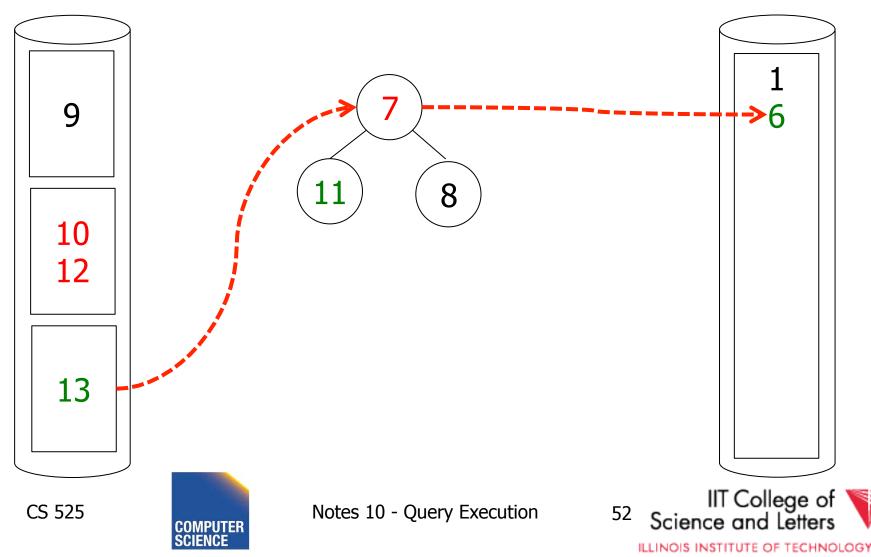
Merging with Priority Queue



Merging with Priority Queue



Merging with Priority Queue

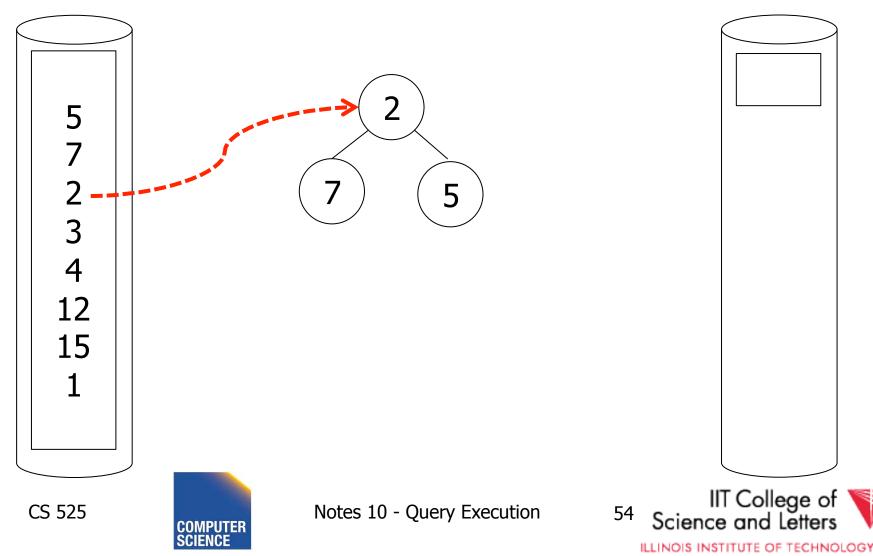


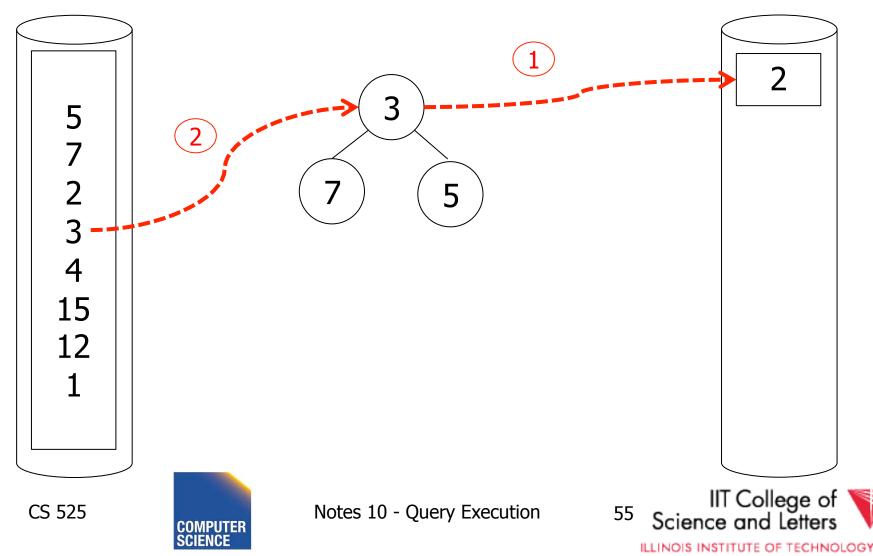
- Read inputs into heap
 Until available memory is full
- Replace elements
 - Remove smallest element from heap
 - If larger then last element written of current run then write to current run
 - Else create a new run
 - Add new element from input to heap

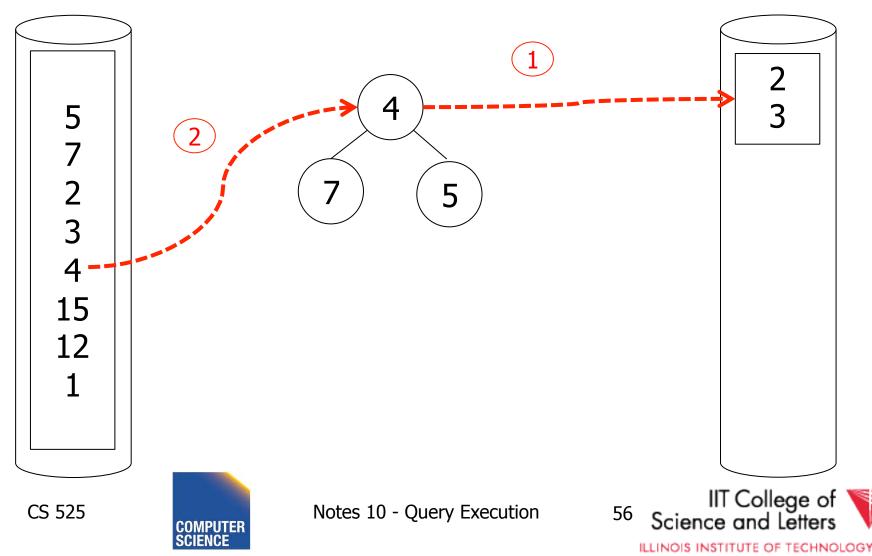


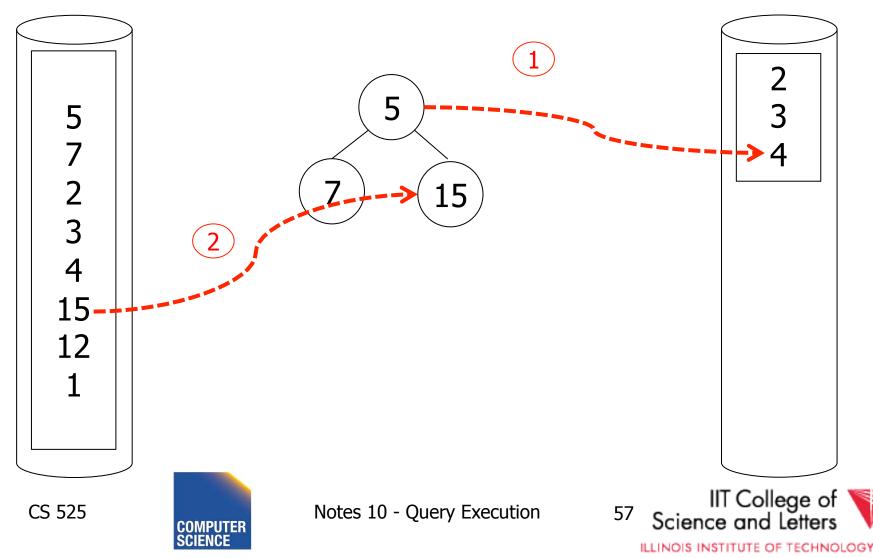
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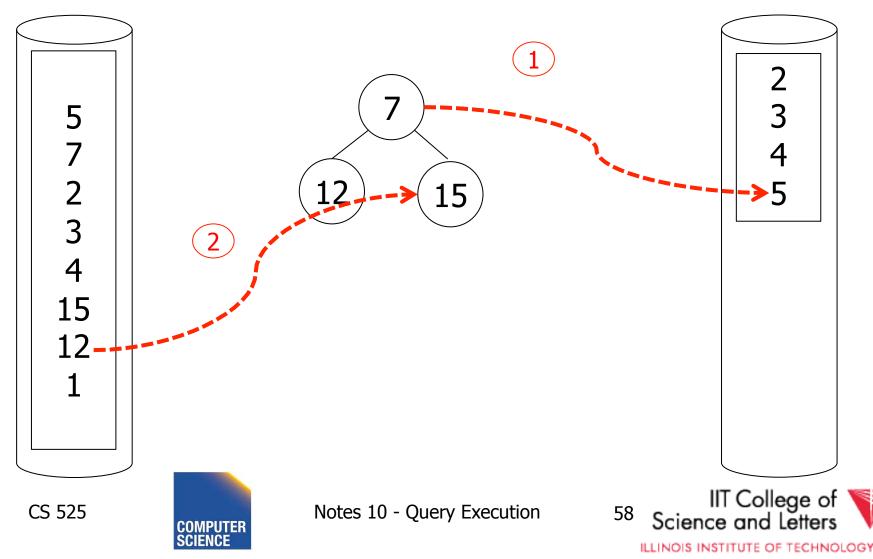


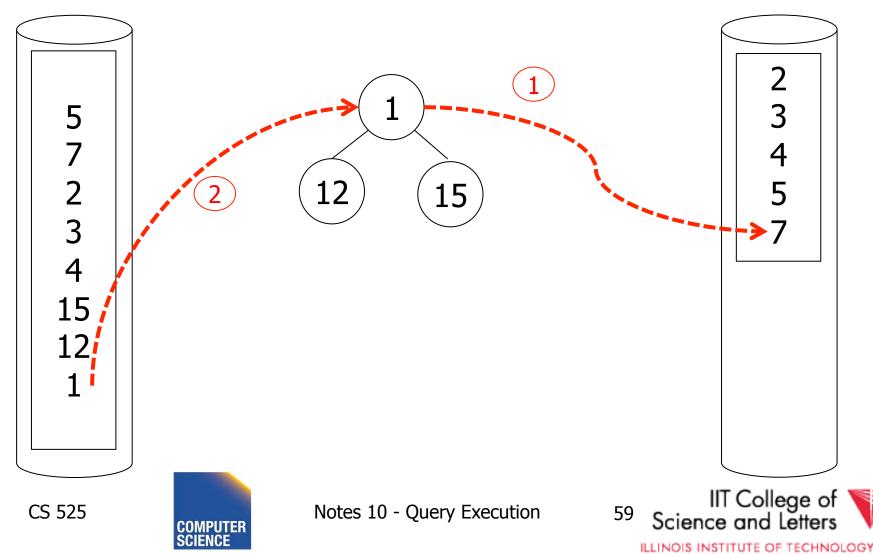


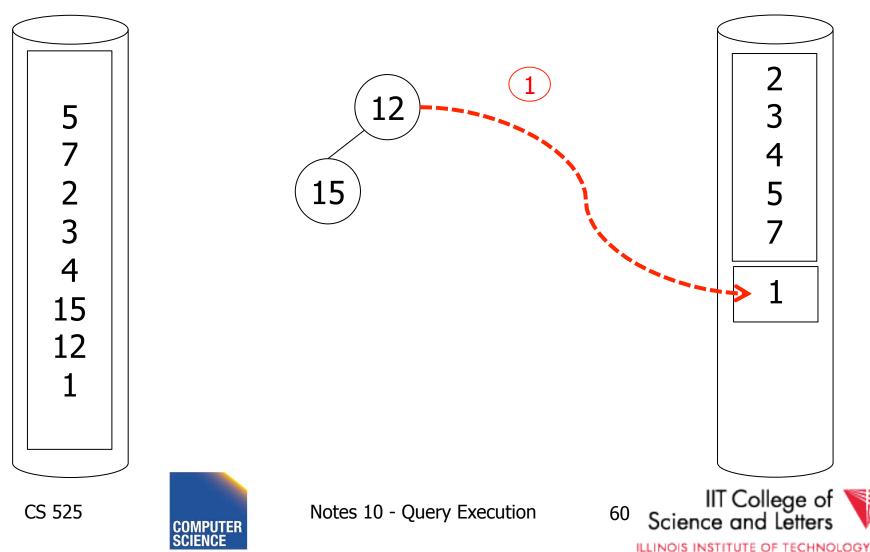












Increases the run-length
 On average by a factor of 2 (see Knuth)





Use clustered B+-tree

- Keys in the B+-tree **I** are in sort order
 - If B+-tree is clustered traversing the leaf nodes is sequential I/O!
 - K = #keys/leaf node
- Approach

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- Traverse from root to first leaf: HT(I)
- Follow sibling pointers: **|R| / K**
- Read data blocks: B(R)





I/O Operations

- HT(I) + |R| / K + B(R) I/Os
- Less than 2 B(R) = 1 pass external mergesort
- ->Better than external merge-sort!



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Unclustered B+-tree?

- Each entry in a leaf node may point to different page of relation R
 - For each leaf page we may read up to K pages from relation R
 - Random I/O
- In worst-case we have
 - -K * B(R)
 - K = 500

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• 500 * B(R) = 250 merge passes





Sorting Comparison

B(R) = number of block of R
M = number of available memory blocks
#RB = records per page
HT = height of B+-tree (logarithmic)
K = number of keys per leaf node

Property	Ext. Mergesort	B+ (clustered)	B+ (unclustered)
Runtime	O (N log _{M-1} (N))	O(N)	O(N)
#I/O (random)	2 B(R) *(1 + [log _{M-1} (B(R) / M)])	HT + R / K + B(R)	HT + R / K + K * #RB
Memory	Μ	1 (better HT + X)	1 (better HT + X)
Disk Space	2 B(R)	0	0
Variants	 Merge with heap Run generation with heap Larger Buffer 		
CS 525		Query Execution 65	Science and Letters

Operators Overview

- (External) Sorting
- Joins (Nested Loop, Merge, Hash, ...)
- Aggregation (Sorting, Hash)
- Selection, Projection (Index, Scan)
- Union, Set Difference
- Intersection

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Duplicate Elimination





Scan

- Implements access to a table
 - Combined with selection
 - Probably projection too
- Variants

- Sequential

• Scan through all tuples of relation

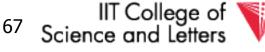
– Index

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• Use index to find tuples that match selection



Notes 10 - Query Execution



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Operators Overview

- (External) Sorting
- Joins (Nested Loop, Merge, Hash, ...)
- Aggregation (Sorting, Hash)
- Selection, Projection (Index, Scan)
- Union, Set Difference
- Intersection

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Duplicate Elimination







- Transformations: $R_1 \Join_c R_2$, $R_2 \Join_c R_1$
- Joint algorithms:
 - Nested loop
 - Merge join
 - Join with index
 - Hash join

Outer join algorithms





<u>Nested Loop Join</u> (conceptually) for each $r \in R_1$ do for each $s \in R_2$ do if (r,s) ⊨ C then output (r,s)

Applicable to:

CS 525

- Any join condition C
- Cross-product





Merge Join (conceptually)

(1) if R₁ and R₂ not sorted, sort them (2) i \leftarrow 1; j \leftarrow 1; While (i \leq T(R₁)) \land (j \leq T(R₂)) do if R₁{ i }.C = R₂{ j }.C then outputTuples else if R₁{ i }.C > R₂{ j }.C then j \leftarrow j+1 else if R₁{ i }.C < R₂{ j }.C then i \leftarrow i+1

Applicable to:

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• C is conjunction of equalities or </> : $A_1 = B_1 AND ... AND A_n = B_n$





```
Procedure Output-Tuples
  While (R_1 \{ i \}, C = R_2 \{ j \}, C) \land (i \leq T(R_1)) do
       [ji ← j;
       while (R_1\{i\}, C = R_2\{jj\}, C) \land (jj \leq T(R_2)) do
                    [output pair R_1{ i }, R_2{ jj };
                    jj ← jj+1 ]
       i ← i+1 ]
```





Example

i	R ₁ {i}.C	R ₂ {j}.C	j
1	10	5	1
2	20	20	2
3	20	20	3
4	30	30	4
5	40	30	5
		50	6
		52	7



Notes 10 - Query Execution



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Index nested loop (Conceptually)

For each $r \in R_1$ do [X ← index (R_2 , C, r.C) for each $s \in X$ do output (r,s) pair]

Note:
$$X \leftarrow$$
 index(rel, attr, value)
then $X =$ set of rel tuples with attr = value



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Notes 10 - Query Execution



Assume R₂.C index

Hash join (conceptual) Hash function h, range $0 \rightarrow k$ Buckets for R₁: G₀, G₁, ... G_k Buckets for R₂: H₀, H₁, ... H_k

Applicable to:

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• C is conjunction of equalities $A_1 = B_1 \text{ AND } \dots \text{ AND } A_n = B_n$





Hash join (conceptual) Hash function h, range $0 \rightarrow k$ Buckets for R₁: G₀, G₁, ... G_k Buckets for R₂: H₀, H₁, ... H_k

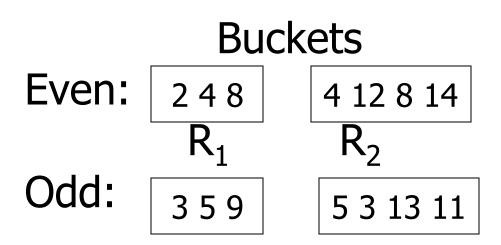
Algorithm (1) Hash R₁ tuples into G buckets (2) Hash R₂ tuples into H buckets (3) For i = 0 to k do match tuples in G_i, H_i buckets



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Factors that affect performance

- (1) Tuples of relation stored physically together?
- (2) Relations sorted by join attribute?

(3) Indexes exist?



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Example 1(a) NL Join $R_1 \bowtie R_2$

- Relations <u>not</u> contiguous
- Recall $\begin{cases} T(R_1) = 10,000 & T(R_2) = 5,000 \\ S(R_1) = S(R_2) = 1/10 & block \\ MEM = 101 & blocks \end{cases}$



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Example 1(a) Nested Loop Join $R_1 \bowtie R_2$

- Relations <u>not</u> contiguous
- Recall $\begin{cases} T(R_1) = 10,000 & T(R_2) = 5,000 \\ S(R_1) = S(R_2) = 1/10 & block \\ MEM = 101 & blocks \end{cases}$

Cost: for each R_1 tuple: [Read tuple + Read R_2] Total =10,000 [1+500]=5,010,000 IOs



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• Can we do better?



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• Can we do better?

Use our memory

- (1) Read 100 blocks of R_1
- (2) Read all of R_2 (using 1 block) + join
- (3) Repeat until done



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Cost: for each R_1 chunk: Read chunk: 100 IOs Read R_2 : 500 IOs 600



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Cost: for each R_1 chunk: Read chunk: 100 IOs Read R_2 : 500 IOs 600

Total = $\frac{1,000}{100} \times 600 = 6,000$ IOs



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• Can we do better?



Notes 10 - Query Execution



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- Can we do better?
 - Reverse join order: $R_2 \triangleright \lhd R_1$
 - Total = $\frac{500}{100}$ x (100 + 1,000) =

5 x 1,100 = 5,500 IOs



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Cost of Block Nested Loop

• Reverse join order: $R_1 > R_2$ Total = $\overline{B(R1)}$ x (min(B(R1), M-1) + B(R2)) M-1



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Block-Nested Loop Join (conceptual) for each M-1 blocks of R₁ do read M-1 blocks of R₁ into buffer for each block of R₂ do read next block of R₂ for each tuple r in R₁ block for each tuple s in R₂ block if $(r,s) \models C$ then output (r,s)





Note

- How much memory for buffering inner and for outer chunks?
 - 1 for inner would minimize I/O
 - But, larger buffer better for I/O



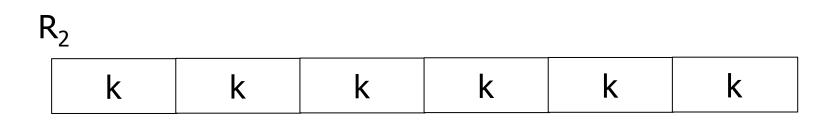
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R_1

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M - k	M - k	M - k
-------	-------	-------



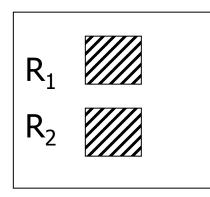




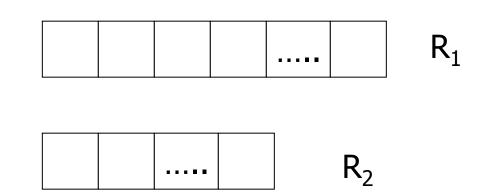
Example 1(b) Merge Join

• Both R₁, R₂ ordered by C; relations contiguous

Memory



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Example 1(b) Merge Join

• Both R₁, R₂ ordered by C; relations contiguous

$\begin{bmatrix} \mathsf{R}_1 & & & \\ \mathsf{R}_2 & & & \\ \hline & & & \\ \end{bmatrix}$

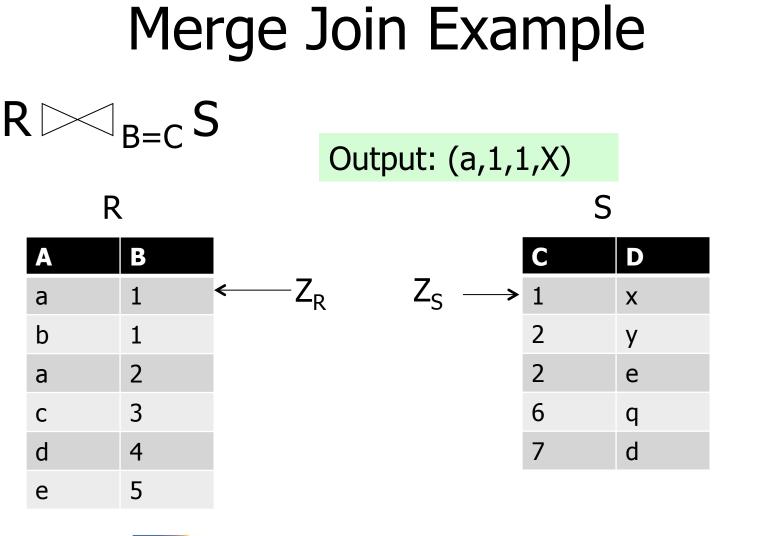
Total cost: Read $R_1 cost + read R_2 cost$ = 1000 + 500 = 1,500 IOs



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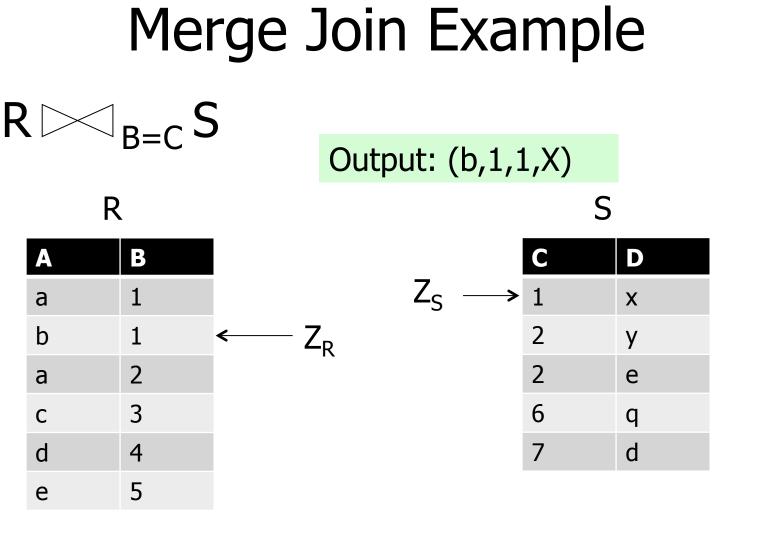
Memory









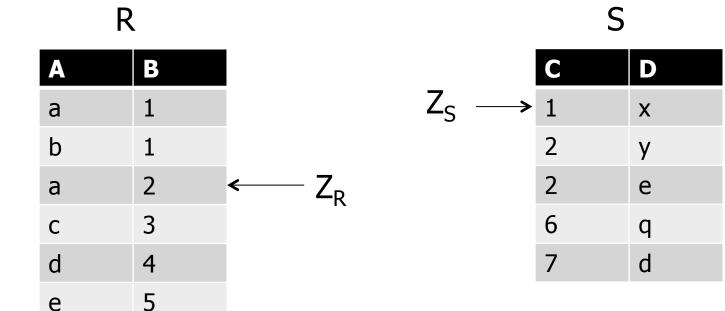






Merge Join Example

R.B > S.C: advance Z_{s}



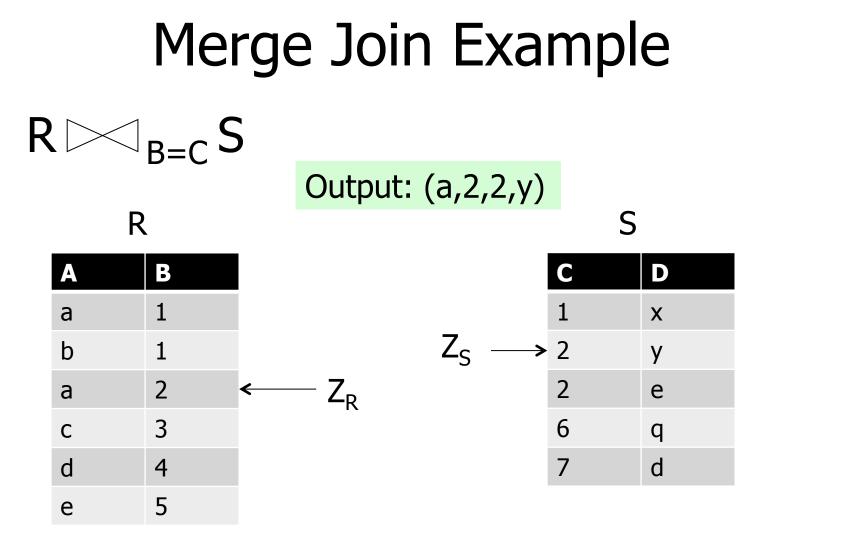


B=C S

R

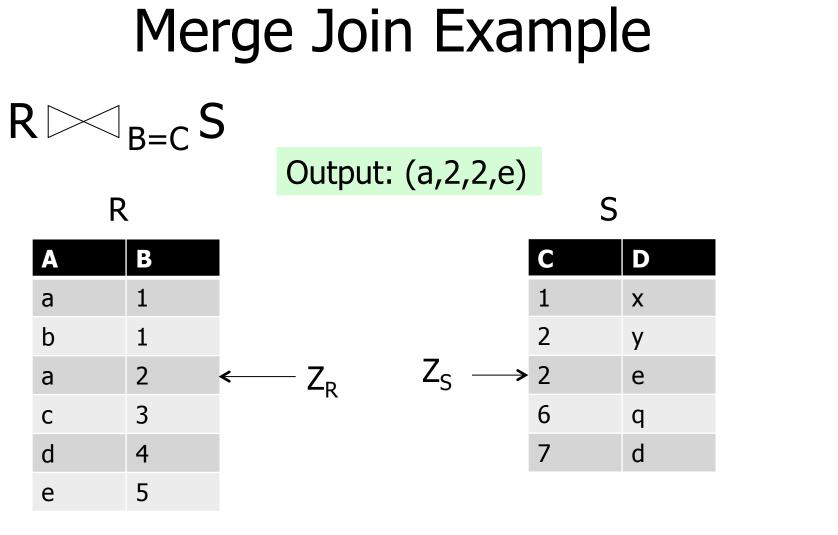
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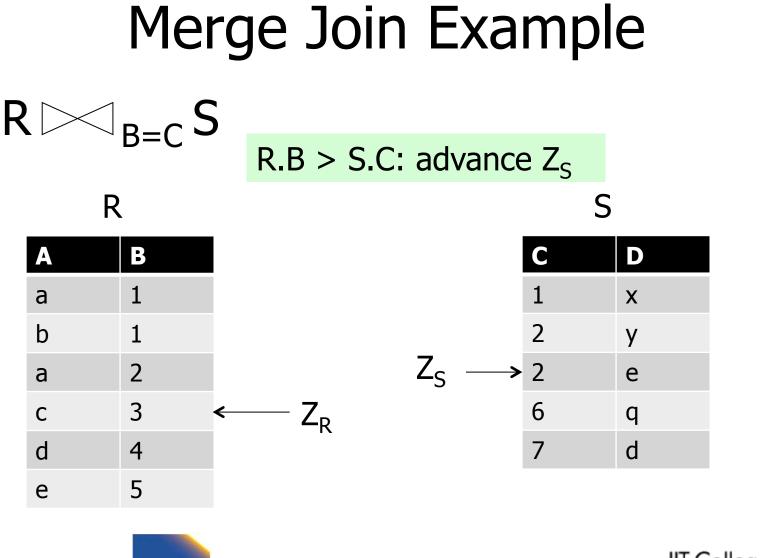








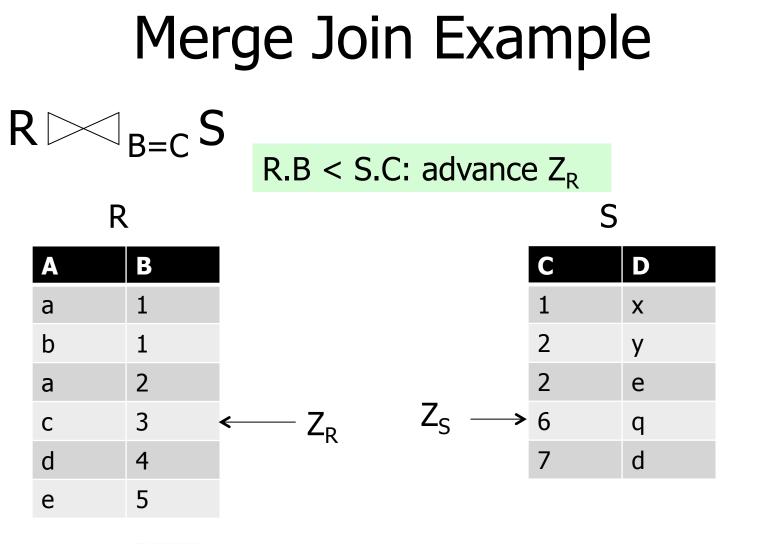






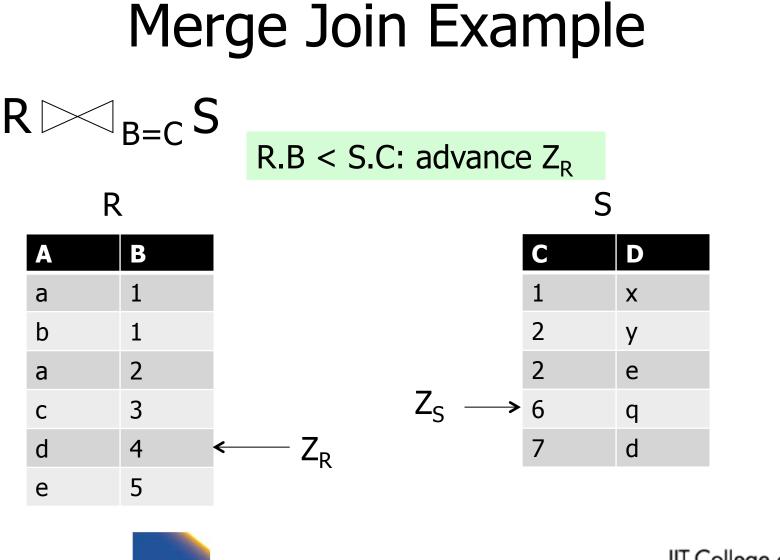








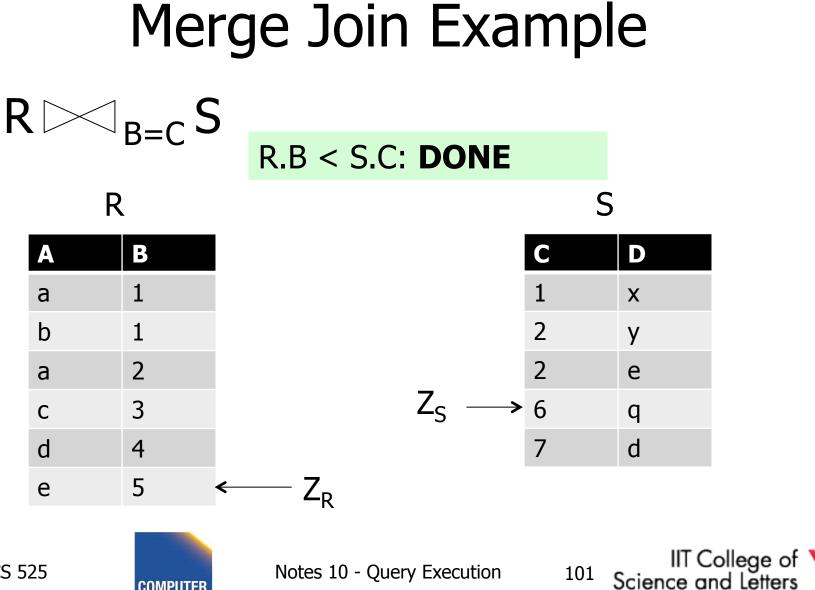






Notes 10 - Query Execution

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Example 1(c) Merge Join

• R₁, R₂ <u>not</u> ordered, but contiguous

--> Need to sort R_1 , R_2 first



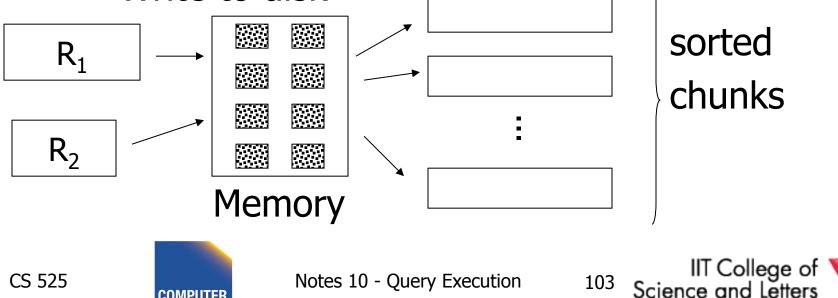
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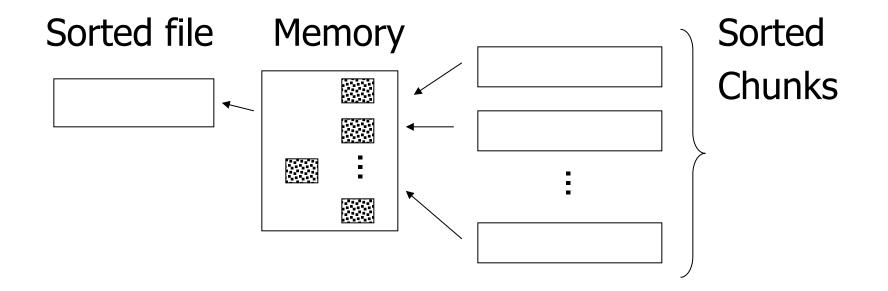
One way to sort: Merge Sort

(i) For each 100 blk chunk of R:

- Read chunk
- Sort in memory
- Write to disk



(ii) Read all chunks + merge + write out





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Cost: Sort Each tuple is read, written, read, written so... Sort cost R_1 : $4 \times 1,000 = 4,000$ Sort cost R_2 : $4 \times 500 = 2,000$



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Example 1(d) Merge Join (continued)

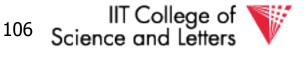
R₁,R₂ contiguous, but unordered

Total cost = sort cost + join cost = 6,000 + 1,500 = 7,500 IOs



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Notes 10 - Query Execution



Example 1(c) Merge Join (continued)

R₁,R₂ contiguous, but unordered

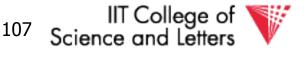
Total cost = sort cost + join cost = 6,000 + 1,500 = 7,500 IOs

<u>But:</u> Iteration cost = 5,500 so merge joint does not pay off!



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Notes 10 - Query Execution



- But say $R_1 = 10,000$ blocks contiguous $R_2 = 5,000$ blocks not ordered
- <u>Iterate:</u> $5000 \times (100+10,000) = 50 \times 10,100$ 100 = 505,000 IOs
- <u>Merge join:</u> 5(10,000+5,000) = 75,000 IOs

Merge Join (with sort) WINS!

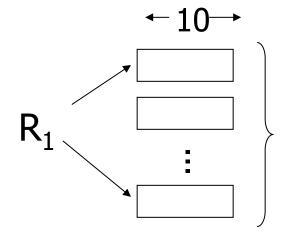


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How much memory do we need for merge sort?

E.g: Say I have 10 memory blocks



100 chunks \Rightarrow to merge, need 100 blocks!



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In general:

Say k blocks in memory x blocks for relation sort # chunks = (x/k) size of chunk = k



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Notes 10 - Query Execution



In general:

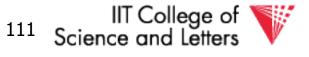
Say k blocks in memory x blocks for relation sort # chunks = (x/k) size of chunk = k

chunks < buffers available for merge</pre>



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Notes 10 - Query Execution



In general:

Say k blocks in memory x blocks for relation sort # chunks = (x/k) size of chunk = k

chunks < buffers available for merge</pre>

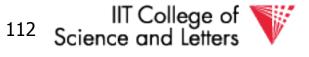
so...
$$(x/k) \le k$$

or $k^2 \ge x$ or $k \ge \sqrt{x}$



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Notes 10 - Query Execution



In our example

R_1 is 1000 blocks, k ≥ 31.62 R_2 is 500 blocks, k ≥ 22.36

Need at least 32 buffers

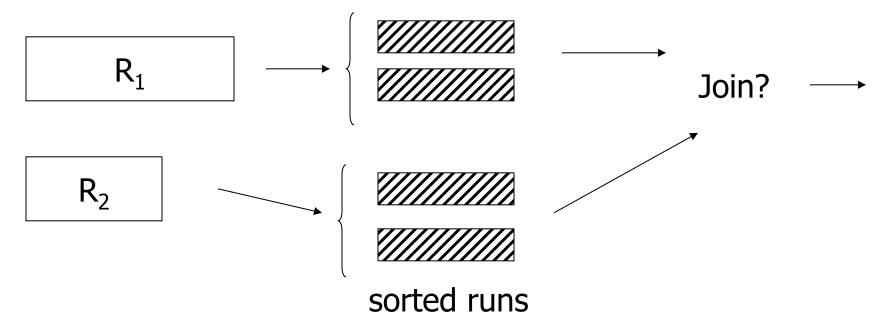
Again: in practice we would not want to use only one buffer per run!



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Can we improve on merge join? Hint: do we really need the fully sorted files?





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Cost of improved merge join:

- $C = Read R_1 + write R_1$ into runs
 - + read R₂ + write R₂ into runs
 - + join

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- = 2,000 + 1,000 + 1,500 = 4,500
- --> Memory requirement?





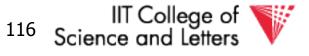
Example 1(d) Index Join

- Assume R₁.C index exists; 2 levels
- Assume R₂ contiguous, unordered
- Assume R₁.C index fits in memory



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Notes 10 - Query Execution

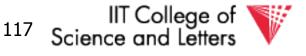


<u>Cost:</u> Reads: 500 IOs for each R₂ tuple: - probe index - free - if match, read R₁ tuple: 1 IO



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Notes 10 - Query Execution



What is expected # of matching tuples?

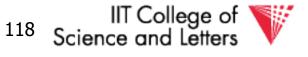
(a) say R_1 .C is key, R_2 .C is foreign key then expect = 1

(b) say $V(R_1,C) = 5000$, $T(R_1) = 10,000$ with uniform assumption expect = 10,000/5,000 = 2



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Notes 10 - Query Execution



What is expected # of matching tuples?

(c) Say DOM(R₁, C)=1,000,000 T(R₁) = 10,000 with alternate assumption Expect = $\frac{10,000}{1,000,000} = \frac{1}{100}$



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Total cost with index join

(a) Total cost = 500+5000(1)1 = 5,500

(b) Total cost = 500+5000(2)1 = 10,500

(c) Total cost = 500+5000(1/100)1=550



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What if index does not fit in memory?

Example: say R₁.C index is 201 blocks

- Keep root + 99 leaf nodes in memory
- Expected cost of each probe is

$$E = (0)\underline{99} + (1)\underline{101} \approx 0.5$$

200 200



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Total cost (including probes)

- = 500+5000 [Probe + get records]
- = 500+5000 [0.5+2] uniform assumption
- = 500+12,500 = 13,000 (case b)



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Notes 10 - Query Execution



Total cost (including probes)

- = 500+5000 [Probe + get records]
- = 500+5000 [0.5+2] uniform assumption
- = 500+12,500 = 13,000 (case b)

For case (c):

- $= 500+5000[0.5 \times 1 + (1/100) \times 1]$
- = 500+2500+50 = 3050 IOs



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So far

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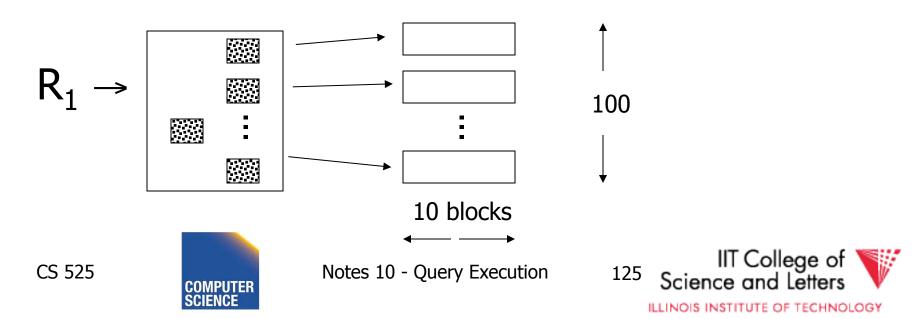
- Nested Loop Merge join Sort+Merge Join R₁.C Index R₂.C Index
- 5500 1500 7500 → 4500 5500 → 3050 → 550



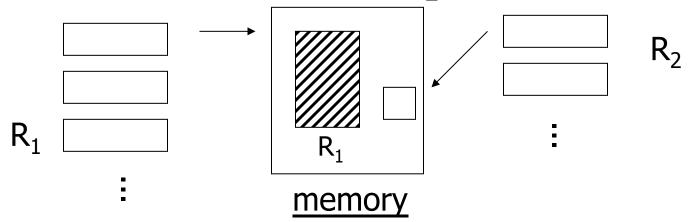


Example 1(e) Partition Hash Join

- R_1 , R_2 contiguous (un-ordered) \rightarrow Use 100 buckets
- \rightarrow Read R₁, hash, + write buckets



- -> Same for R₂
- -> Read one R₁ bucket; build memory hash table -using different hash function h'
- -> Read corresponding R_2 bucket + hash probe



⇒ Then repeat for all buckets



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"Bucketize:" Read R_1 + write Read R_2 + write Join: Read R_1 , R_2

Total cost = $3 \times [1000+500] = 4500$







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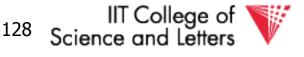
"Bucketize:" Read R_1 + write Read R_2 + write Join: Read R_1 , R_2

Total cost = $3 \times [1000+500] = 4500$

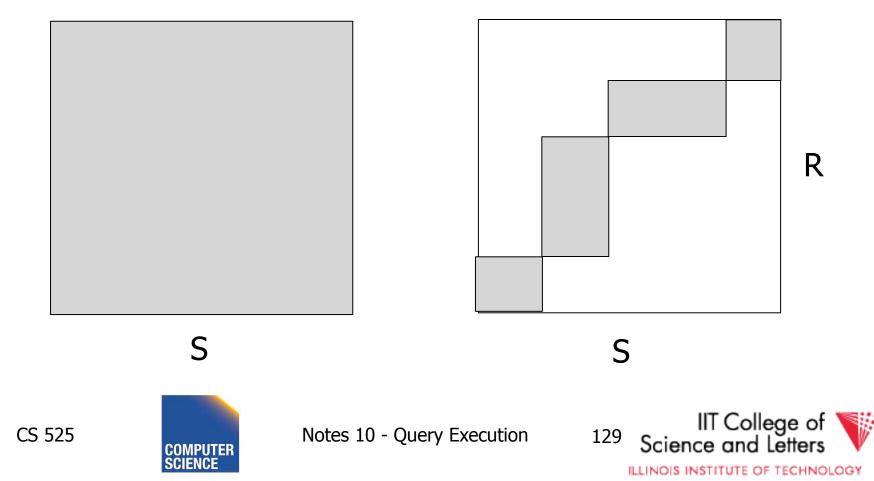
<u>Note:</u> this is an approximation since buckets will vary in size and we have to round up to blocks



Notes 10 - Query Execution



Why is Hash Join good?



R

Minimum memory requirements:

Size of R_1 bucket = (x/k) k = number of memory buffers x = number of R_1 blocks

So... (x/k) < k

 $k > \sqrt{x}$

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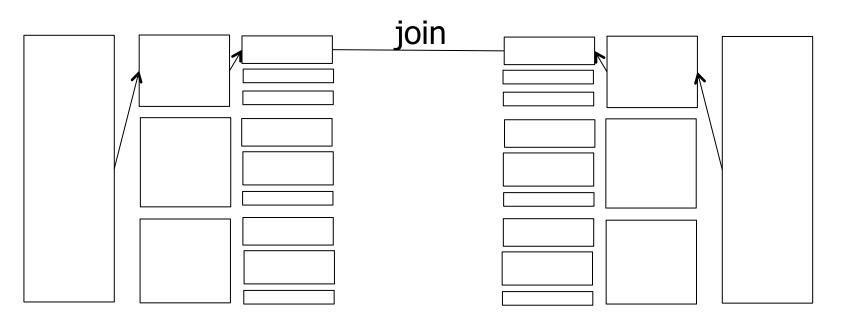
need: k+1 total memory buffers





Can we use Hash-join when buckets do not fit into memory?:

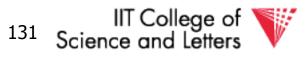
• Treat buckets as relations and apply Hash-join recursively





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Notes 10 - Query Execution



Duality Hashing-Sorting

- Both partition inputs
- Until input fits into memory
- Logarithmic number of phases in memory size

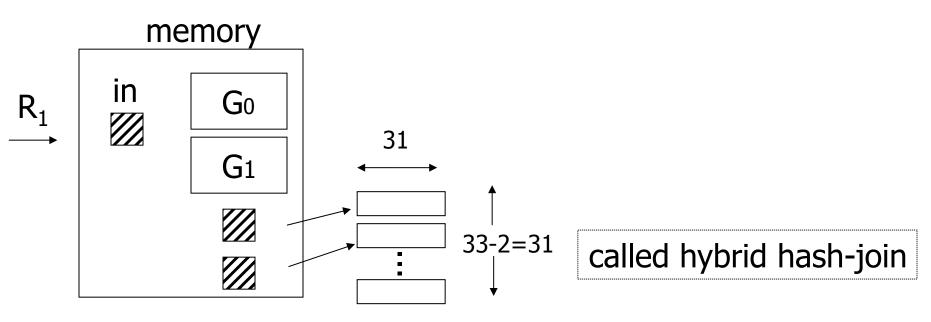


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Trick: keep some buckets in memory

E.g., k' = 33 R_1 buckets = 31 blocks keep 2 in memory



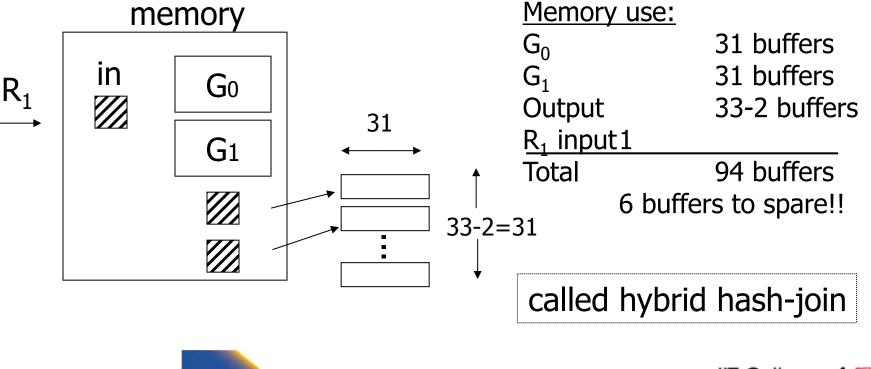


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Trick: keep some buckets in memory

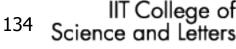
E.g., k' = 33 R_1 buckets = 31 blocks keep 2 in memory





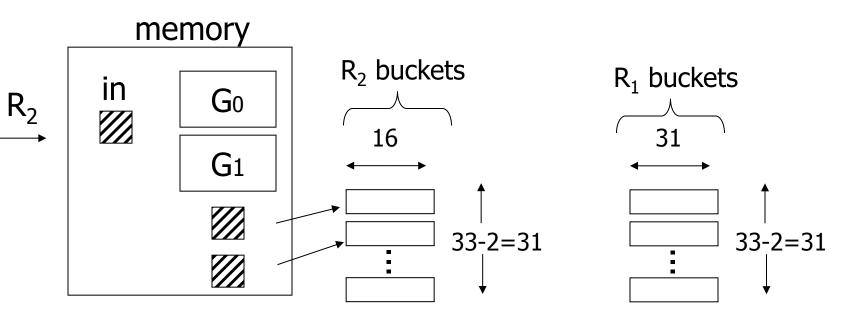


Notes 10 - Query Execution



Next: Bucketize R₂

- $-R_2$ buckets =500/33= 16 blocks
- Two of the $\rm R_2$ buckets joined immediately with $\rm G_0, \rm G_1$

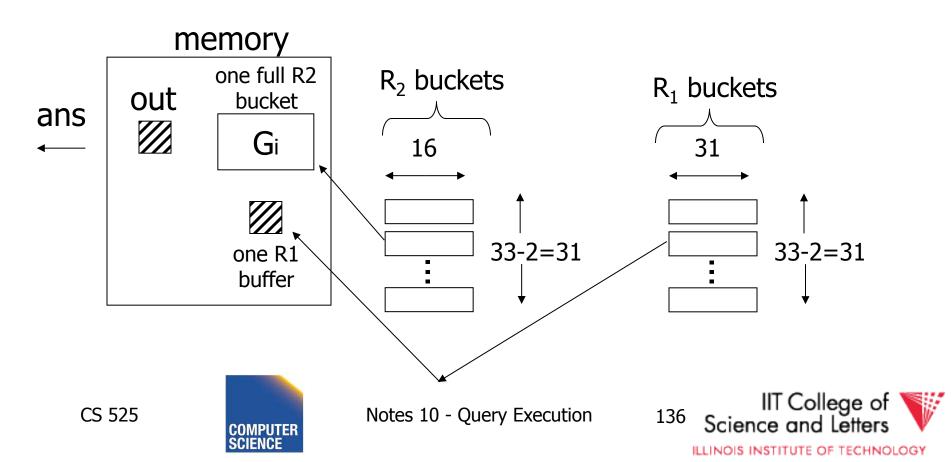






Finally: Join remaining buckets

- for each bucket pair:
 - read one of the buckets into memory
 - join with second bucket



<u>Cost</u>

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- Bucketize $R_1 = 1000 + 31 \times 31 = 1961$
- To bucketize R_2 , only write 31 buckets: so, cost = 500+31×16=996
- To compare join (2 buckets already done) read 31×31+31×16=1457

Total cost = 1961 + 996 + 1457 = 4414

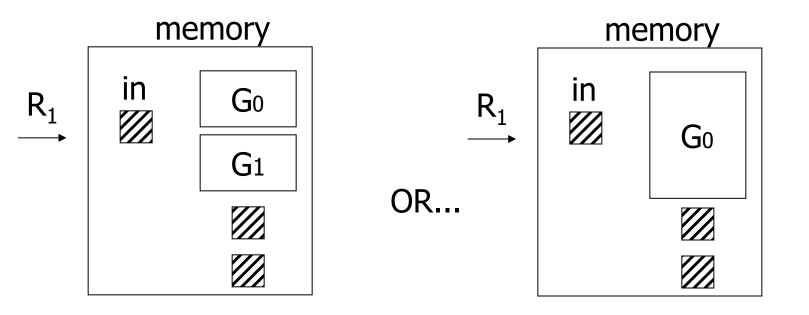


Notes 10 - Query Execution



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How many buckets in memory?



See textbook for answer...



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Notes 10 - Query Execution



?

Another hash join trick:

- Only write into buckets <val,ptr> pairs
- When we get a match in join phase, must fetch tuples



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• To illustrate cost computation, assume:

- 100 <val,ptr> pairs/block

– expected number of result tuples is 100



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- To illustrate cost computation, assume:
 - 100 <val,ptr> pairs/block
 - expected number of result tuples is 100
- Build hash table for R_2 in memory 5000 tuples \rightarrow 5000/100 = 50 blocks
- Read R₁ and match
- Read ~ 100 R_2 tuples



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• To illustrate cost computation, assume:

- expected number of result tuples is 100
- Build hash table for R_2 in memory 5000 tuples \rightarrow 5000/100 = 50 blocks
- Read R₁ and match
- Read ~ 100 R_2 tuples

<u>Total cost</u> =

Read R₂: Read R₁: Get tuples: 500 1000 <u>100</u> 1600 IIT College of

142



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So far:

Iterate Merge join Sort+merge joint R₁.C index R₂.C index Build R₁.C index Build R₂.C index Hash join with trick, R₁ first with trick, R₂ first Hash join, pointers

4500+ 4414

1600



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Yet another hash join trick:

- Combine the ideas of
 - block nested-loop with hash join
- Use memory to build hash-table for one chunk of relation
- Find join partners in O(1) instead of O(M)
- Trade-off
 - Space-overhead of hash-table
 - Time savings from look-up

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<u>Summary</u>

- Nested Loop ok for "small" relations (relative to memory size)
 – Need for complex join condition
- For equi-join, where relations not sorted and no indexes exist, <u>hash join</u> usually best



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- Sort + merge join good for non-equi-join (e.g., R₁.C > R₂.C)
- If relations already sorted, use merge join
- If index exists, it <u>could</u> be useful (depends on expected result size)



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Join Comparison

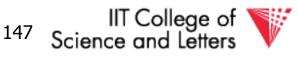
 N_i = number of tuples in R_i $B(R_i)$ = number of blocks of R_i #P = number of partition steps for hash join P_{ii} = average number of join partners

Algorithm	#I/O	Memory	Disk Space
Nested Loop (block)	B(R ₁)/(M-1)* [min(B(R),M-1) + B(R ₂)]	3	0
Index Nested Loop	$B(R_1) + N_1 * P_{12}$	B(Index) + 2	0
Merge (sorted)	$B(R_1) + B(R_2)$	Max tuples =	0
Merge (unsorted)	$B(R_1) + B(R_2) +$ (sort - 1 pass)	sort	$B(R_1) + B(R_2)$
Hash	$(2\#P + 1) (B(R_1) + B(R_2))$	root(max(B(R_1), B(R_2)), #P + 1)	$\sim B(R_1) + B(R_2)$



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Notes 10 - Query Execution



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Why do we need nested loop?

 Remember not all join implementations work for all types of join conditions

Algorithm	Type of Condition	Example
Nested Loop	any	a LIKE `%hello%'
Index Nested Loop	Supported by index: Equi-join (hash) Equi or range (B-tree)	a = b a < b
Merge	Equalities and ranges	a < b, a = b AND c = d
Hash	Equi-join	a = b



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Outer Joins

- How to implement (left) outer joins?
- Nested Loop and Merge
 - Use a flag that is set to true if we find a match for an outer tuple
 - If flag is false fill with NULL
- Hash

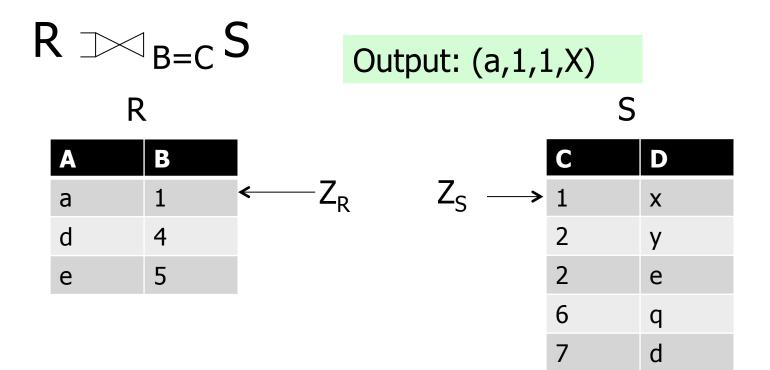
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– If no matching tuple fill with NULL





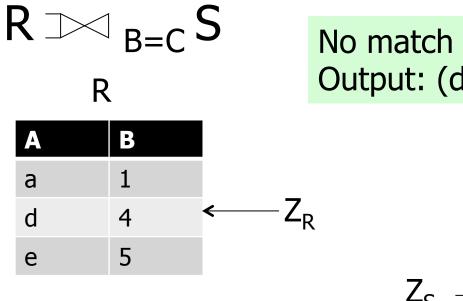
Merge Left Outer Join







Merge Left Outer Join



No match for (d,4) Output: (d,4,NULL,NULL)

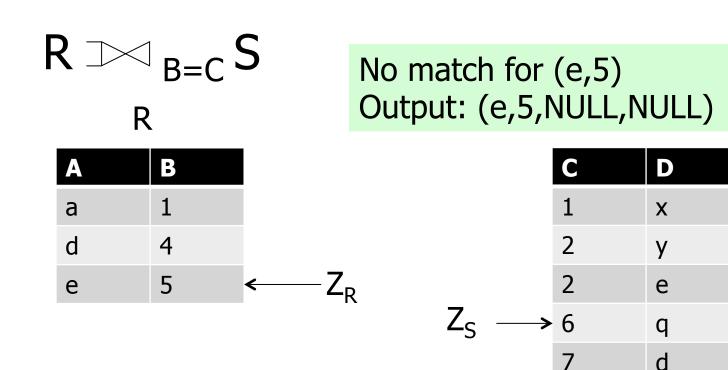
	С	D
	1	x
	2	у
	2	е
$Z_{S} \longrightarrow$	6	q
	7	d



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Merge Left Outer Join





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Operators Overview

- (External) Sorting
- Joins (Nested Loop, Merge, Hash, ...)
- Aggregation (Sorting, Hash)
- Selection, Projection (Index, Scan)
- Union, Set Difference
- Intersection

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Duplicate Elimination





Aggregation

- Have to compute aggregation functions
 for each group of tuples from input
- Groups

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 Determined by equality of group-by attributes





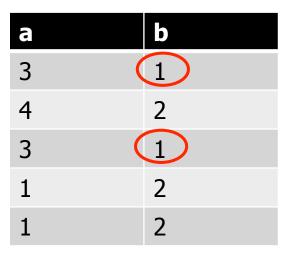
Aggregation Example

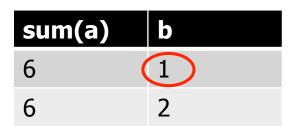
SELECT sum(a),b

FROM R

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GROUP BY b









Aggregation Function Interface

- init()
 - Initialize state
- update(tuple)
 - Update state with information from tuple
- close()
 - Return result and clean-up





Implementation SUM(A)

- init()
 - -sum := 0
- update(tuple)
 - -sum += tuple.A
- close()
 - -return sum





Aggregation Implementations

• Sorting

- Sort input on group-by attributes
- On group boundaries output tuple
- Hashing

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- Store current aggregated values for each group in hash table
- Update with newly arriving tuples
- Output result after processing all inputs





Grouping by sorting

- Similar to Merge join
- Sort R on group-by attribute
- Scan through sorted input
 - If group-by values change
 - Output using close() and call init()
 - Otherwise

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• Call update()



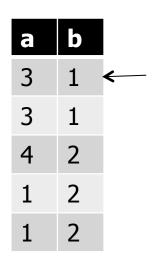


Aggregation Example SELECT sum(a),b FROM R GROUP BY b init() sort b b a a ()

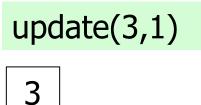


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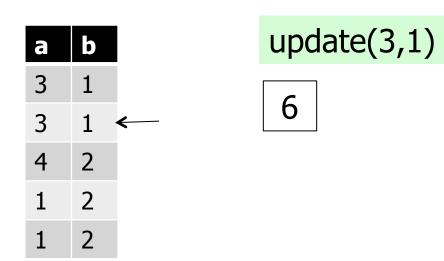


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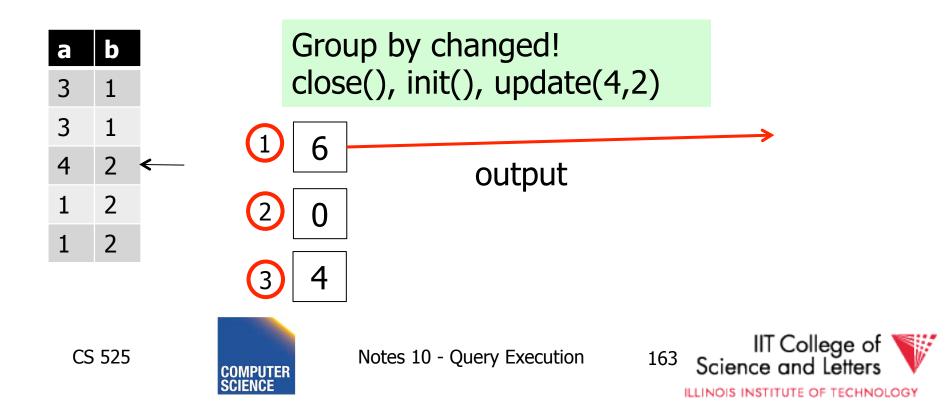






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Grouping by Hashing

- Create in-memory hash-table
- For each input tuple probe hash table with group by values
 - If no entry exists then call init(), update(), and add entry
 - Otherwise call update() for entry
- Loop through all entries in hash-table and ouput calling close()

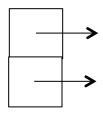


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a	b
3	1
4	2
3	1
1	2
1	2

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Aggregation Example SELECT sum(a),b FROM R GROUP BY b Init() and update(3,1)





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Aggregation Example SELECT sum(a),b FROM R GROUP BY b Init() and update(4,2)





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Aggregation Example SELECT sum(a),b FROM R GROUP BY b update(3,1)





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Aggregation Example

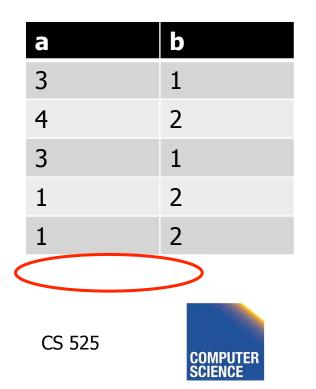
SELECT sum(a),b

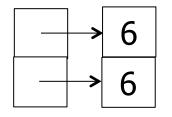
FROM R

GROUP BY b

• Loop through hash table entries

• Output tuples





Notes 10 - Query Execution 169 Scie



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Aggregation Summary

- Hashing
 - No sorting -> no extra I/O
 - Hash table has to fit into memory
 - No outputs before all inputs have been processed
- Sorting

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- No memory required
- Output one group at a time





Operators Overview

- (External) Sorting
- Joins (Nested Loop, Merge, Hash, ...)
- Aggregation (Sorting, Hash)
- Selection, Projection (Index, Scan)
- Union, Set Difference
- Intersection

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Duplicate Elimination





Duplicate Elimination

- Equivalent to group-by on all attributes
- -> Can use aggregation implementations
- Optimization
 - Hash

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• Directly output tuple and use hash table only to avoid outputting duplicates





Operators Overview

- (External) Sorting
- Joins (Nested Loop, Merge, Hash, ...)
- Aggregation (Sorting, Hash)
- Selection, Projection (Index, Scan)
- Union, Set Difference
- Intersection

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Duplicate Elimination





Set Operations

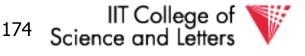
- Can be modeled as join
 with different output requirements
- As aggregation/group by on all columns

 with different output requirements



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Union

- Bag union
 - Append the two inputs
 - E.g., using three buffers
- Set union

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– Apply duplicate removal to result





Intersection

- Set version
 - Equivalent to join + project + duplicate removal
 - 3-state aggregate function (found left, found right, found both)
- Bag version

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- Join + project + min(i,j)
- Aggegate min(count(i),count(j))





Set Difference

- Using join methods
 - Find matching tuples
 - If no match found, then output
- Using aggregation
 - count(i) count(j) (bag)
 - true(i) AND false(j) (set)



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Summary

- Operator implementations
 - Joins!
 - Other operators
- Cost estimations
 - -I/O

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- memory
- Query processing architectures





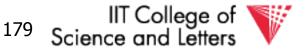
Next

- Query Optimization Physical
- -> How to efficiently choose an efficient plan



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Notes 10 - Query Execution



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CS 525: Advanced Database Organization



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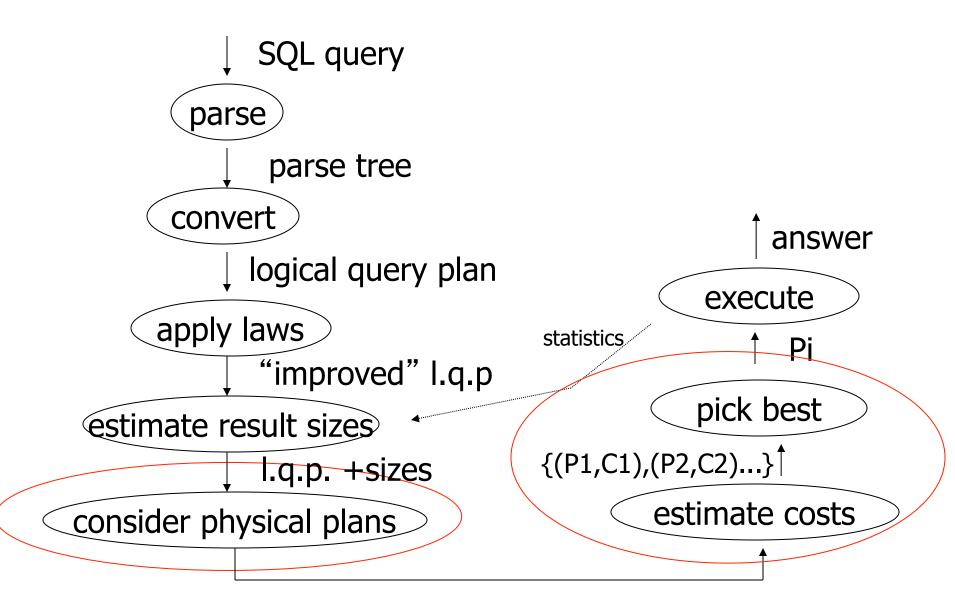
11: Query Optimization Physical

Boris Glavic

Slides: adapted from a <u>course</u> taught by <u>Hector Garcia-Molina</u>, Stanford InfoLab

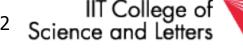






{P1,P2,....}

Notes 11 - Physical Optimization







Cost of Query

- Parse + Analyze
- Optimization Find plan
- Execution

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• Return results to client





Cost of Query

- Parse + Analyze
 - Can parse MB of SQL code in milisecs
- Optimization Find plan
 - Generating plans, costing plans
- Execution

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- Execute plan
- Return results to client
 - Can be expensive but not discussed here





Physical Optimization

- Apply after applying heuristics in logical optimization
- 1) Enumerate potential execution plans
 - All?

- Subset
- 2) Cost plans
 - What cost function?





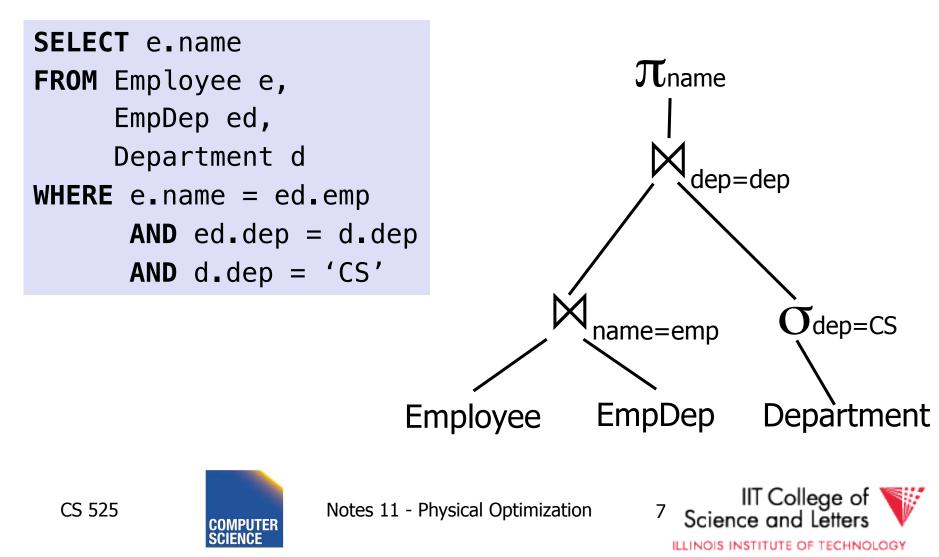
Physical Optimization

- To apply pruning in the search for the best plan
 - Steps 1 and 2 have to be interleaved
 - Prune parts of the search space
 - if we know that it cannot contain any plan that is better than what we found so far

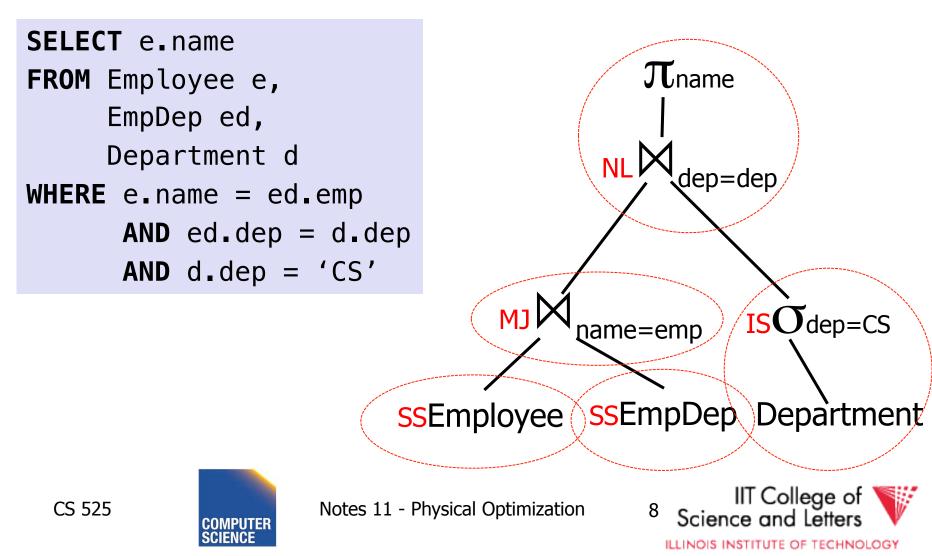




Example Query



Example Query – Possible Plan



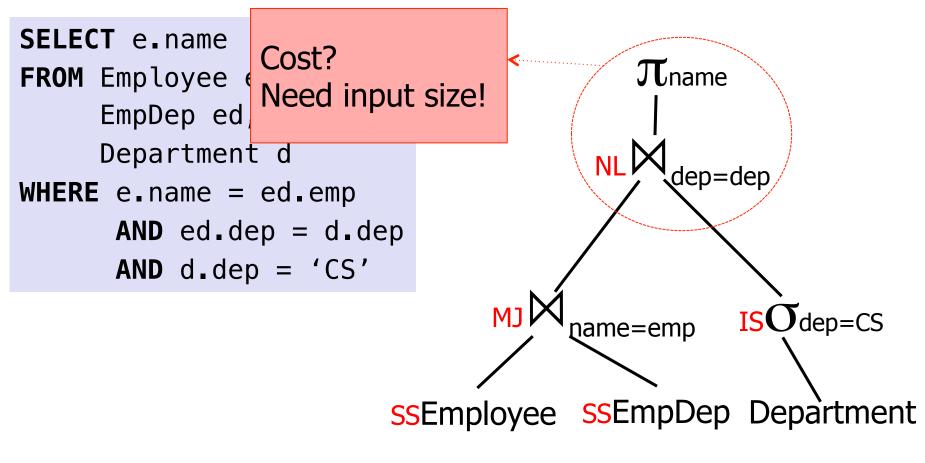
Cost Model

- Cost factors
 - #disk I/O
 - CPU cost
 - Response time
 - Total execution time
- Cost of operators
 - I/O as discussed in query execution (part 10)
 - Need to know size of intermediate results (part 09)



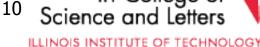


Example Query – Possible Plan





Notes 11 - Physical Optimization



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Cost Model Trade-off

Precision

 Incorrect cost-estimation -> choose suboptimal plan

Cost of computing cost

- Cost of costing a plan
 - We may have to cost millions or billions of plans
- Cost of maintaining statistics
 - Occupies resources needed for query processing





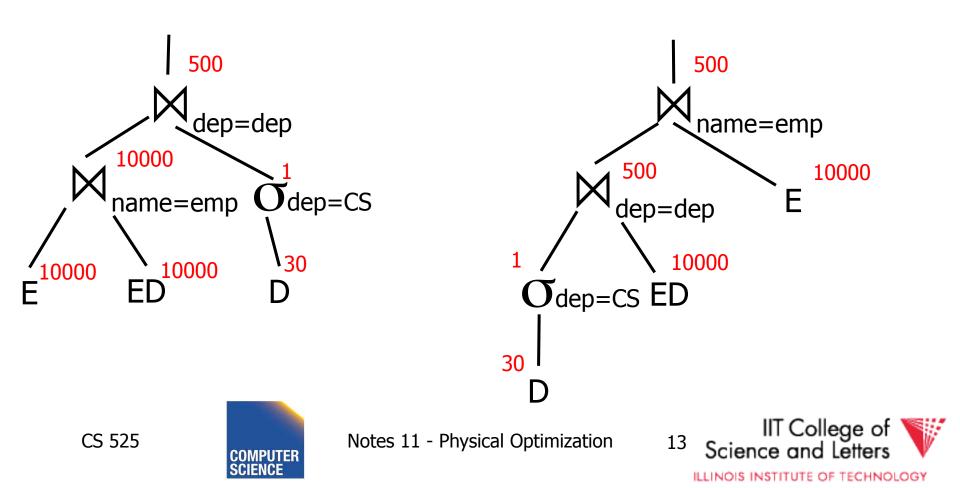
Plan Enumeration

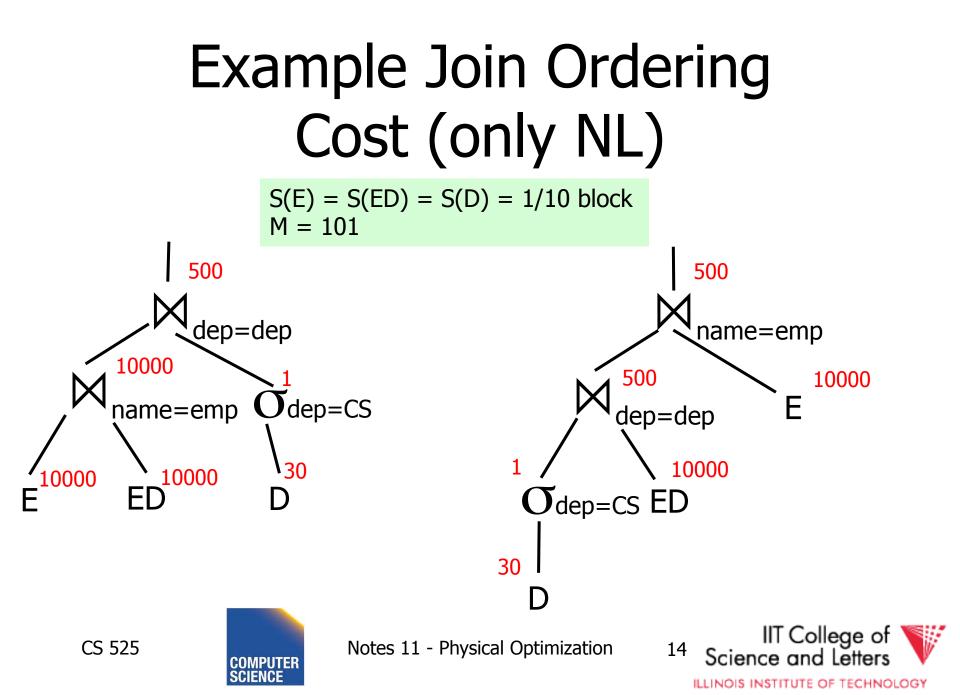
- For each operator in the query
 Several implementation options
- Binary operators (joins)
 - Changing the order may improve performance a lot!
- -> consider both different implementations and order of operators in plan enumeration

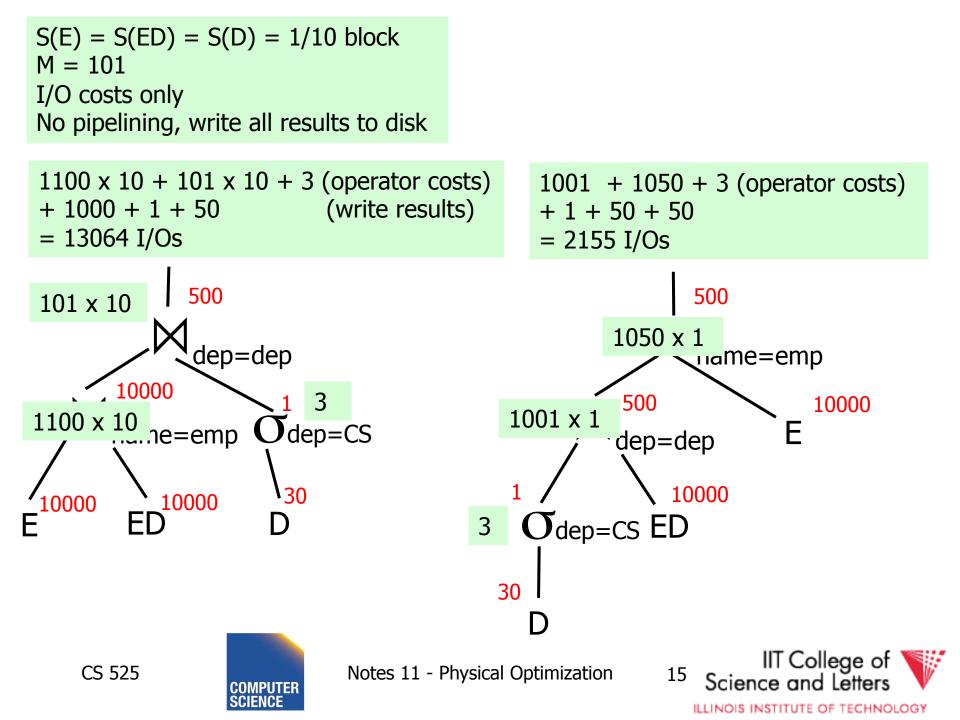




Example Join Ordering Result Sizes







Plan Enumeration

• All

- Consider all potential plans of a certain type (discussed later)
- Prune only if sure
- Heuristics
 - Apply heuristics to prune search space
- Randomized Algorithms





Plan Enumeration Algorithms

- All
 - Dynamic Programming (System R)
 - A* search
- Heuristics
 - Minimum Selectivity, Intermediate result size, ...
 - KBZ-Algorithm, AB-Algorithm
- Randomized
 - Genetic Algorithms
 - Simulated Annealing





Reordering Joins Revisited

• Equivalences (Natural Join)

1. $R \bowtie S \equiv S \bowtie R$

2. (R \bowtie S) \bowtie T \equiv R \bowtie (S \bowtie T)

- Equivalences Equi-Join
 - 1. $R \bowtie_{a=b} S \equiv S \bowtie_{a=b} R$ 2. $(R \bowtie_{a=b} S) \bowtie_{c=d} T \equiv R \bowtie_{a=b} (S \bowtie_{c=d} T)?$ 3. $\sigma_{a=b} (R X S) \equiv R \bowtie_{a=b} S?$



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Equi-Join Equivalences

- ($\mathbb{R} \bowtie_{a=b} S$) $\bowtie_{c=d} T \equiv \mathbb{R} \bowtie_{a=b} (S \bowtie_{c=d} T)$
- What if c is attribute of R?
- $(\mathsf{R}\bowtie_{\mathsf{a}=\mathsf{b}}\mathsf{S})\bowtie_{\mathsf{c}=\mathsf{d}}\mathsf{T}\equiv\mathsf{R}\bowtie_{\mathsf{a}=\mathsf{b}\wedge\mathsf{c}=\mathsf{d}}(\mathsf{S}\mathsf{X}\mathsf{T})$
- $\sigma_{a=b} (R X S) \equiv R \bowtie_{a=b} S?$
- Only useful if a is from R and S from b (viceversa)



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Why Cross-Products are bad

- We discussed efficient join algorithms
 - Merge-join O(n) resp. O(n log(n))
 - Vs. Nested-loop O(n²)
- R X S

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- Result size is $O(n^2)$
 - Cannot be better than O(n²)
- Surprise, surprise: merge-join doesn't work no need to sort, but degrades to nested loop





Agenda

- Given some query

 How to enumerate all plans?
- Try to avoid cross-products
- Need way to figure out if equivalences can be applied
 - Data structure: Join Graph



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Join Graph

- Assumptions
 - Only equi-joins (a = b)
 - a and b are either constants or attributes
 - Only conjunctive join conditions (AND)



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Join Graph

- Nodes: Relations R₁, ..., R_n of query
- Edges: Join conditions
 - Add edge between R_i and R_j labeled with C
 - if there is a join condition C
 - \bullet That equates an attribute from $R_{\rm i}$ with an attribute from $R_{\rm i}$
 - Add a self-edge to R_i for each simple predicate





Join Graph Example

SELECT e.name
FROM Employee e,
 EmpDep ed,
 Department d
WHERE e.name = ed.emp
 AND ed.dep = d.dep
 AND d.dep = 'CS'

Department

EmpDep

Employee



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Notes 11 - Physical Optimization



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Join Graph Example dep='CS' SELECT e.name Department FROM Employee e, EmpDep ed, name=emp Department d WHERE e.name = ed.emp EmpDep **AND** $ed_dep = d_dep$ dep=dep **AND** $d_{dep} = 'CS'$

Employee



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Notes 11 - Physical Optimization

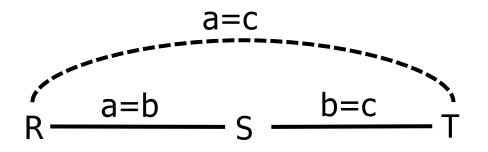


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Notes on Join Graph

- Join Graph tells us in which ways we can join without using cross products
- However, ...

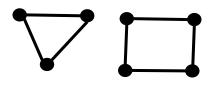
- Only if transitivity is considered





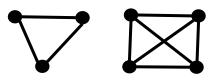
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Cycle queries

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Clique queries



Notes 11 - Physical Optimization



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Join Graph Shapes



Chain queries

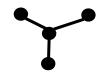
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SELECT * FROM R,S,T WHERE R.a = S.b AND S.c = T.d





Join Graph Shapes



Star queries

SELECT *
FROM R,S,T,U
WHERE R.a = S.a
AND R.b = T.b
AND R.c = U.c



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Join Graph Shapes

SELECT *
FROM R,S,T,U,V
WHERE R.a = S.a
 AND R.b = T.b
 AND T.c = U.c
 AND T.d = V.d



Tree queries

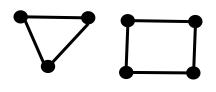


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Join Graph Shapes

SELECT *
FROM R,S,T
WHERE R.a = S.a
AND S.b = T.b
AND T.c = R.c



Cycle queries

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Join Graph Shapes

SELECT *
FROM R,S,T
WHERE R.a = S.a
AND S.b = T.b
AND T.c = R.c



Clique queries



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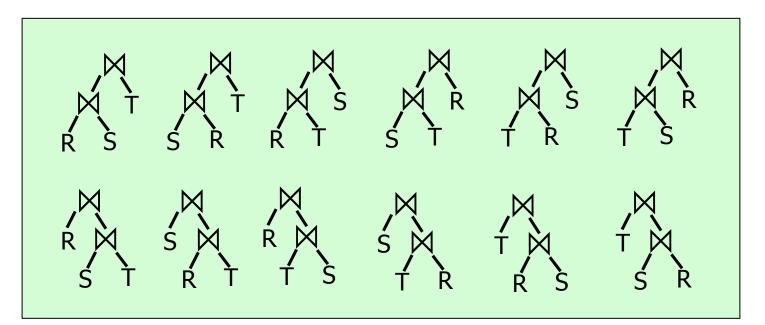


- Assumption
 - Use cross products (can freely reorder)
 - Joins are binary operations
 - Two inputs
 - Each input either join result or relation access





- Example 3 relations R,S,T
 - 12 orders

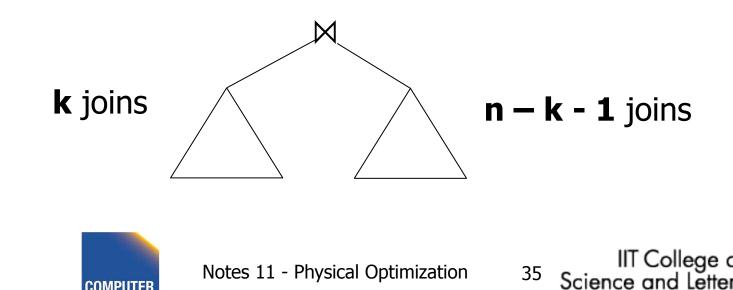




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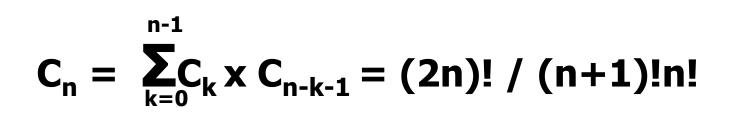
- A join over **n+1** relations requires **n** binary joins
- The root of the join tree joins k with n k 1 join operators (0 <= k <= n-1)

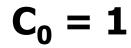


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• This are the **Catalan numbers**





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- This are the **Catalan numbers**
- For each such tree we can permute the input relations (n+1)! Permutations

(2n)! / (n+1)!n! * (n+1)! = (2n)!/n!



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#relations	#join trees
2	2
3	12
4	120
5	1,680
6	30,240
7	665,280
8	17,297,280
9	17,643,225,600
10	670,442,572,800
11	28,158,588,057,600



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• If for each join we consider **k** join algorithms then for **n** relations we have

– Multiply with a factor **k**ⁿ⁻¹

- Example consider
 - Nested loop
 - Merge
 - Hash





#relations	#join trees
2	6
3	108
4	3240
5	136,080
6	7,348,320
7	484,989,120
8	37,829,151,360
9	115,757,203,161,600
10	13,196,321,160,422,400
11	1,662,736,466,213,222,400





- Even if costing is cheap
 - Unrealistic assumption 1 CPU cycle
 - Realistic are thousands or millions of instructions
- Cost all join options for 11 relations
 - 3GHz CPU, 8 cores
 - 69,280,686 sec > 2 years





How to deal with excessive number of combinations?

- Prune parts based on optimality
 - Dynamic programming
 - A*-search
- Only consider certain types of join trees

 Left-deep, Right-deep, zig-zag, bushy
- Heuristic and random algorithms





Dynamic Programming

- Assumption: Principle of Optimality
 - To compute the **global** optimal plan it is only necessary to consider the optimal solutions for its **sub-queries**
- Does this assumption hold?
 - Depends on cost-function





What is dynamic programming?

- Recall data structures and algorithms 101!
- Consider a **Divide-and-Conquer** problem
 - Solutions for a problem of size **n** can be build from solutions for sub-problems of smaller size (e.g., **n/2** or **n-1**)

Memoize

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- Store solutions for sub-problems
- -> Each solution has to be only computed once
- -> Needs extra memory





Example Fibonacci Numbers

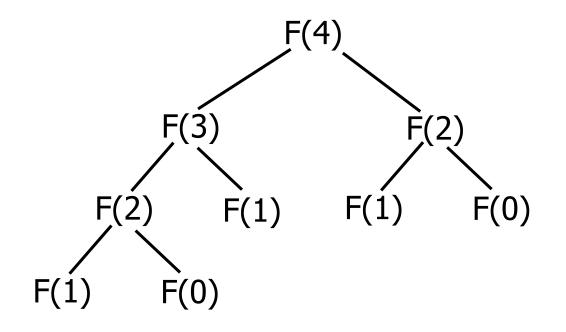
- F(n) = F(n-1) + F(n-2)
- F(0) = F(1) = 1



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Example Fibonacci Numbers





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Complexity

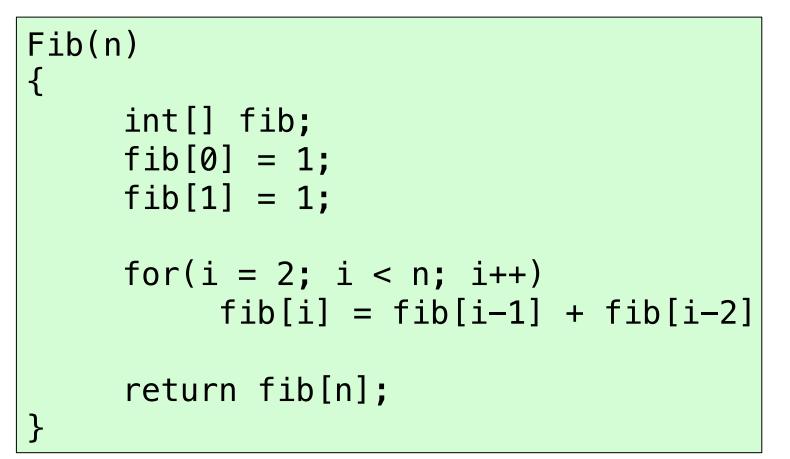
• Number of calls -C(n) = C(n-1) + C(n-2) + 1 = Fib(n+2) $-O(2^n)$



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Using dynamic programming





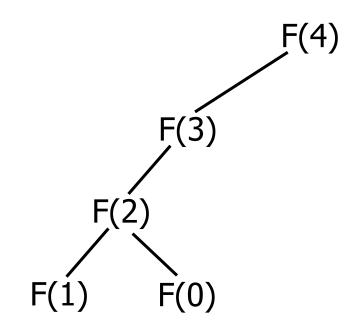
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Notes 11 - Physical Optimization



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Example Fibonacci Numbers





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What do we gain?

• O(n) instead of O(2ⁿ)



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Dynamic Programming for Join Enumeration

- Find cheapest plan for n-relation join in n passes
- For each **i** in **1** ... **n**
 - Construct solutions of size i from best solutions of size < i



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DP Join Enumeration

```
optPlan \leftarrow Map({R},{plan})
find_join_dp(q(R_1, ..., R_n))
{
  for i=1 to n
     optPlan[{R_i}] \leftarrow access_paths(R_i)
  for i=2 to n
     foreach S \subseteq \{R_1, ..., R_n\} with |S|=i
       optPlan[S] ← Ø
        foreach 0 \subset S with 0 \neq \emptyset
          optPlan[S] ← optPlan[S] ∪
                possible_joins(optPlan(0), optPlan(S\0))
        prune_plans(optPlan[S])
  return optPlan[{R<sub>1</sub>,...,R<sub>n</sub>}]
}
```

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Science and Letters

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Dynamic Programming for Join Enumeration

• access_paths (R)

– Find cheapest access path for relation R

- possible_joins(plan, plan)
 - Enumerate all joins (merge, NL, ...)
 variants between the input plans
- prune_plans({plan})
 - Only keep cheapest plan from input set



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DP-JE Complexity

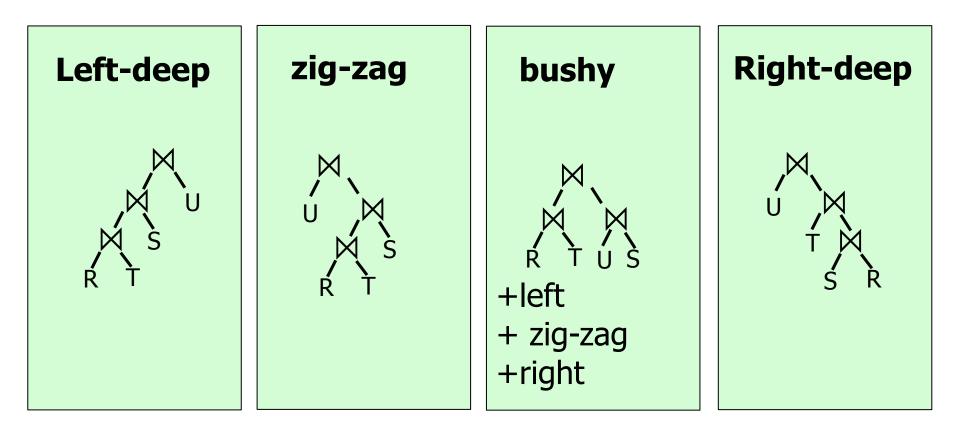
- Time: O(3ⁿ)
- Space: O(2ⁿ)
- Still to much for large number of joins (10-20)



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Types of join trees





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Number of Join-Trees

- Number of join trees for **n** relations
- Left-deep: **n!**
- Right-deep: **n!**
- Zig-zag: 2ⁿ⁻²n!





#relations	#bushy join trees	#left-deep join trees
2	2	2
3	12	6
4	120	24
5	1,680	120
6	30,240	720
7	665,280	5040
8	17,297,280	40,230
9	17,643,225,600	362,880
10	670,442,572,800	3,628,800
11	28,158,588,057,600	39,916,800

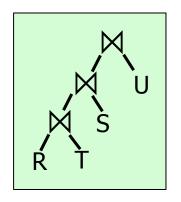


Notes 11 - Physical Optimization



DP with Left-deep trees only

- Reduced search-space
- Each join is with input relation
 - –->can use index joins
 - –->easy to pipe-line



 DP with left-deep plans was introduced by system R, the first relational database developed by IBM Research





Revisiting the assumption

- Is it really sufficient to only look at the best plan for every sub-query?
- Cost of merge join depends whether the input is already sorted
 - -> A sub-optimal plan may produce results ordered in a way that reduces cost of joining above

– Keep track of **interesting orders**



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Interesting Orders

- Number of interesting orders is usually small
- ->Extend DP join enumeration to keep track of interesting orders
 - Determine interesting orders
 - For each sub-query store best-plan for each interesting order

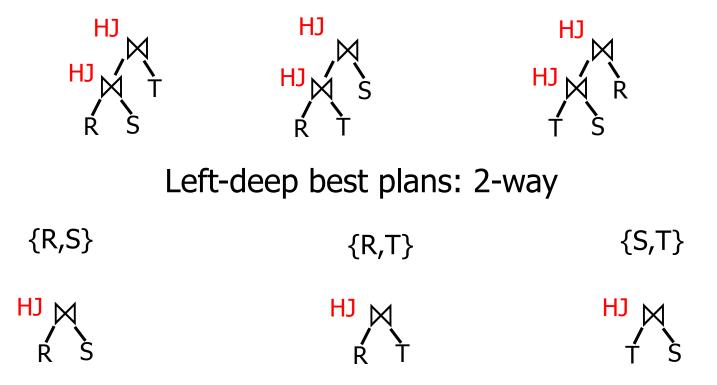


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Example Interesting Orders

Left-deep best plans: 3-way {R,S,T}



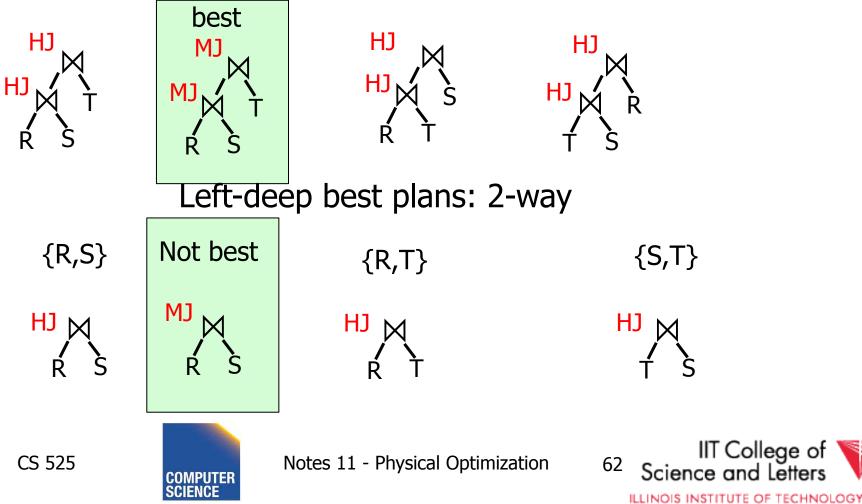


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Example Interesting Orders

Left-deep best plans: 3-way {R,S,T}



Greedy Join Enumeration

- Heuristic method
 - Not guaranteed that best plan is found
- Start from single relation plans
- In each iteration greedily join to plans with the minimal cost
- Until a plan for the whole query has been generated





Greedy Join Enumeration

```
plans \leftarrow list({plan})
find_join_dp(q(R_1, ..., R_n))
{
   for i=1 to n
       plans \leftarrow plans \cup access_paths(R<sub>i</sub>)
   for i=n to 2
       cheapest = \operatorname{argmin}_{j,k \in \{1,...,n\}} (\operatorname{cost}(P_j \bowtie P_k))
plans \leftarrow plans \setminus \{P_j, P_k\} \cup \{P_j \bowtie P_k\}
    return plans // single plan left
}
```



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Greedy Join Enumeration

- Time: O(n³)
 - Loop iterations: O(n)
 - In each iterations looking of pairs of plans in of max size n: O(n²)
- Space: O(n²)
 - Needed to store the current list of plans





Randomized Join-Algorithms

- Iterative improvement
- Simulated annealing
- Tabu-search
- Genetic algorithms





Transformative Approach

- Start from (random) complete solutions
- Apply transformations to generate new solutions
 - Direct application of equivalences
 - Commutativity
 - Associativity
 - Combined equivalences
 - E.g., (R \bowtie S) \bowtie T \equiv T \bowtie (S \bowtie R)



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Concern about Transformative Approach

- Need to be able to generate random plans fast
- Need to be able to apply transformations fast
 - Trade-off: space covered by transformations vs. number and complexity of transformation rules



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Iterative Improvement

```
improve(q(R_1, ..., R_n))
{
  best ← random_plan(q)
  while (not reached time limit)
    curplan ← random_plan(q)
    do
      prevplan ← curplan
      curplan ← apply_random_trans (prevplan)
    while (cost(curplan) < cost(prevplan))</pre>
    if (cost(prevplan) < cost(best)</pre>
      best ← prevplan
  return best
```







Iterative Improvement

- Easy to get stuck in local minimum
- **Idea:** Allow transformations that result in more expensive plans with the hope to move out of local minima

– ->Simulated Annealing



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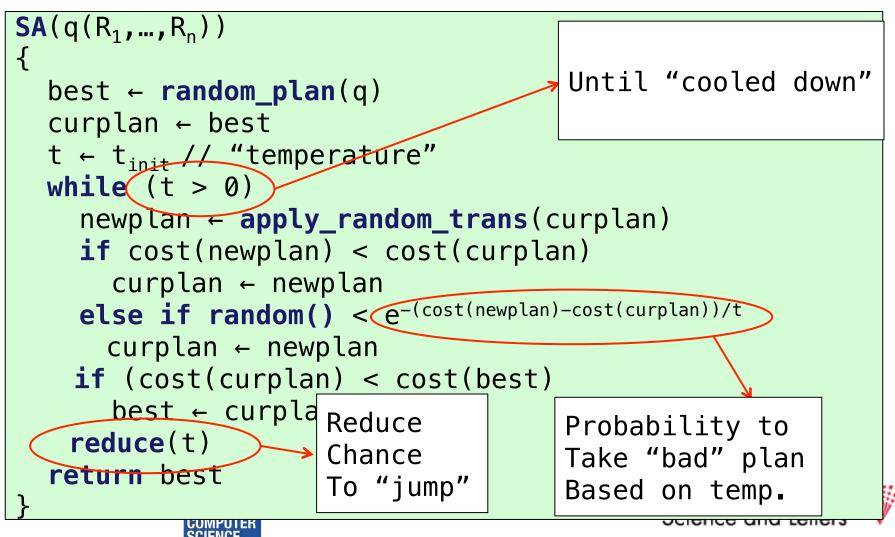


Simulated Annealing

```
SA(q(R_1, ..., R_n))
{
  best ← random_plan(q)
  curplan ← best
  t ← t<sub>init</sub> // "temperature"
  while (t > 0)
     newplan ← apply_random_trans(curplan)
     if cost(newplan) < cost(curplan)</pre>
       curplan ← newplan
    else if random() < e<sup>-(cost(newplan)-cost(curplan))/t</sup>
       curplan ← newplan
    if (cost(curplan) < cost(best)</pre>
       best ← curplan
    reduce(t)
  return best
```



Simulated Annealing



Genetic Algorithms

- Represent solutions as sequences (strings) = genome
- Start with random population of solutions
- Iterations = Generations
 - Mutation = random changes to genomes
 - Cross-over = Mixing two genomes

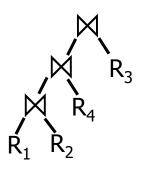


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Genetic Join Enumeration for Left-deep Plans

- A left-deep plan can be represented as a permutation of the relations
 - Represent each relation by a number
 - E.g., encode this tree as "1243"





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Mutation

- Switch random two random positions
- Is applied with a certain fixed probability



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Cross-over

- Sub-set exchange
 - For two solutions find subsequence
 - equals length with the same set of relations
 - Exchange these subsequences
- Example

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- $-J_1 = 5632478''$ and $J_2 = 5674328''$
- Generate J' = "5643278"





Survival of the fittest

- Probability of survival determined by rank within the current population
- Compute ranks based on costs of solutions
- Assign Probabilities based on rank
 Higher rank -> higher probability to survive
- Roll a dice for each solution



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Genetic Join Enumeration

- Create an initial population **P** random plans
- Apply crossover and mutation with a fixed rate
 - E.g., crossover 65%, mutation 5%
- Apply selection until size is again **P**
- Stop once no improvement for at least X iterations





Comparison Randomized Join Enumeration

- Iterative Improvement
 - Towards local minima (easy to get stuck)
- Simulated Annealing
 - Probability to "jump" out of local minima
- Genetic Algorithms
 - Random transformation
 - Mixing solutions (crossover)
 - Probabilistic chance to keep solution based on cost





Join Enumeration Recap

- Hard problem
 - Large problem size
 - Want to reduce search space
 - Large cost differences between solutions
 - Want to consider many solution to increase chance to find a good one.





Join Enumeration Recap

- Tip of the iceberg
 - More algorithms
 - Combinations of algorithms
 - Different representation subspaces of the problem
 - Cross-products / no cross-products





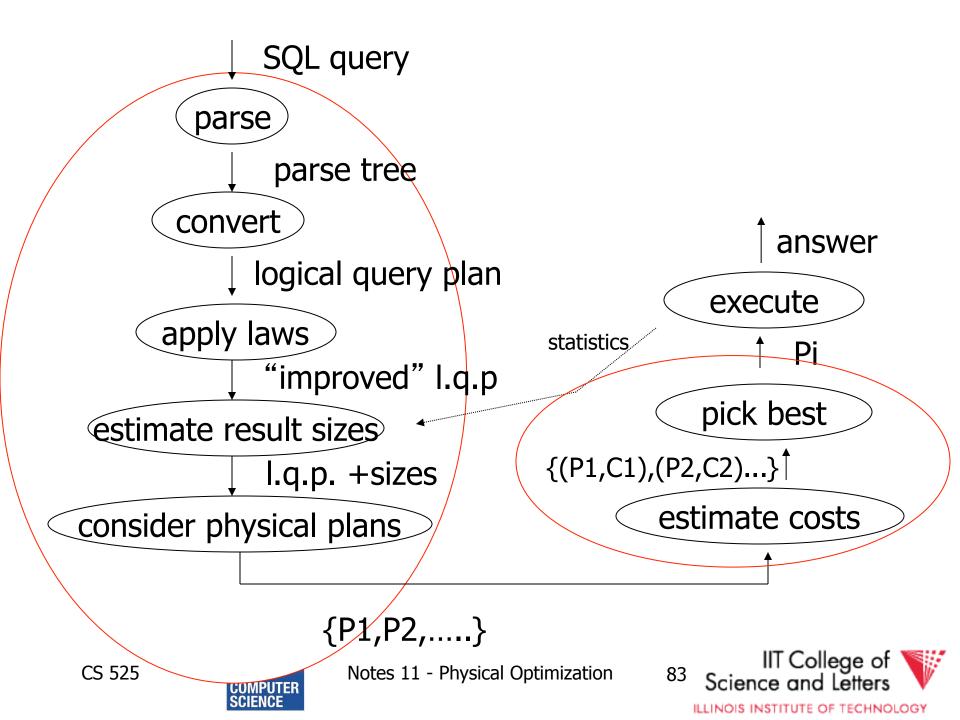
From Join-Enumeration to Plan Enumeration

- So far we only know how to reorder joins
- What about other operations?
- What if the query does consist of several SQL blocks?
- What if we have nested subqueries?



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From Join-Enumeration to Plan Enumeration

- Lets reconsider the input to plan enumeration!
 - We briefly touched on Query graph models
 - We discussed briefly why relational algebra is not sufficient





Query Graph Models

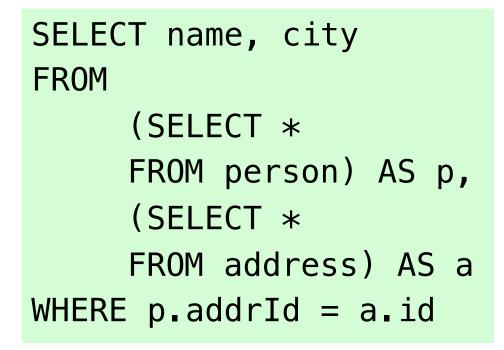
- Represents an SQL query as query blocks
 - A query block corresponds to the an SQL query block (SELECT FROM WHERE ...)
 - Data type/operator/function information
 - Needed for execution and optimization decisions
 - Structured in a way suited for optimization

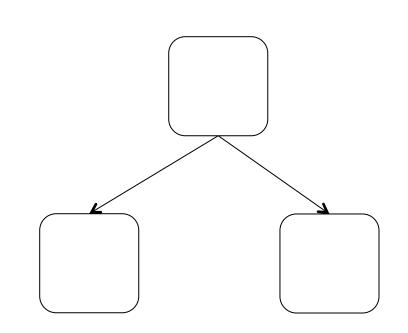


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QGM example







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Postgres Example

{QUERY

:commandType 1 :querySource 0 :canSetTag true :utilityStmt <> :resultRelation 0 :intoClause <> :hasAggs false :hasSubLinks false :rtable ({RTE :alias {ALIAS :aliasname p :colnames <> } :eref {ALIAS :aliasname p :colnames ("name" "addrid") } :rtekind 1 :subquery {QUERY :commandType 1 :querySource 0 :canSetTag true

. . .





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How to enumerate plans for a QGM query

- Recall the correspondence between SQL query blocks and algebra expressions!
- If block is (A)SPJ
 - Determine join order
 - Decide which aggregation to use (if any)
- If block is set operation
 - Determine order





More than one query block

- Recursive create plans for subqueries
 Start with leaf blocks
- Consider our example
 - Even if blocks are only SPJ we would not consider reordering of joins across blocks
 - -> try to "pull up" subqueries before optimization



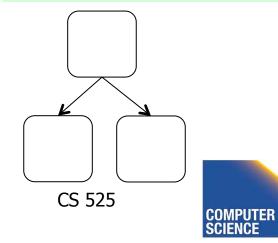


Subquery Pull-up

SELECT name, city FROM

(SELECT *
 FROM person) AS p,
 (SELECT *
 FROM address) AS a
WHERE p.addrId = a.id

SELECT name, city
FROM
 person p,
 address a
WHERE p.addrId = a.id







Parameterized Queries

- Problem
 - Repeated executed of similar queries
- Example

- Webshop
- Typical operation: Retrieve product with all user comments for that product
- Same query modulo product id





Parameterized Queries

- Naïve approach
 - Optimize each version individually
 - Execute each version individually
- Materialized View
 - Store common parts of the query
 - -> Optimizing a query with materialized views
 - --> Separate topic not covered here





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Caching Query Plans

- Caching Query Plans
 - Optimize query once
 - Adapt plan for specific instances
 - Assumption: varying values do not effect optimization decisions
 - Weaker Assumption: Additional cost of "bad" plan less than cost of repeated planning





Parameterized Queries

- How to represent varying parts of a query
 - Parameters
 - Query planned with parameters assumed to be unknown
 - For execution replace parameters with concrete values





PREPARE statement

• In SQL

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- **PREPARE** name (parameters) **AS** query
- **EXECUTE** name (parameters)





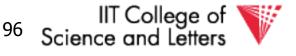
Nested Subqueries

SELECT name
FROM person p
WHERE EXISTS (SELECT newspaper
 FROM hasRead h
 WHERE h.name = p.name
 AND h.newspaper = 'Tribune')



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How to evaluate nested subquery?

- If no correlations:
 - Execute once and cache results
- For correlations:
 - Create plan for query with parameters
- -> called nested iteration





Nested Iteration - Correlated

```
q ← outer query
q' ← inner query
result ← execute(q)
foreach tuple t in result
  q<sub>t</sub> ← q'(t) // parameterize q' with values from t
  result' ← execute (q<sub>t</sub>)
  evaluate_nested_condition (t,result')
```



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Nested Iteration -Uncorrelated

```
q ← outer query
q' ← inner query
result ← execute(q)
result' ← execute (q<sub>t</sub>)
foreach tuple t in result
    evaluate_nested_condition (t,result')
```



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Nested Iteration - Example

person

name	gender
Alice	female
Bob	male
Joe	male

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hasRead

name	newspaper
Alice	Tribune
Alice	Courier
Joe	Courier





Nested Iteration - Example

```
q ← outer query
q' ← inner query
result ← execute(q)
foreach tuple t in result
q<sub>t</sub> ← q'(t)
result' ← execute (q<sub>t</sub>)
evaluate_nested_condition (t,result')
```

person

	name	gender
≯	Alice	female
	Bob	male
	Joe	male

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hasRead

name	newspaper
Alice	Tribune
Alice	Courier
Joe	Courier





```
q ← outer query
q' ← inner query
result ← execute(q)
foreach tuple t in result
q<sub>t</sub> ← q'(t)
result' ← execute (q<sub>t</sub>)
evaluate_nested_condition (t,result')
```

person

	name	gender
≯	Alice	female
	Bob	male
	Joe	male

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hasRead

name	newspaper
Alice	Tribune
Alice	Courier
Joe	Courier





```
q ← outer query
q' ← inner query
result ← execute(q)
foreach tuple t in result
q<sub>t</sub> ← q'(t)
result' ← execute (q<sub>t</sub>)
evaluate_nested_condition (t,result')
```

SELECT newspaper
FROM hasRead h
WHERE h.name = p.name
AND h.newspaper
= 'Tribune')

person

	name	gender	
≻	Alice	female	
	Bob	male	
	Joe	male	

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hasReadnamenewspaperAliceTribuneAliceCourierJoeCourier

result' newspaper Tribune





```
q ← outer query
q' ← inner query
result ← execute(q)
foreach tuple t in result
q<sub>t</sub> ← q'(t)
result' ← execute (q<sub>t</sub>)
evaluate_nested_condition (t,result')
```

EXISTS evaluates to true!

Output(Alice)

person

	name	gender
≻	Alice	female
	Bob	male
	Joe	male

hasReadnamenewspaperAliceTribuneAliceCourierJoeCourier

result' newspaper Tribune



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```
q ← outer query
q' ← inner query
result ← execute(q)
foreach tuple t in result
q<sub>t</sub> ← q'(t)
result' ← execute (q<sub>t</sub>)
evaluate_nested_condition (t,result')
```

Empty result set -> EXISTS evaluates to false

person

	name	gender
	Alice	female
>	Bob	male
	Joe	male

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hasRead name newspaper Alice Tribune Alice Courier

Courier

result'

newspaper



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Joe



```
q ← outer query
q' ← inner query
result ← execute(q)
foreach tuple t in result
q<sub>t</sub> ← q'(t)
result' ← execute (q<sub>t</sub>)
evaluate_nested_condition (t,result')
```

Empty result set -> EXISTS evaluates to false

person

name		gender	
	Alice	female	
	Bob	male	
>	Joe	male	

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hasRead

namenewspaperAliceTribuneAliceCourierJoeCourier

result'

newspaper





Nested Iteration - Discussion

- Repeated evaluation of nested subquery

 If correlated
 - Improve:
 - Plan once and substitute parameters
 - EXISTS: stop processing after first result
 - IN/ANY: stop after first match
- No optimization across nesting boundaries



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Unnesting and Decorrelation

- Apply equivalences to transform nested subqueries into joins
- Unnesting:

– Turn a nested subquery into a join

• Decorrelation:

– Turn correlations into join expressions



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Equivalences

- Classify types of nesting
- Equivalence rules will have preconditions
- Can be applied heuristically before plan enumeration or using a transformative approach

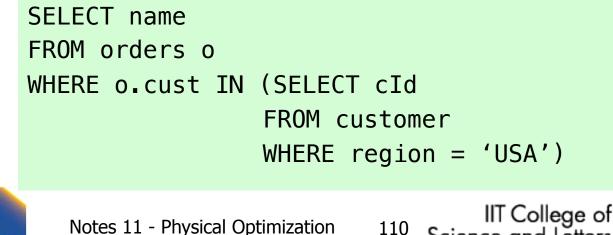


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N-type Nesting

- Properties
 - Expression ANY comparison (or IN)
 - No Correlations
 - Nested query does not use aggregation
- Example





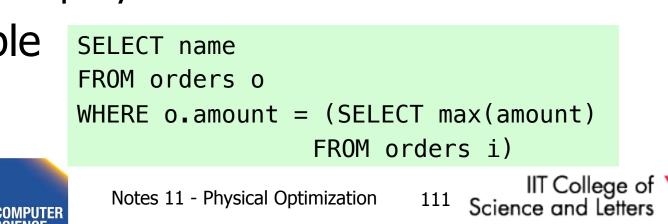


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A-type Nesting

- Properties
 - Expression is ANY comparison (or scalar)
 - No Correlations
 - Nested query uses aggregation
 - No Group By
- Example

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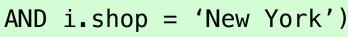
J-type Nesting

- Properties
 - Expression is ANY comparison (IN)
 - Nested query uses equality comparison with correlated attribute
 - No aggregation in nested query
- Example SELECT name

FROM orders o WHERE o.amount IN (SELECT amount

FROM orders i

WHERE i.cust = o.cust





JA-type Nesting

- Properties
 - Expression equality comparison
 - Nested query uses equality comparison with correlated attribute
 - Nested query uses aggregation and no GROUP BY
- Example SELECT name
 - FROM orders o
 - WHERE o.amount = (SELECT max(amount)

FROM orders i

WHERE i.cust = o.cust)





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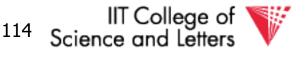
Unnesting A-type

- Move nested query to FROM clause
- Turn nested condition (op ANY, IN) into op with result attribute of nested query



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Unnesting N/J-type

- Move nested query to FROM clause
- Add DISTINCT to SELECT clause of nested query
- Turn equality comparison with correlated attributes into join conditions
- Turn nested condition (op ANY, IN) into op with result attribute of nested query



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- 1. To FROM clause
- 2. Add DISTINCT
- 3. Correlation to join
- 4. Nesting condition to join

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SELECT name
FROM orders o,
 (SELECT amount
 FROM orders i
 WHERE i.cust = o.cust
 AND i.shop = 'New York') AS sub





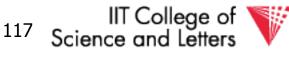
- 1. To FROM clause
- 2. Add DISTINCT
- 3. Correlation to join
- 4. Nesting condition to join

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```
SELECT name
FROM orders o,
  (SELECT DISTINCT amount
  FROM orders i
  WHERE i.cust = o.cust
     AND i.shop = 'New York') AS sub
```



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- 1. To FROM clause
- 2. Add DISTINCT
- 3. Correlation to join
- Nesting condition to join

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```
SELECT name
FROM orders o,
   (SELECT DISTINCT amount, cust
   FROM orders i
   WHERE i.shop = 'New York') AS sub
WHERE sub.cust = o.cust
```





- 1. To FROM clause
- 2. Add DISTINCT
- 3. Correlation to join
- Nesting condition to join

```
SELECT name
FROM orders o,
   (SELECT DISTINCT amount, cust
   FROM orders i
   WHERE i.shop = 'New York') AS sub
WHERE sub.cust = o.cust
   AND o.amount = sub.amount
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```



Unnesting JA-type

- Move nested query to FROM clause
- Turn equality comparison with correlated attributes into
 - GROUP BY
 - Join conditions
- Turn nested condition (op ANY, IN) into op with result attribute of nested query



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- 1. To FROM clause
- 2. Introduce GROUP BY and join conditions
- Nesting condition to join

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```
SELECT name
FROM orders o,
  (SELECT max(amount)
  FROM orders I
  WHERE i.cust = o.cust) sub
```





1. To FROM clause

2. Introduce GROUP BY and join conditions

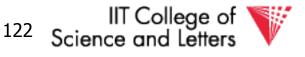
 Nesting condition to join

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```
SELECT name
FROM orders o,
   (SELECT max(amount) AS ma, i.cust
   FROM orders i
   GROUP BY i.cust) sub
WHERE i.cust = sub.cust
```



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1. To FROM clause

2. Introduce GROUP BY and join conditions

3. Nesting condition to join

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```
SELECT name
FROM orders o,
   (SELECT max(amount) AS ma, i.cust
   FROM orders i
   GROUP BY i.cust) sub
WHERE sub.cust = o.cust
   AND o.amount = sub.ma
```



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Unnesting Benefits Example

- N(orders) = 1,000,000
- V(cust,orders) = 10,000
- S(orders) = 1/10 block

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```
SELECT name
FROM orders o,
   (SELECT max(amount) AS ma, i.cust
   FROM orders i
   GROUP BY i.cust) sub
WHERE sub.cust = o.cust
   AND o.amount = sub.ma
```





- N(orders) = 1,000,000
- V(cust,orders) = 10,000
- S(orders) = 1/10 block
- M = 10,000

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- Inner query:
 - One scan B(orders) = 100,000 I/Os
- Outer query:
 - One scan B(orders) = 100,000 I/Os
 - 1,000,000 tuples
- Total cost: 1,000,001 x 100,000=~ 10¹¹ I/Os





- N(orders) = 1,000,000
- V(cust,orders) = 10,000
- S(orders) = 1/10 block
- M = 10,000

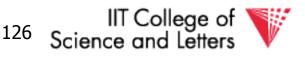
```
SELECT name
FROM orders o,
  (SELECT max(amount) AS ma, i.cust
  FROM orders i
   GROUP BY i.cust) sub
WHERE sub.cust = o.cust
   AND o.amount = sub.ma
```

- Inner queries:
 - One scan B(orders) = 100,000 I/Os
 - 1,000,000 result tuples
 - Aggregation: Sort (assume 1 pass) = $3 \times 100,000 = 300,000$ I/Os
 - 10,000 result tuples -> + 1,000 pages to write to disk
- The join: use merge join during merge
 3 x (1,000 + 100,000) I/Os = 303,000 I/Os
- Total cost: 604,000 I/Os

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CS 525: Advanced Database Organization 12: Transaction Management

Boris Glavic

Slides: adapted from a <u>course</u> taught by <u>Hector Garcia-Molina</u>, Stanford InfoLab



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Concurrency and Recovery

- DBMS should enable multiple clients to access the database concurrently
 - This can lead to problems with correctness of data because of interleaving of operations from different clients
 - ->System should ensure correctness (concurrency control)



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Concurrency and Recovery

- DBMS should enable reestablish correctness of data in the presence of failures
 - ->System should restore a correct state after failure (recovery)





Integrity or correctness of data

• Would like data to be "accurate" or "correct" at all times

EMP	Name	Age
	White Green Gray	52 3421 1



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Integrity or consistency constraints

- Predicates data must satisfy
- Examples:
 - x is key of relation R
 - $x \rightarrow y$ holds in R
 - Domain(x) = {Red, Blue, Green}
 - α is valid index for attribute x of R
 - no employee should make more than twice the average salary



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Definition:

- Consistent state: satisfies all constraints
- Consistent DB: DB in consistent state



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<u>Constraints</u> (as we use here) may <u>not</u> capture "full correctness"

Example 1 Transaction constraints

- When salary is updated,
 new salary > old salary
- When account record is deleted, balance = 0



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<u>Note:</u> could be "emulated" by simple constraints, e.g.,

account

Acct #		balance	deleted?
--------	--	---------	----------

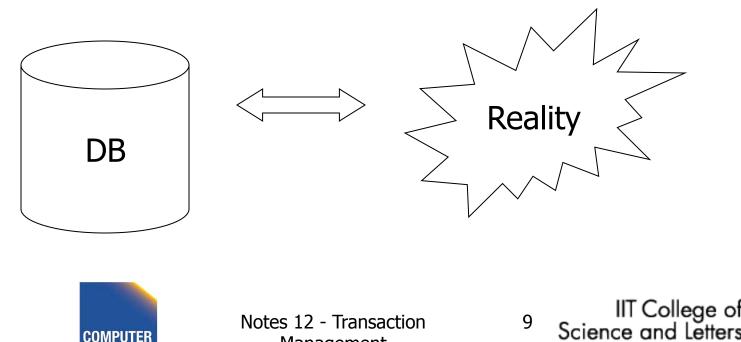


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<u>Constraints</u> (as we use here) may not capture "full correctness"

Example 2 Database should reflect real world





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Management

in any case, continue with constraints...

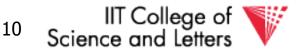
Observation: DB <u>cannot</u> be consistent always!

Example: $a_1 + a_2 + \dots = TOT$ (constraint) Deposit \$100 in a_2 : $\begin{cases} a_2 \leftarrow a_2 + 100 \\ TOT \leftarrow TOT + 100 \end{cases}$

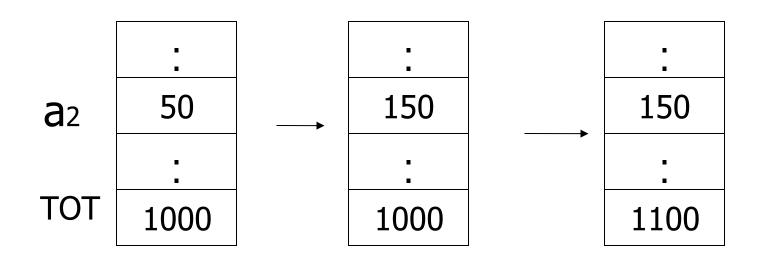


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Notes 12 - Transaction Management



Example: $a_1 + a_2 + \dots = TOT$ (constraint) Deposit \$100 in a_2 : $a_2 \leftarrow a_2 + 100$ TOT $\leftarrow TOT + 100$





Notes 12 - Transaction Management



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Transactions

 Transaction: Sequence of operations executed by one concurrent client that preserve consistency

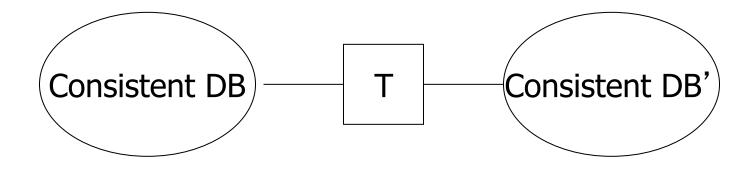


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<u>Transaction:</u> collection of actions that preserve consistency





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Big assumption:

If T starts with consistent state + T executes in isolation \Rightarrow T leaves consistent state



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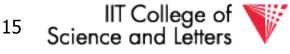
<u>Correctness</u> (informally)

- If we stop running transactions, DB left consistent
- Each transaction sees a consistent DB



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Notes 12 - Transaction Management



Transactions - ACID

- Atomicity
 - Either all or no commands of transaction are executed (their changes are persisted in the DB)
- Consistency
 - After transaction DB is consistent (if before consistent)
- Isolation
 - Transactions are running isolated from each other
- Durability
 - Modifications of transactions are never lost





How can constraints be violated?

- Transaction bug
- DBMS bug
- Hardware failure

e.g., disk crash alters balance of account

• Data sharing

e.g.: T1: give 10% raise to programmers

T2: change programmers \Rightarrow systems analysts



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Notes 12 - Transaction Management



How can we prevent/fix violations?

- Part 13 (Recovery):
 –due to failures
- Part 14 (Concurrency Control): –due to data sharing



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Will not consider:

- How to write correct transactions
- How to write correct DBMS
- Constraint checking & repair

That is, solutions studied here do not need to know constraints



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Data Items:

- Data Item / Database Object / ...
- Abstraction that will come in handy when talking about concurrency control and recovery
- Data Item could be
 - Table, Row, Page, Attribute value



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Operations:

- Input (x): block containing $x \rightarrow$ memory
- Output (x): block containing $x \rightarrow disk$



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Operations:

- Input (x): block containing $x \rightarrow$ memory
- Output (x): block containing $x \rightarrow disk$
- Read (x,t): do input(x) if necessary
 t ← value of x in block
- Write (x,t): do input(x) if necessary value of x in block ← t



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Key problem Unfinished transaction (Atomicity)

Example

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Constraint: A=B

- T1: $A \leftarrow A \times 2$
 - $B \leftarrow B \times 2$



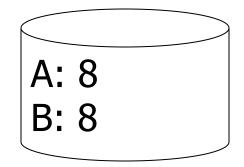
Notes 12 - Transaction Management



T1: Read (A,t); $t \leftarrow t \times 2$ Write (A,t); Read (B,t); $t \leftarrow t \times 2$ Write (B,t); Output (A); Output (B);

A: 8 B: 8

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24

memory



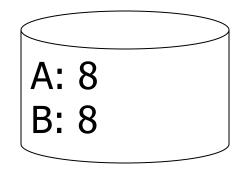
Notes 12 - Transaction Management





T1: Read (A,t); $t \leftarrow t \times 2$ Write (A,t); Read (B,t); $t \leftarrow t \times 2$ Write (B,t); Output (A); Output (B);

A: 8 16 B: 8 16



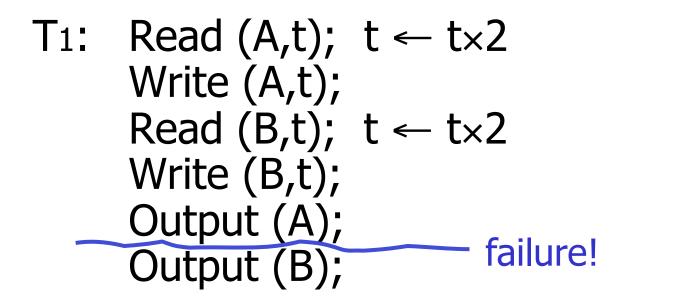
disk

memory

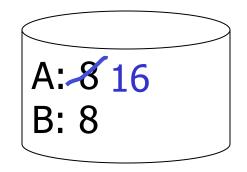


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A: 8 16 B: 8 16



memory



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Transactions in SQL

- BEGIN WORK
 - Start new transaction
 - Often implicit
- COMMIT

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- Finish and make all modifications of transactions persistent
- ABORT/ROLLBACK
 - Finish and undo all changes of transaction



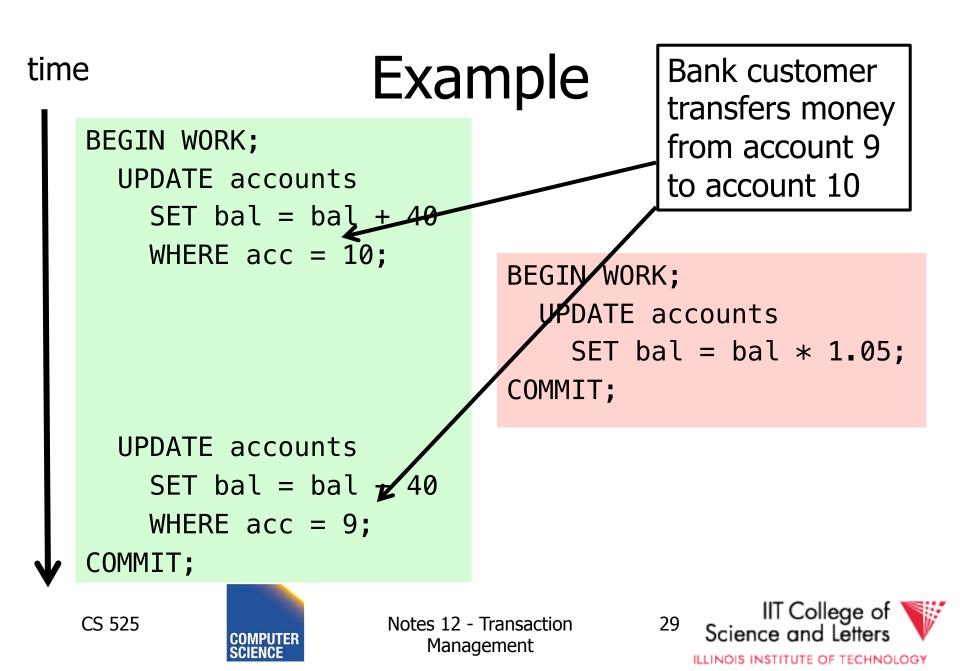
Notes 12 - Transaction Management

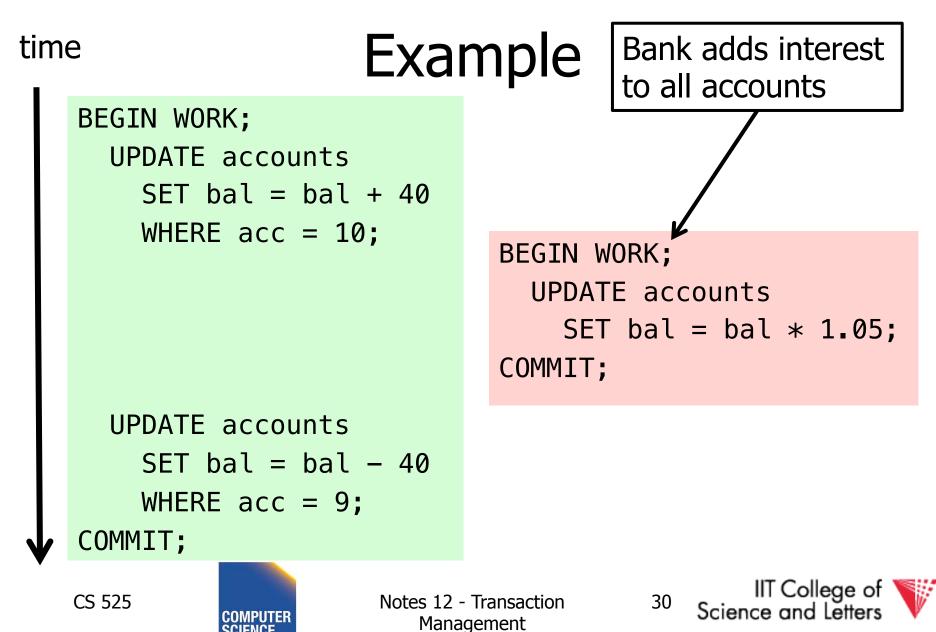


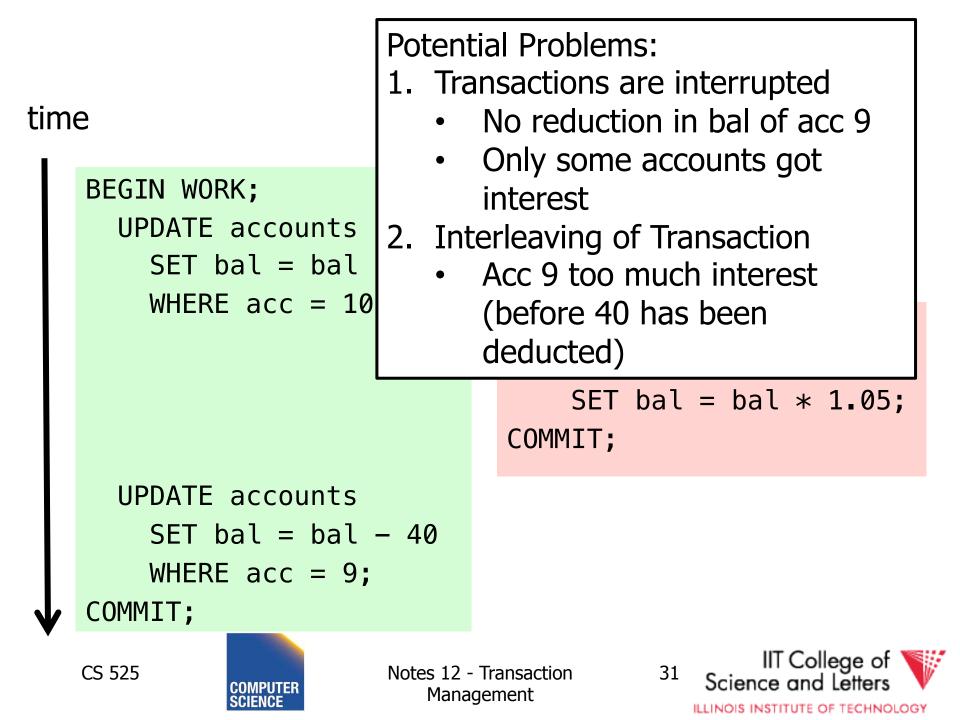
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```
time
                        Example
    BEGIN WORK;
      UPDATE accounts
        SET bal = bal + 40
        WHERE acc = 10;
                                  BEGIN WORK;
                                    UPDATE accounts
                                       SET bal = bal * 1.05;
                                  COMMIT;
      UPDATE accounts
        SET bal = bal -40
        WHERE acc = 9;
    COMMIT;
                                                    IIT College of
   CS 525
                         Notes 12 - Transaction
                                             28
                                                Science and Letters
```

Management







Modeling Transactions and their Interleaving

- Transaction is sequence of operations
 - read: r_i(x) = transaction i read item x
 - write: w_i(x) = transaction i wrote item x
 - commit: c_i = transaction i committed
 - abort: a_i =transaction i aborted



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$$T_1 = r_1(a_{10}), w_1(a_{10}), r_1(a_9), w_1(a_9), c_1$$

time

```
BEGIN WORK;
  UPDATE accounts
    SET bal = bal + 40
    WHERE acc = 10;
  UPDATE accounts
    SET bal = bal -40
    WHERE acc = 9;
COMMIT;
```





Notes 12 - Transaction Management



 $T_1 = r_1(a_{10}), w_1(a_{10}), r_1(a_9), w_1(a_9), c_1$

 $T_2 = r_2(a_1), w_2(a_1), r_2(a_2), w_2(a_2), r_2(a_9), w_2(a_9), r_2(a_{10}), w_2(a_{10}), c_1$

```
BEGIN WORK;
  UPDATE accounts
    SET bal = bal + 40
    WHERE acc = 10;
  UPDATE accounts
    SET bal = bal -40
    WHERE acc = 9;
COMMIT;
```

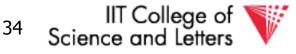
Assume we have accounts: a_1, a_2, a_9, a_{10}

BEGIN WORK; UPDATE accounts SET bal = bal * 1.05; COMMIT;

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Notes 12 - Transaction Management



Schedules

- A schedule S for a set of transactions
 T = {T₁, ..., T_n} is an partial order over operations of T so that
 - **S** contains a prefix of the operations of each T_i
 - Operations of Ti appear in the same order in **S** as in Ti
 - For any two conflicting operations they are ordered



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Note

• For simplicity: We often assume that the schedule is a total order



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Notes 12 - Transaction Management



How to model execution order?

 Schedules model the order of the execution for operations of a set of transactions



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Conflicting Operations

- Two operations are conflicting if
 - At least one of them is a write
 - Both are accessing the same data item
- Intuition

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The order of execution for conflicting operations can influence result!





Conflicting Operations

• Examples

 $-w_1(X)$, $r_2(X)$ are conflicting $-w_1(X)$, $w_2(Y)$ are not conflicting $-r_1(X)$, $r_2(X)$ are not conflicting $-w_1(X)$, $w_1(X)$ are not conflicting



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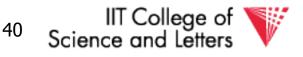
Complete Schedules = History

- A schedule S for T is complete if it contains all operations from each transaction in T
- We will call complete schedules **histories**



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Notes 12 - Transaction Management



 $T_1 = r_1(a_{10}), w_1(a_{10}), r_1(a_9), w_1(a_9), c_1$

 $T_2 = r_2(a_1), w_2(a_1), r_2(a_2), w_2(a_2), r_2(a_9), w_2(a_9), r_2(a_{10}), w_2(a_{10}), c_1$

Complete Schedule

$$\begin{split} \mathsf{S} = \mathsf{r}_2(\mathsf{a}_1), \mathsf{r}_1(\mathsf{a}_{10}), \mathsf{w}_2(\mathsf{a}_1), \mathsf{r}_2(\mathsf{a}_2), \mathsf{w}_1(\mathsf{a}_{10}), \mathsf{w}_2(\mathsf{a}_2), \mathsf{r}_2(\mathsf{a}_9), \mathsf{w}_2(\mathsf{a}_9), \mathsf{v}_1(\mathsf{a}_9), \mathsf{v}_1(\mathsf{a}_9), \mathsf{v}_1(\mathsf{a}_9), \mathsf{v}_1(\mathsf{a}_{10}), \mathsf{v}_2(\mathsf{a}_{10}), \mathsf{v}_2(\mathsf{a}_{10}), \mathsf{v}_1(\mathsf{a}_{10}), \mathsf{v}_2(\mathsf{a}_{10}), \mathsf{v}_2(\mathsf{a$$

Incomplete Schedule

 $S=r_2(a_1), r_1(a_{10}), w_2(a_1), w_1(a_{10})$

Not a Schedule

 $S=r_2(a_1), r_1(a_{10}), c_1$

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Notes 12 - Transaction Management



 $T_1 = r_1(a_{10}), w_1(a_{10}), r_1(a_9), w_1(a_9), c_1$

 $T_2 = r_2(a_1), w_2(a_1), r_2(a_2), w_2(a_2), r_2(a_9), w_2(a_9), r_2(a_{10}), w_2(a_{10}), c_1$

Conflicting operations

- Conflicting operations $w_1(a_{10})$ and $w_2(a_{10})$
- Order of these operations determines value of a₁₀
- S1 and S2 do not generate the same result

$$S_1 = ... w_2(a_1) ... w_1(a_{10})$$

 $S_2 = ... w_1(a_1) ... w_2(a_{10})$

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Notes 12 - Transaction Management



Why Schedules?

- Study properties of different execution orders
 - Easy/Possible to recover after failure
 - Isolation
 - --> preserve ACID properties
- Classes of schedules and protocols to guarantee that only "good" schedules are produced



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CS 525: Advanced Database Organization 13: Failure and Recovery

Boris Glavic

Slides: adapted from a <u>course</u> taught by <u>Hector Garcia-Molina</u>, Stanford InfoLab



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Now

Crash recovery



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<u>Correctness</u> (informally)

- If we stop running transactions, DB left consistent
- Each transaction sees a consistent DB



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How can constraints be violated?

- Transaction bug
- DBMS bug
- Hardware failure

e.g., disk crash alters balance of account

• Data sharing

e.g.: T1: give 10% raise to programmers

T2: change programmers \Rightarrow systems analysts



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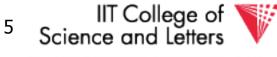




• First order of business: <u>Failure Model</u>

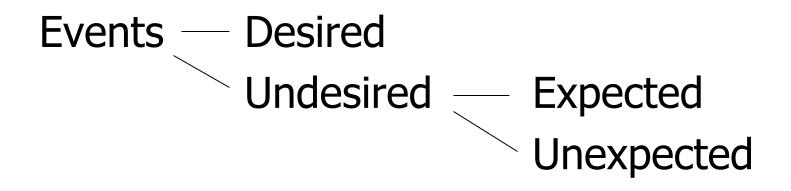


Notes 13 - Failure and Recovery



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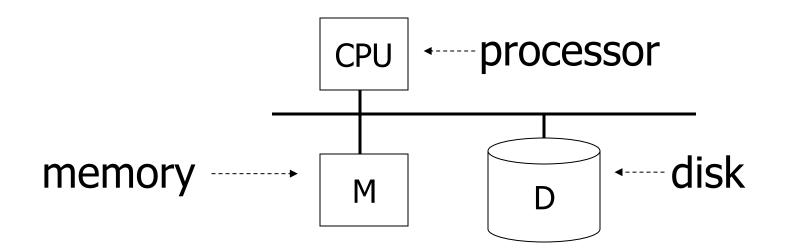




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Our failure model





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Desired events: see product manuals....

<u>Undesired expected events:</u> System crash

- memory lost
- cpu halts, resets



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Desired events: see product manuals....

<u>Undesired expected events:</u> System crash - memory lost - cpu halts, resets

=that' s it!!=

<u>Undesired Unexpected:</u> Everything else!



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Undesired Unexpected: Everything else!

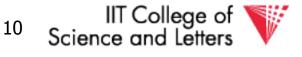
Examples:

- Disk data is lost
- Memory lost without CPU halt
- CPU implodes wiping out universe....



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Notes 13 - Failure and Recovery



Is this model reasonable?

Approach: Add low level checks + redundancy to increase probability model holds

E.g., Replicate disk storage (stable store) Memory parity CPU checks



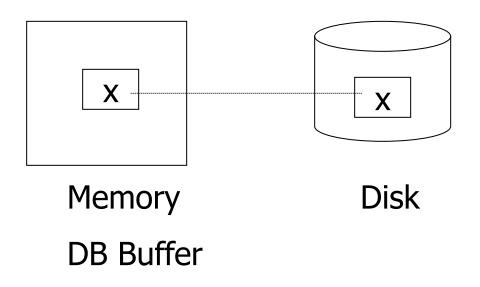
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Notes 13 - Failure and Recovery



Second order of business:

Storage hierarchy







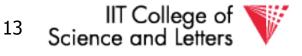
Operations:

- Input (x): block containing $x \rightarrow$ memory
- Output (x): block containing $x \rightarrow disk$



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Notes 13 - Failure and Recovery



Operations:

- Input (x): block containing $x \rightarrow$ memory
- Output (x): block containing $x \rightarrow disk$
- Read (x,t): do input(x) if necessary
 t ← value of x in block
- Write (x,t): do input(x) if necessary value of x in block ← t



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Key problem Unfinished transaction

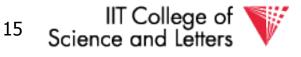
Example

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Constraint: A=BT1: $A \leftarrow A \times 2$ $B \leftarrow B \times 2$



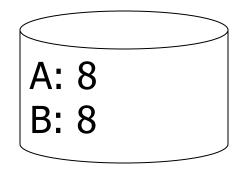
Notes 13 - Failure and Recovery



T1: Read (A,t); $t \leftarrow t \times 2$ Write (A,t); Read (B,t); $t \leftarrow t \times 2$ Write (B,t); Output (A); Output (B);

A: 8 B: 8

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disk

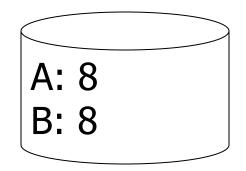
memory





T1: Read (A,t); $t \leftarrow t \times 2$ Write (A,t); Read (B,t); $t \leftarrow t \times 2$ Write (B,t); Output (A); Output (B);

A: 8 16 B: 8 16



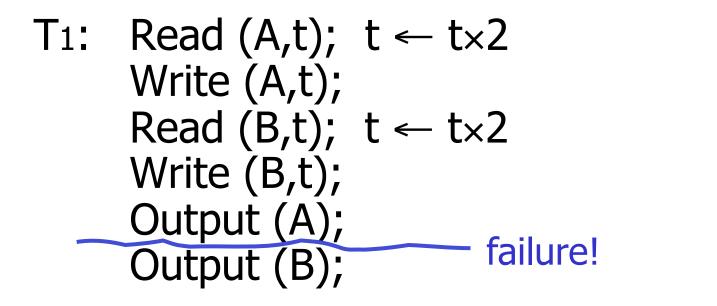
disk

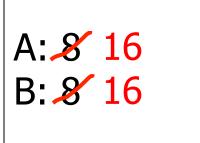
memory

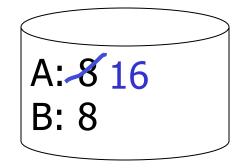


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disk

memory



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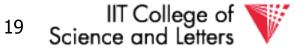


- Need atomicity:
 - execute all actions of a transaction or none at all



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Notes 13 - Failure and Recovery



How to restore consistent state after crash?

- Desired state after recovery:
 - Changes of committed transactions are reflected on disk
 - Changes of unfinished transactions are not reflected on disk
- After crash we need to
 - Undo changes of unfinished transactions that have been written to disk
 - Redo changes of finished transactions that have not been written to disk



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Notes 13 - Failure and Recovery



How to restore consistent state after crash?

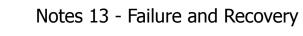
- After crash we need to
 - Undo changes of unfinished transactions that have been written to disk
 - Redo changes of finished transactions that have not been written to disk
- We need to either
 - Store additional data to be able to Undo/Redo
 - Avoid ending up in situations where we need to Undo/Redo





T1: Read (A,t);
$$t \leftarrow t \times 2$$

Write (A,t);
Read (B,t); $t \leftarrow t \times 2$
Write (B,t);
Output (A);
Output (B);
Failure!
A: \mathscr{E} 16
B: 8
Motes 13 - Failure and Recovery 22 IT College of Science and Letters



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Logging

- After crash need to
 - Undo
 - Redo
- We need to know
 - Which operations have been executed
 - Which operations are reflected on disk
- ->Log upfront what is to be done



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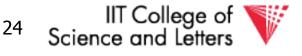
Buffer Replacement Revisited

• Now we are interested in knowing how buffer replacement influences recovery!



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Notes 13 - Failure and Recovery



Buffer Replacement Revisited

• **Steal**: all pages with fix count = 0 are replacement candidates

– Smaller buffer requirements

- No steal: pages that have been modified by active transaction -> not considered for replacement
 - No need to undo operations of unfinished transactions after failure



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Buffer Replacement Revisited

- Force: Pages modified by transaction are flushed to disk at end of transaction
 – No redo required
- No force: modified (dirty) pages are allowed to remain in buffer after end of transaction

– Less repeated writes of same page



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Effects of Buffer Replacement

	force	No force
No steal	No UndoNo Redo	No UndoRedo
steal	UndoNo Redo	RedoUndo



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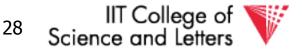
Schedules and Recovery

• Are there certain schedules that are easy/hard/impossible to recover from?



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Notes 13 - Failure and Recovery



Recoverable Schedules

- We should never have to rollback an already committed transaction (D in ACID)
- Recoverable (RC) schedules require that
 - A transaction does not commit before every transaction that is has read from has committed
 - A transaction **T** reads from another transaction **T**' if it reads an item X that has last been written by T' and T' has not aborted before the read



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$$T_1 = w_1(X), c_1$$

$$T_2 = r_2(X), w_2(X), c_2$$

Recoverable (RC) Schedule

$$S_1 = w_1(X), r_2(X), w_2(X), c_1, c_2$$

Nonrecoverable Schedule

$$S_2 = w_1(X), r_2(X), w_2(X), c_2, c_1$$



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Cascading Abort

- Transaction T has written an item that is later read by T' and T aborts after that
 - we have to also abort **T'** because the value it read is no longer valid anymore
 - This is called a cascading abort
 - Cascading aborts are complex and should be avoided

$$S = ... w_1(X) ... r_2(X) ... a_1$$



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Cascadeless Schedules

- **Cascadeless (CL)** schedules guarantee that there are no cascading aborts
 - Transactions only read values written by already committed transactions



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$$T_1 = w_1(X), c_1$$

$$T_2 = r_2(X), w_2(X), c_2$$

Cascadeless (CL) Schedule

$$S_1 = w_1(X), c_1, r_2(X), w_2(X), c_2$$

Recoverable (RC) Schedule

$$S_2 = w_1(X), r_2(X), w_2(X), c_1, c_2$$

Nonrecoverable Schedule

$$S_3 = w_1(X), r_2(X), w_2(X), c_2, c_1$$



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$$T_1 = w_1(X), a_1$$

$$T_2 = r_2(X), w_2(X), c_2$$

Cascadeless (CL) Schedule

 $S_1 = w_1(X), a_1, r_2(X), w_2(X), c_2$

Recoverable (RC) Schedule

$$S_2 = w_1(X), r_2(X), w_2(X), a_1, a_2$$

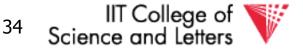
Nonrecoverable Schedule

 $S_3 = w_1(X), r_2(X), w_2(X), c_2, a_1$



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Notes 12 - Transaction Management Consider what happens if T1 aborts!



Strict Schedules

- Strict (ST) schedules guarantee that to Undo the effect of an transaction we simply have to undo each of its writes
 - Transactions do not read nor write items written by uncommitted transactions



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$$T_1 = w_1(X), c_1$$

$$T_2 = r_2(X), w_2(X), c_2$$

Cascadeless (CL) + Strict Schedule (ST)

$$S_1 = w_1(X), c_1, r_2(X), w_2(X), c_2$$

Recoverable (RC) Schedule

$$S_2 = w_1(X), r_2(X), w_2(X), c_1, c_2$$

Nonrecoverable Schedule

$$S_3 = w_1(X), r_2(X), w_2(X), c_2, c_1$$



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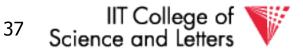
Compare Classes

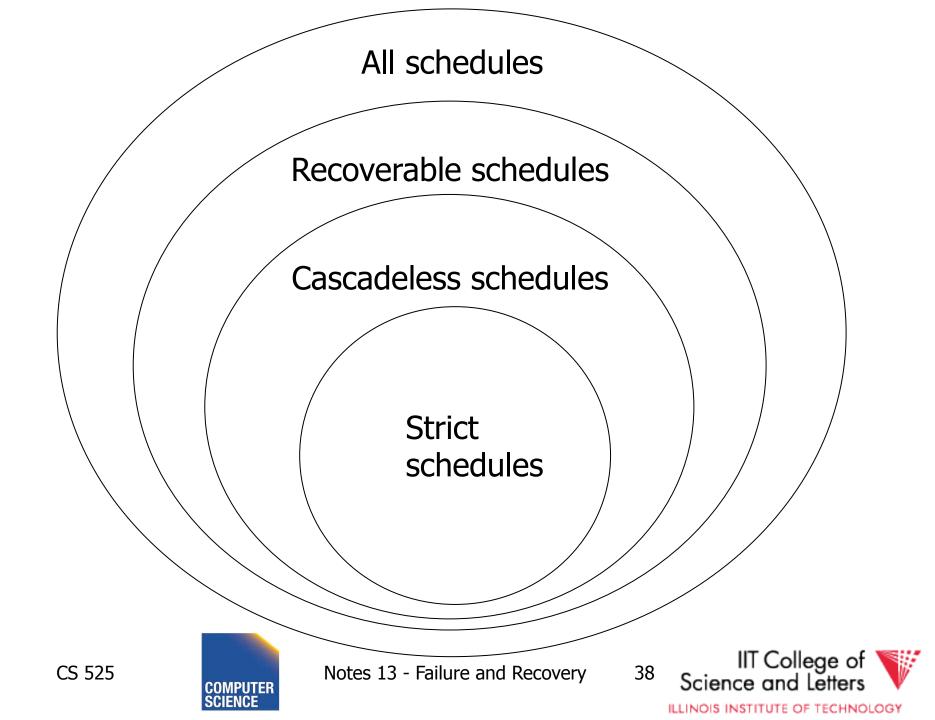
$\mathsf{ST} \subset \mathsf{CL} \subset \mathsf{RC} \subset \mathsf{ALL}$



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Notes 13 - Failure and Recovery





Logging and Recovery

• We now discuss approaches for logging and how to use them in recovery



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Notes 13 - Failure and Recovery



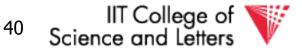
One solution: undo logging (immediate modification)

due to: Hansel and Gretel, 782 AD



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Notes 13 - Failure and Recovery



One solution: undo logging (immediate modification)

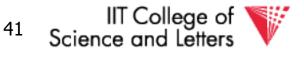
due to: Hansel and Gretel, 782 AD

 Improved in 784 AD to durable undo logging

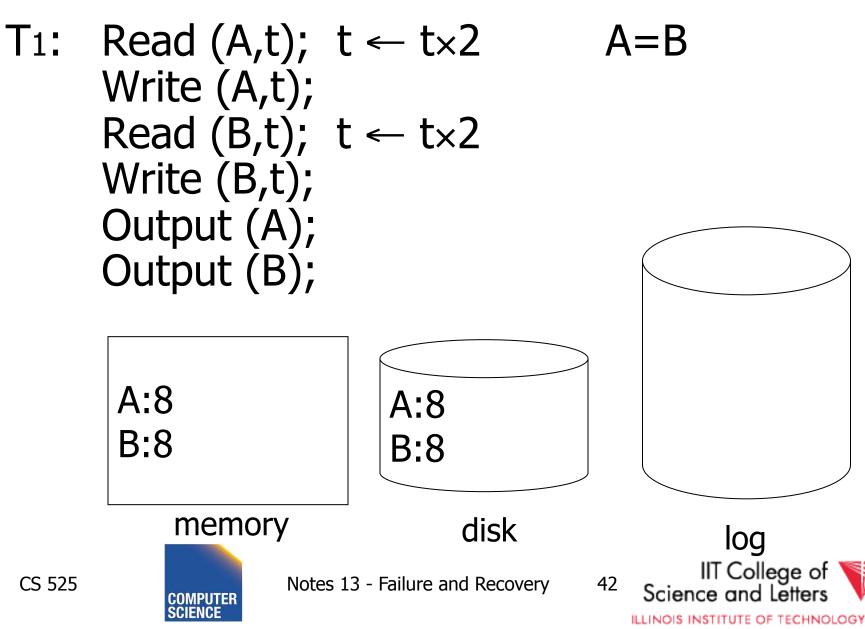


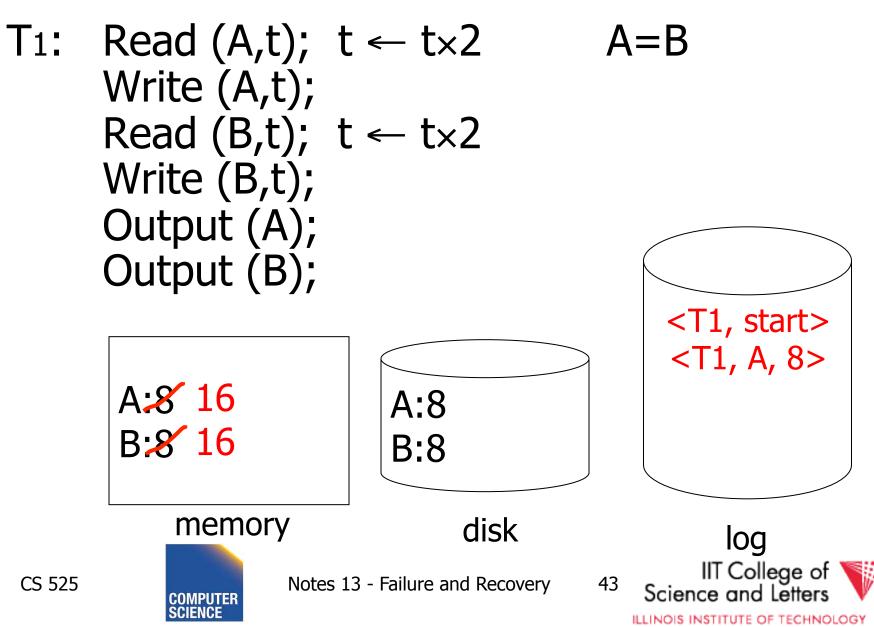
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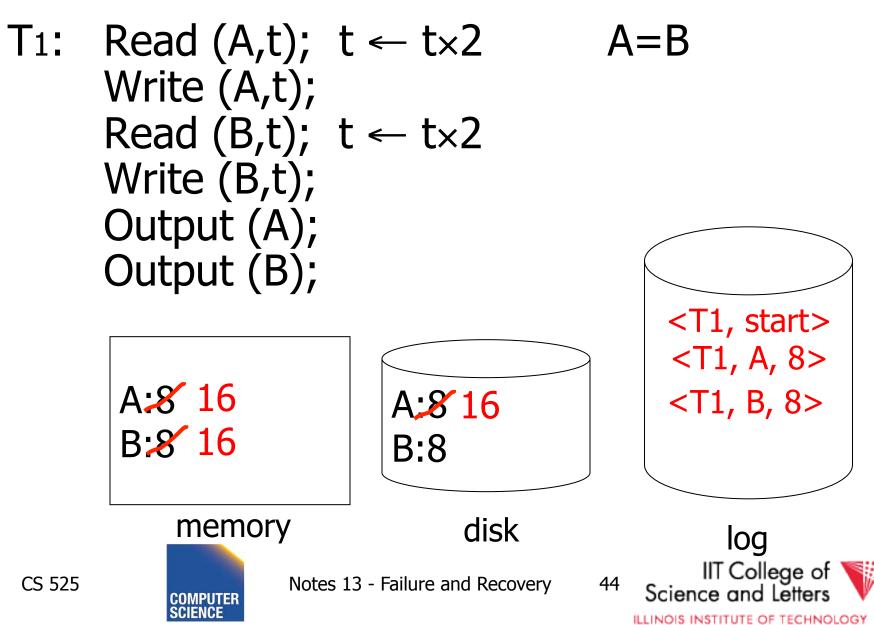
Notes 13 - Failure and Recovery

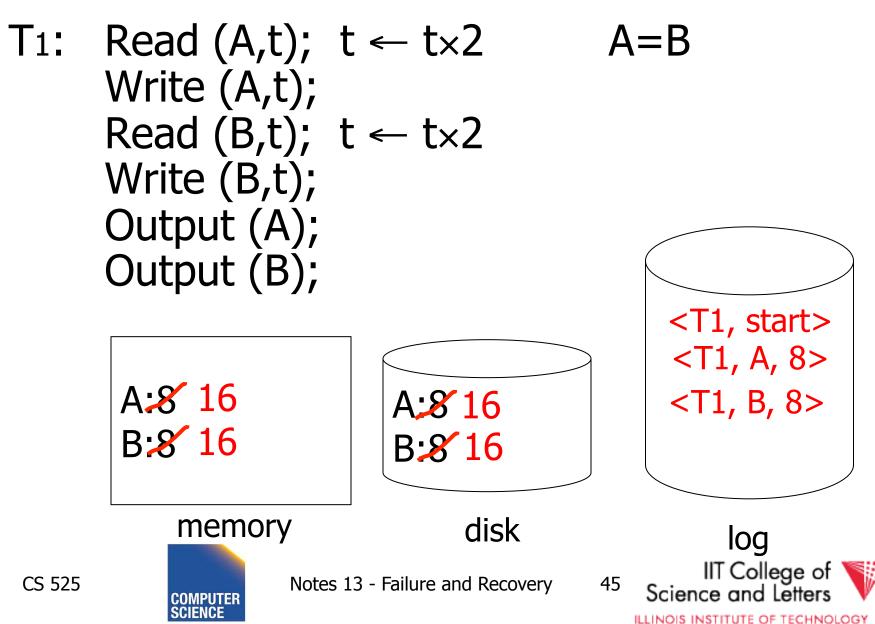


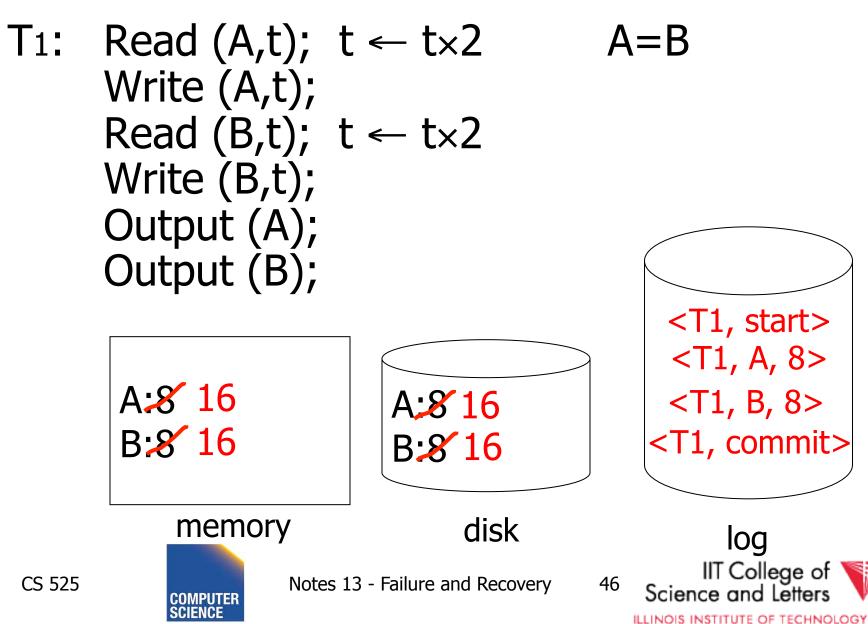
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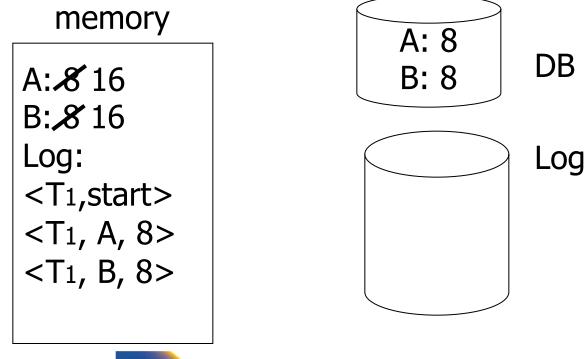






One "complication"

- Log is first written in memory
- Not written to disk on every action



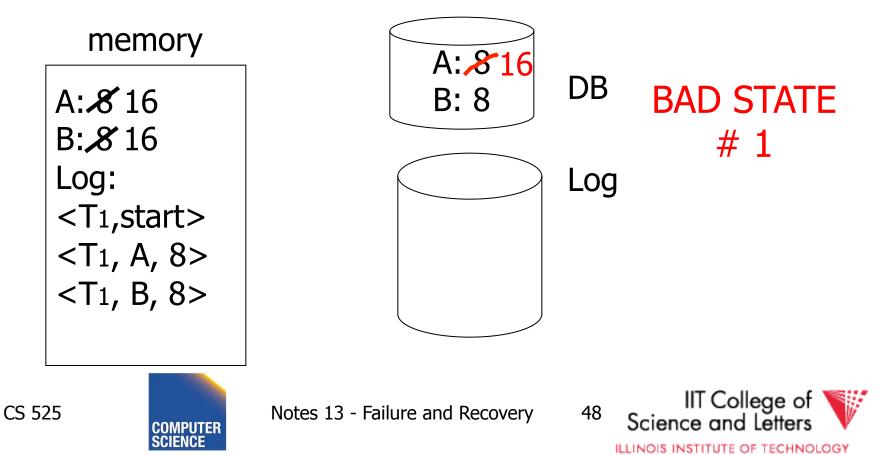


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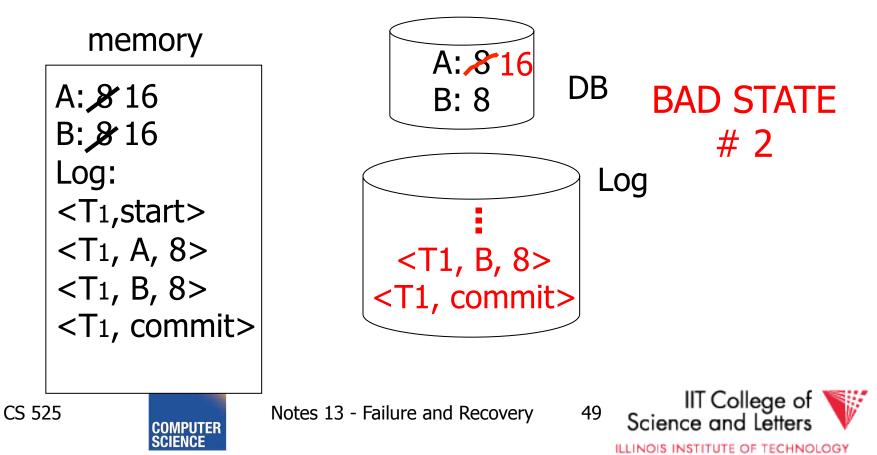
One "complication"

- Log is first written in memory
- Not written to disk on every action



One "complication"

- Log is first written in memory
- Not written to disk on every action



Undo logging rules

(1) For every action generate undo log record (containing old value) (2) Before x is modified on disk, log records pertaining to x must be on disk (write ahead logging: **WAL**) (3) Before commit is flushed to log, all writes of transaction must be reflected on disk





Recovery rules: Undo logging

• For every Ti with <Ti, start > in log: - If <Ti,commit> or <Ti,abort> in log, do nothing - Else | For all <Ti, *X*, *v*> in log: $\begin{cases} \text{write } (X, v) \\ \text{output } (X) \\ \text{Write } <\text{Ti, abort} > \text{ to log} \end{cases}$





Recovery rules: Undo logging

• For every Ti with <Ti, start > in log: - If <Ti,commit> or <Ti,abort> in log, do nothing - Else (For all <Ti, X, v> in log: $\begin{cases} \text{write } (X, v) \\ \text{output } (X) \\ \text{Write <Ti, abort> to log} \end{cases}$

➡IS THIS CORRECT??



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(1) Let S = set of transactions with <Ti, start> in log, but no
Ti, commit> (or <Ti, abort>) record in log
(2) For each <Ti, X, v> in log,

in reverse order (latest \rightarrow earliest) do:

- if Ti \in S then $\left\{ \begin{array}{l} - \text{ write } (X, v) \\ - \text{ output } (X) \end{array} \right\}$

(3) For each Ti \in S do

- write <Ti, abort> to log

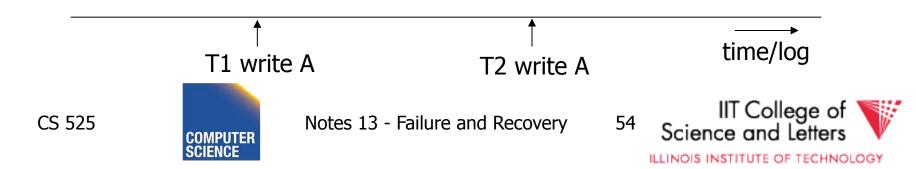


CS 525



<u>Question</u>

- Can writes of <Ti, abort> records be done in any order (in Step 3)?
 - Example: T1 and T2 both write A
 - T1 executed before T2
 - T1 and T2 both rolled-back
 - <T1, abort> written but NOT <T2, abort>?
 - <T2, abort> written but NOT <T1, abort>?



- An operation is called idempotent if the number of times it is applied do not effect the result
- For Undo:

CS 525

 Undo(log) = Undo(Undo(... (Undo(log)) ...))





Undo is idempotent

- We store the values of data items before the operation
- Undo can be executed repeatedly without changing effects

– idempotent



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Physical vs. Logical Logging

- How to represent values in log entries?
- Physical logging
 - Content of pages before and after
- Logical operations
 - Operation to execute for undo/redo
 - E.g., delete record x
- Hybrid (Physiological)
 - Delete record x from page y



CS 525



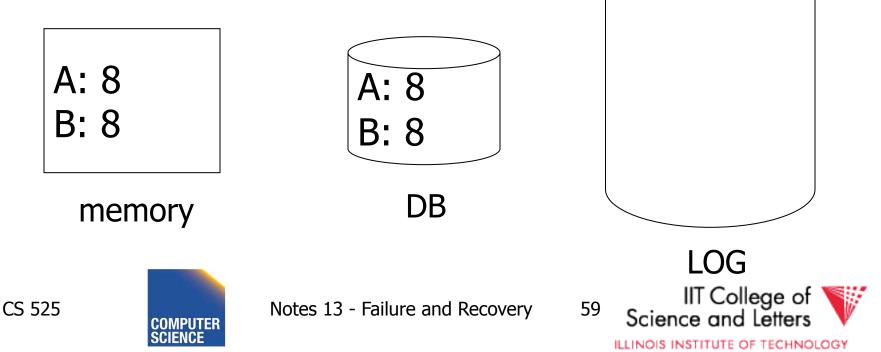
To discuss:

- Redo logging
- Undo/redo logging, why both?
- Real world actions
- Checkpoints
- Media failures

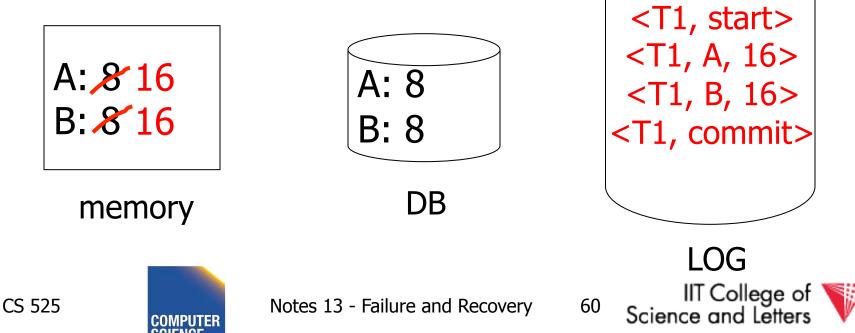




T1: Read(A,t); t- t×2; write (A,t); Read(B,t); t-t×2; write (B,t); Output(A); Output(B)

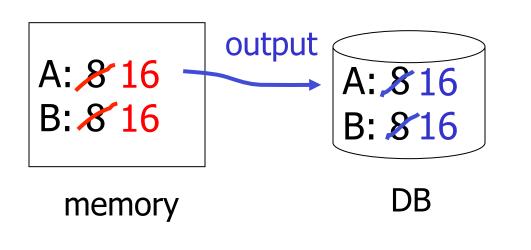


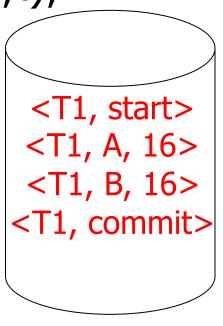
T1: Read(A,t); t- $t\times 2$; write (A,t); Read(B,t); t- $t\times 2$; write (B,t); Output(A); Output(B)



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T1: Read(A,t); t- t×2; write (A,t); Read(B,t); t-t×2; write (B,t); Output(A); Output(B)







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Notes 13 - Failure and Recovery

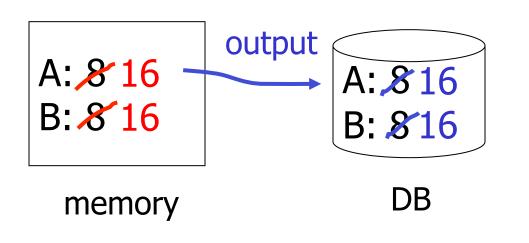
Science and Letters

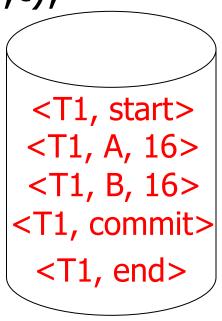
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T1: Read(A,t); t- t×2; write (A,t); Read(B,t); t-t×2; write (B,t); Output(A); Output(B)









Redo logging rules

(1) For every action, generate redo log record (containing new value)

(2) Before X is modified on disk (DB), all log records for transaction that modified X (including commit) must be on disk

(3) Flush log at commit

(4) Write END record after DB updates flushed to disk



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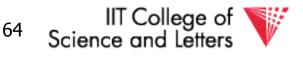


Redo logging



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Notes 13 - Failure and Recovery



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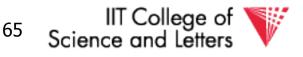
Redo logging

➡IS THIS CORRECT??



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Notes 13 - Failure and Recovery



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(1) Let S = set of transactions with <Ti, commit> (and no <Ti, end>) in log (2) For each <Ti, X, v> in log, in forward order (earliest \rightarrow latest) do: - if Ti \in S then Write(X, v) Output(X) (3) For each Ti \in S, write <Ti, end>



CS 525



Crash During Redo

- Since Redo log contains values after writes, repeated application of a log entry does not change result
 - -->idempotent

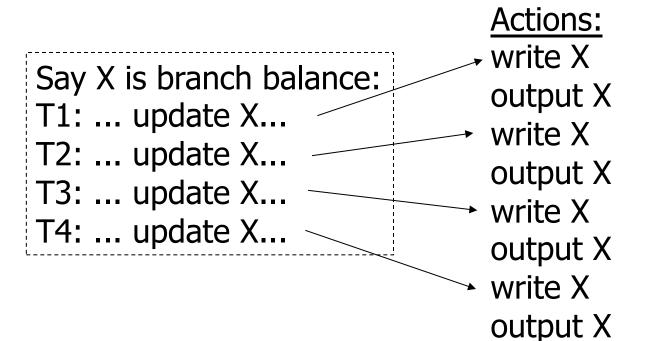


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<u>Combining <Ti, end> Records</u>

• Want to delay DB flushes for hot objects



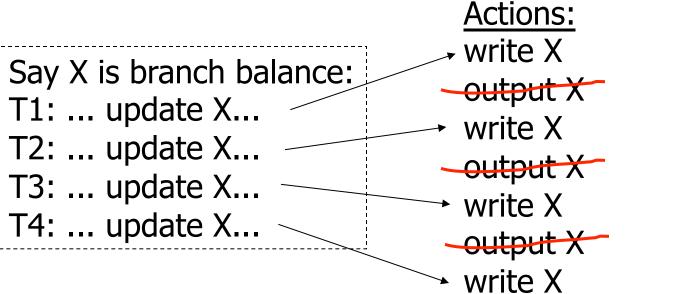


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<u>Combining <Ti, end> Records</u>

• Want to delay DB flushes for hot objects



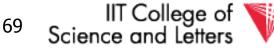
output X

combined <end> (checkpoint)



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Notes 13 - Failure and Recovery



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Solution: Checkpoint

no <ti, end> actions>
simple checkpoint

Periodically:

(1) Do not accept new transactions (2) Wait until all transactions finish (3) Flush all log records to disk (log) (4) Flush all buffers to disk (DB) (do not discard buffers) (5) Write "checkpoint" record on disk (log) (6) Resume transaction processing

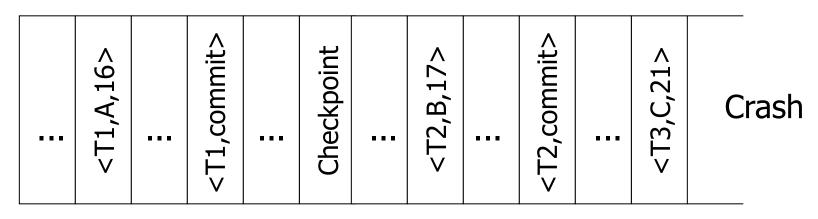


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Example: what to do at recovery?

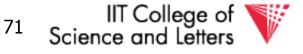
Redo log (disk):





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Notes 13 - Failure and Recovery



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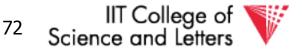
Advantage of Checkpoints

- Limits recovery to parts of the log after the checkpoint
 - Think about system that has been online for months
 - ->Analyzing the whole log is too expensive!
- Source of backups
 - If we backup checkpoints we can use them for media recovery!



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Notes 13 - Failure and Recovery



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Checkpoints Justification

- Checkpoint should be consistent DB state
 - No active transactions
 - Do not accept new transactions
 - Wait until all transactions finish
 - DB state reflected on disk
 - Flush log
 - Flush buffers



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Key drawbacks:

- Undo logging:
 - cannot bring backup DB copies up to date
- Redo logging:
 - need to keep all modified blocks in memory until commit



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<u>Solution: undo/redo logging!</u>

Update \Rightarrow <Ti, Xid, New X val, Old X val> page X



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<u>Rules</u>

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- Page X can be flushed before or after Ti commit
- Log record flushed before corresponding updated page (WAL)
- Flush at commit (log only)

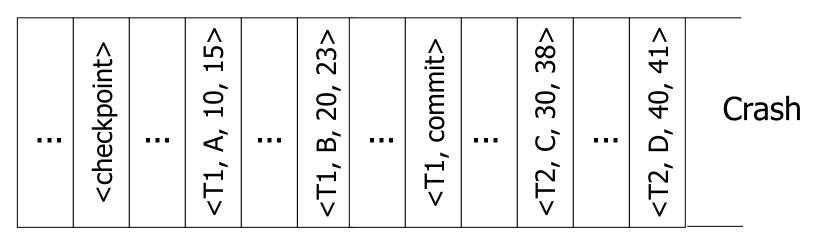




Example: Undo/Redo logging what to do at recovery?

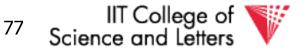
log (disk):

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Notes 13 - Failure and Recovery



Checkpoint Cost

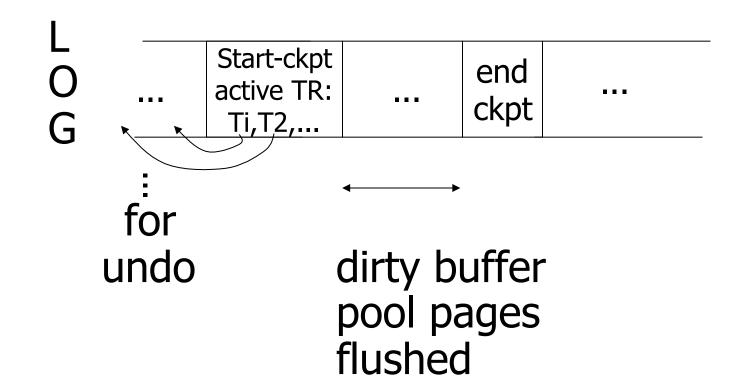
- Checkpoints are expensive
 - No new transactions can start
 - A lot of I/O
 - Flushing the log
 - Flushing dirty buffer pages



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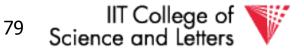
Non-quiesce checkpoint





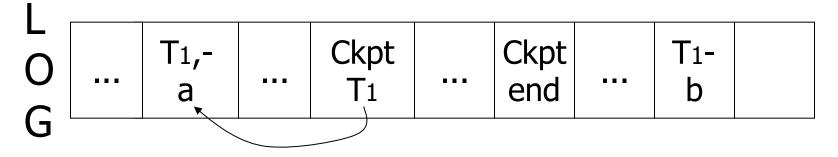
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Notes 13 - Failure and Recovery



Examples what to do at recovery time?

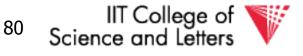
no T1 commit





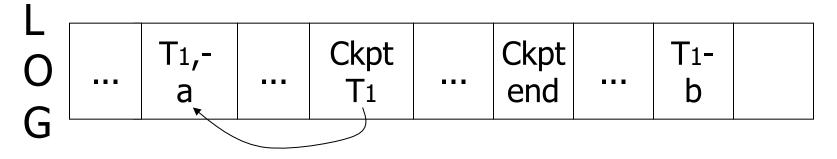
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Notes 13 - Failure and Recovery



Examples what to do at recovery time?

no T1 commit

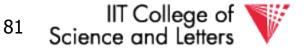


➡ Undo T1 (undo a,b)

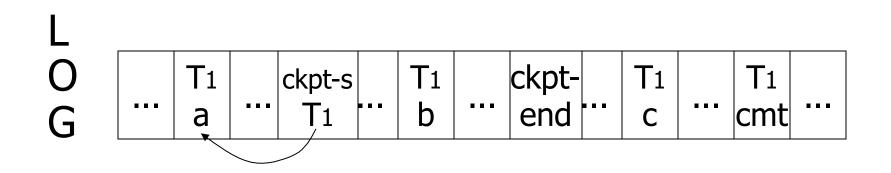


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Notes 13 - Failure and Recovery



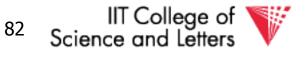
Example



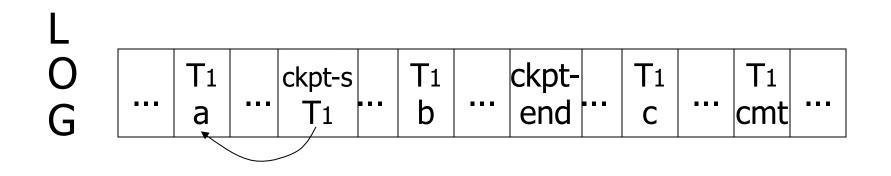


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Notes 13 - Failure and Recovery



Example



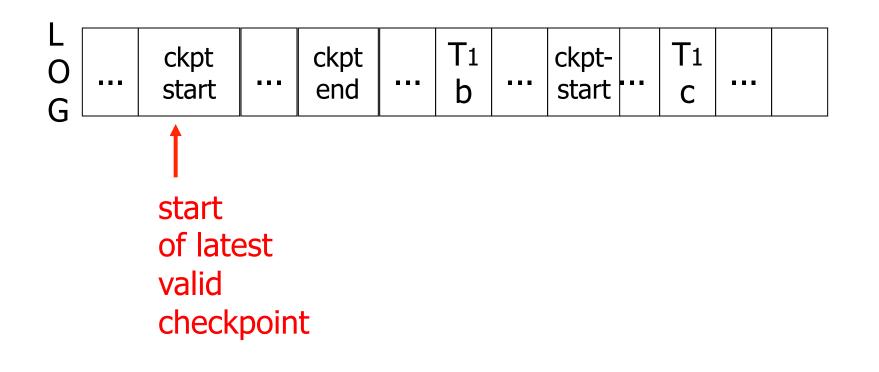
➡ Redo T1: (redo b,c)



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Recover From Valid Checkpoint:



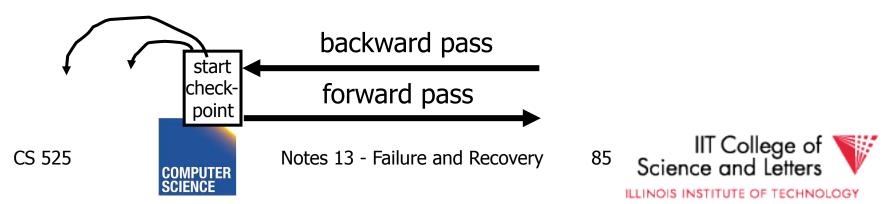


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Recovery process:

- Backwards pass (end of log → latest valid checkpoint start)
 - construct set S of committed transactions
 - undo actions of transactions not in S
- Undo pending transactions
 - follow undo chains for transactions in (checkpoint active list) - S
- Forward pass (latest checkpoint start → end of log)
 - redo actions of S transactions



Real world actions

E.g., dispense cash at ATM $Ti = a_1 a_2 \dots a_j \dots a_n$ \downarrow \$



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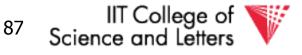


(1) execute real-world actions after commit(2) try to make idempotent



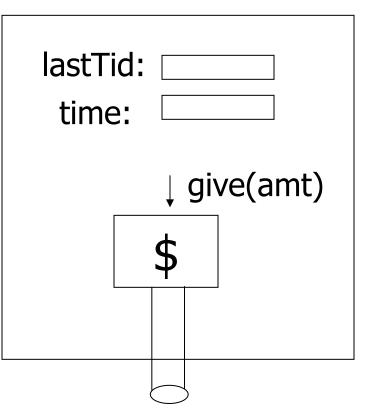
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Notes 13 - Failure and Recovery



Give\$\$ (amt, Tid, time)

ATM



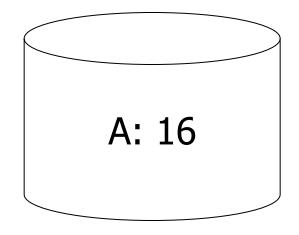


Notes 13 - Failure and Recovery



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<u>Media failure</u> (loss of non-volatile storage)

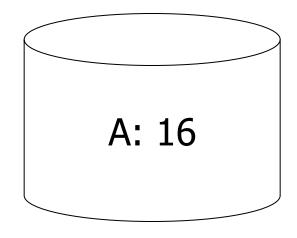




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<u>Media failure</u> (loss of non-volatile storage)



Solution: Make copies of data!

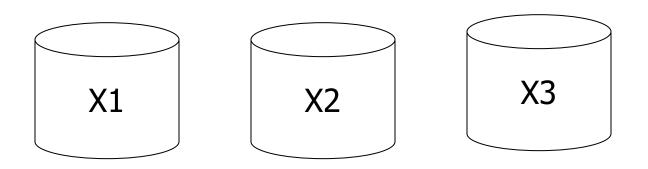


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Example 1 Triple modular redundancy

- Keep 3 copies on separate disks
- Output(X) --> three outputs
- Input(X) --> three inputs + vote





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Example #2 Redundant writes, Single reads

- Keep N copies on separate disks
- Output(X) --> N outputs
- Input(X) --> Input one copy

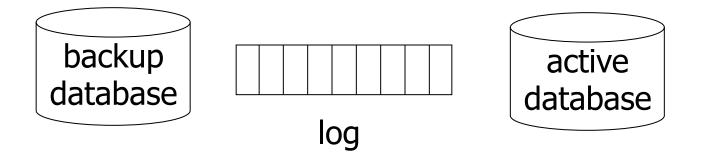
 if ok, done
 else try another one
- Assumes bad data can be detected



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Example #3: DB Dump + Log

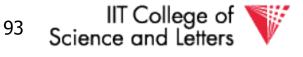


- If active database is lost,
 - restore active database from backup
 - bring up-to-date using redo entries in log

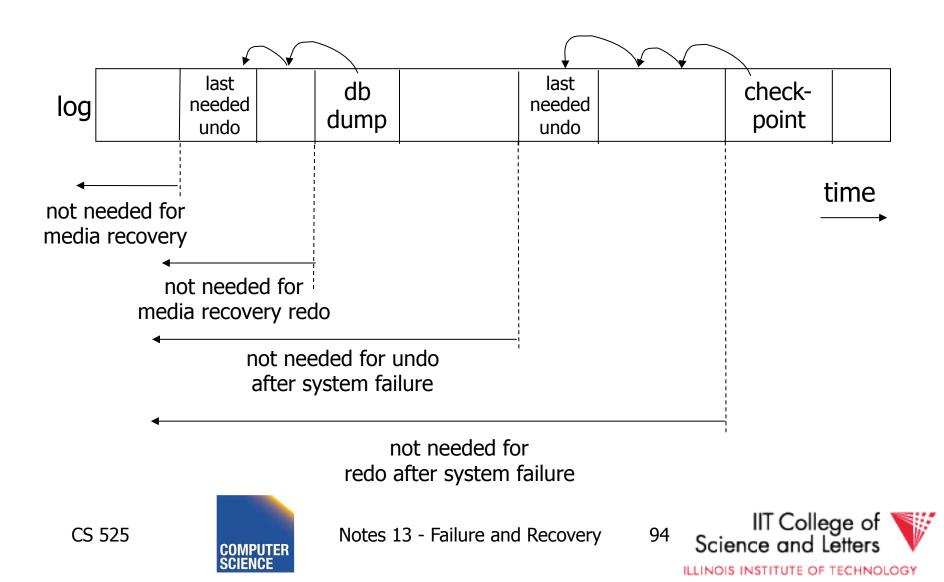


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Notes 13 - Failure and Recovery



When can log be discarded?



Practical Recovery with ARIES

• ARIES

- Algorithms for Recovery and Isolation
 Exploiting Semantics
- Implemented in, e.g.,
 - DB2

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– MSSQL





Underlying Ideas

- Keep track of state of pages by relating them to entries in the log
- WAL

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• Recovery in three phases

- Analysis, Redo, Undo
- Log entries to track state of Undo for repeated failures
- **Redo**: page-oriented -> efficient
- **Undo**: logical -> permits higher level of concurrency





Log Entry Structure

• LSN

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- Log sequence number
- Order of entries in the log
- Usually **log file id** and **offset** for direct access





• LSN

• Entry type

- Update, compensation, commit, ...
- TID

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Transaction identifier

PrevLSN

- LSN of previous log record for same transaction

UndoNxtLSN

Next undo operation for CLR (later!)

Undo/Redo data

Data needed to undo/redo the update





Page Header Additions

• PageLSN

- LSN of the last update that modified the page
- Used to know which changes have been applied to a page



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Forward Processing

- Normal operations when no ROLLBACK is required
 - WAL: write redo/undo log record for each action of a transaction
- Buffer manager has to ensure that
 - changes to pages are not persisted before the corresponding log record has been persisted
 - Transactions are not considered committed before all their log records have been flushed



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Dirty Page Table

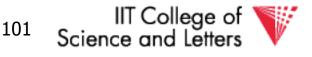
• PageLSN

- Entries <PageID,RecLSN>
- Whenever a page is first fixed in the buffer pool with indention to modify
 - Insert **< PageId, RecLSN >** with **RecLSN** being the current end of the log
- Flushing a page removes it from the Dirty page table



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Notes 13 - Failure and Recovery



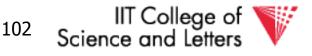
Dirty Page Table

- Used for checkpointing
- Used for recovery to figure out what to redo



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Notes 13 - Failure and Recovery



Transaction Table

- TransID
 - Identifier of the transaction
- State

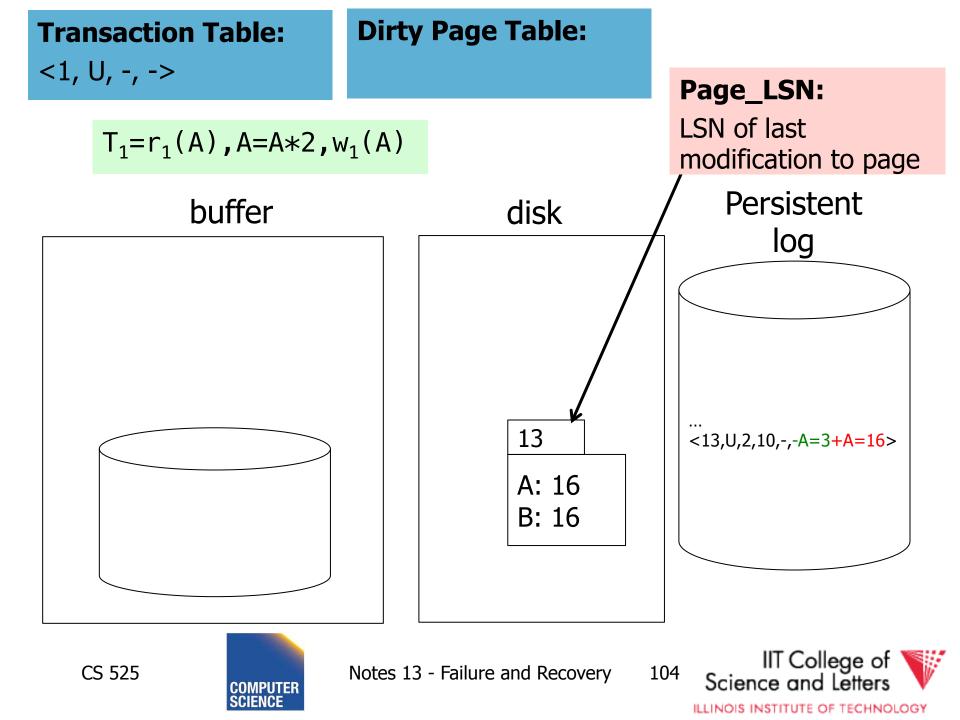
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- Commit state
- LastLSN
 - LSN of the last update of the transaction
- UndoNxtLSN
 - If last log entry is a CLR then UndoNxtLSN from that record
 - Otherwise = LastLSN

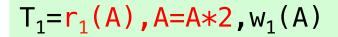


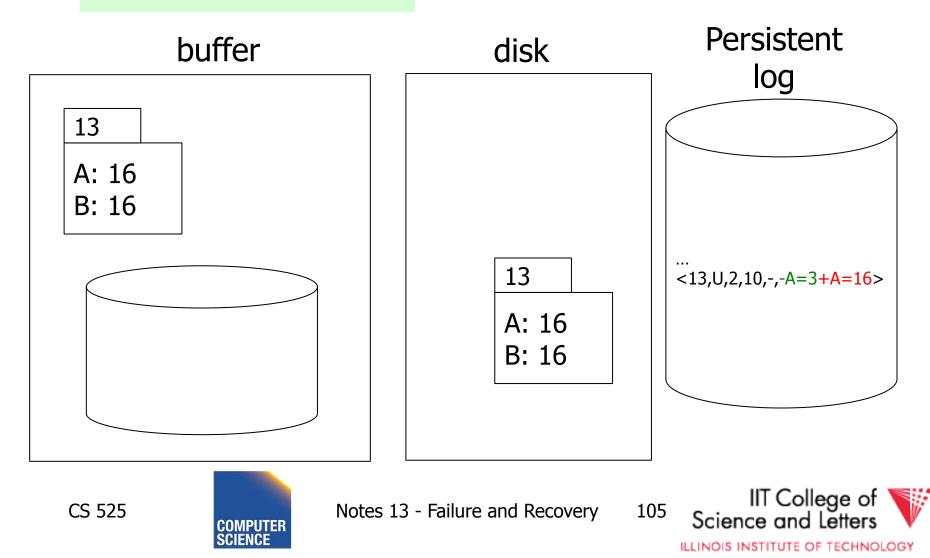


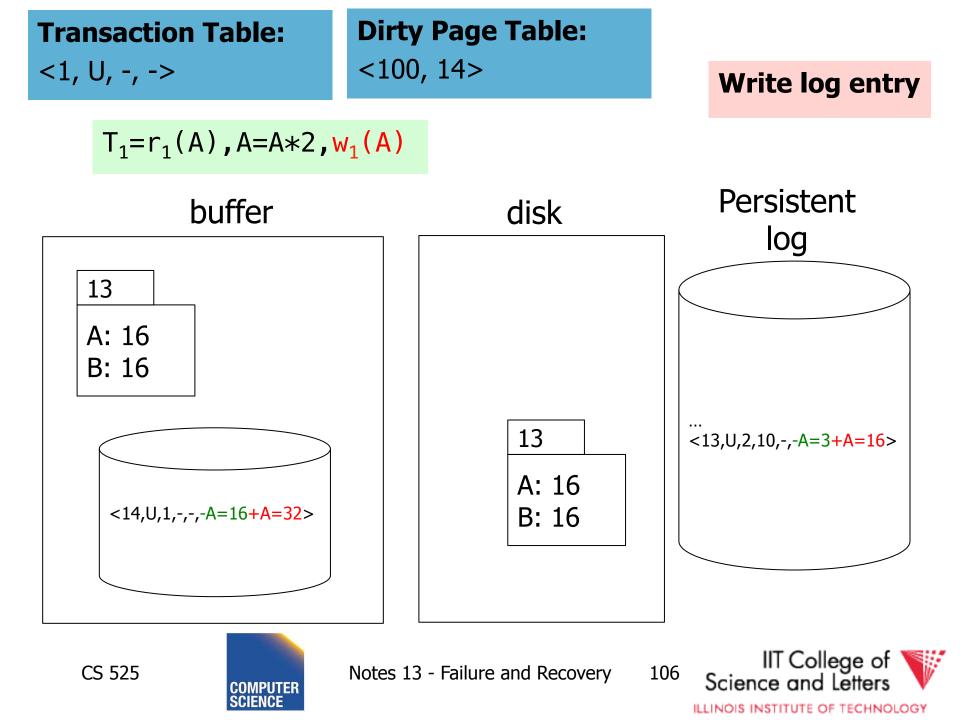
103

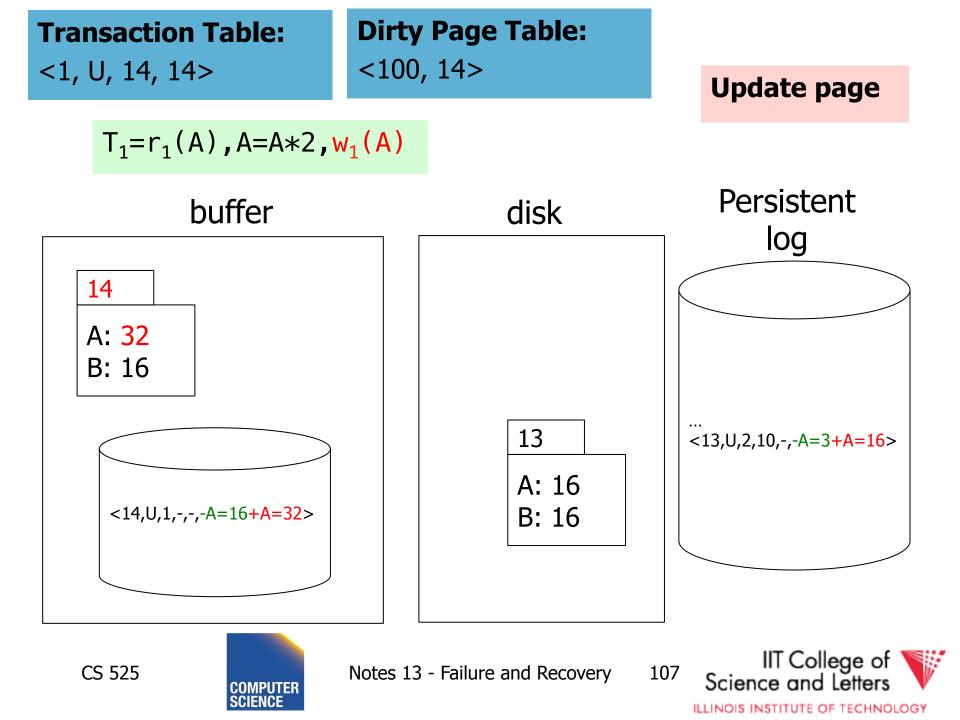


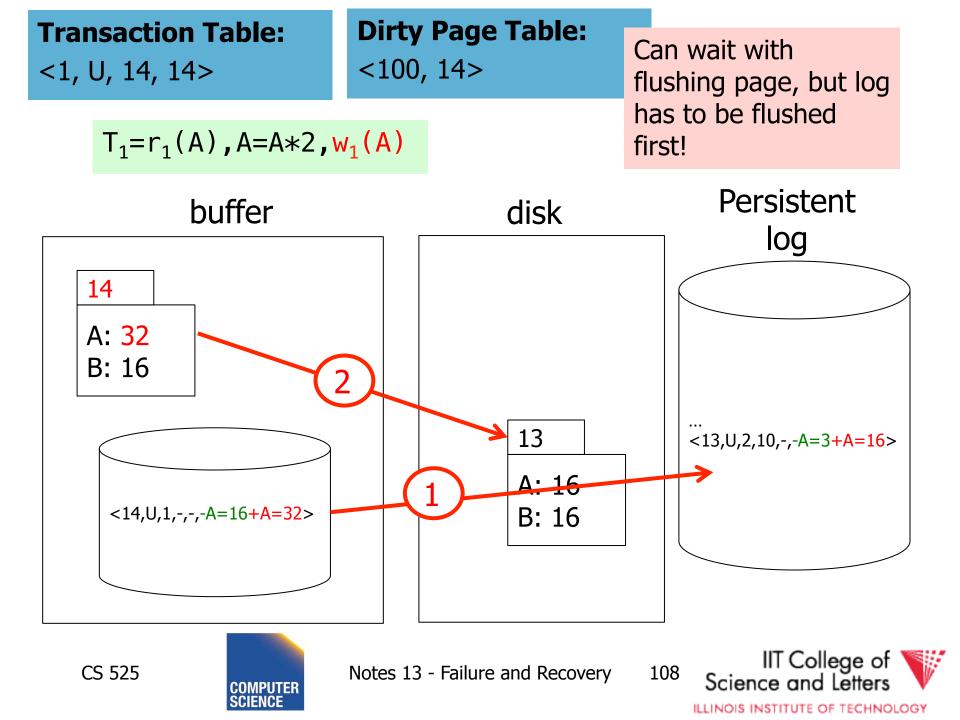












Undo during forward processing

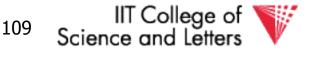
- Transaction was rolled back
 User aborted, aborted because of error, ...
- Need to undo operations of transaction
- During Undo

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- Write log entries for every undo
- Compensation Log Records (CLR)
- Used to avoid repeated undo when failures occur



Notes 13 - Failure and Recovery



Undo during forward processing

- Starting with the LastLSN of transaction from transaction table
 - Traverse log entries of transaction last to first using PrevLSN pointers
 - For each log entry use undo information to undo action
 - <LSN, Type, TID, PrevLSN, -, Undo/Redo data>
 - Before modifying data write an CLR that stores redo-information for the undo operation
 - **UndoNxtLSN** = **PrevLSN** of log entry we are undoing
 - **Redo data** = How to redo the undo



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Notes 13 - Failure and Recovery

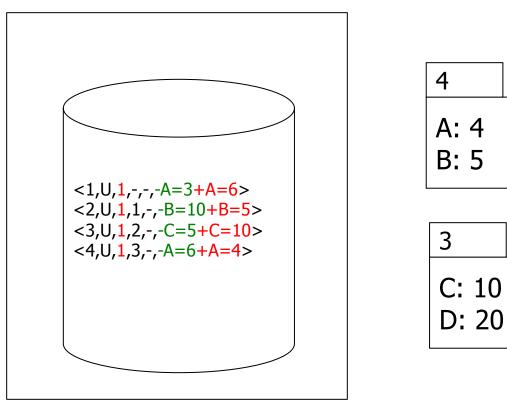


Transaction Table: <1, U, 4, 4>

Undo T₁

$$T_1 = w_1(A), w_1(B), w_1(C), w_1(A), a_1$$

buffer





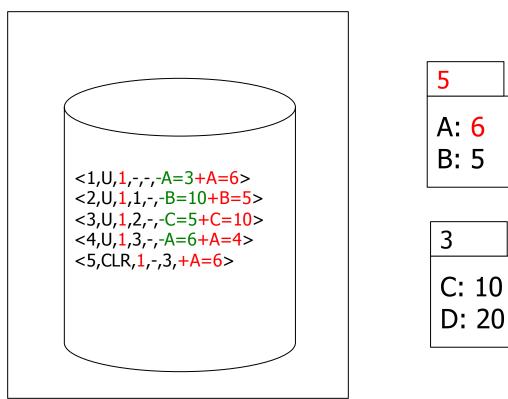


Transaction Table: <1, U, **5**, **3**>

Undo T₁

$$T_1 = w_1(A), w_1(B), w_1(C), w_1(A), a_1$$

buffer





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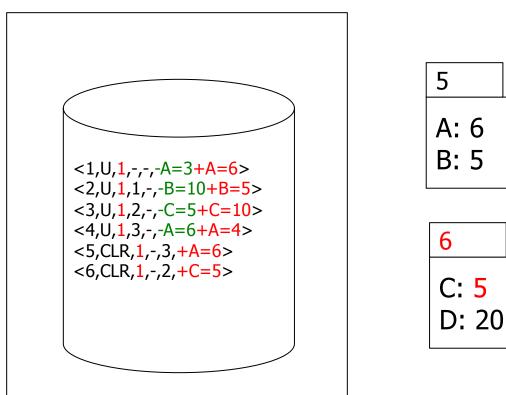


Transaction Table: <1, U, **6**, **2**>

Undo T₁

$$T_1 = w_1(A), w_1(B), w_1(C), w_1(A), a_1$$

buffer





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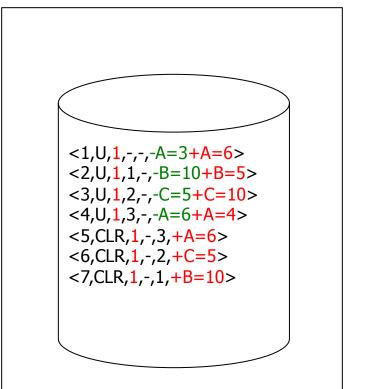


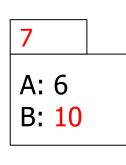
Transaction Table: <1, U, **7**, **1**>

Undo T₁

$$T_1 = w_1(A), w_1(B), w_1(C), w_1(A), a_1$$

buffer







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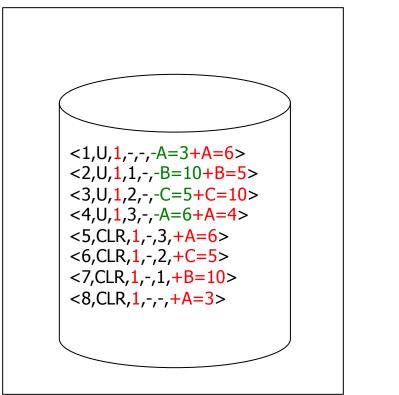


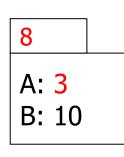
Transaction Table: <1, U, **8**, ->

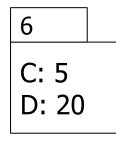
Undo T₁

$$T_1 = w_1(A), w_1(B), w_1(C), w_1(A), a_1$$

buffer











Fuzzy Checkpointing in ARIES

- Begin of checkpoint
 - Write **begin_cp** log entry
 - Write **end_cp** log entry with
 - Dirty page table
 - Transaction table

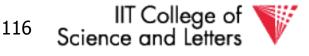
Master Record

 LSN of begin_cp log entry of last complete checkpoint



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Notes 13 - Failure and Recovery



Restart Recovery

- 1. Analysis Phase
- 2. Redo Phase
- 3. Undo Phase



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Notes 13 - Failure and Recovery



Analysis Phase

1) Determine LSN of last checkpoint using Master Record

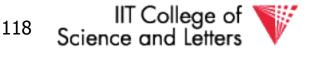
2) Get Dirty Page Table and Transaction Table from checkpoint end record

3) RedoLSN = min(RecLSN) from Dirty Page Table or checkpoint LSN if no dirty page



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Notes 13 - Failure and Recovery



Analysis Phase

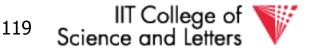
4) Scan log forward starting from RedoLSN

- Update log entry from transaction
 - If necessary: Add Page to Dirty Page Table
 - Add Transaction to Transaction Table or update LastLSN
- Transaction end entry
 - Remove transaction from Transaction Table



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Notes 13 - Failure and Recovery



Analysis Phase

• Result

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- Transaction Table
 - Transactions to be later undone
- RedoLSN
 - Log entry to start Redo Phase
- Dirty Page Table
 - Pages that may not have been written back to disk



Notes 13 - Failure and Recovery



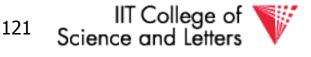
Redo Phase

- Start at RedoLSN scan log forward
- Unconditional Redo
 - Even redo actions of transactions that will be undone later
- Only redo once
 - Only redo operations that have not been reflected on disk (PageLSN)



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Notes 13 - Failure and Recovery



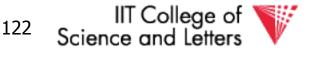
Redo Phase

- For each update log entry
 - If affected page is not in Dirty Page Table or RecLSN > LSN
 - skip log entry
 - Fix page in buffer
 - If PageLSN >= LSN then operation already reflected on disk
 - Skip log entry
 - Otherwise apply update



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Notes 13 - Failure and Recovery



Redo Phase

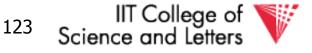
• Result

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– State of DB before Failure



Notes 13 - Failure and Recovery



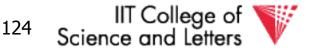
Undo Phase

- Scan log backwards from end using Transaction Table
 - Repeatedly take log entry with max LSN from all the current actions to be undone for each transaction
 - Write CLR
 - Update Transaction Table



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Notes 13 - Failure and Recovery



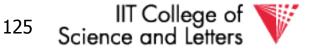
Undo Phase

• All unfinished transactions have been rolled back



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Notes 13 - Failure and Recovery



Idempotence?

- Redo
 - We are not logging during Redo so repeated Redo will result in the same state
- Undo

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If we see CLRs we do not undo this action again





Avoiding Repeated Work

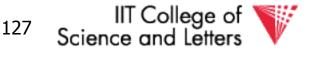
- Redo
 - If operation has been reflected on disk
 (PageLSN) we do not need to redo it again
- Undo

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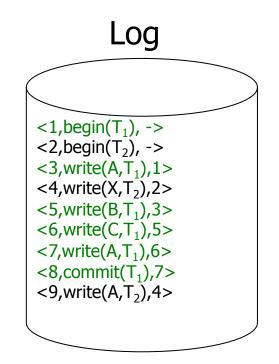
If we see CLRs we do not undo this action again



Notes 13 - Failure and Recovery



$$T_{1} = w_{1}(A), \qquad w_{1}(B), w_{1}(C), w_{1}(A), c_{1}$$
$$T_{2} = w_{1}(X), \qquad r(A), w(A)$$





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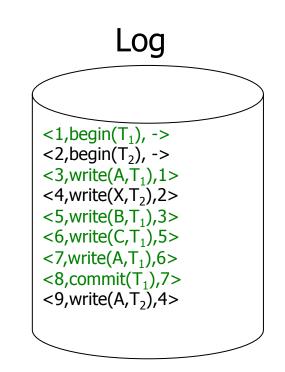


$$T_{1} = w_{1}(A), \qquad w_{1}(B), w_{1}(C), w_{1}(A), c_{1}$$
$$T_{2} = w_{1}(X), \qquad r(A), w(A)$$

Analysis Phase:

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- start at log entry 1
- add T₁ to transaction table (rec. 1)
- add T₂ to transaction table (rec. 2)
- add A to dirty page table (RecLSN 3)
- add X to dirty page table (RecLSN 4)
- add B to dirty page table (RecLSN 5)
- add C to dirtypage table (RecLSN 6)
- remove T1 from Transaction Table (rec. 8)





Notes 13 - Failure and Recovery



$$T_{1} = w_{1}(A), \qquad w_{1}(B), w_{1}(C), w_{1}(A), c_{1}$$

$$T_{2} = w_{1}(X), \qquad r(A), w(A)$$

Analysis Phase Result:

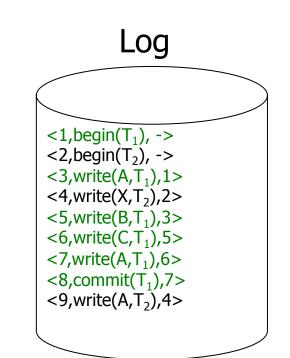
- Transaction Table:

<T₂, 9>

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- Dirty Page Table:

$$- \text{RedoLSN} = \min(3,5,6,4) = 3$$



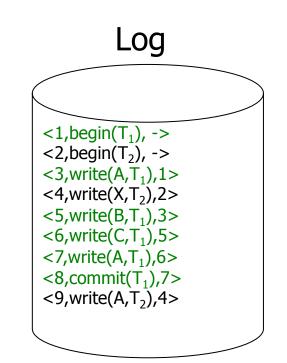




$$T_{1} = w_{1}(A), \qquad w_{1}(B), w_{1}(C), w_{1}(A), c_{1}$$
$$T_{2} = w_{1}(X), \qquad r(A), w(A)$$

Redo Phase (RedoLSN 3):

- Read A if PageLSN < 3 apply write
- Read X if PageLSN < 4 apply write
- Read B if PageLSN < 5 apply write
- Read C if PageLSN < 6 apply write
- Read A if PageLSN < 7 apply write
- Read A if PageLSN < 9 apply write





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Notes 13 - Failure and Recovery



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$$T_{1} = w_{1}(A), \qquad w_{1}(B), w_{1}(C), w_{1}(A), c_{1}$$
$$T_{2} = w_{1}(X), \qquad r(A), w(A)$$

Undo Phase (T₂):

- Undo entry 9

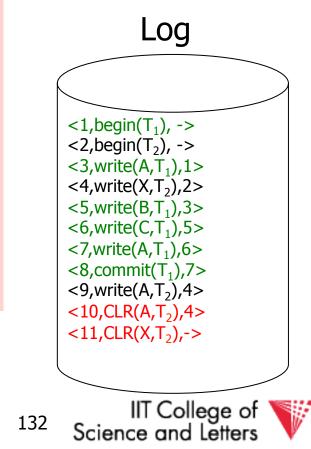
-write CLR with UndoNxtLSN = 4 -modify page A

- Undo entry 4

-write CLR with UndoNxtLSN = 2 -modify page X

- Done

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Notes 13 - Failure and Recovery

ARIES take away messages

- Provide good performance by
 - Not requiring complete checkpoints
 - Linking of log records
 - Not restricting buffer operations (no-force/steal is ok)
- Logical Undo and Physical (Physiological) Redo
- Idempotent Redo and Undo
 - Avoid undoing the same operation twice



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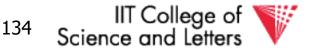
Media Recovery

- What if disks where log or DB is stored failes
 - -->keep backups of log + DB state



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Notes 13 - Failure and Recovery



Log Backup

- Split log into several files
- Is append only, backup of old files cannot interfere with current log operations



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Notes 13 - Failure and Recovery



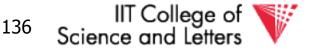
Backup DB state

- Copy current DB state directly from disk
- May be inconsistent
- ->Use log to know which pages are upto-date and redo operations not yet reflected



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Notes 13 - Failure and Recovery



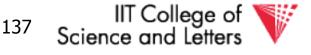
<u>Summary</u>

- Consistency of data
- One source of problems: failures
 - Logging
 - Redundancy
- Another source of problems: Data Sharing..... next



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Notes 13 - Failure and Recovery





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CS 525: Advanced Database Organization 14: Concurrency Control

Boris Glavic

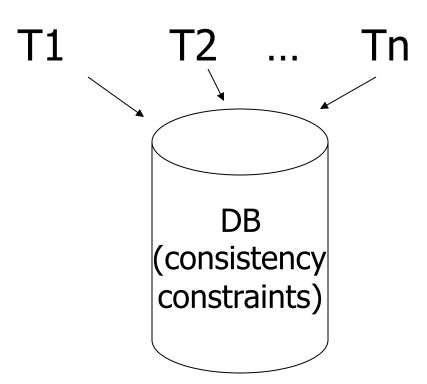
Slides: adapted from a <u>course</u> taught by

Hector Garcia-Molina, Stanford InfoLab





Chapter 18 [18] Concurrency Control





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Example:

T1: Read(A) $A \leftarrow A+100$ Write(A) Read(B) $B \leftarrow B+100$ Write(B) Constraint: A=B

T2: Read(A) $A \leftarrow A \times 2$ Write(A) Read(B) $B \leftarrow B \times 2$ Write(B)



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Schedule A

T1

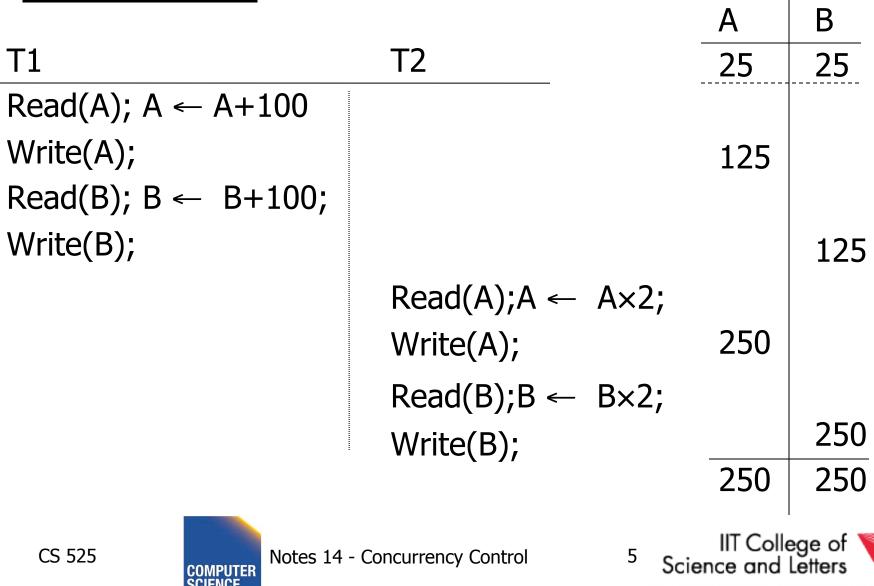
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T2 Read(A); $A \leftarrow A+100$ Write(A); Read(B); $B \leftarrow B+100$; Write(B); Read(A); $A \leftarrow A \times 2$; Write(A); Read(B); $B \leftarrow B \times 2$; Write(B);





Schedule A



Schedule B

T1

T2

Read(A);A \leftarrow A×2; Write(A); Read(B);B \leftarrow B×2; Write(B);

Read(A); $A \leftarrow A+100$ Write(A); Read(B); $B \leftarrow B+100$; Write(B);





Schedule B			
		А	В
T1	T2	25	25
	Read(A); $A \leftarrow A \times 2;$	50	
	Write(A);	50	
	Read(B);B \leftarrow B×2;		
	Write(B);		50
Read(A); A ← A+100			
Write(A);		150	
Read(B); $B \leftarrow B+100$;			
Write(B);			150
		150	150

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Notes 14 - Concurrency Control

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Schedule C

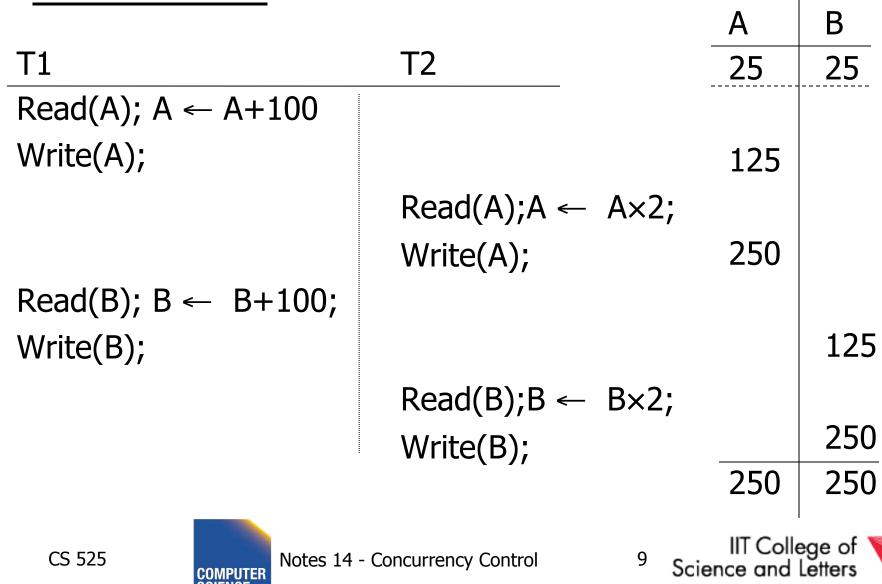
T2 T1 Read(A); $A \leftarrow A+100$ Write(A); Read(A); $A \leftarrow A \times 2$; Write(A); Read(B); $B \leftarrow B+100$; Write(B); Read(B); $B \leftarrow B \times 2$; Write(B);



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Schedule C



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Schedule D

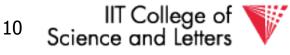
T2 **T1** Read(A); $A \leftarrow A+100$ Write(A); Read(A); $A \leftarrow A \times 2$; Write(A); Read(B); $B \leftarrow B \times 2$; Write(B);

Read(B); $B \leftarrow B+100$; Write(B);

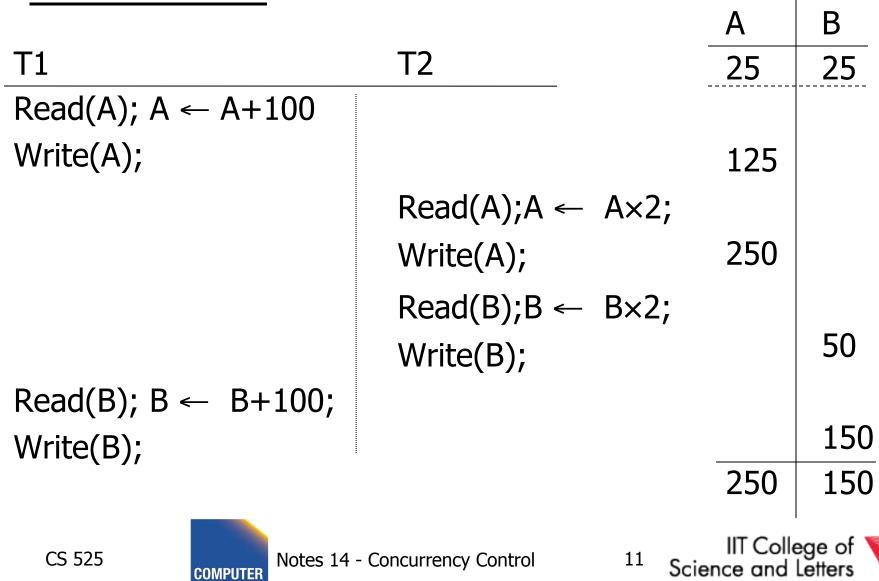
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Schedule D



<u>Schedule E</u>	Same as Schedule D but with new T2'
T1	T2'
Read(A); $A \leftarrow A+100$	
Write(A);	
	Read(A);A \leftarrow A×1;
	Write(A);
	Read(B);B ← B×1;
	Write(B);
Read(B); B ← B+100 Write(B);	;





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Schedule E	Same as Schedule D but with new T2'		
<u> </u>		Α	В
T1	T2'	25	25
Read(A); A ← A+100			
Write(A);		125	
	Read(A);A \leftarrow A×1;		
	Write(A);	125	
	Read(B);B \leftarrow B×1;		
	Write(B);		25
Read(B); B ← B+100);		
Write(B);			125
		125	125
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Serial Schedules

- As long as we do not execute transactions in parallel and each transaction does not violate the constraints we are good
 - All schedules with no interleaving of transaction operations are called serial schedules



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Definition: Serial Schedule

- No transactions are interleaved
 - There exists no two operations from transactions Ti and Tj so that both operations are executed before either transaction commits



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Notes 14 - Concurrency Control



$$T_1 = r_1(A), w_1(A), r_1(B), w_1(B), c_1$$

$$T_2 = r_2(A), w_2(A), r_2(B), w_2(B), c_2$$

Serial Schedule

 $S_1 = r_2(A), w_2(A), r_2(B), w_2(B), c_2, r_1(A), w_1(A), r_1(B), w_1(B), c_1$

Nonserial Schedule

 $S_2 = r_2(A), w_2(A), r_1(A), w_1(A), r_2(B), w_2(B), c_2, r_1(B), w_1(B), c_1$



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Notes 12 - Transaction Management



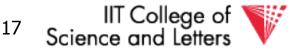
Compare Classes

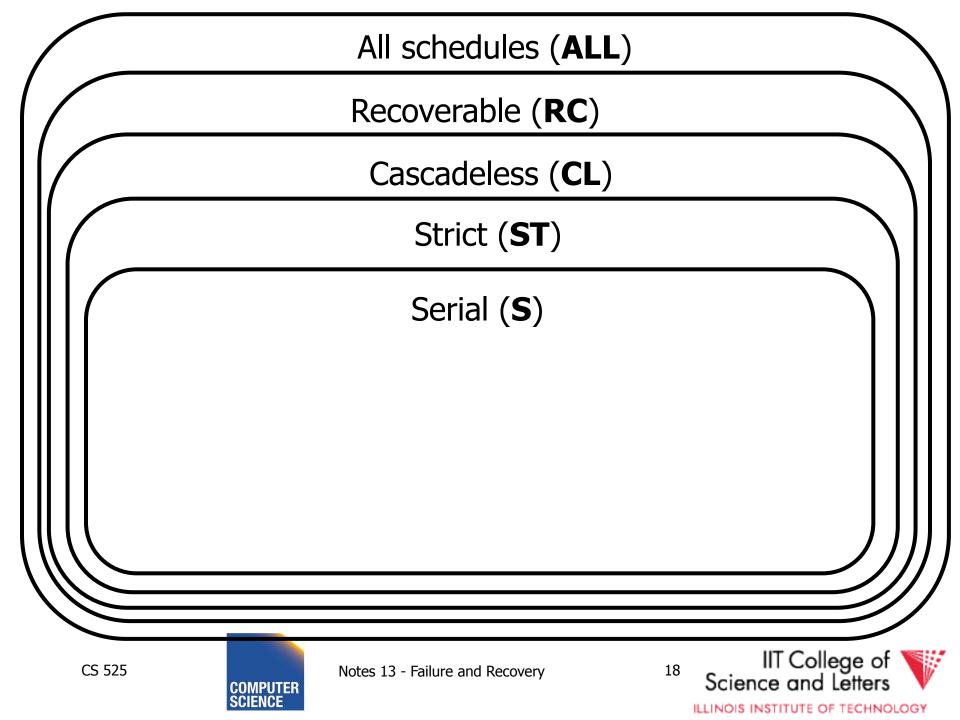
$S \subset ST \subset CL \subset RC \subset ALL$

- Abbreviations
 - -S = Serial
 - -ST = Strict
 - -CL = Cascadeless
 - -RC = Recoverable
 - -ALL = all possible schedules

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Notes 13 - Failure and Recovery





Why not serial schedules?

● No concurrency! ⊗



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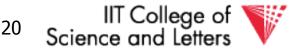
- Want schedules that are "good", regardless of
 - initial state and
 - transaction semantics
- Only look at order of read and writes

Example: $Sc=r_1(A)w_1(A)r_2(A)w_2(A)r_1(B)w_1(B)r_2(B)w_2(B)$



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Outline

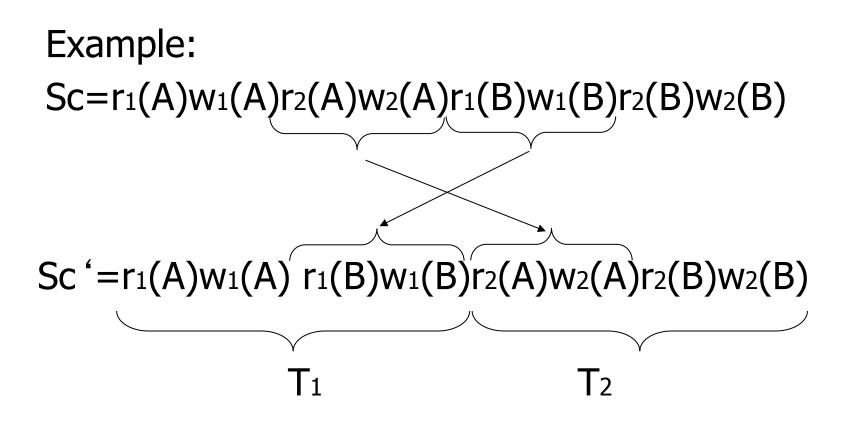
- Since serial schedules have good properties we would like our schedules to behave like (be **equivalent** to) serial schedules
 - 1. Need to define equivalence based solely on order of operations
 - 2. Need to define class of schedules which is equivalent to serial schedule
 - 3. Need to design scheduler that guarantees that we only get these good schedules



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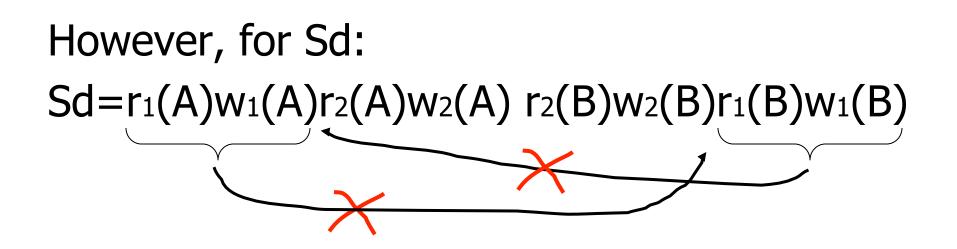




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 as a matter of fact, T₂ must precede T₁ in any equivalent schedule, i.e., T₂ → T₁



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• $T_2 \rightarrow T_1$

T₂

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• Also, $T_1 \rightarrow T_2$

 ⇒ Sd cannot be rearranged into a serial schedule
 ⇒ Sd is not "equivalent" to any serial schedule
 ⇒ Sd is "bad"





Returning to Sc

Sc=r₁(A)w₁(A)r₂(A)w₂(A)r₁(B)w₁(B)r₂(B)w₂(B) $T_1 \rightarrow T_2$ $T_1 \rightarrow T_2$



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Returning to Sc

Sc=r₁(A)w₁(A)r₂(A)w₂(A)r₁(B)w₁(B)r₂(B)w₂(B) $T_1 \rightarrow T_2$ $T_1 \rightarrow T_2$

• no cycles \Rightarrow Sc is "equivalent" to a serial schedule (in this case T₁,T₂)



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Concepts

- *Transaction:* sequence of $r_i(x)$, $w_i(x)$ actions *Conflicting actions:* $r_1(A) \xrightarrow{W2(A)} W1(A) \xrightarrow{W1(A)} W2(A)$
- Schedule: represents chronological order in which actions are executed
- Serial schedule: no interleaving of actions or transactions

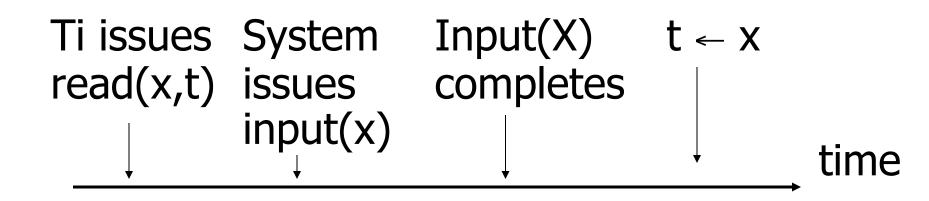


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What about concurrent actions?



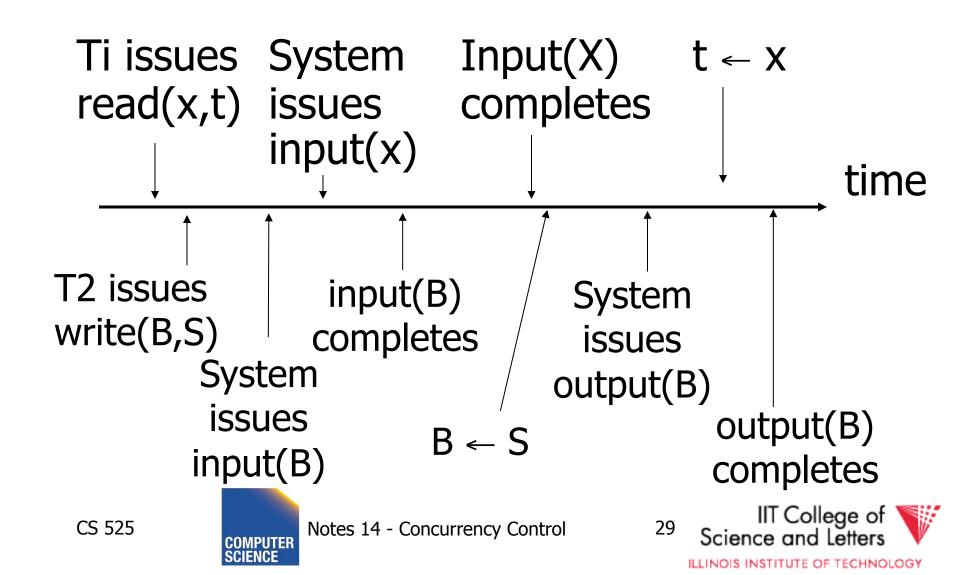


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What about concurrent actions?



So net effect is either

- S=...r₁(x)...w₂(b)... or
- $S=...w_2(B)...r_1(x)...$

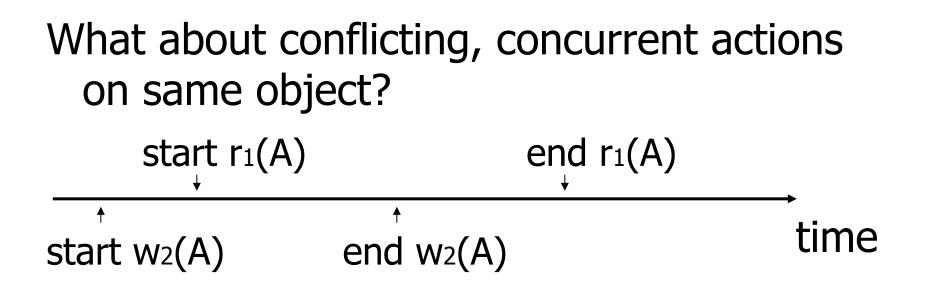


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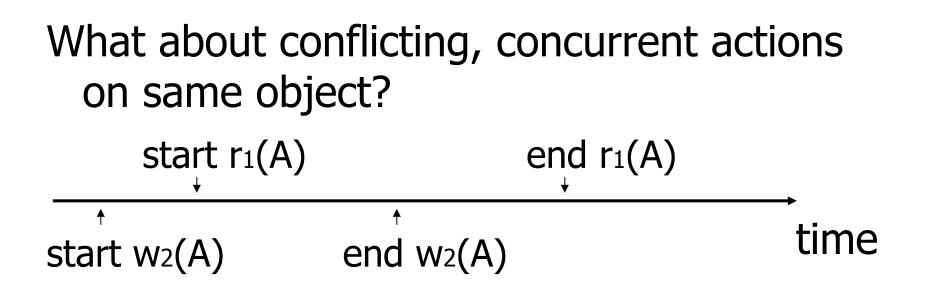


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- Assume equivalent to either r₁(A) w₂(A) or w₂(A) r₁(A)
- \Rightarrow low level synchronization mechanism
- Assumption called "atomic actions"

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Outline

- Since serial schedules have good properties we would like our schedules to behave like (be **equivalent** to) serial schedules
 - 1. Need to define equivalence based solely on order of operations
 - 2. Need to define class of schedules which is equivalent to serial schedule
 - 3. Need to design scheduler that guarantees that we only get these good schedules



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Conflict Equivalence

• Define equivalence based on the order of conflicting actions



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Definition

S₁, S₂ are <u>conflict equivalent</u> schedules if S₁ can be transformed into S₂ by a series of swaps on non-conflicting actions.

Alternatively:

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If the order of conflicting actions in S_1 and S_2 is the same



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Outline

- Since serial schedules have good properties we would like our schedules to behave like (be **equivalent** to) serial schedules
 - 1. Need to define equivalence based solely on order of operations
 - 2. Need to define class of schedules which is equivalent to serial schedule
 - 3. Need to design scheduler that guarantees that we only get these good schedules



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Definition

A schedule is <u>conflict serializable</u> (**CSR**) if it is conflict equivalent to some serial schedule.



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How to check?

- Compare orders of all conflicting operations
- Can be simplified because there is some redundant information here, e.g.,

 $S_1 = w_2(A), w_2(B), r_1(A), w_1(B)$

- W2(A) conflicts with R1(A)
- W2(B) conflicts with W1(B)
- Both imply that T2 has to be executed before T1 in any equivalent serial schedule



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Conflict graph P(S) (S is schedule)

Nodes: transactions in S Arcs: Ti \rightarrow Tj whenever

- p_i(A), q_j(A) are actions in S
- $p_i(A) <_S q_j(A)$
- at least one of pi, qj is a write





Exercise:

What is P(S) for
 S = w₃(A) w₂(C) r₁(A) w₁(B) r₁(C) w₂(A) r₄(A) w₄(D)

• Is S serializable?

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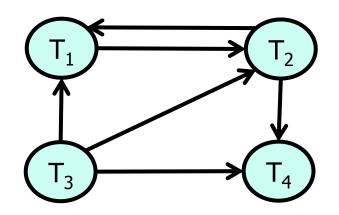
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Exercise:

What is P(S) for
 S = w₃(A) w₂(C) r₁(A) w₁(B) r₁(C) w₂(A) r₄(A) w₄(D)



• Is S serializable?

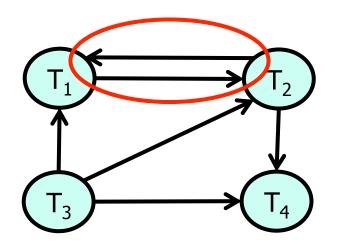
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Exercise:

What is P(S) for
 S = w₃(A) w₂(C) r₁(A) w₁(B) r₁(C) w₂(A) r₄(A) w₄(D)



• Is S serializable?

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Another Exercise:

• What is P(S) for S = w₁(A) r₂(A) r₃(A) w₄(A) ?



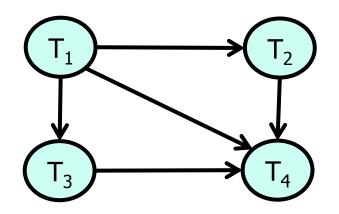
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Another Exercise:

• What is P(S) for S = w₁(A) r₂(A) r₃(A) w₄(A) ?









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S₁, S₂ conflict equivalent \Rightarrow P(S₁)=P(S₂)



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<u>Lemma</u>

 S_1 , S_2 conflict equivalent $\Rightarrow P(S_1)=P(S_2)$ Proof: (a \rightarrow b same as \neg b \rightarrow \neg a) Assume $P(S_1) \neq P(S_2)$ \Rightarrow 3 T_i: T_i \rightarrow T_j in S₁ and not in S₂ \Rightarrow S₁ = ...p_i(A)... q_j(A)... Pi, Qj conflict $S_2 = ...q_j(A)...p_i(A)...$

\Rightarrow S₁, S₂ not conflict equivalent





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Note: $P(S_1)=P(S_2) \not\Rightarrow S_1, S_2$ conflict equivalent



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Note: $P(S_1)=P(S_2) \neq S_1$, S_2 conflict equivalent

Counter example:

 $S_1 = w_1(A) r_2(A) w_2(B) r_1(B)$

 $S_2 = r_2(A) w_1(A) r_1(B) w_2(B)$



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Theorem

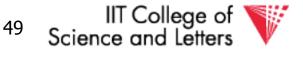
 $P(S_1)$ acyclic $\iff S_1$ conflict serializable

(\Leftarrow) Assume S₁ is conflict serializable \Rightarrow 3 S_s: S_s, S₁ conflict equivalent \Rightarrow P(S_s) = P(S₁) \Rightarrow P(S₁) acyclic since P(S_s) is acyclic



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Theorem

 $P(S_1)$ acyclic $\iff S_1$ conflict serializable

(⇒) Assume P(S₁) is acyclic T²
Transform S₁ as follows:
(1) Take T₁ to be transaction with no incident arcs
(2) Move all T₁ actions to the front

$$S_1 =, q_j(A)..., p_1(A)...$$

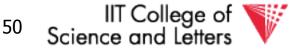


(3) we now have S1 = < T1 actions ><... rest ...>
(4) repeat above steps to serialize rest!

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Notes 14 - Concurrency Control



What's the damage?

- Classification of "bad" things that can happen in "bad" schedules
 - Dirty reads
 - Non-repeatable reads
 - Phantom reads (later)



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Notes 14 - Concurrency Control

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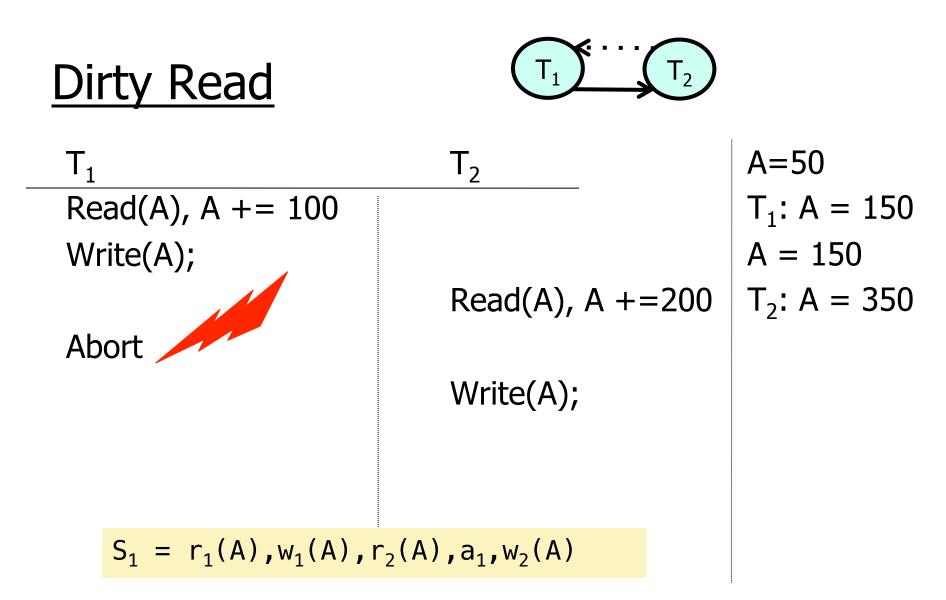
Dirty Read

- A transaction T₁ read a value that has been updated by an uncommitted transaction T₂
- If T₂ aborts then the value read by T₁ is invalid



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Non-repeatable Read

- A transaction T₁ reads items; some before and some after an update of these item by a transaction T₂
- Problem

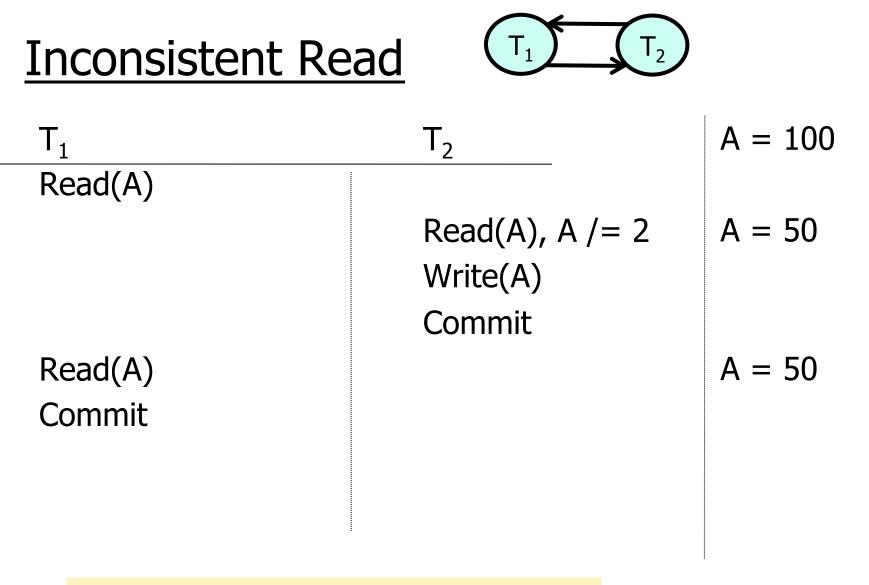
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- Repeated reads of the same item see different values
- Some values are modified and some are not



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Notes 14 - Concurrency Control

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Option 1: run system, recording P(S); at end of day, check for P(S) cycles and declare if execution was good



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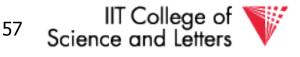
Option 1: run system, recording P(S); at end of day, check for P(S) cycles and declare if execution was good

This is called **optimistic concurrency control**

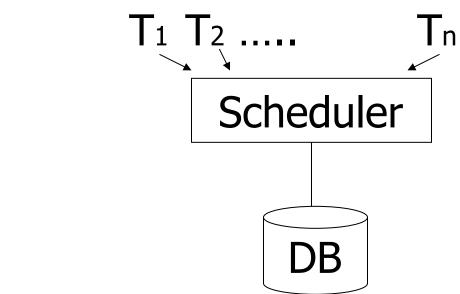


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Option 2: prevent P(S) cycles from occurring





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Option 2: prevent P(S) cycles from occurring

This is called **pessimistic concurrency control**



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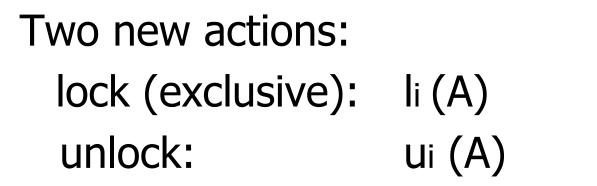
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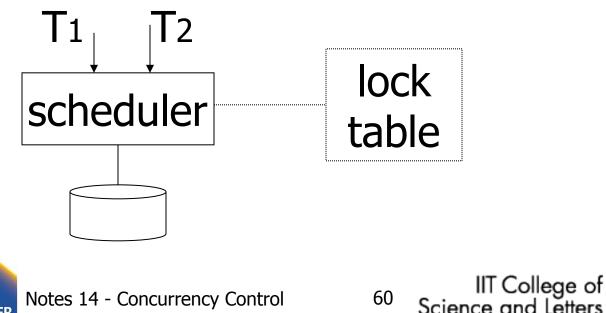
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A locking protocol







<u>Rule #1:</u> Well-formed transactions

Ti: ... li(A) ... pi(A) ... ui(A) ...

- 1) Transaction has to lock A before it can access A
- 2) Transaction has to unlock A eventually
- 3) Transaction cannot access A after unlock



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Rule #2 Legal scheduler

$S = \dots$ $Ii(A) \dots Ui(A) \dots$ no Ij(A)

4) Only one transaction can hold a lock on A at the same time



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Exercise:

 What schedules are legal? What transactions are well-formed?
 S₁ = l1(A)l1(B)r1(A)w1(B)l2(B)u1(A)u1(B) r2(B)w2(B)u2(B)l3(B)r3(B)u3(B)

 $S_2 = I_1(A)r_1(A)w_1(B)u_1(A)u_1(B)$ $I_2(B)r_2(B)w_2(B)I_3(B)r_3(B)u_3(B)$

 $S_3 = I_1(A)r_1(A)u_1(A)I_1(B)w_1(B)u_1(B)$ $I_2(B)r_2(B)w_2(B)u_2(B)I_3(B)r_3(B)u_3(B)$



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Exercise:

- What schedules are legal? What transactions are well-formed?
 S1 = l1(A)l1(B)r1(A)w1(B)l2(B)u1(A)u1(B) r2(B)w2(B)u2(B)l3(B)r3(B)u3(B)
 - $S2 = I_1(A)r_1(A)w_1(B)u_1(A)u_1(B)$ $I_2(B)r_2(B)w_2(B)I_3(B)r_3(B)u_3(B)$
 - $S3 = I_1(A)r_1(A)u_1(A)I_1(B)w_1(B)u_1(B)$ $I_2(B)r_2(B)w_2(B)u_2(B)I_3(B)r_3(B)u_3(B)$

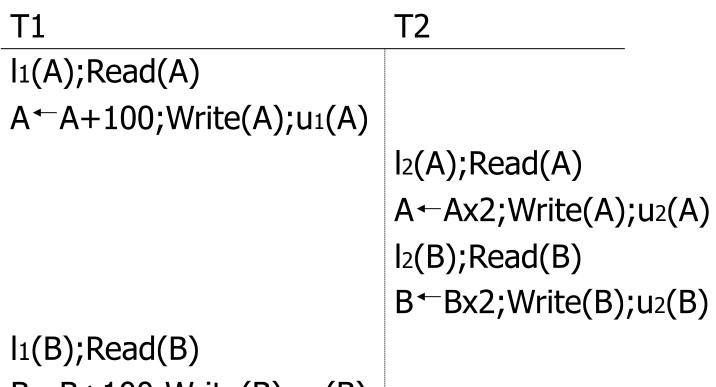


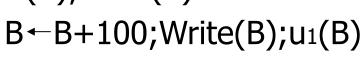
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Schedule F

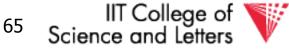






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Schedule F

		<u>A</u>	B
T1	T2	25	25
I1(A);Read(A)			
A←A+100;Write(A);u1(A)		125	
	I ₂ (A);Read(A)		
	A←Ax2;Write(A);u ₂ (A)	250	
	I ₂ (B);Read(B)		
	B←Bx2;Write(B);u ₂ (B)		50
I1(B);Read(B)			
B←B+100;Write(B);u1(B)			150
		250	150
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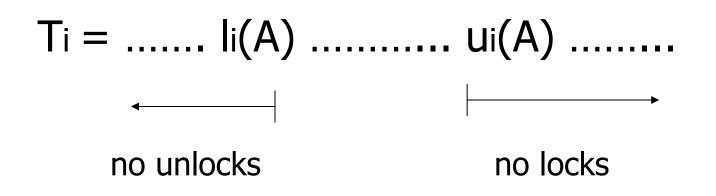
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Rule #3 Two phase locking (2PL) for transactions

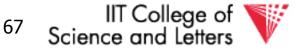


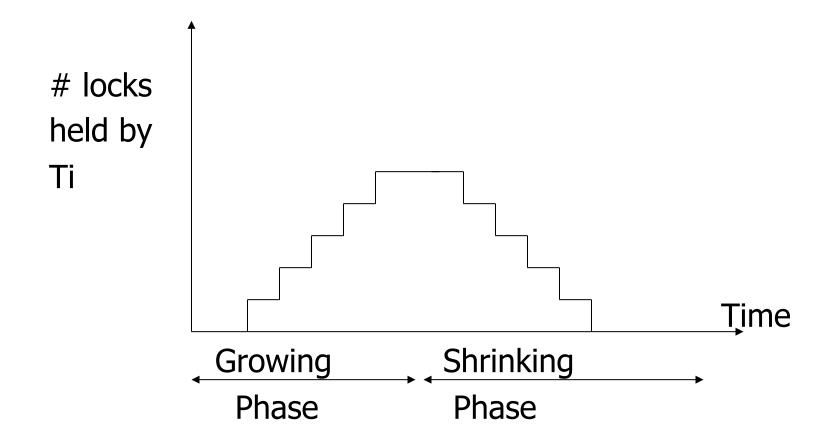
5) A transaction does not require new locks after its first unlock operation



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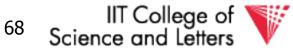




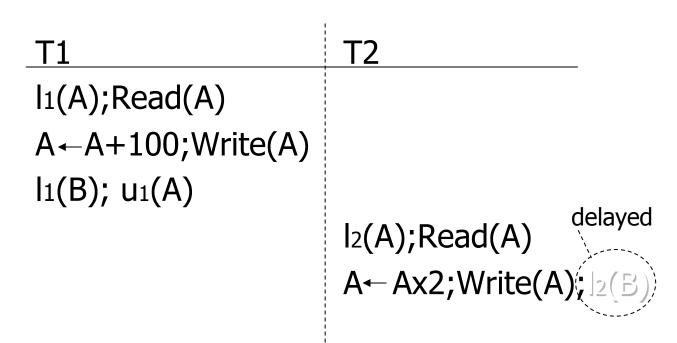


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Schedule G





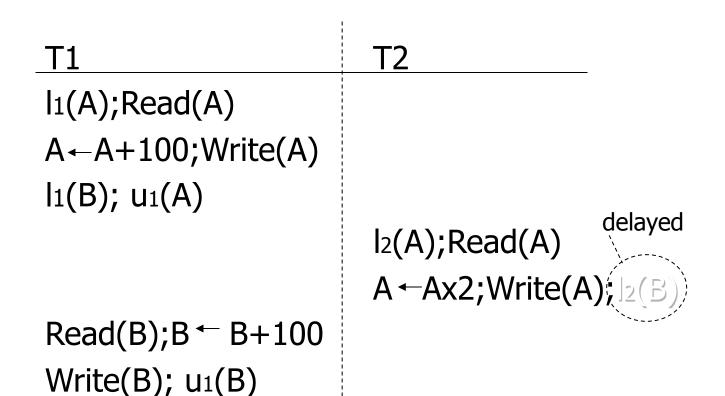
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Schedule G



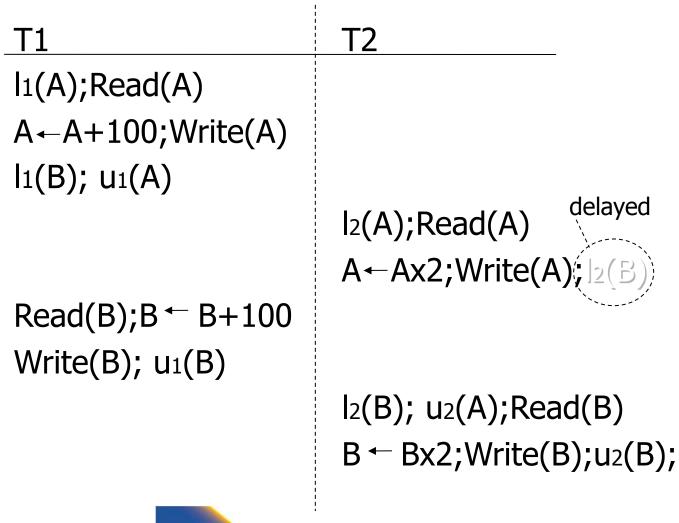


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Schedule G



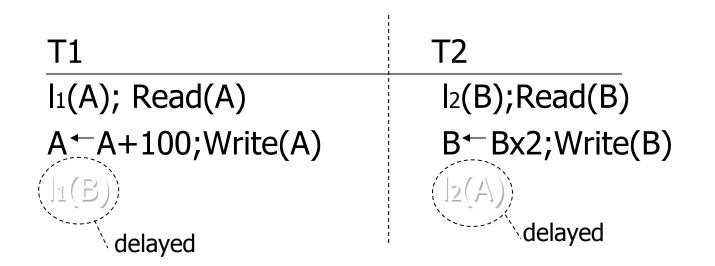




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Schedule H (T₂ reversed)





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Deadlock

- Two or more transactions are waiting for each other to release a lock
- In the example
 - T_1 is waiting for T_2 and is making no progress
 - T_2 is waiting for T_1 and is making no progress
 - -> if we do not do anything they would wait forever

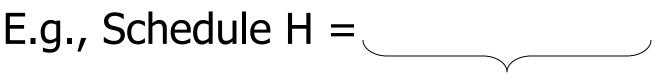


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- Assume deadlocked transactions are rolled back
 - They have no effect
 - They do not appear in schedule
 - Come back to that later



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Next step:

Show that rules $#1,2,3 \Rightarrow$ conflictserializable schedules



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<u>Conflict rules for</u> I_i(A), u_i(A):

- Ii(A), Ij(A) conflict
- Ii(A), Uj(A) conflict

Note: no conflict < ui(A), uj(A)>, < li(A), rj(A)>,...



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$\frac{\text{Theorem}}{(2\text{PL})} \text{ conflict}$ $\frac{\text{Schedule}}{\text{schedule}}$



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TheoremRules #1,2,3 \Rightarrow conflict(2PL)serializableschedule

To help in proof: <u>Definition</u> Shrink(Ti) = SH(Ti) = first unlock action of Ti



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<u>Lemma</u> Ti \rightarrow Tj in S \Rightarrow SH(Ti) <_S SH(Tj)



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<u>Lemma</u>

 $Ti \rightarrow Tj$ in $S \Rightarrow SH(Ti) <_{S} SH(Tj)$ Proof of lemma: Ti \rightarrow Tj means that $S = ... p_i(A) ... q_j(A) ...; p,q conflict$ By rules 1,2: $S = ... p_i(A) ... u_i(A) ... l_j(A) ... q_j(A) ...$



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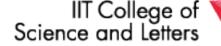
Lemma

 $Ti \rightarrow Tj$ in $S \Rightarrow SH(Ti) <_{S} SH(Tj)$ Proof of lemma: Ti \rightarrow Tj means that $S = ... p_i(A) ... q_i(A) ...; p,q conflict$ By rules 1,2: $S = ... p_i(A) ... u_i(A) ... l_j(A) ... q_j(A) ...$ By rule 3: SH(Ti) SH(Tj) So, SH(Ti) \leq_{S} SH(Tj)

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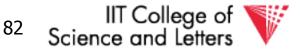
$\begin{array}{ll} \underline{\text{Theorem}} & \text{Rules } \#1,2,3 \implies \text{conflict} \\ & (2\text{PL}) & \text{serializable} \\ & \text{schedule} \end{array}$

Proof: (1) Assume P(S) has cycle $T_1 \rightarrow T_2 \rightarrow ..., T_n \rightarrow T_1$ (2) By lemma: SH(T₁) < SH(T₂) < ... < SH(T₁) (3) Impossible, so P(S) acyclic (4) \Rightarrow S is conflict serializable



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2PL subset of Serializable

$S \subset 2PL \subset CSR \subset ALL$

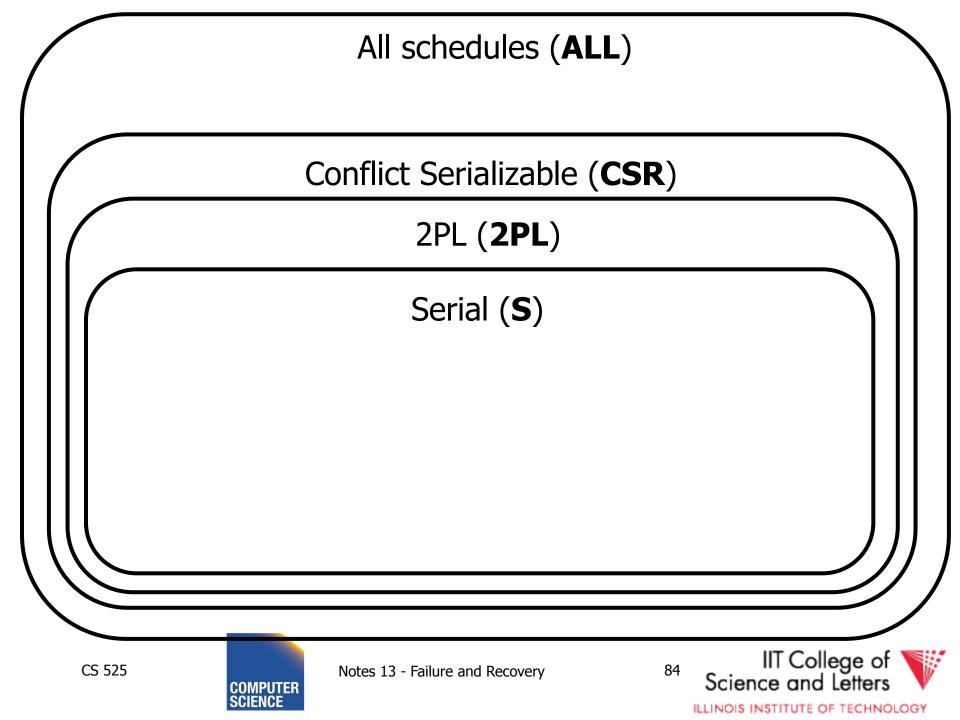


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S1: w1(x) w3(x) w2(y) w1(y)

- S1 cannot be achieved via 2PL: The lock by T1 for y must occur after w2(y), so the unlock by T1 for x must occur after this point (and before w1(x)). Thus, w3(x) cannot occur under 2PL where shown in S1 because T1 holds the x lock at that point.
- However, S1 is serializable (equivalent to T2, T1, T3).



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If you need a bit more practice: Are our schedules S_c and S_D 2PL schedules?

S_{c} : w1(A) w2(A) w1(B) w2(B)

S_{D} : w1(A) w2(A) w2(B) w1(B)



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- Beyond this simple **2PL** protocol, it is all a matter of improving performance and allowing more concurrency....
 - Shared locks
 - Multiple granularity
 - Avoid Deadlocks
 - Inserts, deletes and phantoms
 - Other types of C.C. mechanisms
 - Multiversioning concurrency control



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Shared locks

So far: $S = ...I_1(A) r_1(A) u_1(A) ... I_2(A) r_2(A) u_2(A) ...$

Do not conflict



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Shared locks

So far: $S = ...I_1(A) r_1(A) u_1(A) ... I_2(A) r_2(A) u_2(A) ...$ Do not conflict

Instead: S=... $Is_1(A) r_1(A) Is_2(A) r_2(A) us_1(A) us_2(A)$



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Lock actions I-t_i(A): lock A in t mode (t is S or X) u-t_i(A): unlock t mode (t is S or X)

<u>Shorthand:</u> u_i(A): unlock whatever modes Ti has locked A



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Rule #1 Well formed transactions

$T_i = ... I - S_1(A) ... r_1(A) ... u_1(A) ...$ $T_i = ... I - X_1(A) ... w_1(A) ... u_1(A) ...$



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 What about transactions that read and write same object?

<u>Option 1:</u> Request exclusive lock $T_i = \dots I - X_1(A) \dots r_1(A) \dots w_1(A) \dots u(A) \dots$



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• What about transactions that read and write same object?

Option 2: Upgrade

(E.g., need to read, but don't know if will write...)

$T_i = \dots I-S_1(A) \dots r_1(A) \dots I-X_1(A) \dots w_1(A) \dots u(A) \dots$ Think of - Get 2nd lock on A, or - Drop S, get X lock



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Rule #2 Legal scheduler $S =I-S_i(A) U_i(A) ...$ no I-X_j(A) $S = ... I - X_i(A) u_i(A) ...$ no I-X_j(A) no I-S_j(A)



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A way to summarize Rule #2

Compatibility matrix

Comp

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	S	X
S	true	false
X	false	false



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Rule # 3 2PL transactions

No change except for upgrades: (I) If upgrade gets more locks (e.g., $S \rightarrow \{S, X\}$) then no change! (II) If upgrade releases read (shared) lock (e.g., $S \rightarrow X$)

- can be allowed in growing phase



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TheoremRules 1,2,3 \Rightarrow Conf.serializablefor S/X locksschedules

Proof: similar to X locks case

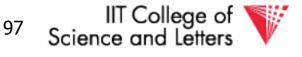
Detail:

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I-t_i(A), I-r_j(A) do not conflict if comp(t,r) I-t_i(A), u-r_j(A) do not conflict if comp(t,r)



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Lock types beyond S/X

Examples:

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(1) increment lock(2) update lock



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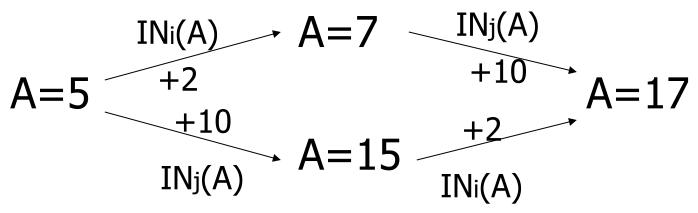
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Example (1): increment lock

• Atomic increment action: INi(A)

{Read(A); $A \leftarrow A+k$; Write(A)}

• IN_i(A), IN_j(A) do not conflict!





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	S	X	Ι
S			
Х			
Ι			



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	S	X	Ι
S	Т	F	F
X	F	F	F
Ι	F	F	Т



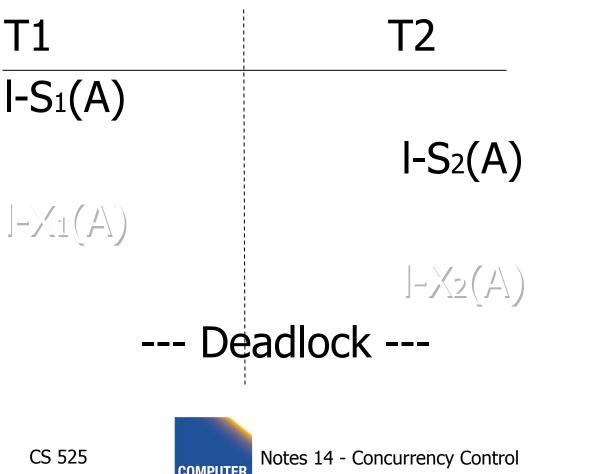
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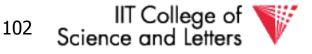
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Update locks

A common deadlock problem with upgrades:





<u>Solution</u>

If T_i wants to read A and knows it may later want to write A, it requests <u>update</u> lock (not shared)



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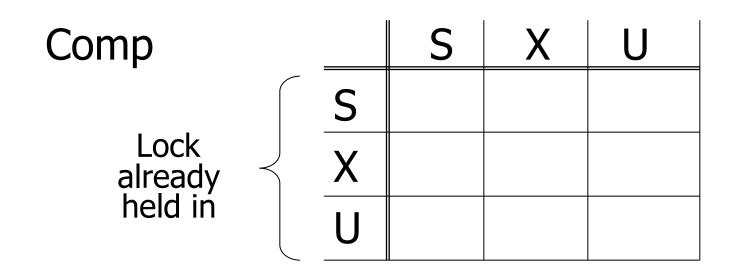
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New request



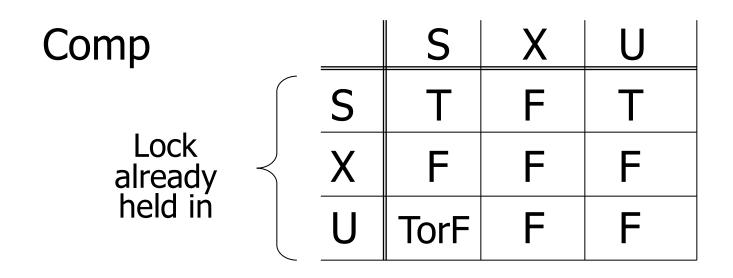


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New request

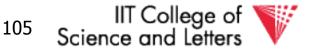


-> symmetric table?



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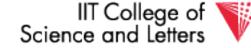
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<u>Note:</u> object A may be locked in different modes at the same time...

$$S_1 = ... I - S_1(A) ... I - S_2(A) ... I - U_3(A) ... I - S_4(A) ...?$$

I - U_4(A) ...?





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<u>Note:</u> object A may be locked in different modes at the same time...

$$S_1 = ... I - S_1(A) ... I - S_2(A) ... I - U_3(A) ... I - S_4(A) ... ?$$

I - U₄(A) ... ?

1

 To grant a lock in mode t, mode t must be compatible with all currently held locks on object



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How does locking work in practice?

• Every system is different

(E.g., may not even provide CONFLICT-SERIALIZABLE schedules)

• But here is one (simplified) way ...



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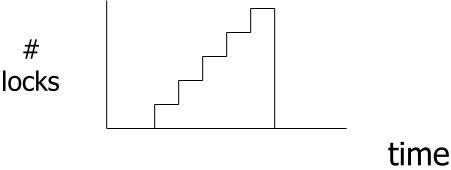
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Sample Locking System:

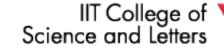
(1) Don't trust transactions to request/release locks (2) Hold all locks until transaction commits





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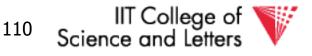
Strict Strong 2PL (SS2PL)

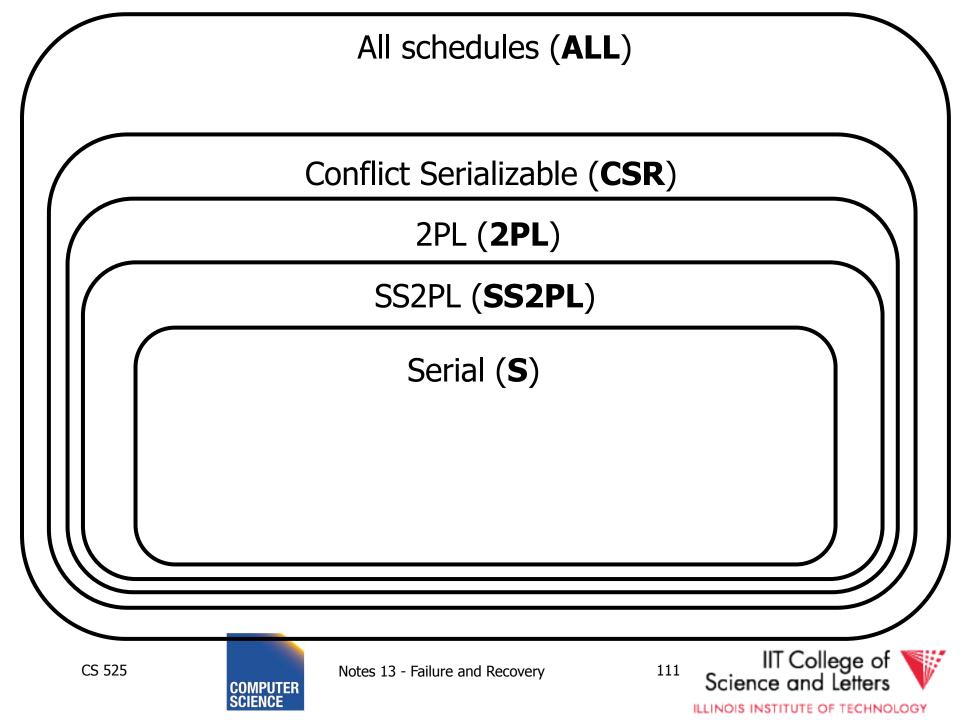
- 2PL + (2) from the last slide
- All locks are held until transaction end
- Compare with schedule class strict
 (ST) we defined for recovery
 - A transaction never reads or writes items written by an uncommitted transactions
- SS2PL = (ST \cap 2PL)

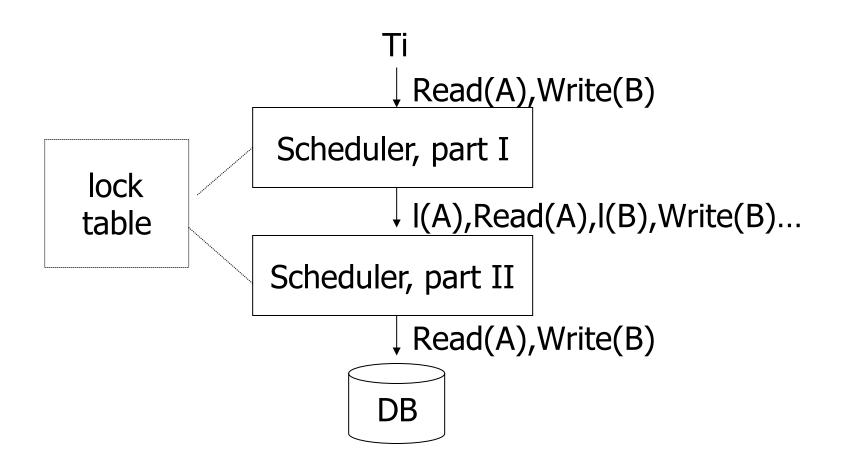


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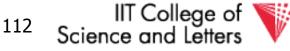




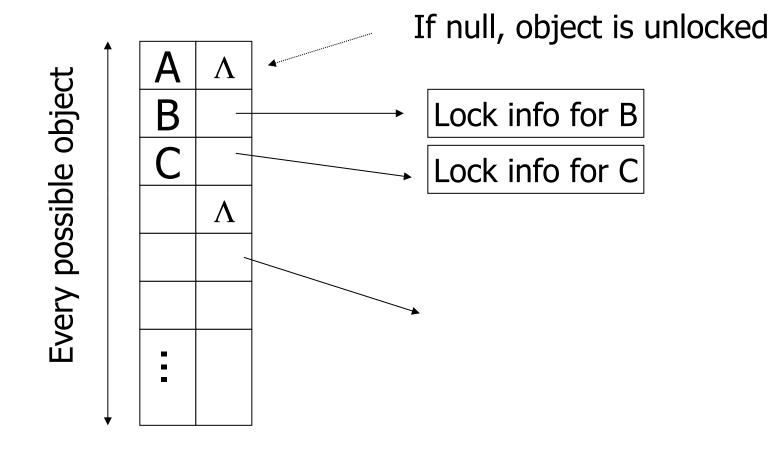


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Lock table Conceptually





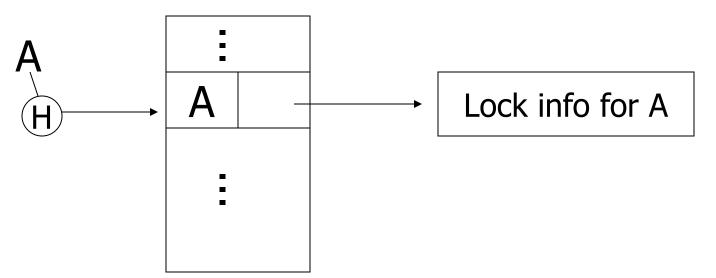
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But use hash table:



If object not found in hash table, it is unlocked



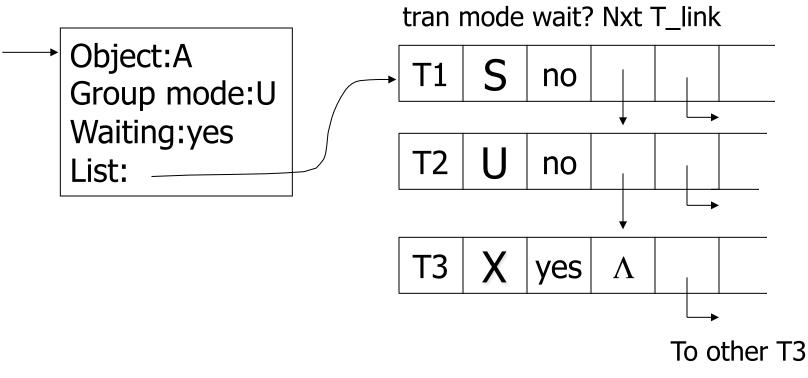
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Lock info for A - example



records

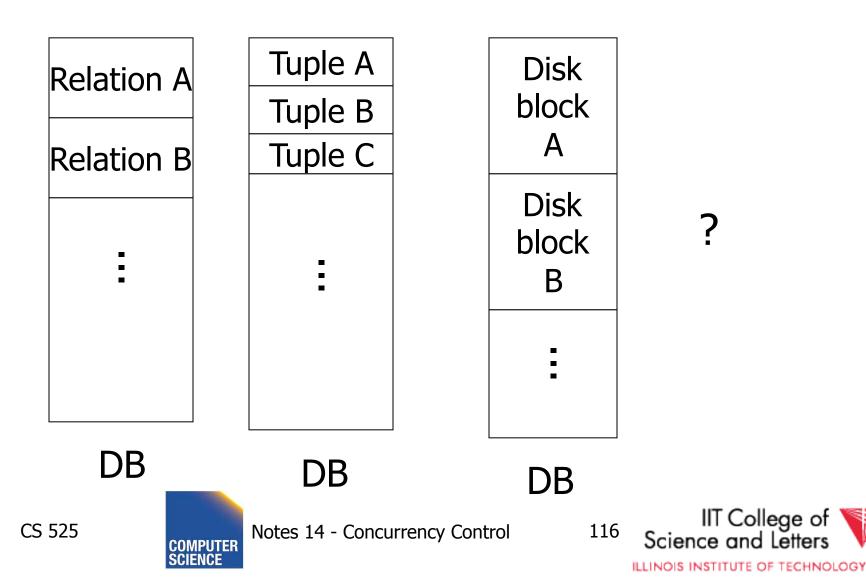


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What are the objects we lock?



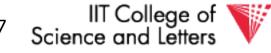
 Locking works in any case, but should we choose <u>small</u> or <u>large objects?</u>



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- Locking works in any case, but should we choose <u>small</u> or <u>large objects?</u>
- If we lock <u>large</u> objects (e.g., Relations)
 Need few locks
 - Low concurrency
- If we lock small objects (e.g., tuples, fields)
 Need more locks
 - More concurrency



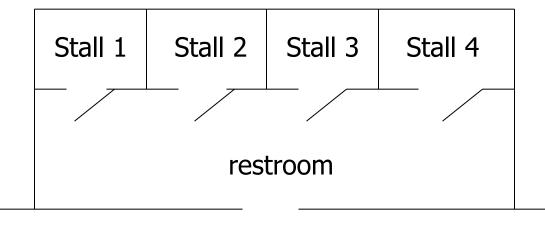
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We <u>can</u> have it both ways!!

Ask any janitor to give you the solution...

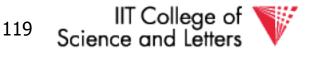


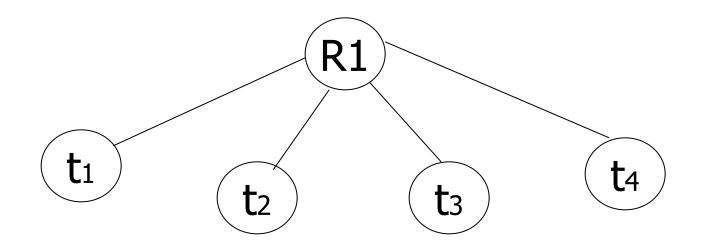
hall



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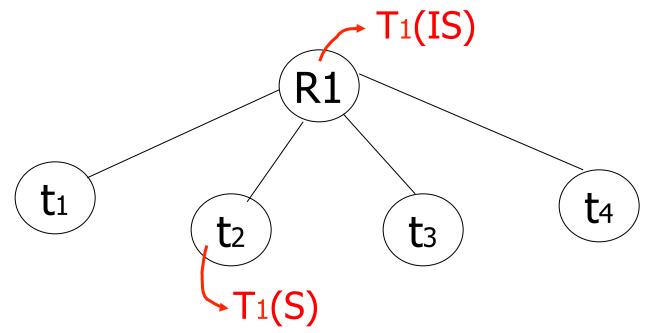


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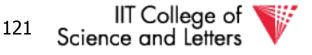
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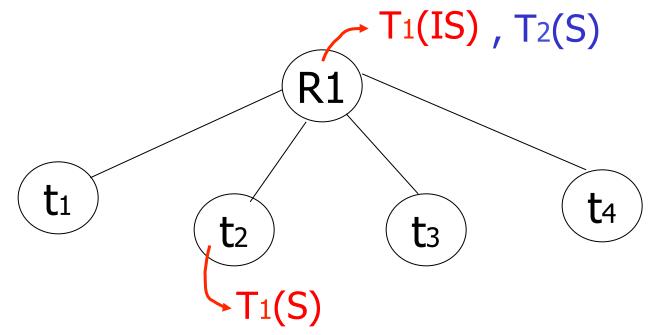




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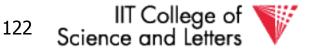




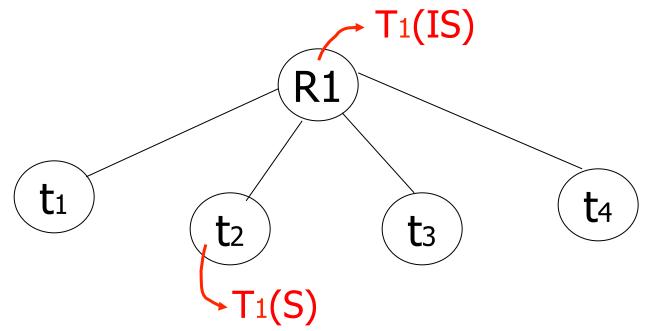


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Example (b)



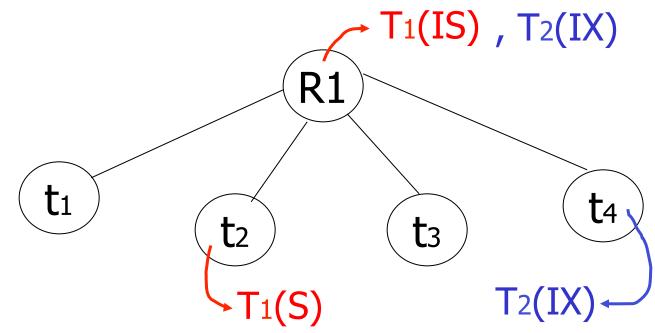


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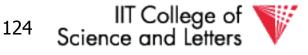
123

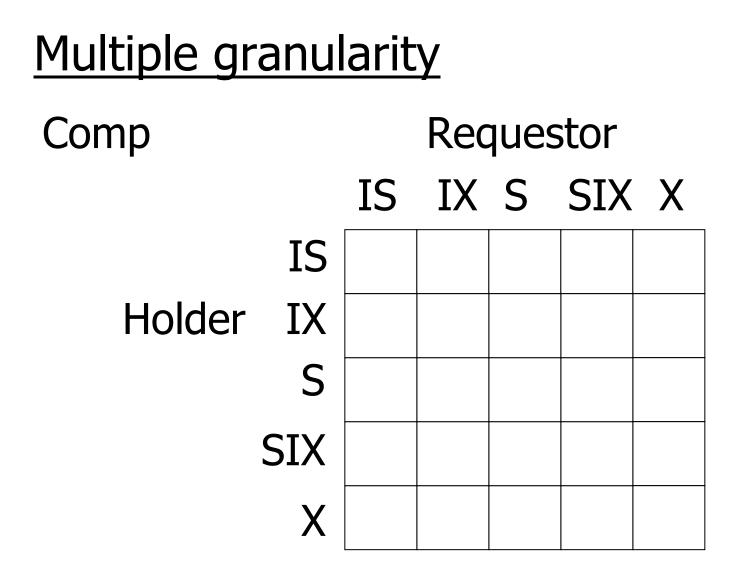




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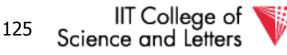


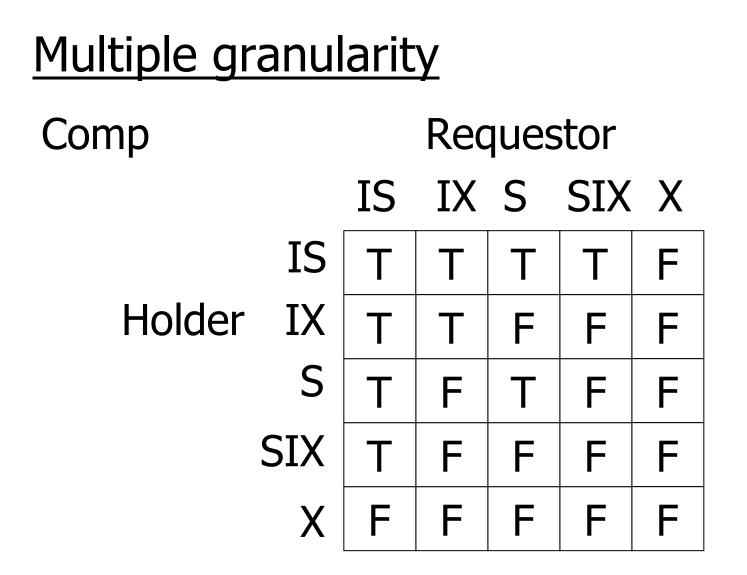




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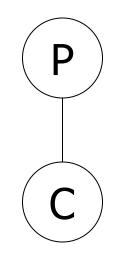




Notes 14 - Concurrency Control

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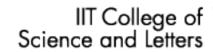
Parent locked in	Child can be locked in	
IS IX		_
S		
SIX		
X		





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Parent locked in	Child can be locked by same transaction	
IS IX S SIX X	IS, S IS, S, IX, X, SIX none X, IX, [SIX] none	PCNot necessary



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<u>Rules</u>

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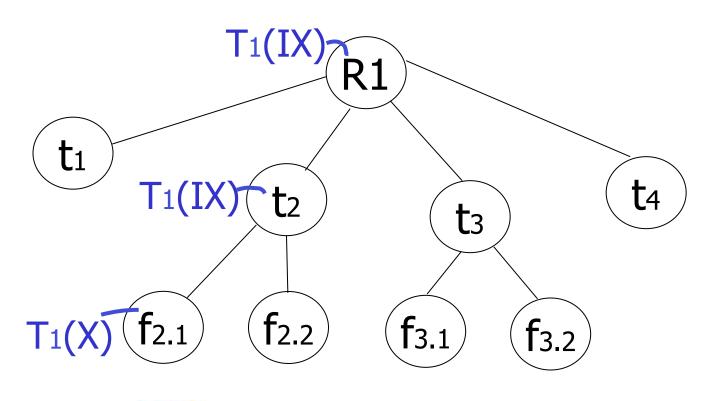
- (1) Follow multiple granularity comp function
- (2) Lock root of tree first, any mode
- (3) Node Q can be locked by Ti in S or IS only if parent(Q) locked by Ti in IX or IS
- (4) Node Q can be locked by Ti in X,SIX,IX only if parent(Q) locked by Ti in IX,SIX
- (5) Ti is two-phase
- (6) Ti can unlock node Q only if none of Q's children are locked by Ti



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• Can T₂ access object f_{2.2} in X mode? What locks will T₂ get?





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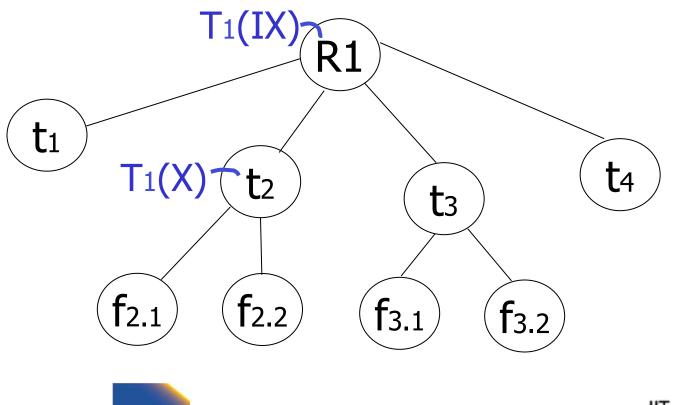
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• Can T₂ access object f_{2.2} in X mode? What locks will T₂ get?





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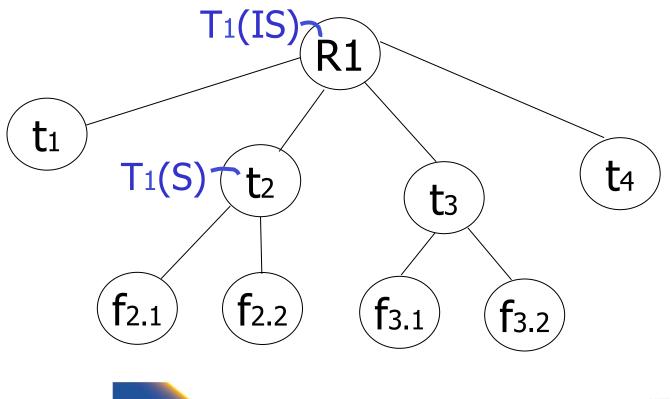
Notes 14 - Concurrency Control

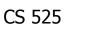
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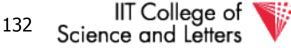
• Can T₂ access object f_{3.1} in X mode? What locks will T₂ get?



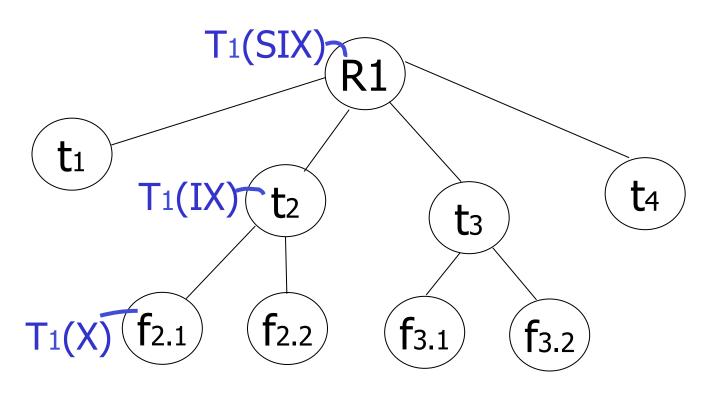


COMPLITE

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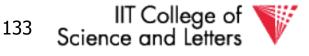
 Can T₂ access object f_{2.2} in S mode? What locks will T₂ get?



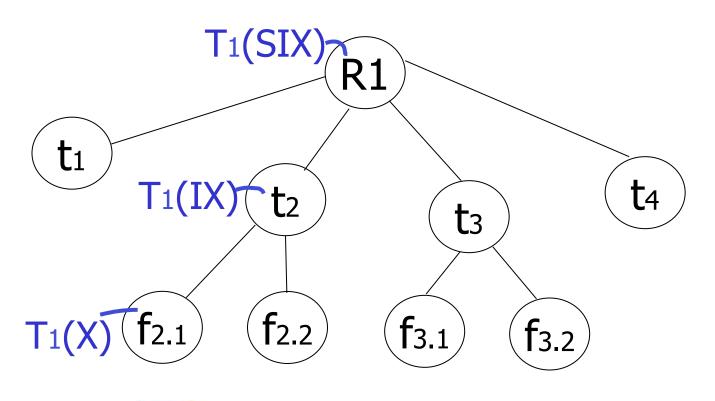


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• Can T₂ access object f_{2.2} in X mode? What locks will T₂ get?



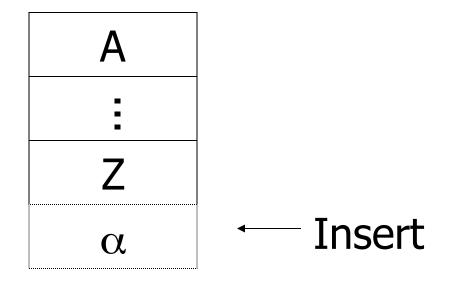


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Insert + delete operations





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Modifications to locking rules:

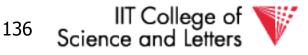
(1) Get exclusive lock on A before deleting A

(2) At insert A operation by Ti,Ti is given exclusive lock on A



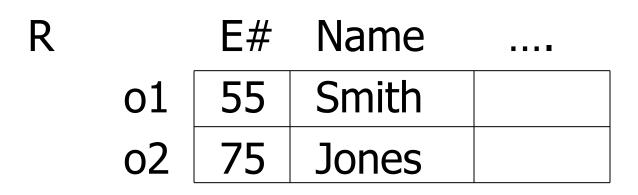
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Still have a problem: Phantoms

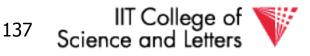
Example: relation R (E#,name,...) constraint: E# is key use tuple locking





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T₁: Insert <08,Obama,...> into R T₂: Insert <08,McCain,...> into R

T1	T 2
S1(01)	S2(01)
S1(02)	S2(02)
Check Constraint	Check Constraint
: Insert o ₃ [08,Obama,]	
	Insert o4[08,McCain,]
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Solution

- Use multiple granularity tree
- Before insert of node Q, lock parent(Q) in X mode

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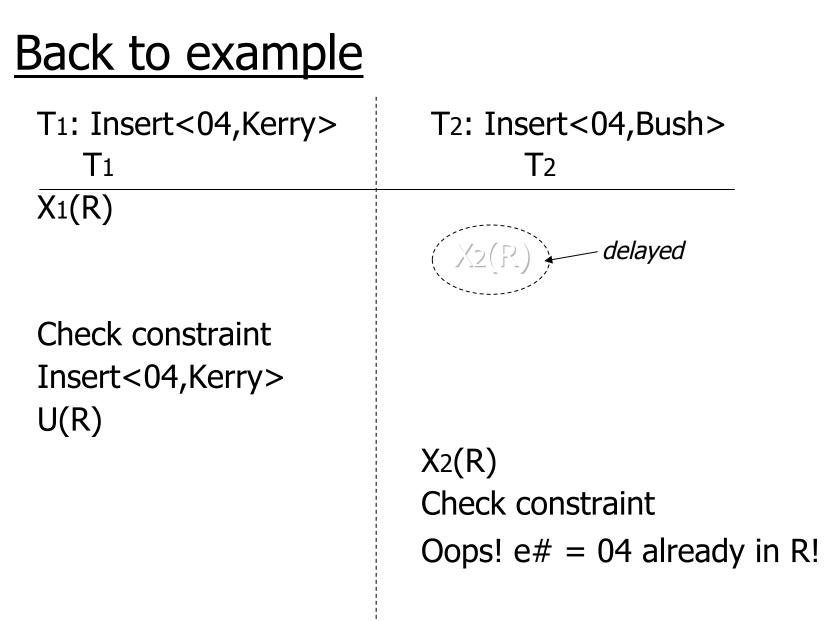
t1



t₃

R1

t₂





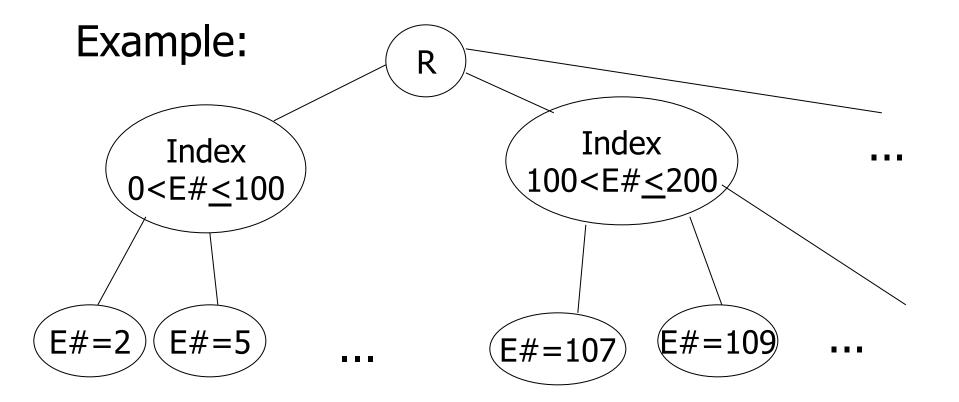
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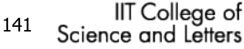
Instead of using R, can use index on R:





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• This approach can be generalized to multiple indexes...



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Next:

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- Tree-based concurrency control
- Validation concurrency control



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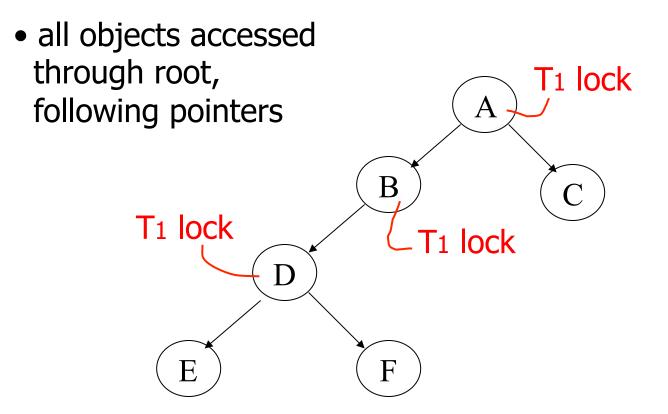
 all objects accessed through root, following pointers A В С D F E



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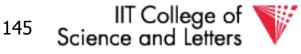


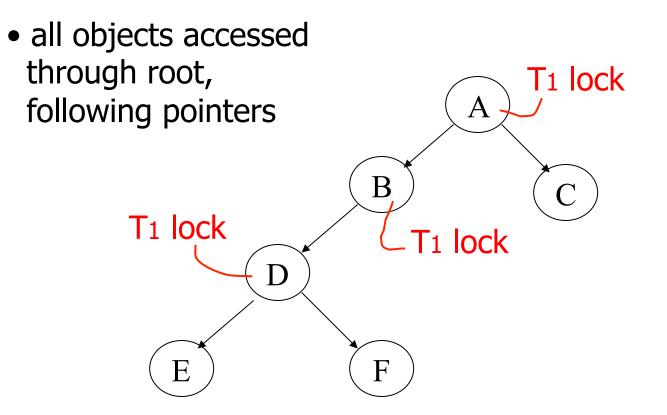




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can we release A lock if we no longer need A??



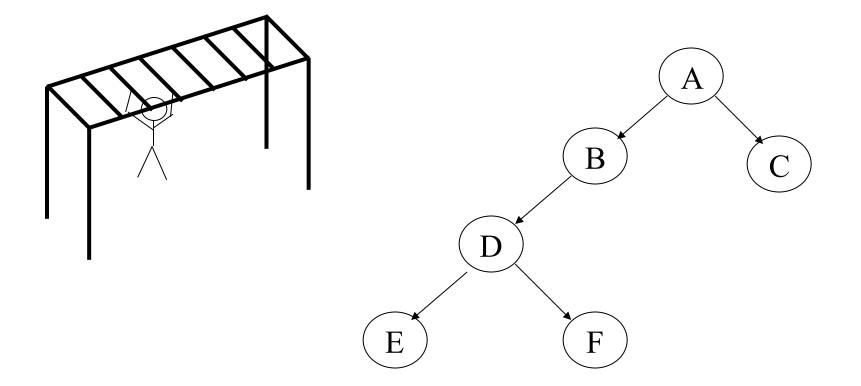
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Idea: traverse like "Monkey Bars"





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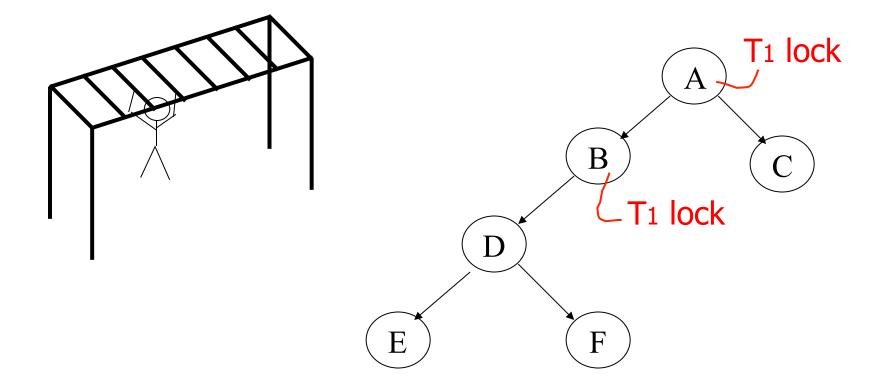
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Idea: traverse like "Monkey Bars"





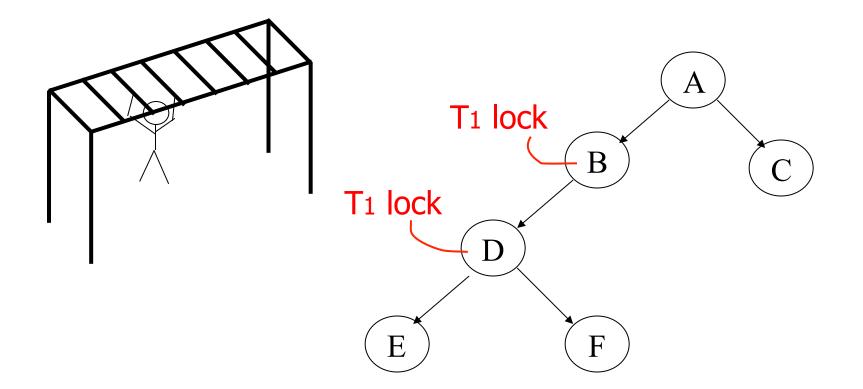
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Idea: traverse like "Monkey Bars"





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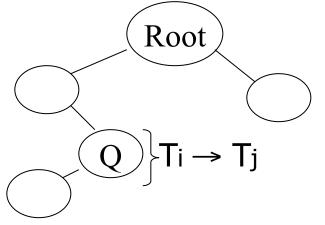
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Why does this work?

- Assume all Ti start at root; exclusive lock
- $T_i \rightarrow T_j \Rightarrow T_i$ locks root before T_j

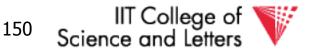


Actually works if we don't always start at root



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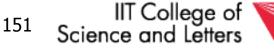
Rules: tree protocol (exclusive locks)

(1) First lock by Ti may be on any item
 (2) After that, item Q can be locked by Ti only if parent(Q) locked by Ti
 (3) Items may be unlocked at any time
 (4) After Ti unlocks Q, it cannot relock Q

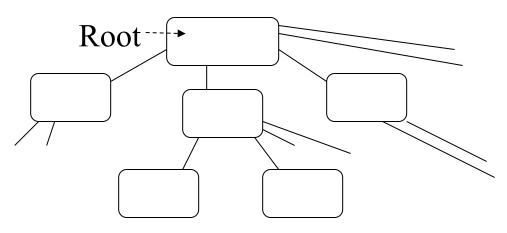


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• Tree-like protocols are used typically for B-tree concurrency control



E.g., during insert, do not release parent lock, until you are certain child does not have to split



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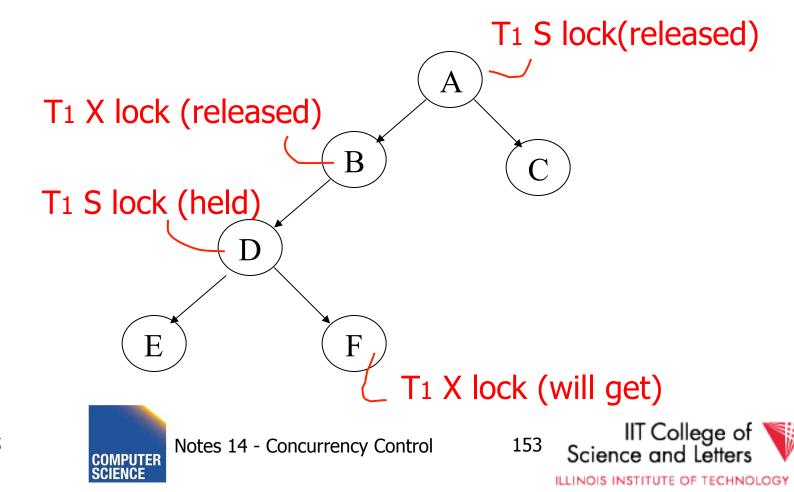
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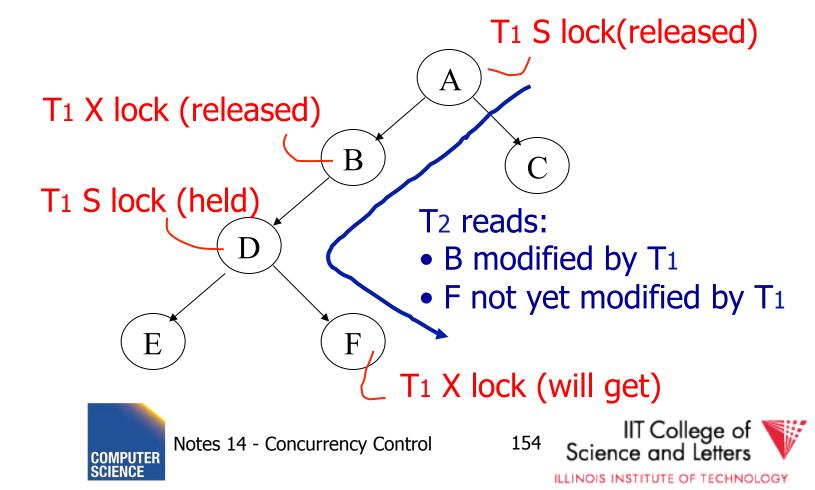
Tree Protocol with Shared Locks

• Rules for shared & exclusive locks?



Tree Protocol with Shared Locks

• Rules for shared & exclusive locks?



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Tree Protocol with Shared Locks

- Need more restrictive protocol
- Will this work??
 - Once T₁ locks one object in X mode, all further locks down the tree must be in X mode



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Deadlocks (again)

- Before we assumed that we are able to detect deadlocks and resolve them
- Now two options
 - -(1) Deadlock detection (and resolving)
 - -(2) Deadlock prevention

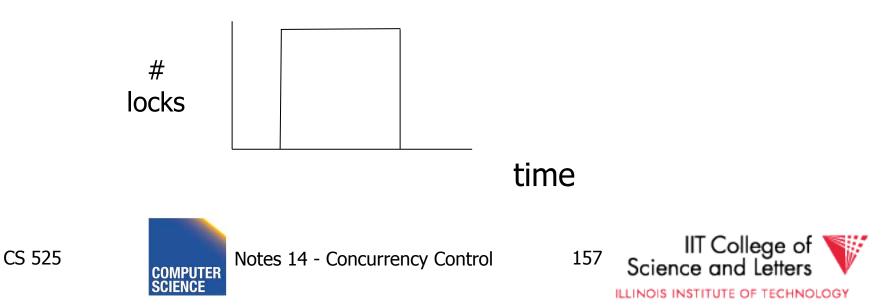


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- Option 1:
 - 2PL + transaction has to acquire all locks at transaction start following a global order

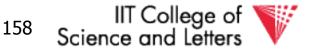


- Option 1:
 - Long lock durations 🛞
 - − Transaction has to know upfront what data items it will access ⊗
 - E.g., UPDATE R SET a = a + 1 WHERE b < 15
 - We don't know what tuples are in R!



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- Option 2:
 - Define some global order of data items O
 - Transactions have to acquire locks according to this order
- Example (X < Y < Z) $I_1(X), I_1(Z)$ (OK) $I_1(Y), I_1(X)$ (NOT OK)



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- Option 2:
 - Accessed data items have to be known upfront ⊗
 - or access to data has to follow the order $\ensuremath{\mathfrak{S}}$



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• Option 3 (**Preemption**)

 Roll-back transactions that wait for locks under certain conditions

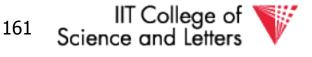
-3 a) **wait-die**

- Assign timestamp to each transaction
- If transaction T_i waits for T_i to release a lock
 - Timestamp $T_i < T_j \rightarrow$ wait
 - Timestamp $T_i > T_j ->$ roll-back T_i



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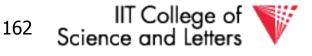
• Option 3 (**Preemption**)

- Roll-back transactions that wait for locks under certain conditions
- -3 a) wound-wait
 - Assign timestamp to each transaction
 - If transaction T_i waits for T_i to release a lock
 - Timestamp $T_i < T_j \rightarrow roll-back T_j$
 - Timestamp $T_i > T_j ->$ wait



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• Option 3:

– Additional transaction roll-backs 😕



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¹⁶³ Scier



Timeout-based Scheme

- Option 4:
 - After waiting for a lock longer than X, a transaction is rolled back



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Timeout-based Scheme

- Option 4:
 - Simple scheme 🙂
 - Hard to find a good value of X
 - To high: long wait times for a transaction before it gets eventually aborted
 - To low: to many transaction that are not deadlock get aborted



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Deadlock Detection and Resolution

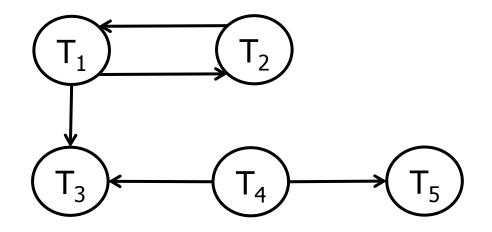
- Data structure to detect deadlocks: wait-for graph
 - One node for each transaction
 - Edge T_i -> T_j if T_i is waiting for T_j
 - Cycle -> Deadlock
 - Abort one of the transaction in cycle to resolve deadlock





Deadlock Detection and Resolution

- When do we run the detection?
- How to choose the victim?





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Optimistic Concurrency Control:

Validation

Transactions have 3 phases:

- (1) <u>Read</u>
 - all DB values read
 - writes to temporary storage
 - no locking
- (2) <u>Validate</u>

- check if schedule so far is serializable

(3) <u>Write</u>

- if validate ok, write to DB







<u>Key idea</u>

- Make validation atomic
- If T₁, T₂, T₃, ... is validation order, then resulting schedule will be conflict equivalent to S_s = T₁ T₂ T₃...



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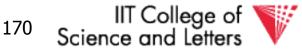
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- To implement validation, system keeps <u>two sets:</u>
- <u>FIN</u> = transactions that have finished phase 3 (and are all done)
- <u>VAL</u> = transactions that have successfully finished phase 2 (validation)

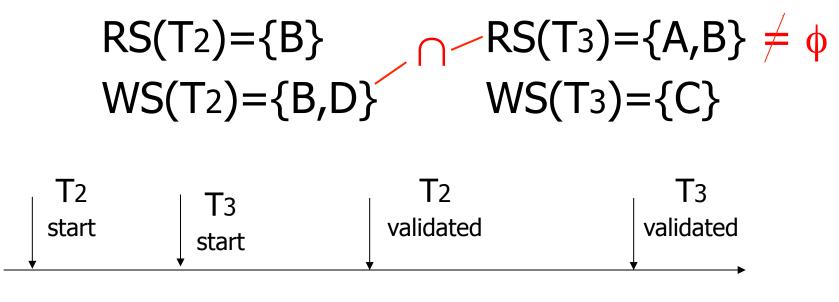


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Example of what validation must prevent:



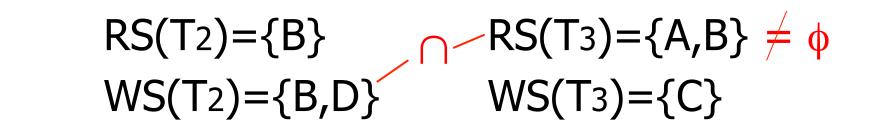
time

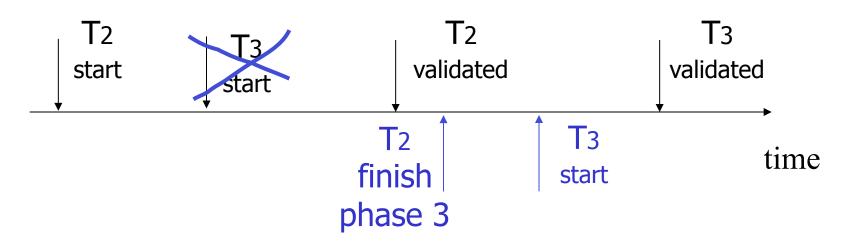


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allow Example of what validation must prevent:

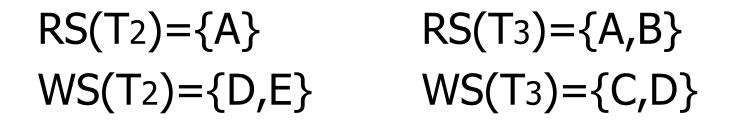


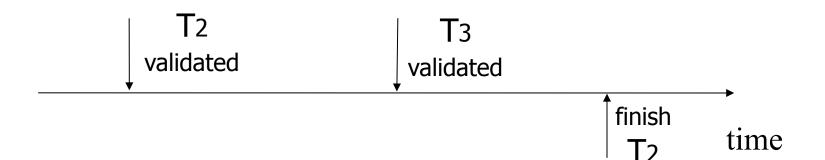






Another thing validation must prevent:

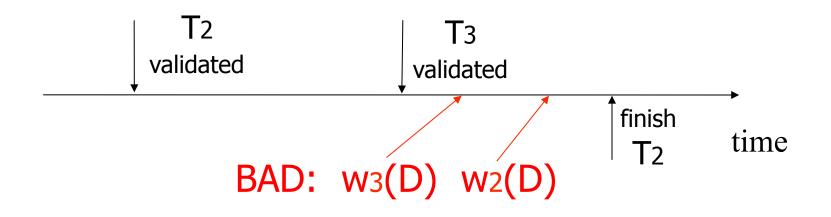






Another thing validation must prevent:

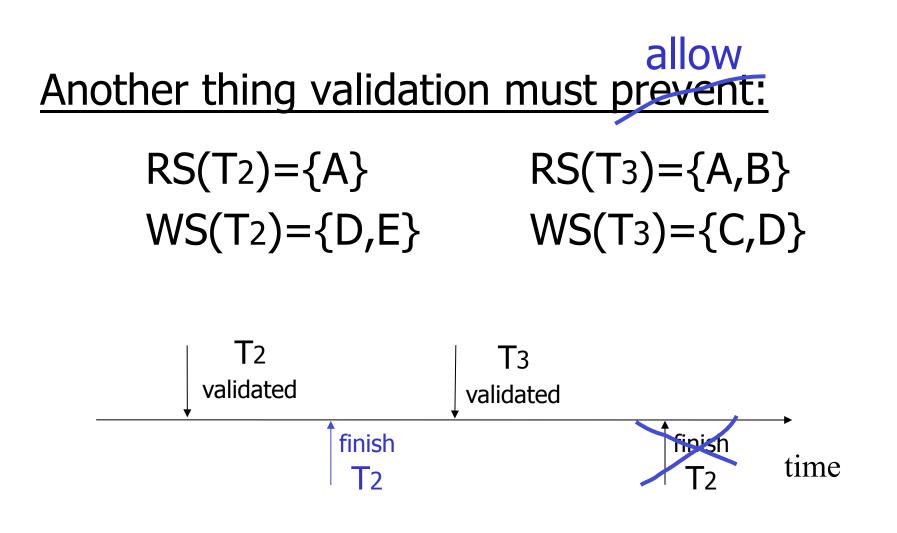






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Validation rules for Tj:

(1) When T_j starts phase 1: ignore(T_j) ← FIN (2) at T_j Validation: if check (T_j) then $[VAL \leftarrow VAL \cup \{T_j\};$ do write phase; FIN \leftarrow FIN U {T_i}]



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Check (Tj): For Ti \in VAL - IGNORE (Tj) DO IF [WS(Ti) \cap RS(Tj) $\neq \emptyset$ OR Ti \notin FIN] THEN RETURN false; RETURN true;



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Check (Tj): For Ti \in VAL - IGNORE (Tj) DO IF [WS(Ti) \cap RS(Tj) $\neq \emptyset$ OR Ti \notin FIN] THEN RETURN false; RETURN true;

Is this check too restrictive ?



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Improving Check(T_j)

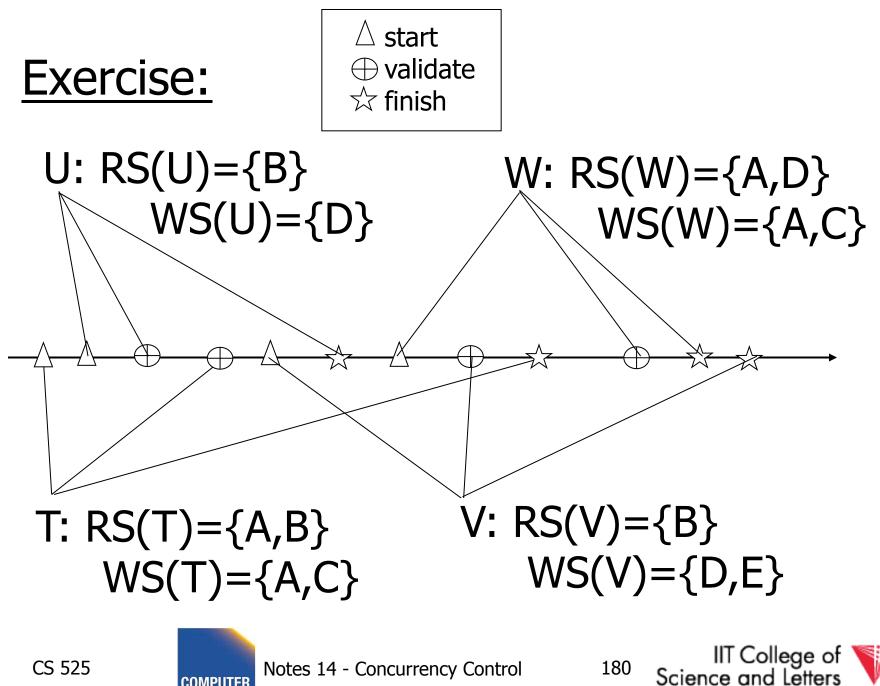
For $Ti \in VAL - IGNORE(Tj) DO$ IF [WS(Ti) \cap RS(Tj) $\neq \emptyset$ OR ($Ti \notin FIN \text{ AND WS}(Ti) \cap WS(Tj) \neq \emptyset$)] THEN RETURN false; RETURN true;



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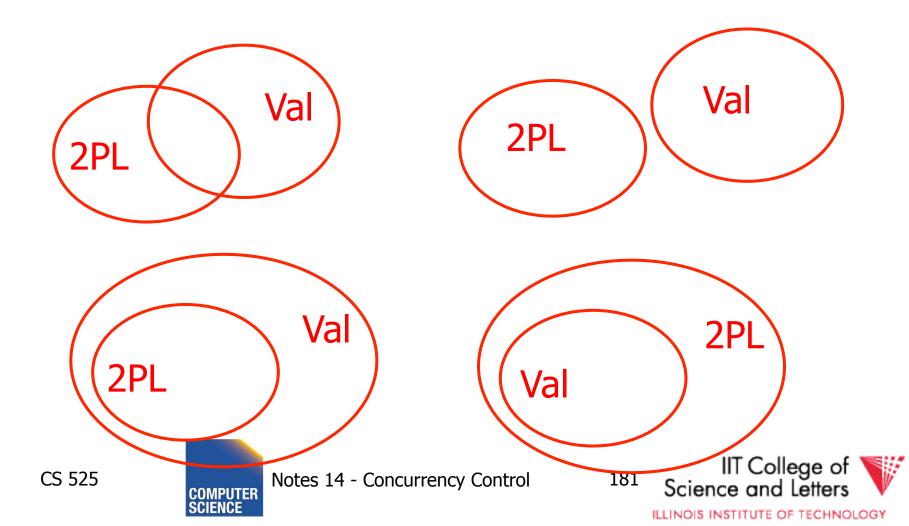
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Is Validation = 2PL?



S2: w2(y) w1(x) w2(x)

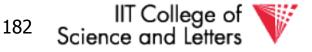
- S2 can be achieved with 2PL:
 l2(y) w2(y) l1(x) w1(x) u1(x) l2(x) w2(x) u2(y) u2(x)
- S2 cannot be achieved by validation: The validation point of T2, val2 must occur before w2(y) since transactions do not write to the database until after validation. Because of the conflict on x, val1 < val2, so we must have something like

S2: val1 val2 w2(y) w1(x) w2(x) With the validation protocol, the writes of T2 should not start until T1 is all done with its writes, which is not the case.



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Validation subset of 2PL?

- Possible proof (Check!):
 - Let S be validation schedule
 - For each T in S insert lock/unlocks, get S':
 - At T start: request read locks for all of RS(T)
 - At T validation: request write locks for WS(T); release read locks for read-only objects
 - At T end: release all write locks
 - Clearly transactions well-formed and 2PL
 - Must show S' is legal (next page)



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- Say S' not legal:
 - S': ... l1(x) w2(x) r1(x) val1 u2(x) ...
 - At val1: T2 not in Ignore(T1); T2 in VAL
 - − T1 does not validate: WS(T2) \cap RS(T1) ≠ Ø
 - contradiction!
- Say S' not legal:
 - S': ... val1 l1(x) w2(x) w1(x) u2(x) ...
 - Say T2 validates first (proof similar in other case)
 - At val1: T2 not in Ignore(T1); T2 in VAL
 - T1 does not validate: T2 ∉ FIN AND WS(T1) \cap WS(T2) ≠ Ø)
 - contradiction!

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Validation (also called **optimistic concurrency control**) is useful in some cases:

- Conflicts rare
- System resources plentiful
- Have real time constraints



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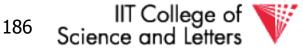
Multiversioning Concurrency Control (MVCC)

- Keep old versions of data item and use this to increase concurrency
- Each write creates a new version of the written data item
- Use version numbers of timestamps to identify versions



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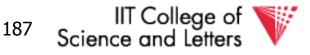
Multiversioning Concurrency Control (MVCC)

- Different transactions operate over different versions of data items
- -> readers never have to wait for writers
- -> great for combined workloads
 - OLTP workload (writes, only access small number of tuples, short)
 - OLAP workload (reads, access large portions of database, long running)



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MVCC schemes

- MVCC timestamp ordering
- MVCC 2PL

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- Snapshot isolation (SI)
 - We will only cover this one



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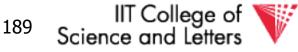
Snapshot Isolation (SI)

- Each transaction **T** is assigned a timestamp
 S(T) when it starts
- Each write creates a new data item version timestamped with the current timestamp
- When a transaction commits, then the latest versions created by the transaction get a timestamp C(T) as of the commit



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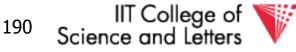
Snapshot Isolation (SI)

- Under snapshot isolation each transaction T sees a consistent snapshot of the database as of S(T)
 - It only sees data item versions of transactions that committed before T started
 - It also sees its own changes



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First Updater Wins Rule (FUW)

- Two transactions Ti and Tj may update the same data item A
 - To avoid lost updates only one of the two can be safely committed

• First Updater Wins Rules

- The transaction that updated A first is allowed to commit
- The other transaction is aborted



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First Committer Wins Rule (FCW)

- Two transactions Ti and Tj may update the same data item A
 - To avoid lost updates only one of the two can be safely committed

• First Committer Wins Rules

- The transaction that attempts to commit first is allowed to commit
- The other transaction is aborted



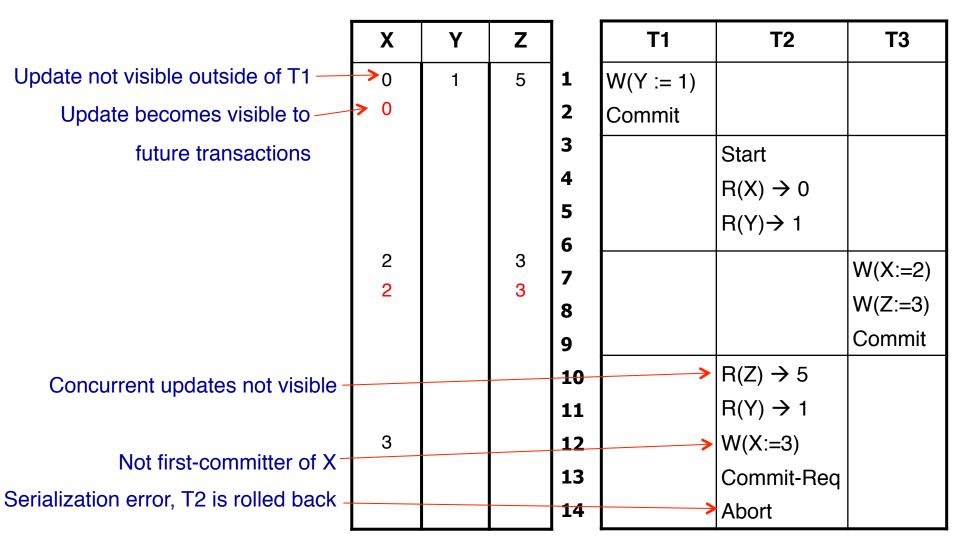
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Why does that work?

- Since all transactions see a consistent snapshot and their changes are only made "public" once they commit
 - It looks like the transactions have been executed in the order of their commits*
- * Recall the writes to the same data item are disallowed for concurrent transactions





Notes 14 - Concurrency Control





Is that serializable?

- Almost ;-)
- There is still one type of conflict which cannot occur in serialize schedules called write-skew



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Write Skew

- Consider two data items A and B -A = 5, B = 5
- Concurrent Transactions T1 and T2

$$-T1: A = A + B$$

- -T2: B = A + B
- Final result under SI

-A = 10, B = 10



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Write Skew

- Consider serial schedules:
 -T1, T2: A=10, B=15
 - -T2, T1: A=15, B=10
- What is the problem
 - Under SI both T1 and T2 do not see each others changes
 - In any serial schedule one of the two would see the others changes



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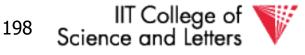
Example: Oracle

- Tuples are updated in place
- Old versions in separate ROLLBACK segment
 GC once nobody needs them anymore
- How to implement the FCW or FUW?
 - Oracle uses write locks to block concurrent writes
 - Transaction waiting for a write lock aborts if transaction holding the lock commits



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Notes 14 - Concurrency Control



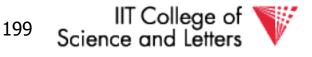
SI Discussion

- Advantages
 - Readers and writers do not block each other
 - If we do not GC old row versions we can go back to previous versions of the database -> Time travel
 - E.g., show me the customer table as it was yesterday
- Disadvantages
 - Storage overhead to keep old row versions
 - GC overhead
 - Not strictly serializable





Notes 14 - Concurrency Control



<u>Summary</u>

Have studied CC mechanisms used in practice

- 2 PL variants
- Multiple lock granularity
- Deadlocks
- Tree (index) protocols
- Optimistic CC (Validation)
- Multiversioning Concurrency Control (MVCC)



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Notes 14 - Concurrency Control

